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ENHANCEMENT OF THE MAGNETIC MOMENT OF THE Λ^0 BARYON

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ABSTRACT

This thesis is about an experiment performed in order to measure the magnetic moment of Λ^0 hyperon. The polarization vector of the Λ^0 hyperons produced in the reaction $\pi^+ p \rightarrow \Lambda^0 e^+$ was made to precess around a transverse magnetic field of 230 kG. Their decays were detected in nuclear emulsions, and from the angular distribution of the decay products in the Λ^0 rest frame, the direction of polarization at the time of decay was determined. The magnetic moment is proportional to the angle of precession of the polarization vector.

The experiment was made at CERN, and the counting, and measurements were done in five laboratories (CERN, Arima, Ibaraki, Munich and Bonn). The result of this collaborative effort is $\mu_{\Lambda^0} = 0.66 \pm 0.07 \mu_N$. The purpose of this thesis is to give the details of the experiment and also to check the complex analytic program of the collaboration by simpler and independent programs. The result obtained is $\mu_{\Lambda^0} = 0.59 \pm 0.10 \mu_N$ using only the events measured in our laboratory, and $\mu_{\Lambda^0} = 0.61 \pm 0.07 \mu_N$ using all of the events measured in the collaboration.

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CHAPTER I

INTRODUCTION

1.1. Meaning of the Magnetic Moment (1.1)

Elementary particles are characterized by a set of quantum numbers like mass, electric charge, spin, intrinsic parity. In addition to these there is other information, such as the nature and frequency of its interactions, which is helpful in understanding the structure of the particle^e. The magnetic moment is also one of such useful characteristics of the particle.

In electrodynamics one can express the external effects of any distribution of charge and currents in terms of a series of "multipole moments". In many cases a few lower order multipoles are sufficient for describing the effects. The energy of interaction, E_{int} between an applied electromagnetic field and a charge-current system can be written as follows

$$\psi_{int} = \psi_0 - \vec{r} \cdot \vec{E}_0 - \vec{r} \cdot \vec{H}_0 - \frac{1}{6} \sum_{i,j} Q_{ij} \left(\frac{\partial^2 \psi_0}{\partial x_i \partial x_j} \right)_0 - \dots \quad (1.1.1)$$

where \vec{E} and \vec{H} are the applied electric and magnetic fields, and ψ is the electrostatic potential of the applied field. The subscript 0 indicates that the quantity in question is to be evaluated at the origin of coordinates which is taken at some convenient point in the charge-current system. The symbol q denotes the total charge of the system, \vec{P} is the electric dipole vector, \vec{M} is the magnetic dipole vector, and Q_{ij} is the electric quadrupole tensor.

\vec{M} , the magnetic dipole vector is the one which interests us. It is given as a function of a current density \vec{J} and the space coordinates \vec{r} by

$$\vec{M} = \frac{1}{2} \int \vec{r} \times \vec{J} \, dV \quad (1.2.2)$$

where dV is the differential volume element and the integral is performed over the volume which includes the current distribution. \vec{M} depends only on the distribution of the current, therefore a knowledge of \vec{M} gives information about the size, shape and rotation of the scatterer. This aspect of the question is related to the many experiments such as electron-proton scattering since an attempt is made to express the results in terms of form factors for the electromagnetic structure of the nucleons. These form factors are usually made of two contributing parts, $F_1(q^2)$ and $F_2(q^2)$, where q is the four-momentum transfer. F_1 describes

the distribution of the electric charge and \vec{P} , the magnetization.

An alternative form of \vec{M} can be obtained if \vec{J} is produced by an electric charge of density ρ , moving with velocity \vec{v} . Then $\vec{J} = \rho \vec{v}/c$. If the charge density is actually composed of particles of charge e and mass m , then the angular momentum density is $\vec{L} = (m \rho / c)(\vec{r} \times \vec{v})$, and one can write

$$\vec{M} = \frac{1}{2} \frac{e}{mc} \int \vec{L} \, dV \quad (1.1.3)$$

In quantum mechanics the energy H_{int} and the various multipole moments become operators. The magnetic dipole operator will include the contribution H_{orb} and H_{spin} of both orbital angular momentum corresponding to the expression (1.1.3) and spin magnetic moment.

The total magnetic-moment operator \vec{M} can be written in the general case of a nucleus composed of A nucleons :

$$\vec{M} = \vec{M}_{orb} + \vec{M}_{spin} = \mu_0 \sum_{k=1}^A (g_k^{(1)} \vec{l}_k + g_k^{(\sigma)} \vec{\sigma}_k) \quad (1.1.4)$$

where μ_0 is the quantity $eh/2m_p c$ (m_p = proton mass) called the nuclear magneton; \vec{l}_k and $\vec{\sigma}_k$ are the orbital and the spin angular momentum operators (divided by \hbar) respectively of the k nucleon; $g_k^{(1)}$ is the orbital factor which is equal to one for protons and zero for neutrons; $g_k^{(\sigma)}$ is the spin gyromagnetic ratio.

The magnetic moment μ is defined as the expectation

value of μ_z in the state in which $J_z = J$, where μ_z obtains its maximum value, i.e.

$$\mu = \mu_0 g_J J = \int \psi_{J,J}^* \mu_z \psi_{J,J} dV \tag{1.1.5}$$

This equation also defines g_J , the nuclear g factor. J , the total angular momentum, is the sum of the orbital angular momentum L and of the intrinsic angular momentum or spin σ . The index J in g_J means that it is the total angular momentum J which contributes to the magnetic moment.

If the particles considered are free particles there is no orbital angular momentum contribution. Equation (1.1.5) then becomes

$$\mu = \mu_0 g_\sigma \sigma \tag{1.1.6}$$

For particles other than nucleons $\mu_0 = eh / 2mc$ where m is the mass of the particle in question. Then μ_0 is called the "intrinsic magneton". For elementary particles usually there is only the spin contribution to the magnetic moment; then subscript σ is dropped from g_σ .

As examples of how magnetic moment measurements give useful information about the fundamental properties of the particles one can mention the cases of proton, neutron and the electron.

If the proton was a uniformly charged classical sphere, its magnetic moment μ_p should 1/2 nuclear magneton. If the

proton and the neutron were adequately described by the relativistic wave equation of Dirac, μ_p should be 1 n.m. and $\mu_n = 0$. Experimental results are 2.79 n.m. for μ_p and -1.91 n.m. for μ_n . These results show that the nucleons have a complex inner electrical structure.

Dirac's relativistic quantum mechanics predicts a gyromagnetic ratio g equal to 2 for the electron. Precision measurements gave a value slightly higher than this ($g = 2.0023$). Schrodinger showed that the interaction energy between electron and an external field must include a radiative correction term representing the interaction of the electron with the quantized electromagnetic field which modifies the value of its magnetic moment. The electron will emit and reabsorb virtual photons as a result of this coupling with the quantized electromagnetic field. The result of the calculations will depend on the number of virtual photons taken into account. Limiting this number to two virtual photons, one finds for the expression of the magnetic moment:

$$\mu_e = 1 + \frac{1}{2} \alpha / \pi = 0.528 \alpha^2 / \pi^2 \quad (1.1.7)$$

where α is the fine structure constant, $(\mu_e - 1)$ is defined as the anomalous magnetic moment, μ_a . Experiments confirm the theoretical predictions with good accuracy.

1.2. Magnetic Moments of Hyperons

Different theoretical models predict different values for the magnetic moments of the hyperons.² A precise knowledge

²See Table 1

of the magnetic moments would provide a powerful test of the theory. Existing experimental results are very few and have large errors. The only one which has a small enough error to be meaningfully compared with the theory is the magnetic moment of the Λ^0 hyperon. The world average is $\mu_{\Lambda} = (-0.73 \pm 0.20)$ nuclear magnetons. (3) The experiments from whose results this value was calculated were all based on the same principles, but used different detection techniques. Their results, all quoted in nuclear magnetons are: -1.5 ± 0.5 by Cool et al. (4) using spark chambers; 0.0 ± 0.6 by Korman et al. (5) using a diffusion cloud chamber; -1.39 ± 0.72 by Anderson and Crawford (6) using hydrogen bubble chamber; -0.50 ± 0.23 by Charriere et al. (7) using emulsions and -0.77 ± 0.27 by Hill et al. (8) using spark chamber.

The purpose of the experiment reported here is to increase the accuracy in the measurement of Λ^0 magnetic moment. This is done mainly by using a stronger magnetic field and increasing statistics by carefully planning the experiment and improving the analysis methods.

CHAPTER II

EXPERIMENTAL METHOD

II.1. Principles of the Experiment

The basic method of the measurement is identical with that used so far in all other experiments to determine the hyperon magnetic moments. This method was proposed by Goldhaber⁽⁹⁾ in 1956 and by T.D. Lee and C.N. Yang⁽¹⁰⁾ in 1957. The method consists of producing polarized hyperons whose polarization is made to precess in a magnetic field. The angle of precession which is directly related to the value of the magnetic moment is measured by determining the polarization vector after the action of the field.

At this point it will be appropriate to define the polarization. Consider a beam of particles of spin σ , and a direction defined by a unit vector \hat{n} . If the expectation value of the spin component in the direction \hat{n} , $\langle \sigma \cdot \hat{n} \rangle$, is not zero for all directions, the beam is said to be

polarized, and there is a direction \vec{e}_0 for which $\langle \vec{\sigma} \cdot \vec{e} \rangle$ reaches a maximum

$$\langle \vec{\sigma} \cdot \vec{e} \rangle_{\text{max}} = \langle \vec{\sigma} \cdot \vec{e}_0 \rangle = P \quad 0 \leq P \leq 1 \quad (II.2.1)$$

where P is the degree of polarization and $\vec{e} = P\vec{e}_0$, the polarization vector.

Three conditions have to be fulfilled for the measurement of the magnetic moments

- (i) a beam of polarized particles must be available, and the initial direction of the polarization must be known;
- (ii) these particles must be kept for a sufficiently long time in an intense enough magnetic field to obtain an appreciable precession;
- (iii) it must be possible to determine the final direction of the polarization.

II.3. The Source of Polarized Hyperons

The hyperons are transversally (normal to the plane of production) polarized in the production reactions of the following type:



Longitudinal polarization is not allowed because of parity conservation.

In this experiment Λ^0 produced in the reaction



were used. They are polarized in the directions

$$\frac{\vec{P}_0}{P} = \frac{\vec{P}_{\Lambda} \cos^2 \theta}{|\vec{P}_{\Lambda} \cos^2 \theta|} \tag{2.2.1}$$

where \vec{P}_0 is the initial polarization vector, $P = |\vec{P}_0| \cos^2 \theta$ and \vec{P}_{Λ} are the norms of incoming pion and outgoing Lambda respectively. The magnitude of the polarization can be calculated using partial wave analysis.²

For this experiment a polyethylene target was exposed to a beam of π^- mesons from the CERN proton synchrotron. A beam was preferred to a K^- beam in spite of the larger cross-section of the reaction $K^- + p \longrightarrow \Lambda^0 + K^0$ because K^- beams have much lower intensity and the Λ^0 polarization is smaller. An incident momentum of 1.05 GeV/c was chosen because it was found out experimentally that at this momentum the cross section for the reaction $\pi^- + p \longrightarrow \Lambda^0 + K^0$ goes through a minimum of about 0.8 mb. and the polarization is close to 100% over a large angular region in the center-of-momentum system of the reaction. (11)(12)

At this energy, the maximum angle of production of the Λ^0 in the laboratory is about 32° .¹³ In order to maximize the Λ^0 to background ratio, it is advantageous to restrict the acceptance of Λ^0 hyperons to a small range of angles just below this kinematical limit. The interval chosen

¹ See Appendix A.1

² See Appendix A.2, Fig. 8, and Table 2.

are 10° to 22° . This corresponds to center of mass angles between 30° and 140° , representing about 33 % of the total cross section. This corresponds to Λ^0 laboratory momenta between 500 MeV/c and 800 MeV/c.²¹

II.3. Precession of the Polarization Vector

The polarization, being defined in terms of expectation values follows a classical equation of motion. In a uniform magnetic induction field \vec{B} , the polarization vector \vec{P} defined in the rest system of Λ^0 particles obeys the equation of motion:

$$\frac{d\vec{P}}{d\tau} = \mu_N \frac{e}{mc} \vec{B} \times \vec{P} \quad (II.3.1)$$

where \vec{B} is the magnetic induction field vector in the rest frame of the particle, τ is the proper time of the particle and μ_N is the magnetic moment in nuclear magnetons if π is the proton mass, in intrinsic magnetons if the mass of the Λ^0 is used. In order to write this equation in the laboratory frame²² one has to consider the two components of \vec{B} separately, one parallel to \vec{p}_Λ , the laboratory momentum of the Λ^0 and another which is perpendicular to it :

$$\vec{B} = \vec{B}_\parallel + \vec{B}_\perp \quad (II.3.2)$$

²¹ See Appendix A.2, Fig. 8, and Table 2.

²² See Appendix B.

where

$$E'_{\parallel} = \frac{E_{\parallel} + \beta \frac{E_{\perp} \wedge}{\beta \wedge}}{\gamma} \quad (11.3.5)$$

and

$$E'_{\perp} = E_{\perp} - \frac{E_{\parallel} \cdot \beta \wedge}{\beta \wedge} \quad (11.3.6)$$

These two components transform under Lorentz transformations in different ways

$$E'_{\perp} = \gamma E_{\perp}$$

$$E'_{\parallel} = E_{\parallel}$$

Using the Eq. (11.3.4) and $dt = \gamma dt'$ one can write the Eq. (11.3.1) in the laboratory frame

$$\gamma \frac{d\mathbf{r}}{dt} = \frac{M_0 e}{m_0} \mathbf{E} \times (\gamma \mathbf{E}_{\perp} + \mathbf{E}_{\parallel}) \quad (11.3.7)$$

or

$$\frac{d\mathbf{r}}{dt} = \frac{M_0 e}{m_0} \mathbf{E} \times \left[\mathbf{E} - \frac{\gamma - 1}{\gamma} \frac{\mathbf{E} \cdot \beta \wedge}{\beta \wedge} \beta \wedge \right] \quad (11.3.8)$$

In this equation \mathbf{E} is expressed in the center of mass system, all other quantities are in the laboratory system.

In the present experiment the magnetic field was applied approximately perpendicular to $\beta \wedge$ in order to remove background due to charged particles originating in the target. This simplifies the geometry and the Eq. (11.3.6). It takes the approximate form

in the Appendix C.

$$\frac{d\vec{E}}{dt} = \mu \frac{e}{mc} \vec{E} \times \vec{E} \quad (\text{II.3.7})$$

Consider the system of reference determined by the three orthogonal unit vectors:

$$\hat{i} = \frac{\vec{F}}{|\vec{F}|}, \quad \hat{j} = \frac{\vec{E}_0}{|\vec{E}_0|}, \quad \hat{k} = \hat{i} \times \hat{j} \quad (\text{II.3.8})$$

Let

$$\vec{E} = E \hat{k} \quad (\text{II.3.9})$$

Then the equation of motion (II.3.7), reduces into two component equations:

$$\frac{dE_x(t)}{dt} = \mu \frac{eB}{mc} E_y(t) \quad (\text{II.3.10})$$

and

$$\frac{dE_y(t)}{dt} = -\mu \frac{eB}{mc} E_x(t) \quad (\text{II.3.11})$$

The solution of this set of equations subject to the initial condition

$$\vec{E}(t=0) = \vec{E}_0 = E \hat{j} \quad (\text{II.3.12})$$

is

$$\vec{E}(t) = E \left[\sin\left(\frac{\mu eB}{mc} t\right) \hat{i} + \cos\left(\frac{\mu eB}{mc} t\right) \hat{j} \right] \quad (\text{II.3.13})$$

This is a vector which is rotating around the magnetic field direction, in the plane defined by \hat{i} and the initial polarization \vec{E}_0 . The angular frequency is $\mu eB/mc$. Thus after the particle

has spent a time t in the field, and travelled a distance $z = \beta ct$, the polarization vector has rotated through an angle:

$$\varphi_0 = \frac{\mu_0 H \beta}{\omega} t = \frac{\mu_0 H z}{\omega \beta c^2} \quad (11.3.14)$$

In the present experiment the magnetic field is not strictly uniform. For this reason instead of H one uses $\int H dz$. This is done by measuring the field at points spaced 5 cm. apart over the whole useful volume and numerically integrating it along the Λ^0 line of flight.

11.4. Observation of the Final Polarization Direction

In the rest system of the polarized Λ^0 hyperon, the angular distribution of the decay $\Lambda^0 \rightarrow p + \pi^-$ is not isotropic but has the form¹⁸

$$N(\theta, \xi) d\theta d\xi = \frac{1}{4\pi} [1 + \alpha P \cos \theta] \sin \theta d\theta d\xi \quad (11.4.1)$$

where θ and ξ are the space and azimuthal angles which \vec{P}_p^* , the proton momentum in the center of mass frame makes with the polarization vector \vec{P} . P is the degree of polarization ($P = |\vec{P}|$) and α , the decay parameter. Its value has been found experimentally to be $0.643 \pm 0.016^{(5)}$ for this decay mode.

Since the rotation of \vec{P} is approximately confined to the $(\vec{H}_0, \vec{P}_\Lambda)$ plane, and the information on the magnetic moment is mainly contained in φ_0 , it is convenient to project the

¹⁸ See Appendix A.1

distribution onto this plane.² The decay now can be characterized by two angles ψ between the \vec{P}_p^* and the plane $(\vec{e}_\lambda, \vec{e}_0)$ and φ between the projection of \vec{P}_p^* onto that plane and \vec{e}_0 . From the geometry (for the approximate case $\beta_z = 0$):²²

$$\cos \theta = \cos \psi \cos(\varphi - \varphi_0) \quad (\text{II.4.2})$$

and

$$d(\cos \theta) d\xi = d(\sin \psi) d\varphi \quad (\text{II.4.3})$$

In terms of the new angles φ and ψ , the decay probability distribution equation (II.4.1) is given by:

$$W(\varphi, \psi) d\varphi d\psi = \frac{1}{4\pi} [1 + \alpha \beta \cos \psi \cos(\varphi - \varphi_0)] \sin \psi d\varphi \quad (\text{II.4.4})$$

To obtain the projection of this distribution onto the $(\vec{e}_\lambda, \vec{e}_0)$ plane one integrates the Eq. (II.4.4) over ψ between $-\psi_0$ and $+\psi_0$:

$$W(\varphi/\psi_0) d\varphi = \frac{\sin \psi_0}{2\pi} [1 + \lambda \alpha \beta \cos(\varphi - \varphi_0)] d\varphi \quad (\text{II.4.5})$$

where

$$\lambda(\psi_0) = \frac{1}{2} (\cos \psi_0 + \psi_0 / \sin \psi_0) \quad (\text{II.4.6})$$

Thus a measurement of the distribution of φ allows the determination of φ_0 and hence μ_λ . The statistical error on the angle φ_0 can be calculated using the approximation in the

²² See Figure 1.

²³ See Appendix D.

deg. It is given in radians as:

$$\delta\varphi \approx \frac{\pi}{2\lambda\alpha P\sqrt{N}} \quad (11.4.7)$$

which leads to an uncertainty on the magnetic moment in magnetons:

$$\delta\mu \approx \frac{\pi\beta}{2\lambda\alpha P\sqrt{N}} \frac{e}{2m} \hbar \quad (11.4.8)$$

where N is the number of observed events.

This formula is useful in the design of the experiment.

One sees that in order to decrease the uncertainty, one has to increase D and N as much as possible and also P . One also sees from this formula that there is an optimum distance L such that $L\sqrt{N} \sim L e^{-1/2} \beta\gamma c\tau$ reaches a maximum:

$$L_{opt} = 2\beta\gamma c\tau \quad (11.4.9)$$

In this experiment this corresponded to a length of ~ 11 centimeters, and the distance between the target and the detector was chosen accordingly.

It can be shown that $\delta\varphi$ is minimized by applying a cut-off at $\sin\psi_0 = 0.91$ which excludes ^{events} with large ψ .

iv See Appendix E.

v See Appendix F.

CHAPTER III

APPARATUS^{*}

III.1. Beam

A non-separated high-intensity beam of negative particles produced at 0° K in a platinum target ($2 \times 2 \times 70 \text{ cm}^3$) by an ejected proton beam of 20.6 GeV/c from the GHEB EC, was designed for this experiment. Its main characteristics are listed below:

- a) a central momentum of 1.070 GeV/c;
- b) a momentum distribution falling almost linearly to zero intensity at $\pm 1.4\%$ of the central momentum;
- c) an angular divergence of $\pm 1^\circ$ in the horizontal plane and $\pm 4^\circ$ in the vertical plane; (The horizontal plane almost coincides with the plane of production for the Λ^0 hyperons)
- d) a burst length of $2 \mu\text{s}$ allowing precise synchronization with the pulsed magnetic field;

* See Fig. 2.

- a) a typical flux of about 1.5×10^7 particles per burst;
 b) an intensity distribution at the position of the final image (secondary target) characterized by 30 % of the total flux going through an area 6 cm wide \times 4 cm high, allowing the beam to enter the pulsed magnet through a narrow channel.

This beam was found to consist of 70 % π^+ mesons, a barious contribution of about 30 % electrons and muons, and $1 \text{ E}^+ \text{ mesons}^{(15)}$.

III.2. Target*

If liquid hydrogen is used as the secondary target (source of the Λ^0 hyperons) the Λ^0 produced have maximum polarization and have a constant energy for a given angle of production; also their magnetic moment can be measured with greater accuracy. Unfortunately, the use of liquid hydrogen in the presence of coils for the pulsed magnetic field is an extremely difficult problem. Therefore polyethylene, $(\text{CH}_2)_n$, was chosen as a target. One disadvantage of this target is that there are also Λ^0 hyperons produced on carbon instead of hydrogen. These hyperons have reduced polarization. Also the Fermi motion of the nucleons means that the energy of the Λ^0 emitted at a given angle is not constant. With the kinematic analysis one can get rid of most of the carbon produced Λ^0 s and the remaining

* See Fig. 3.

contamination reduces the polarization slightly but does not bias the estimate of the magnetic moment. Moreover the polyethylene contains a higher concentration of protons than liquid hydrogen itself, therefore the polyethylene target can be smaller for the same amount of protons.

III.3. The Pulsed Magnet ⁽¹⁴⁾

In the present experiment the target and the detectors had to be located inside the magnet. In order to make a precise measurement of the Λ^0 magnetic moment it was necessary to impose a field in excess of 200 kilogauss in a direction transverse to the flight paths of the hyperons and over a length of 10 to 12 cm. Moreover in order to eliminate the biases and to increase the number of events, a layout which allows the detection of hyperons both to the left and to the right of the primary beam was needed. Finally it was required that the magnet should withstand operation for of the order of 10^4 pulses.

A magnet was specially designed and built to satisfy these requirements. It was of the flux concentrator type. This type of magnets are essentially pulsed transformers containing a single-turn secondary with a multi-turn primary. In general the secondary consists of a single block of conductor containing a central bore which is linked radially to the outside of the block by means of a slot.² The current pulse through the

² See Figs. 5, 4 and 6.

primary windings induces a current in the opposite sense in the outer surface of the secondary which is constrained by the skin effect. This current is forced to flow along the faces of the slot and round the central bore, producing a magnetic field in it. Alternatively one can say that the magnetic flux produced by the primary current is concentrated in the bore of the secondary, and the slot prevents a short-circuit. This is the reason for the name "flux concentration".

The advantages of the magnets of this type are the following:

- (i) The principal forces are exerted on a single block of metal, thus the magnet does not depend critically on the resistance to stress of relatively weak insulating materials.
- (ii) The inductance presented to the external circuit can be adjusted by choosing the number of primary turns.
- (iii) A field of a given configuration may be produced by shaping the inside surface of the secondary.

The main disadvantage is the low efficiency with which energy is transferred into high magnetic field in the useful volume of the magnet.

The magnet designed for this experiment represented a more general application of the flux concentration principle. It was essentially a "double" or "twice" flux concentrator built up of two identical halves made of Co-Cr-Fe alloy.* They were

* See Figs. 5 and 6.

in contact in a plane of mirror symmetry and have their primary windings connected in series. Each block was machined out of a thick circular disc. Into the outer surface of the blocks a deep helical groove was turned to receive the primary windings. The insides were turned and milled out to form the corridor through which the magnetic flux threading the coil was concentrated. Cylindrically-shaped cavities in one end of each corridor provided room for the particle detectors. Cooling water was circulated through four holes traversing the secondary blocks.

The primary windings consisted of four spirals of copper, each having four turns and rectangular cross section.

A heavy stainless-steel yoke was necessary to restrain the secondary block so that the forces generated across the plane of the slot during a pulse would be taken up without causing the slot to open permanently and to constrain the primary windings against the radial forces which tend to eject them from the secondary.

The magnets were powered by a 0.075-F capacitor bank. The electrical characteristic of the magnets, when connected to this bank were the following: inductance $8 \mu\text{H}$, a.c. resistance 4Ω , current rise time 1 ns. Averaged over a typical Δ^0 flight path 11 cm. long, the component of the field normal to the mean Δ^0 momentum and initial polarization was 192 k Gauss (190 k Gauss) for a discharge voltage of 2.9 kV (5.2 kV).

During the experiment two such magnets were used and withstood a total of about 9000 pulses at 2.9 kV and 1000 at 3.2 kV.

III.4. The Detector

Nuclear emulsion was the only kind of detector which could be made small enough to fit inside a high-field magnet. It has high spatial resolution and it is possible to make direct precise measurements on the tracks as required for this experiment.

Strips made of 9 pellicles of Ilford K5 nuclear-emulsion emulsion were used as detectors. The pellicles (1200 μ thick) were of circular shape (22 mm diameter) with two segments cut off to provide straight front and back edges.⁸

Several technical problems had to be solved, connected with the handling of pellicles of such small size exposed to temperatures around 40°C which is a typical temperature for irradiation inside a pulsed magnet of 200 kG.⁽¹⁵⁾

As a reference system for scanning and measurements, a grid was photographed onto each emulsion pellicle after the exposure. It consisted of lines of polar coordinates originating at the target center, with one line every 2 mm in the radial direction and every degree in azimuth.

⁸ See Fig. 7.

CHAPTER IV

EXPOSURES, SCANNING AND READINGS

IV.3. Exposures

A total of 72 stacks were exposed to between 50 and 100 machine pulses each. 56 of the stacks were exposed with a tension of 2.9 kV (~ 192 Hz), the remaining with 5.2 kV (~ 308 Hz). This corresponded to about 10^9 particles on the target per exposure. Tests had shown that higher exposures lead to unacceptable densities of background tracks.

The stacks were exposed in pairs symmetrically situated with respect to the median plane of the coil.² (Odd and even stacks) In this way, in one exposure, two samples of events with opposite initial polarization were obtained to reduce biases. As another precaution against possible asymmetric effects the field direction was reversed after every five or six pairs of stacks. The direction of the precession of the polarization vector is opposite

² See Fig. 2.

in odd and even numbered stacks since the magnetic field, is in opposite directions. The orientation of the stacks was such that the Δ^0 momenta \vec{p}_Δ and the initial polarization \vec{P}_0 lay approximately in the plane of the pellicles.

The timing of the particle burst with respect to the magnetic field pulse was checked continuously by means of the photographic record of oscilloscope traces of the field pulse and particle burst.

The magnetic field just outside the channel traversed by the Δ^0 's was monitored by means of a pick up coil for every discharge of the capacitor bank.

For calibration purposes, some pellicles were exposed directly in the beam which had been tuned for positive particles of various momenta between 450 and 1050 MeV/c; they were made from the same emulsion and were processed in the same way as the Δ^0 plates. These plates were used in establishing the relation between the normalized grain density and the velocity, which was needed in the analysis.

The pellicles were processed using a special routine: freeze in cold (4°C) distilled water, cold stage development in Kodak developer, dry hot stage ($20-24^\circ\text{C}$), stop bath at 4°C , several days of fixing, dilution, washing and alcohol and air drying. In order to decrease the fading at high temperatures reached during the exposure they were protected at 4°C . (15) After the processing the pellicles were stuck on glass plates.

IV.2. Scanning

Scanning was done by specially trained operators. The microscopes used were the Leitz Ortholux and the Zeiss 4000 with the magnification $\times 55$ objective and $\times 15$ ocular. This was the most time-consuming part of the experiment. The purpose was to develop a fast and efficient scanning procedure with least possible biases.

The momenta of the hyperons lie in the 500-800 Mev/c range and in this range the decay protons are emitted within 14° of the Λ^0 line of flight, and have momenta ranging from 326 to 800 Mev/c (ionisation between 5.5 and 1.5 times the plasma ionisation) in the laboratory system.²² Taking into account the finite dimensions of the target and the curvature due to the magnetic field, one obtains that up to 7 cm beyond the decay point the proton track cannot make an angle larger than 20° with the line joining the target center to the point of observation. This line is the mean direction of the Λ^0 's at that point.

The scanning was done as follows: a plane was chosen in the emulsion approximately perpendicular to the average line of flight of neutral particles from the target and at some distance from the front edge of the pellicle. The intersection of this plane with the emulsion plane is called the "scan-line". Tracks crossing the scan-line were picked up if they satisfied

* See Appendix A.2, Fig. 9, and Table 3.

the criteria which will be described below. All such tracks were followed back over a maximum distance of 7 cm, or to their point of entry into the pellicle, or to their origin inside the emulsion. However a track originated in a two prong event (i.e. was one branch of a γ^n) the event was recorded.

For convenience, angular criteria for picking up tracks were defined independently in the plane of the emulsion (plane-angle criteria), and in the plane perpendicular to it (dip angle criteria). To avoid following a very large number of background tracks, it was necessary to choose an interval of plane-angle out of which most of the charged background had been swept by the action of the magnetic field. At a given distance from the target, the limits of this interval were determined by the curvatures of the most energetic particles reaching this point. These particles were the elastically scattered π^+ mesons on one side and recoil protons from elastic scattering on the other side of the average \wedge^0 direction. They made a minimum angle of 15° with the mean \wedge^0 direction. Particles from inelastic processes crossed the mean line at larger angles since they had smaller momenta. Therefore only a 7° interval of plane angle was allowed to both protons from \wedge^0 decay and tracks on protons from elastic scattering.

The main background within the chosen angular interval consisted of the electrons and positrons coming from the conversion of γ -rays in the emulsion. These made up about 60% of the tracks. Grain density criteria were used to discriminate against this

background.

An especially designed superstage for the microscope was used as an aid to scanning. This revolved about a point representing the effective target center, so that the plate always moved along radial lines from this point.

As another aid to scanning a graticule was placed into the eyepiece of the microscope². This helped the scanner in applying the plane-angle criteria.

In each stack which consisted of 9 pellicles, the central 7 pellicles were scanned. In order to determine the exact orientation of each pellicle, the direction of the radial gold lines printed on the pellicle were compared with that of the electron pairs produced by energetic photons from the target. For this purpose 50 electron pairs were found at the beginning of scanning of each plate and their plane angle distribution was drawn. By using these electron pairs since the efficiency in sliding pairs at different Z , and the existence of a grain density gradient were tested. The local platinum grain density was determined by counting grains on these electron tracks.

Two scan lines were taken, situated at 115 μ m. and 117 μ m. from the target center (9 μ m. and 16 μ m. from the entrance edge of the pellicles). The tracks which crossed these lines were followed whenever they had:

² See Fig. 3.

(i) a dip angle with a tangent smaller than $30/200$, (this corresponded in the unprocessed analysis to a dip angle $\pm 15^\circ$ with respect to the plane of the pellicles.)

(ii) a plane angle within $\pm 22^\circ$ with the mean Δ° direction, (this meant that among the tracks which crossed the upper line of the graticule the ones inside the plane angular filter as defined by the graticule lines^z were to be followed.)

(iii) a grain density g , greater than 1.3 times that of the electron density g_0 , i.e. $g^z = g/g_0 > 1.3$. In order to increase the counting speed the scanners were trained to estimate the grain density visually rather than by counting except in the border-line cases. They rejected the tracks which they estimated having smaller g^z than 1.1 and accepted the ones with g^z larger than 1.5 and counted only the ones in between. In the 7° interval of plane angle, which can be reached by the knock-on protons, modified grain density criteria were used to discriminate against this background also. In this region the scanners rejected the tracks with $g^z < 1.5$ and accepted the ones with $g^z > 2$ by visual estimation and counted the ones in between to accept the ones with $g^z > 1.7$; because in this angular region the energy of the decay protons is smaller than the maximum^{zz}. Therefore as one increases the lower limit to grain density in order to eliminate the tracks of knock on protons which generally have larger energies than the decay protons in this angular interval.

^z See Fig. 3.

^{zz} See Table 3.

For the selected tracks the track number, the distance of the pick-up point from the glass surface on which the emulsion was mounted and its fate after being followed were recorded. If the fate was a V event, stop or start, then the plane angle, the x, y, z coordinates of the end point were recorded (the glass surface was taken as $z = 0$). These tracks were followed back to the pick up point to record g^2 and the plane and dip angles. Plane angle, dip angle and grain density distributions² were drawn to check the criteria used to choose the tracks to be followed.

For the V-events a drawing of the event was made and the estimates of the opening angle, grain count of both tracks, the direction of dip, location with respect to the grid were recorded on a half in refixing the event in order to measure.

Some of the plates were circulated among the collaborating laboratories according to a plan and recommended. This plan was as follows:

- a) One plate was circulated through all laboratories, to be measured by one scanner in each laboratory.
- b) One plate from each laboratory (with laboratory number n) was sent to the Laboratory number $n+1$.
- c) One plate from each laboratory (with laboratory number n) was sent to the laboratory number $n+2$.

2/ See Progress 1, 2 and 3.

This system of reason produced a total of 14 reason
 results:

5 from the $n \rightarrow (n+1)$ series

5 from the $n \rightarrow (n+2)$ series and an additional 4
 from the plate which was passed on. This provided a check
 on the correctness of the visual estimation and helped to
 maintain the quality of scanning and uniformity between labo-
 ratories through most the experiment. The reasons for missing
 an event in one laboratory which was found in another were
 investigated. In this way one could make sure that events with
 certain characteristics were not being missed systematically i.e.
 the counting was not biased.

The scanning yielded a total of 2123 events in the whole
 collaboration and 423 event in Ankara.

IV.3. Measurements

All the V-events recorded in scanning were reviewed by
 physicists unless they were obviously incompatible with Δ^0
 decay kinematics. A decay chart* of Δ^0 (proton momenta plotted
 versus pion momenta for different opening angles) was used to
 make the decision. The obviously non Δ^0 events were of four
 types:

1. Proton Scattered Ionization of both tracks (L_1, L_2)
 about the same, dip angles of both tracks (δ_1, δ_2) less than
 15° and projected opening angle (α_{12}) greater than 150° .

* See Fig. 9.

2. Electron pairs: $I_1 \cong I_2 \cong$ minimum ionization $\pm 20\%$
 $|\delta_1| < 15^\circ$, $|\delta_2| < 15^\circ$.
 $\alpha_{12} \leq 3.00^\circ$

3. Obvious neutron stars: Star with one fast secondary (the track followed) and one black stopping track, with the conditions:

$$R_2 > 50 \mu$$

$$\theta_{12} < 60^\circ$$

where R_2 is the range of track 2 and θ is the space opening angle.

4. Events obviously not from targets: Both tracks on the same side of the grid line, and both at more than 10° from the gridline.

The following measurements were made on the other events:

a) the plane angles of both tracks with respect to the grid.

b) the dip angles of both tracks. This was done by measuring the distance from the glass surface, of two points (one of which was usually the decay vertex) which were separated by a known distance on a track. The separation of these two points was taken as $\sim 500 \mu$ for proton tracks and $\sim 250 \mu$ for pion tracks since they get scattered much more than the protons.

c) the grain densities. When a new photo was obtained

being measured 300 grains were counted on each track of four electron pairs and thus the plateau grain density was determined. On proton and pion tracks 1000 grains were counted corresponding to a statistical error of $\sim 3.3\%$.

d) the range in the emulsion stack of the secondary particle if it stopped and was not clearly a proton. Obtaining the velocity from the range-energy relationship⁸ is more accurate than obtaining it from the normalized grain densities. Therefore range measurements were made whenever it was possible.

e) the x and y coordinates of the event vertex with respect to the grid photographed and a coordinate with respect to the glass surface.

If the secondary tracks left the plate in which they originated, they were followed into the next plate. In spite of their being kept in humid environment the emulsion plates shrink with time. Their thickness had been measured just after the exposure at the center of each plate (monitor point).

In order to find the shrinkage factor and thus correct the dip measurements, everyday the thickness of the plate at the same point was measured.

Some of the plates were remeasured in different laboratories according to the plan explained in the measuring part and some of them were remeasured by the first scanner after a

⁸ See Fig. 10.

long time or by another measurer in the same laboratory². In this way it was possible to check the estimated standard errors in the measurements

a) the plane angles of the proton and the pion were normally very well measured, the absolute value of each one, due to the uncertainty of the alignment has an error of about 0.1° .

b) the uncertainty on the dip angles come from an uncertainty of about $\pm 4 \mu$ in z -measurement and emission date-age and about $\pm 2 \mu$ in x -measurement. This corresponded to a standard error of about 1° in the dip angles.

c) the uncertainty in the grain densities is due to the statistical fluctuation of the number of grains existing on a finite length of tracks which was around 3% assuming a Poisson distribution, since ~ 1000 grains were counted on each track. Another reason for the differences of grain density counts in measurements was the fact that each measurer estimated the number of grains in a blob differently. This was taken care of by drawing a $g^{obs} - \beta$ calibration curve for each measurer. On the calibration plates which were exposed to proton beams of known momenta between 450 and 950 GeV/c ~ 600 grains were counted on 10 different tracks for each momentum. The counting was done at the central region of the plate, 1 cm from the entrance edge. The proton tracks of known momenta were picked up by plotting the grain density versus the plane angle for a number of tracks counted

² See Table 4.

in a plate. In this way beams of different momenta were easily separated because the plates were exposed to the beams of different momenta at certain plane angles. The differentiation between the proton and electron beams at a definite plane angle was done by means of grain counts. This differentiation was more difficult especially for beams with high momenta. In calculating β from the given momenta the energy lost in travelling 1 cm through the emulsion was taken into account. The effect of the distance travelled in the stack holder etc. was considered negligible. To determine the plateau ionisation in these calibration plates ~ 6000 grains were counted on several electron tracks. The statistical error on the grain counts on the protons was 1.3%. Combined with the error on the plateau grain density (which was also about 1.3%) this gave about 2% error. The grain density-velocity data is given for the two measurements in Annex.²

(i) the uncertainty in the range measurements were due to the misalignment of the scale with the track due to the curvature of the track and were of the order of a few microns ($\sim 0.5\%$).

There was a sharp decrease in sensitivity near the top and bottom surfaces of the emulsion. Because of this reason V events in the top or bottom 5% of the plate thickness were discarded.

The total numbers of events measured was 2225 in the whole collaboration and 459 in Ankara.

² See Table 5.

CHAPTER V

ANALYSIS

V.1. Grain Density Calibration

The types of curves were fitted to the experimental points*

$$g^{\beta} = a + b \beta^{-c} \tag{V.1.1}$$

and

$$\log g^{\beta} = a + b \log \beta + c(\log \beta)^2 \tag{V.1.2}$$

These curves were also forced to go through the point $(g^{\beta}, \beta) = (1.00, 0.36)$ of the universal $g^{\beta} - \beta$ curve (master curve)** in order to extrapolate it to the high nonlinear range and get the right curvature in this range.

The parameters of the above curves calculated by the

* See Appendix 3 and programs 4 and 5.
** See Fig. 11.

least squares method are given in the form of tables^x and the curves obtained are plotted^{xx} for the two sources of Fisher Laboratory.

The results showed that both types of functions were reasonably suitable to represent the $g^x - \beta$ dependence in the region of the measured points. However, the second function, $\log g^x = a + b \log \beta + c (\log \beta)^2$ gave slightly better fit (smaller χ^2) and had a more realistic shape when extrapolated to higher grain densities, therefore it was chosen as the $g^x - \beta$ calibration curve.

The experimental χ^2 was larger than the theoretical χ^2 . This indicated that the only errors on the experimental points were not the statistical errors in counting. The variations in the counting of the same person^{xxx}, local fluctuations in the sensitivity of the emulsion, fluctuations in the position and energy of the selected tracks, all contributed to the total error. However the actual χ^2 values indicated that these errors are of the same order of magnitude as the statistical errors on counting. As long as they were random there was no need^{iv} to worry about them much.

The fitted curves of the two sources were compared^v. The variations of these from the "average" curve (i.e. the curve

x See Table 6.

xx See Figs. 12, 13.

xxx See Table 7.

iv See Table 7.

fitted to the experimental points of both of the measurements taken together) were not very large. They were of the same order of magnitude as the differences between curves belonging to the two different functions fitted to the same experimental points. Hence it was concluded that the average curve of the two measurements from fitting of the function

$$\log g^* = a + b \log \beta + c (\log \beta)^2$$

to all experimental points plus the point $(g^*, \beta) = (2.00, 0.36)$ could be used for all the events measured in Jackson. This had the parameters

$$a = -0.245$$

$$b = -1.663$$

$$c = -0.138$$

(V.1.5)

V.2. Section of the Events

In order to evaluate the magnetic moment, one has to select a sample of events which have a high probability of being decays of Δ^0 's produced in hydrogen in the target. For this purpose one compares the measured moments and angles with those required by the kinematics of the Δ^0 decay.^{*} The goodness of fit was tested by calculating χ^2 for each event.^{**} The fitted moments and the opening angle were also calculated. From these

* See Appendix A.2 and Prog. 6.

** See Appendix B.

the direction and magnitude of the Δ^0 momenta were obtained²².

The "production point" was then estimated as being the point of closest approach of the fitted path of Δ^0 to the central ray of the incident beam. The distributions of the coordinates of the production point were drawn.²³

The first cut-off for selection of true Δ^0 events was put on χ^2 . The theoretical χ^2 distribution for one degree of freedom is given by:

$$f_{\chi^2}(\chi^2)d\chi^2 = \frac{(\chi^2)^{-1/2}}{\sqrt{2\pi}} e^{-\chi^2/2} d\chi^2 \quad (V.2.2)$$

where $f_{\chi^2}(\chi^2)d\chi^2$ is the probability that χ^2 is between χ^2 and $\chi^2 + d\chi^2$.

The probability that χ^2 is greater than or equal to a given value χ^2_0 is

$$P_{\chi^2}(\chi^2 \geq \chi^2_0) = \int_{\chi^2_0}^{\infty} f_{\chi^2}(\chi^2)d\chi^2 \quad (V.2.3)$$

The theoretical and experimental P_{χ^2} versus χ^2_0 curves were plotted.²⁴ One sees that the shapes of the two curves are very similar, only the experimental χ^2 scale is different by a factor

²² See Appendix I and Fig. 6.

²³ See Figures 14, 15, 16.

²⁴ See Figure 17.

of about 6. The similarity indicates that the background event contamination is rather small and the ratios of the several error estimates are realistic. The difference in the χ^2 scales is due to the fact that all the errors were estimated smaller than their actual values.

The cut-off was put at $\chi^2 = 25$ corresponding to a probability of about 2 %.

Another condition for an event to be accepted as a Λ^0 decay from the target was that the estimated production point should lie in the region of the target traversed by the beam. Considering the dimension of the beam and the target and comparing them with the distributions of the production point coordinates the following restrictions were put on the coordinates

$$\begin{aligned} |x_{\text{target}}| &\leq 24 \text{ mm} \\ |y_{\text{target}}| &\leq 3 \text{ mm} \\ |z_{\text{target}}| &\leq 1 \text{ mm} \end{aligned} \quad (\text{V.2.5})$$

Still another condition to be satisfied for selection was $|\sin \psi_0| \leq 0.91$ as explained in the section (II.4).

The quantity $\Delta = (m_x^2 - m_{\Lambda}^2)$ was calculated for each event. m_x is the missing mass of the production vertex and is given by

$$m_x^2 = (E_1 + E_2 - E_{\Lambda})^2 - |\vec{p}_1 - \vec{p}_{\Lambda}|^2 \quad (\text{V.2.6})$$

where E refers to total energy, m to mass, \vec{P} to momentum, the subscript i to the incident pions in the reaction creating the hyperons, and the other subscripts to the other particles. For infinite precision in the measured quantities of Eq.(V.2.4), $\Delta^2 = 0$ if production occurred on a free proton. If the production occurred on a bound proton with Fermi momentum $\vec{P}_F = \Delta^2$ is approximately $-2 \vec{P}_F \cdot \vec{P}_{p0}$. For infinite measurement precision this again gives a central value of $\Delta^2 = 0$ since \vec{P}_F is randomly orientated with respect to \vec{P}_{p0} , but this time the distribution has a width of about 0.14 (GeV)^2 . The Δ^2 distributions were drawn for the Σ -events which satisfy the restrictions explained above in this section and also for those which do not satisfy^{xx} these restrictions. The former have a distribution consistent with their being due to Λ^0 hyperons from the reaction on free protons in the target. The shift of the central value from 0 to 0.11 is due to the tilt of the initial π^- beam because of the magnetic field^{xx} and the width of the distribution can be completely explained by measurement errors. The second group of events gives a Δ^2 distribution which is very broad and not at all consistent with what would be expected if it consisted of Λ^0 hyperons.

Λ^0 's produced on protons with Fermi momenta have smaller or larger momenta than those produced on free protons

xx See Fig. 10

xxx See Appendix J.

depending on the direction of the Fermi momentum. In order to reduce the small no. of Λ^0 's produced on carbon in the sample still further the acceptance was restricted to the region $400 \text{ MeV/c} < P_D < 600 \text{ MeV/c}$.

As a further check the distributions of the fitted pion and proton momenta, opening angle, plane and dip angles and momenta of Λ^0 were drawn to see if they were the expected distributions.² The number of events left (in Ankara) after each restriction are given in the form of a table.³ In the whole collaboration, 1355 events survived.

All the distributions drawn in this section are only for the events measured in Ankara.

V.3. Evaluation of the Λ^0 Magnetic Moment

For each event in the selected sample φ , the angle between the projection of \vec{P}'_p onto the plane (P_D, S_0) and \vec{P}'_p was calculated.⁴ The distribution of φ -angles is shown.⁵ This distribution is not exactly that given in Eq. (11.4.3) but still very similar to a cosine distribution.

² See Figures 19, 20, 21, 22, 23, 24.

³ See Table D.

⁴ See Fig. 1.

⁵ See Appendix K and Fig. 6.

⁶ See Fig. 23.

The reasons for the discrepancy between the theoretical and experimental distributions are the following:

1) To each event there corresponds different values of M , β and t and therefore a different value of φ_0 .

2) A proton from a Λ^0 decay may leave the surface of a particle before it reaches the scan line. The probability that this should happen increases with the angle between the proton and the Λ^0 direction, and φ is related to this angle. This means that the probability of observing values of φ of around $\pm 90^\circ$ is not the same as that for φ in the region of 0° and $\pm 180^\circ$. This effect is called the "list chamber" effect.

3) Because of the restrictions imposed on scanning and acceptance of events, some events are lost. This will be discussed in more detail in the coming sections.

The normalized probability density for the observation of an angle φ_1 in the decay of a Λ^0 is:

$$P(\varphi_1 | \mu_\Lambda = \alpha F) = \frac{1 + \lambda \alpha F \cos(\varphi_1 \pm \frac{\mu_\Lambda \cdot (M)_1}{mc^2 \beta_1})}{\int (1 + \lambda \alpha F \cos(\varphi_i \pm \frac{\mu_\Lambda \cdot (M)_i}{mc^2 \beta_i})) d\varphi} \quad (V.2.1)$$

The + or - sign corresponds to the two possible orientations of the field. The integral in the denominator can be replaced by a sum over all events. Its value should be approximately equal to 2π .

This equation contains two unknown parameters: the magnetic moment μ_λ and αP . Given a sample of N events, the best estimates of these quantities are the values which maximize the likelihood function² $L(\mu_\lambda, \alpha P)$

$$L(\mu_\lambda, \alpha P) = \sum_{i=1}^N Q(\varphi_i | \mu_\lambda, \alpha P) \quad (7.3.2)$$

or its logarithm

$$\ln L(\mu_\lambda, \alpha P) = \sum_{i=1}^N \ln Q(\varphi_i | \mu_\lambda, \alpha P) \quad (7.3.3)$$

The summation runs over all finally selected events.

7.4. Results $\mu_\lambda, \alpha P$ and their Statistical Errors

The results will be given both for Ankara events and events of all the collaboration. Only the Lanzhou events are excluded because of their very low αP and strange looking likelihood contours.

Contour diagrams of the likelihood function were drawn both for Ankara events and all events²².

For Ankara events the maximum likelihood point lies at $\mu_\lambda = -0.61 \mu_B$ and $\lambda \alpha P = 0.49$ ($\alpha P = 0.50$). This value of μ_λ corresponds to an average precession angle of 46° .

²² See Fig. 7.

²³ See Fig. 26.

When all of the events are considered the maximum likelihood point is at $\mu_\Lambda = -0.59$ and $\lambda \alpha P = 0.47 (\alpha = 0.54)$ corresponding to a precession angle of 44° .

To state the statistical uncertainty in this result one uses the following contours which define 68% confidence levels if the likelihood surface is Gaussian:

a) the closed contour $\ln(L/L_{\max}) = -1.15$ if μ_Λ and αP are estimated simultaneously, i.e. the true values of both μ_Λ and αP lie inside the region enclosed by this contour with 68% confidence limit.

From Fig. 25 one deduces the following uncertainties:

For Ankara	For the collaboration
$\delta(\mu_\Lambda) = \pm 0.22 \mu_\Lambda$	$\delta(\mu_\Lambda) = \pm 0.09 \mu_\Lambda$
$\delta(\alpha P) = \pm 0.14$	$\delta(\alpha P) = \pm 0.09$

b) the tangents parallel to the αP axis to the contour $\ln(L/L_{\max}) = -0.5$ which correspond to the 68% confidence limit for μ_Λ alone.

Again from Fig. 25 one gets $\delta(\mu_\Lambda) = \pm 0.14 \mu_\Lambda$ for Ankara and $\delta(\mu_\Lambda) = \pm 0.06 \mu_\Lambda$ for the collaboration.

In order to check for the consistency of the maximum likelihood values for μ_Λ and αP the theoretical distribution given by Eq. (11.4.5) was drawn* using the values of μ_Λ and αP

* see Fig. 27.

obtained above and normalising to the number of events used in the analysis and compared with the experimental distribution.

V.5. Systematic errors

Systematic errors which may arise in the estimate of μ_{Λ} are listed below:

1) Loss of events at the scanning stages

Events may be lost because of too strict scanning criteria and because of the errors made in angle measurements and grain density guesses. The safety regions used were large enough to prevent this.

Some tracks which satisfy the scanning criteria were sometimes not picked up by the scanners. By rescanning part of the material the overall scanning efficiency was found to be of the order of 95%. The events missed in one of the two scans appear to be a random sample, with no bias in φ or p_{Λ} . The distributions of counts and angles of the Λ^0 's are consistent with the expected ones. So we can neglect the error due to loss of events.

2) Measurement errors

Systematic errors in the measurements can affect the final result in three ways:

(i) The value of μ_{Λ} is directly affected via the decay angle φ or p_{Λ} .

(ii) The field integral $\int Edl$ is affected through the determination of the production point.

(iii) By causing the rejection of Λ^0 decays with particular characteristics, the selection is biased.

By using β -vs- g^2 calibration curves in calculating the momenta and excluding events near the surfaces of the emulsion where the distortion probability is highest the measurement errors were tried to be minimized.

All of the measurements were made by physicists and about 10% of the events were remeasured. The remeasurements gave consistent results and the inconsistencies were random.

2) Errors in the field integrals:

Errors in the field integral directly affect the magnetic moment since the angle φ_0 is proportional to $\int B dl$. They may arise from:

- (i) errors in the field measurements,
- (ii) changes in the field during the experiment that could not be taken into account in the calculation,
- (iii) errors in the determination of the production point,
- (iv) approximations in the evaluation of the field integral.

The measurements and control of the field during the experiment, and calculation of the path integral $\int B dl$ were performed by the other members of the collaboration. In the analysis the average value of the field over the Λ^0 path given by them ($\bar{B} = 200 \text{ K Gauss}$) was used. The systematic error they

associated with this value was 2 %.

4) Λ^0 - simulating two-prong events

Of the 3123 events accepted for measurement, 2708 were rejected. A large proportion of these are nuclear disintegrations, produced by fast neutrons from the target, in which one of the tracks satisfy the pick-up criteria for a proton from Λ^0 decay. Since their number is quite large it is possible that a small number of such events are included in our Λ^0 sample. However any bias caused by this inclusion operates in opposite direction in the two stacks of each pair with opposite initial polarizations.

5) Background Λ^0 decays

Some Λ^0 are produced in the carbon nuclei in the polyethylene target will be included in the selected sample although their number were reduced by the cut off on Λ^0 momenta. Any one of these will not be polarized in the direction of \vec{E}_0 . Because of the spatial isotropy of the Fermi-momenta vectors, their average direction of polarization will be the same as that of the hydrogen-produced ones, so that this background will reduce the average value of αP but not introduce any bias into the estimate of M_λ .

6) Errors introduced in the analysis, approximations

Two main effects were neglected in the analysis: The small curvature of the initial π^+ beam due to the magnetic field*

* See Appendix J.

and flat chamber effect explained in section V.3. Since the experimental distribution of the angle φ is quite similar to the theoretical one we concluded that the effect of this neglect is small.

Small changes in the acceptance criteria does not have any significant effect on the estimate of μ_A .

To test the existence of any asymmetry between the two sets of stacks exposed on opposite sides of the π^- beam (odd and even numbered stacks) μ_A was estimated for the two sets of stacks separately. The result is as follows:

	For Ankara events	For all events
Odd-numbered stacks	-0.44 ± 0.23 n.m.	-0.54 ± 0.09 n.m.
Even-numbered stacks	-0.71 ± 0.20 n.m.	-0.63 ± 0.09 n.m.

It is seen that 68 % confidence interval includes the values of μ_A obtained from odd stacks or even stacks alone for both Ankara events and the whole sample and so the statistical increase the values for odd and even stacks get closer, i.e. statistics might explain the discrepancy between the two sets. But the difference might also be due to an unknown asymmetry since it consistently appears in the same direction in all samples of events. Another fact which supports this view is that number of events found in even stacks is always larger than those found in odd stacks by 15-20 %. Allowing 6 % systematic error for this and combining in with the other

systematic errors one obtains that systematic error is less
than 7% or $\pm 0.04 \mu \text{H}$.



CHAPTER VI

DISCUSSION AND CONCLUSIONS

Correcting both systematic and statistical errors on standard errors one finds $\mu_\lambda = (-0.59 \pm 0.07) \mu_H$. If only Ankara events are used the result is $\mu_\lambda = (-0.61 \pm 0.19) \mu_H$. The two results are consistent with each other, with the previous world average which is $(-0.73 \pm 0.20) \mu_H$ and also with the result of the collaboration published earlier. ⁽¹⁶⁾ This result is $(-0.66 \pm 0.07) \mu_H$. It was obtained by a very detailed analysis program using the larger computer at CERN. All the effects which could influence the final result were taken into account. Therefore the systematic error is smaller. The value obtained in this thesis is based on only the maximum of the analysis.

When compared with Table I, one sees that this result is in agreement with the predictions of various broken SU_3 models. But one should remember that most of the theoretical

results in Table I are subject to the validity of assumption and depend on the values of adjustable parameters. For example let us review now the pure SU(3) prediction, $\mu_{\Lambda} = \frac{1}{2} \mu_{\Sigma} = -0.26 \mu_N$ is derived. (17, 18, 19) One uses the hypothesis that the electromagnetic properties are represented by operators which are invariant under U-spin, and transform like a combination of scalar and vector in I-spin. Because of invariance under U-spin the elements of a U-spin multiplet have the same magnetic moments

$$\mu_{\Sigma^+} = \mu_{\Sigma^0} \quad (VI.1)$$

$$\mu_{\Sigma^-} = \mu_{\Sigma^0} \quad (VI.2)$$

$$\mu_{\Sigma^0} = \mu_{\Sigma^+} = \mu_{\Sigma^-} \quad (VI.3)$$

where Σ^0 is an eigenstate of U-spin with the eigenvalue 1. The other eigenstate belonging to the eigenvalue -1 is Λ^0 :

$$\Lambda^0 = -\frac{1}{2} \Sigma^0 - \frac{\sqrt{3}}{2} \Sigma^+ \quad (VI.4)$$

$$\Sigma^0 = \frac{\sqrt{3}}{2} \Lambda^0 - \frac{1}{2} \Sigma^+ \quad (VI.5)$$

From these two equations one gets:

$$\mu_{\Sigma^0} = \frac{1}{2} \mu_{\Lambda^0} + \frac{1}{2} \mu_{\Sigma^+} - \frac{\sqrt{3}}{2} \mu_{\Sigma^+ \Lambda^0} \quad (VI.6)$$

$$\mu_{\Lambda^0} = \frac{1}{2} \mu_{\Lambda^0} + \frac{1}{2} \mu_{\Sigma^+} - \frac{\sqrt{3}}{2} \mu_{\Lambda^0 \Sigma^+} \quad (VI.7)$$

$$\mu_{\Lambda^0 \Sigma^+} = -\frac{\sqrt{3}}{2} \mu_{\Lambda^0} - \frac{\sqrt{3}}{2} \mu_{\Sigma^+} - \frac{1}{2} \mu_{\Lambda^0 \Sigma^+} \quad (VI.8)$$

The transition moment $\mu_{\lambda \Sigma} = \sum_{\alpha} \mu_{\alpha} \Sigma$ has to vanish again because of invariance under U-spin

$$\mu_{\lambda \Sigma} = 0 \quad (VI.9)$$

Since the operators representing the electromagnetic properties are scalar-vector combinations in I-spin they have the form $a + bI_3$ and only I_3 has expectation values different from zero, in the states of an isotopic multiplet. The operator O has a matrix element $\langle \alpha | O | \beta \rangle = \delta_{\alpha\beta} (a + mb)$ between two eigenstates α, β of I_3 where m is such that $I_3 | \beta \rangle = m | \beta \rangle$. Since for a multiplet, m takes the $(2n + 1)$ integer values, $-n, \dots, 0, \dots, n$, it follows that

$$\mu_{\Sigma^+} = \mu_{\Sigma^0} = \mu_{\Sigma^-} = \mu_{\Lambda} = \mu_{\Xi^0} = \mu_{\Xi^-} = 0 \quad (VI.10)$$

From the fact that the charge operator Q may be written as $Q = \frac{2}{3} (2I_3 + U_3)$ one can assume that the current operator J has the same transformation properties under SU(3) and can be written as

$$J = J_1(x)I_3 + J_2(x)U_3 \quad (VI.11)$$

Since averaging over the whole baryon octet the expectation values of the operators I_3 and U_3 are zero, one obtains a further relation

$$\mu_{\Sigma^+} + \mu_{\Sigma^-} + \mu_{\Sigma^0} + \mu_{\Lambda} + \mu_{\Xi^0} + \mu_{\Xi^-} + \mu_{\Xi^+} + \mu_{\Xi^-} = 0 \quad (VI.12)$$

From the nine equations (VI.1), (VI.2), (VI.5), (VI.6), (VI.7), (VI.8), (VI.9), (VI.10), (VI.12) one can solve for the nine

of a partial symmetry group. A partial symmetry group is a set of transformations under which a significant portion of an effective Lagrangian, referring to specific physical circumstances remains invariant.

Equations (VI.14) and (VI.15) have been plotted.²² The experimental value of μ_{Λ} presented here and the present world average for μ_{Σ^+} which is (23)

$$\mu_{\Sigma^+} = 2.59 \pm 0.46 \mu_{\Lambda}$$

are shown on the graph. One sees that our result is in good agreement with Franklin's or Schelinger's results. Using this one can predict $\mu_{\Sigma^+} = 2.63 \pm 0.03 \mu_{\Lambda}$ which is in agreement with the present world average, but due to the large error of the present μ_{Σ^+} value one cannot conclude much.

²² See Fig. 26.

APPENDIX A

PRODUCTION AND DECAY OF THE Λ^0 BARYON

A.1. Calculation of the initial polarization and angular distribution of the decay products

Λ^0 is produced in the reaction



when a π^- beam is sent to a proton target.

Assume that the incoming particle is in the x -direction and choose the y - z plane as the production plane, i.e. the outgoing particle is in the direction $(0, \sin \theta, \cos \theta)$.

Since parity transformation changes positive helicity into negative helicity, longitudinal polarization of Λ^0 is not allowed because it violates parity conservation. Therefore the only non-zero polarization component will be P_x which will be calculated below

The spin up and down states of the scattered wave

(taking $\theta=0$) given by (24),

$$\psi_{20}^+ = \frac{R^{1/2}}{r^2} \left\{ [a_2 + (2a_{22} + a_{21}) \cos \theta] Y_{2,0} - [a_{22} - a_{21}] \sin \theta Y_{2,-1} \right\} \quad (A.1.2)$$

$$\psi_{20}^- = \frac{R^{1/2}}{r^2} \left\{ [a_2 + (2a_{22} + a_{21}) \cos \theta] Y_{2,0} - [a_{22} - a_{21}] \sin \theta Y_{2,-1} \right\} \quad (A.1.3)$$

where a 's are the partial wave amplitudes. The notation used is

a_{22}, a_{21} for p-waves

a_2 for s-wave

where l is the l-quantum and J is the total angular momentum of the final state.

$Y_{2,0}$ and $Y_{2,-1}$ are the spin eigenfunctions of Λ^0 . $Y_{2,0} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ represents a spin up state and $Y_{2,-1} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ represents a spin down state.

To simplify the notation introduce:

$$a = a_2 + (2a_{22} + a_{21}) \cos \theta$$

$$b = (a_{22} - a_{21}) \sin \theta \quad (A.1.4)$$

$$\alpha = Y_{2,0}, \quad \beta = Y_{2,-1}$$

Then (A.1.2) and (A.1.3) take the form

$$\psi_{20}^+ = a\alpha - b\beta \quad (A.1.5)$$

$$\Psi_{\text{in}} = -ib\alpha + a\beta \quad (\text{A.1.6})$$

The polarization in the x direction is the expectation value of σ_x :

$$P_x = \frac{\Psi^\dagger \sigma_x \Psi}{\Psi^\dagger \Psi} \quad (\text{A.1.7})$$

Since the initial state was unpolarized average over the two possible states:

$$P_x = \frac{1}{2} \frac{(a^* \alpha^* + ib^* \beta^*) \sigma_x (a\alpha - ib\beta)}{(a^* \alpha^* + ib^* \beta^*)(a\alpha - ib\beta)} + \frac{1}{2} \frac{(ib^* \alpha^* - a^* \beta^*) \sigma_x (-ib\alpha + a\beta)}{(ib^* \alpha^* - a^* \beta^*)(-ib\alpha + a\beta)} \quad (\text{A.1.8})$$

Since $\sigma_x \alpha = \beta$; $\sigma_x \beta = \alpha$; $\alpha^\dagger \beta = 0$, $\alpha^\dagger \alpha = 1$ etc.

$$P_x = -\frac{1}{2} \frac{iaa^* - ia^*b}{aa^* + ibb^*} + \frac{1}{2} \frac{-ia^*b + iaab}{aa^* + ibb^*} = \frac{ab^* - a^*b}{|a|^2 + |b|^2} \quad (\text{A.1.9})$$

or

$$P_x = -2 \frac{\text{Im}(ab^*)}{(|a|^2 + |b|^2)} \quad (\text{A.1.10})$$

Substitute (A.1.4) into (A.1.10) to get:

$$P_x = -\frac{\text{Im} \left[a_y^* (2a_{yy} + a_{xx}) \cos \theta \right] \left[(a_{yy}^* - a_{xx}^*) \sin \theta \right]}{\left| a_y^* (2a_{yy} + a_{xx}) \cos \theta \right|^2 + \left| (a_{yy}^* - a_{xx}^*) \sin \theta \right|^2} \quad (\text{A.1.11})$$

As it is seen from this formula, magnitude of the polarisation depends on the direction of the outgoing particle and also on the phase shifts since α & β are dependent on the phase shifts (δ) as :

$$a = e^{i\delta} \sin \delta \quad (A.1.12)$$

One can show that $P_y = P_z = 0$ as follows :

$$P_y = \frac{1}{2} \frac{(\alpha^2 \alpha^2 + \beta^2 \beta^2) \tau_y (\alpha \alpha - \beta \beta)}{(\alpha^2 \alpha^2 + \beta^2 \beta^2)(\alpha \alpha - \beta \beta)} + \frac{1}{2} \frac{(\beta^2 \alpha^2 + \alpha^2 \beta^2) \tau_y (-\beta \alpha + \alpha \beta)}{(\beta^2 \alpha^2 + \alpha^2 \beta^2)(-\beta \alpha + \alpha \beta)} \quad (A.1.13)$$

Since $\tau_y \alpha = \beta$; $\tau_y \beta = -\alpha$; $\alpha^2 \beta = 0$; $\alpha^2 \alpha = 1$ etc.

$$P_y = \frac{1}{2} \frac{\alpha^2 \beta - \alpha \beta^2}{|\alpha|^2 + |\beta|^2} + \frac{1}{2} \frac{\alpha \beta^2 + \alpha^2 \beta}{|\alpha|^2 + |\beta|^2} = 0 \quad (A.1.14)$$

Similarly

$$P_z = \frac{1}{2} \frac{(\alpha^2 \alpha^2 + \beta^2 \beta^2) \tau_z (\alpha \alpha - \beta \beta)}{(\alpha^2 \alpha^2 + \beta^2 \beta^2)(\alpha \alpha - \beta \beta)} + \frac{1}{2} \frac{(\beta^2 \alpha^2 + \alpha^2 \beta^2) \tau_z (-\beta \alpha + \alpha \beta)}{(\beta^2 \alpha^2 + \alpha^2 \beta^2)(-\beta \alpha + \alpha \beta)} \quad (A.1.15)$$

Since $\tau_z \alpha = \alpha$; $\tau_z \beta = -\beta$; $\alpha^2 \beta = 0$; $\alpha^2 \alpha = 1$ etc.

$$p_a = \frac{1}{2} \frac{aa^* - bb^*}{|a|^2 + |b|^2} + \frac{1}{2} \frac{bb^* - aa^*}{|a|^2 + |b|^2} = 0 \quad (A.2.15)$$

Angular distribution of the proton from the decay



Since the parity is not conserved in this decay one expects both $S_{1/2}$ and $P_{1/2}$ states of the decay products. The decay can then be described by a matrix

$$M(\Lambda^0 \longrightarrow \pi^- + p) = a + p \vec{\sigma} \cdot \hat{q} \quad (A.2.17)$$

where a and p indicate the amplitude of S -waves and P -waves proton emission respectively and $\hat{q} = (\sin \theta \cos \varphi, \sin \theta \sin \varphi, \cos \theta)$ is the direction of proton emission.

The cross-section is :

$$\frac{d\sigma}{d\Omega} = \psi_f^* M^* M \psi_i \quad (A.2.18)$$

where ψ_i and ψ_f are the initial and final states.

$$\frac{d\sigma}{d\Omega} = |a|^2 + |p|^2 + 2 \operatorname{Re}(a^* p) \langle \vec{\sigma} \rangle \cdot \hat{q} \quad (A.2.19)$$

Let

$$\alpha = \frac{2 \operatorname{Re}(a^* p)}{|a|^2 + |p|^2} \quad (A.2.20)$$

Then

$$\frac{d\sigma}{d\Omega} = (|a|^2 + |p|^2) (1 + \alpha \langle \vec{\sigma} \rangle \cdot \hat{q}) \quad (A.2.21)$$

If the Λ^0 is polarized along the s-direction

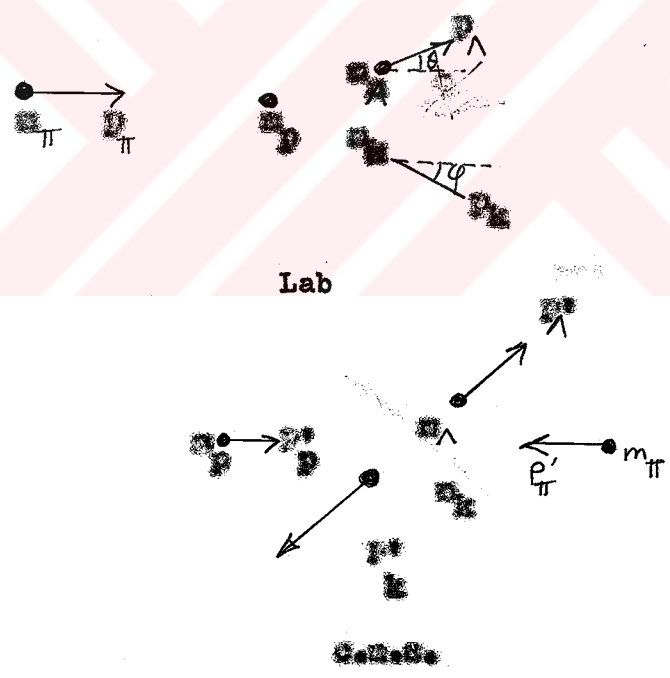
$$\frac{d\sigma}{d\Omega} = (|a|^2 + |b|^2) (1 + \alpha P \cos \theta)$$

where P is the magnitude of the polarization calculated earlier.

4.2 Kinematics

(1) Production

Consider the reaction $p + \pi^- \rightarrow \Lambda^0 + \pi^0$ in the laboratory frame and c.m.s. frame



One obtains the velocity β of the c.m.s. frame with respect to the laboratory frame as follows :

In the c.m.s. frame the momenta of p^0 and π^- are equal :

$$p_{\pi}^* = - p_p^* \tag{4.2.1}$$

Writing this equation in the laboratory frame:

$$\gamma(p_{\pi} - \beta E_{\pi}) = -\gamma(-\beta m_p) \quad (A.2.2)$$

where

$$\gamma = 1/(1 - \beta^2)^{1/2} \quad \text{and} \quad E_{\pi} = \sqrt{p_{\pi}^2 + m_{\pi}^2}$$

Solving from this equation one obtains

$$\beta = \frac{p_{\pi}}{E_{\pi} + m_p} \quad (A.2.3)$$

Converting the available laboratory energy into the c.m.s. frame we get

$$E_{\text{c.m.}}^2 = (E_{\pi} + m_p - \beta p_{\pi})^2 \quad (A.2.4)$$

This energy is the sum of Δ^0 and K^0 energies in this frame:

$$E_{\text{c.m.}}^2 = E_{\Delta^0}^2 + E_{K^0}^2 \quad (A.2.5)$$

or

$$E_{\text{c.m.}}^2 = (E_{\Delta^0} - E_{K^0})^2 \quad (A.2.6)$$

$$E_{\Delta^0}^2 + E_{K^0}^2 = E_{\text{c.m.}}^2 - 2E_{\Delta^0}E_{K^0} + E_{\Delta^0}^2 + E_{K^0}^2 \quad (A.2.7)$$

since $p_{\Delta^0} = -p_{K^0}$ we can solve for the c.m.s. energy of Δ^0

$$E_{\Delta^0} = \frac{E_{\text{c.m.}}^2 + E_{K^0}^2}{2E_{\text{c.m.}}} \quad (A.2.8)$$

The c.m.s. momentum of Λ^0 is :

$$p_{\Lambda^0}^* = \sqrt{E_{\Lambda^0}^{*2} - m_{\Lambda^0}^2} \quad (4.2.9)$$

We can find the laboratory momentum and angle of Λ^0 as follows

$$\tan \theta = \frac{p_{\Lambda^0}^* \sin \alpha}{p_{\Lambda^0}^* \cos \alpha + \beta E_{\Lambda^0}^*} = \frac{p_{\Lambda^0}^* \sin \alpha}{\gamma (p_{\Lambda^0}^* \cos \alpha + \beta E_{\Lambda^0}^*)} \quad (4.2.10)$$

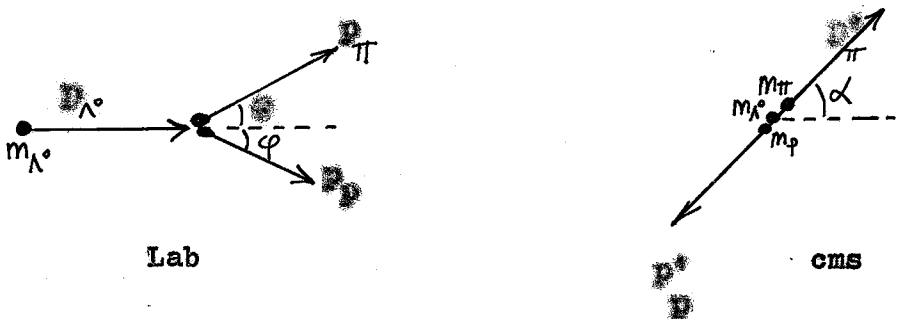
In the above equations the unprimed quantities are in the laboratory frame and the primed ones in the c.m.s. frame. α , the c.m.s. emission angle of Λ^0 changes from 0° to 180° . As calculated in Prog. 3 during this change the maximum value θ attains is $\sim 31^\circ$.

$$p_{\Lambda^0} = \frac{\gamma (p_{\Lambda^0}^* \cos \alpha + \beta E_{\Lambda^0}^*)}{\cos \theta} \quad (4.2.11)$$

From the output of Prog. 3 we see that p_{Λ^0} changes between 504 and 810 MeV/c (both values for $\theta = 10^\circ$) for $\alpha > 10^\circ$ as is the case in the actual experiment.

(ii) Decay

Consider the reaction $\Lambda^0 \rightarrow p + \pi^-$ in the laboratory frame and c.m.s. frame :



The energy available in the c.m.s. frame is just the rest mass of Λ^0 and it is equal to the sum of proton and pion energies in this frame :

$$E_{\text{CM}}^{\Lambda^0} = m_{\Lambda^0} = E_{\pi}^* + E_p^* \quad (\text{A.2.24})$$

or

$$E_{\pi}^* = m_{\Lambda^0} - E_p^* \quad (\text{A.2.25})$$

squaring both sides we get

$$m_{\Lambda^0}^2 + p_{\pi}^{*2} = m_{\Lambda^0}^2 - 2m_{\Lambda^0} E_p^* + m_p^2 + p_p^{*2} \quad (\text{A.2.26})$$

since $p_p^* = -p_{\pi}^*$

we get

$$E_p^* = \frac{m_{\Lambda^0}^2 + m_p^2 - m_{\pi}^2}{2m_{\Lambda^0}} \quad (\text{A.2.27})$$

and

$$E_{\pi}^* = m_{\Lambda^0} - E_p^* \quad (\text{A.2.28})$$

The energies are

$$E_p^* = \sqrt{p_p^{*2} + m_p^2} \quad (\text{A.2.29})$$

$$E_{\pi}^* = \sqrt{p_{\pi}^{*2} + m_{\pi}^2} \quad (\text{A.2.30})$$

The laboratory angles and momenta of the proton and pion are obtained as follows:

$$\tan \theta = \frac{p_{\pi y}}{p_{\pi x}} = \frac{p_{\pi y}^*}{\gamma(p_{\pi x}^* + \beta E_{\pi}^*)} = \frac{p_{\pi}^* \sin \alpha}{\gamma(p_{\pi}^* \cos \alpha + \beta E_{\pi}^*)} \quad (\text{A.2.31})$$

$$\tan \varphi = \frac{E_p^* \sin \alpha}{\gamma (E_p^* \cos \alpha + \beta E_p^*)} \quad (A.2.20)$$

$$E_p^* \pi = \frac{\gamma (E_p^* \cos \alpha + \beta E_p^*)}{\cos \varphi} \quad (A.2.21)$$

$$E_p^* = \frac{(E_p^* \cos \alpha + \beta E_p^*)}{\cos \varphi} \quad (A.2.22)$$

β and γ occurring in these equations are those of the Λ° frame (c.o.c. frame) and given by

$$\beta = \frac{E_p^* \Lambda^\circ}{E_p^* \Lambda^\circ} \quad (A.2.23)$$

$$\gamma = \frac{1}{\sqrt{1 - \beta^2}} \quad (A.2.24)$$

Prog. 3 calculates the limits between which these quantities change:

$$0.782 < \beta < 0.933 \quad (A.2.25)$$

$$1.077 < \gamma < 1.231$$

$\tan \varphi$, $\tan \varphi \cdot \pi$ and E_p^* are all monotonically increasing or decreasing functions of β . Therefore in order to find the values between which they change it is sufficient to look at how they change with α for the extremum values of β and γ .

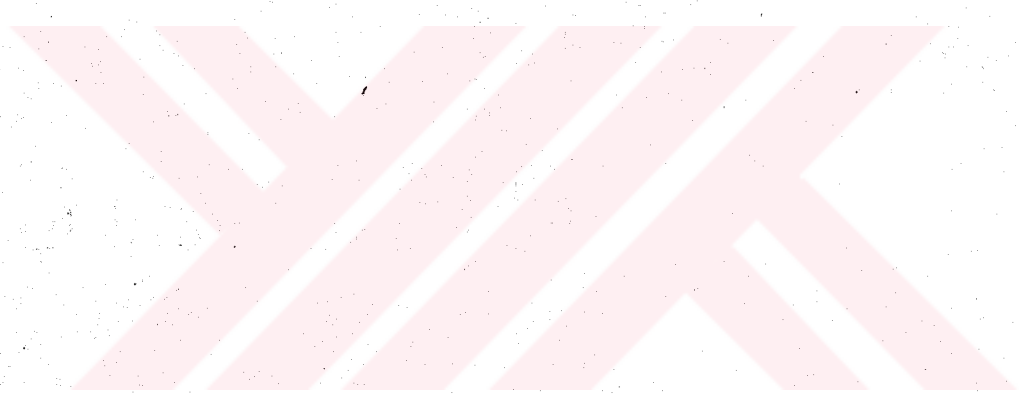
Step 3 establishes the following limits:

$$0 < \theta < 180^\circ$$

$$0 < \varphi < 180^\circ$$

$$0 < \psi < 180^\circ \text{ (not } \pi)$$

$$0 < \chi < 180^\circ$$



APPENDIX B

THE COVARIANT FORM OF THE PRECESSION EQUATIONS

The problem of the precession of the polarization vector of particles moving in an electromagnetic field has been treated by several authors.

Handberg and Jørgensen⁽²⁵⁾ used a quantum mechanical approach. They considered the Hamiltonian for a particle with an anomalous moment of magnitude $g\mu_0$ (μ_0 is the Bohr magneton) in a constant homogeneous magnetic field \vec{H} , in the Foldy-Wouthoff representation. Restricting themselves only to positive-energy solutions of the wave equation, up to terms of first order in $\mu_0 H$ the Hamiltonian is

$$H = \epsilon_{\pi} - \mu_0 \vec{\sigma} \cdot \vec{H} \left[\frac{1}{\gamma} + g \right] + g \mu_0 \frac{(\vec{\sigma} \cdot \vec{v})(\vec{v} \cdot \vec{H})}{v^2} \left[1 - \frac{1}{\gamma} \right] \quad (B.1)$$

where $\epsilon_{\pi} = (m_0^2 c^4 + \vec{p}^2 c^2)^{1/2}$ for an uncharged particle, $\vec{\sigma}$ is the spin operator, \vec{v} is the velocity, \vec{p} momentum, m_0 rest mass

of the particle and $\gamma = (1 - v^2/c^2)^{-1/2}$.

The equation of motion for the spin operator is :

$$\dot{\vec{\sigma}} = -\frac{1}{\hbar} [\vec{\sigma}, H] \quad (3.2)$$

For the two orientations of the magnetic field with respect to the particle velocity one gets :

$$\vec{B} \parallel \vec{v} \quad \dot{\vec{\sigma}} = -\frac{e\hbar}{m_0 c} \vec{\sigma} \times \vec{B} \quad (3.3)$$

$$\vec{B} \perp \vec{v} \quad \dot{\vec{\sigma}} = -\frac{e\hbar}{m_0 c} \vec{\sigma} \times \vec{B} \quad (3.4)$$

These equations are equivalent to the equation (22.5.6) which we have used in our calculations.

Later other authors (26, 27, 28) obtained a covariant classical equation of motion for the polarization four-vector. Since polarization is the expectation value of the spin operator it should obey classical laws (threefold theorem). They start with the classical equation of motion in the rest system (R) of the particles :

$$\frac{d\vec{\sigma}}{d\tau} = \frac{\mu e}{m_0 c} \vec{\sigma} \times \vec{B} \quad (3.5)$$

where \vec{B} is the polarization vector, and τ is the proper time of the particle. In order to generalize this equation, a polarization four-vector (axial) is introduced :

$$s = (s_0, \vec{s}) \quad , \quad s = (0, \vec{s}) \quad \text{in } (B) \quad (2.6)$$

Also the particle motion is expressed by a velocity four-vector:

$$v = (v^0, \vec{v}) = \gamma (1, \vec{\beta}) \quad , \quad v = (1, 0) \quad \text{in } (B) \quad (2.7)$$

One has the relationship :

$$s \cdot v = s^0 v^0 - \vec{s} \cdot \vec{v} = 0 \quad (2.8)$$

Therefore

$$s^0 v^0 = \vec{s} \cdot \vec{v} \quad (2.9)$$

Since $\vec{v} = 0$ in (B) one has :

$$\frac{ds^0}{d\tau} = \vec{s} \cdot \frac{d\vec{v}}{d\tau} \quad (2.10)$$

If the particle is neutral $\frac{d\vec{v}}{d\tau} = 0$ and consequently one has :

$$\frac{ds^0}{d\tau} = 0 \quad (2.11)$$

or

$$\frac{ds}{d\tau} = (0, \frac{\mu_0}{mc} \vec{s} \times \vec{B}) \quad \text{in } (B) \quad (2.12)$$

In terms of the skew-symmetric electromagnetic field tensor F and polarization four-vector, $\vec{s} \times \vec{B}$ can be written as :

$$(\vec{s} \times \vec{B})_{\vec{R}} = (s\vec{r})_{\vec{R}} = (\vec{B}_{\vec{R}} \cdot \vec{s}, \vec{s}_{\vec{R}} \times \vec{B}) \quad (2.13)$$

$$\text{Let } \frac{ds}{d\tau} = (0, \frac{\mu_0}{mc} (s\vec{r})_{\vec{R}}) \equiv \vec{z}_{\vec{R}} \quad (2.14)$$

To obtain a general expression for \dot{Z} one uses the properties of \dot{Z}_μ . It is linear in both \dot{S} and V . The only four-vectors with these properties which one can form from \dot{S} , V and F are \dot{S} , $V(SV)$. Therefore one can write \dot{Z} as follows:

$$\dot{Z} = a \dot{S} + b V(SV) \quad (2.29)$$

or

$$\dot{Z}_\mu = \left\{ a(\dot{S})^\mu_\mu + b(SV)^\mu_\mu, a(\dot{S}V)^\mu_\mu \right\} \quad (2.30)$$

Comparing the equations (2.16) and (2.14) one gets:

$$a = \mu e / m_0 \quad b = - \mu e / m_0$$

Therefore the equation for \dot{S} is:

$$\dot{S} = \frac{\mu e}{m_0} [\dot{S} - V(SV)] \quad (2.31)$$

This is the covariant equation of motion for an uncharged particle with an anomalous magnetic moment μ , in an electromagnetic field. To see that this equation leads to the equation (II.3.6) one first writes the covariant equation in the laboratory frame:

$$\dot{S}_\mu = \frac{\mu e}{m_0} (\dot{S})_\mu - v_\mu (SV) \quad (2.32)$$

The polarization three-vector should always be considered in the rest frame, because its magnitude and direction depends on the frame. Therefore in order to obtain an equation with a physical meaning one expresses \dot{S}_μ in terms of $S_\mu = (0, \vec{S})$ using the Lorentz transformation:

$$\dot{E}_1 = (\dot{E}_1^0, \dot{E}_1) = \left(\gamma \bar{\beta} \cdot \dot{E}_2, \dot{E}_2 + \bar{\beta} \frac{\gamma^2}{\gamma+1} \bar{\beta} \cdot \dot{E}_2 \right) \quad (11.19)$$

and

$$\dot{E}_2 = (\dot{E}_2^0, \dot{E}_2) = \left(\gamma \bar{\beta} \cdot \dot{E}_1, \dot{E}_1 + \bar{\beta} \frac{\gamma^2}{\gamma+1} \bar{\beta} \cdot \dot{E}_1 \right) \quad (11.20)$$

Also one has for zero electric field :

$$(\dot{B})_2 = (0, \dot{E}_2 \times \bar{\beta}) = \left\{ 0, (\dot{E}_2 + \bar{\beta} \frac{\gamma^2}{\gamma+1} \bar{\beta} \cdot \dot{E}_2) \times \bar{\beta} \right\} \quad (11.21)$$

and

$$\text{div} = \gamma (\bar{\beta} \cdot \nabla, \dot{E}_2) = \gamma (\bar{\beta} \cdot \nabla, \dot{E}_1) \quad (11.22)$$

The last equation is written using equation (11.19). Substitution (11.20), (11.21), and (11.22) into the equation (11.18) one gets :

$$\begin{aligned} (\gamma \bar{\beta} \cdot \dot{E}_2, \dot{E}_2 + \bar{\beta} \frac{\gamma^2}{\gamma+1} \bar{\beta} \cdot \dot{E}_2) &= \frac{\mu_0}{4\pi} \left[-\gamma^2 (\bar{\beta} \cdot \nabla, \dot{E}_2) \cdot \bar{\beta} \times \bar{\beta} \right. \\ &\quad \left. + \frac{\gamma^2}{\gamma+1} (\bar{\beta} \cdot \nabla) \bar{\beta} \times \bar{\beta} \right. \\ &\quad \left. - \gamma^2 \bar{\beta} (\bar{\beta} \cdot \nabla, \dot{E}_2) \right] \quad (11.23) \end{aligned}$$

or

$$\dot{E}_2 = \frac{\mu_0}{4\pi} \left[\dot{E}_2 \times \bar{\beta} + \frac{\gamma^2}{\gamma+1} (\bar{\beta} \cdot \nabla) \bar{\beta} \times \bar{\beta} - \frac{\gamma^2}{\gamma+1} \bar{\beta} (\bar{\beta} \cdot \nabla, \dot{E}_2) \right] \quad (11.24)$$

Using $\beta^2 \gamma^2 = \gamma^2 - 1$ one obtains

$$\dot{E}_2 = \frac{\mu_0}{4\pi} \left[\dot{E}_2 \times \bar{\beta} + \frac{\gamma-1}{\beta^2} (\bar{\beta} \cdot \nabla) \bar{\beta} \times \bar{\beta} - \frac{\gamma-1}{\beta^2} \bar{\beta} (\bar{\beta} \cdot \nabla, \dot{E}_2) \right] \quad (11.25)$$

Let $\bar{\beta} \times B = \bar{A}$

Then

$$\begin{aligned}
 (\bar{\beta} \cdot E_2) \bar{\beta} \times B - \beta (\bar{\beta} \cdot B, E_2) &= (\bar{\beta} \cdot E_2) \bar{A} - (\bar{\beta} \cdot E_2) \bar{\beta} \\
 &= E_2 \times (\bar{A} \times \bar{\beta}) \\
 &= E_2 \times [(\bar{\beta} \times B) \times \bar{\beta}] \\
 &= E_2 \times [\beta^2 B - (\bar{\beta} \cdot B) \bar{\beta}]
 \end{aligned}
 \tag{11.26}$$

Using the equation (11.26) equation (11.25) is put into the form :

$$\dot{\bar{a}}_2 = \frac{d\bar{a}_2}{dt} = \frac{H_0}{m_0} E_2 \times \left[\gamma B - (\gamma - 1) \frac{(\bar{\beta} \cdot B)}{\beta^2} \bar{\beta} \right]
 \tag{11.27}$$

or

$$\frac{d\bar{a}_2}{dt} = \frac{H_0}{m_0} E_2 \times \left[B - \frac{\gamma - 1}{\gamma} \frac{\bar{\beta} \cdot B}{\beta^2} \bar{\beta} \right]
 \tag{11.28}$$

This is the same equation as the equation (11.3.6) which we have derived earlier in a simple way.

APPENDIX C

THE SOLUTION OF THE PROPAGATION EQUATION

The equation to be solved is

$$\frac{d\vec{S}}{dt} = \vec{S} \times \vec{\Omega} \tag{C.1}$$

where

$$\vec{\Omega} = \frac{\mu_0}{\hbar} \left[\vec{S} - \frac{\gamma-1}{\gamma} \frac{\vec{S} \cdot \vec{P}}{P^2} \vec{P} \right] \tag{C.2}$$

subject to the initial condition $\vec{S} = (0, P, 0)$ in the coordinate system defined by the equation (II.36). Writing the equation (C.1) in terms of the components one gets:

$$\frac{dS_1}{dt} = \Omega_3 S_2 - \Omega_2 S_3$$

$$\frac{dS_2}{dt} = \Omega_1 S_3 - \Omega_3 S_1 \tag{C.3}$$

$$\frac{dS_3}{dt} = \Omega_2 S_1 - \Omega_1 S_2$$

This set of equations is very easy to solve in a coordinate system (primed) whose z -axis is along the direction $\vec{\Omega}$. In such a system they take the form:

$$\frac{d\Omega_1'}{dt} = \Omega \Omega_2'$$

$$\frac{d\Omega_2'}{dt} = -\Omega \Omega_1'$$

(0.4)

$$\frac{d\Omega_3'}{dt} = 0$$

The solutions are :

$$\Omega_1' = A \cos \Omega t + B \sin \Omega t$$

$$\Omega_2' = -A \sin \Omega t + B \cos \Omega t$$

(0.5)

$$\Omega_3' = C$$

The constants A , B , C are to be determined from the initial conditions.

One has to transform these components of the vector $\vec{\Omega}$ into a general coordinate system in which the vector $\vec{\Omega}$ has components Ω_1 , Ω_2 , Ω_3 . The transformed components of $\vec{\Omega}$ will be solutions of the equation (0.3).

In order to rotate the unprimed system to the primed system one first performs a rotation around the z -axis by an angle φ , and then another rotation around the new y -axis by

an angle θ . The transformation matrix is :

$$\begin{pmatrix} \cos\theta & 0 & -\sin\theta & \cos\varphi & \sin\varphi & 0 \\ 0 & 1 & 0 & -\sin\varphi & \cos\varphi & 0 \\ \sin\theta & 0 & \cos\theta & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \cos\theta & \cos\varphi & -\cos\theta \sin\varphi & -\sin\theta \\ -\sin\varphi & \cos\varphi & 0 \\ \sin\theta & \cos\varphi & \sin\theta \cos\varphi & \cos\theta \end{pmatrix} \quad (C.5)$$

The angles θ and φ are related to the components of $\vec{\Omega}$ in the unprimed system as follows:

$$\varphi = \cos^{-1}(\Omega_2 / (\Omega_1^2 + \Omega_2^2)^{1/2})$$

$$\theta = \cos^{-1}(\Omega_3 / \Omega) \quad (C.7)$$

where

$$\Omega = (\Omega_1^2 + \Omega_2^2 + \Omega_3^2)^{1/2}$$

Therefore the initial condition in the unprimed system ($\vec{\Omega} = (\vec{\Omega}_0) = (0, 0, \Omega_0)$) corresponds in the primed system to

$$\vec{\Omega}(t=0) = \begin{pmatrix} \frac{\Omega_1 \Omega_3}{(\Omega_1^2 + \Omega_2^2)^{1/2} \Omega} & \frac{\Omega_2 \Omega_3}{\Omega (\Omega_1^2 + \Omega_2^2)^{1/2}} & \frac{(\Omega_1^2 + \Omega_2^2)^{1/2}}{\Omega} \\ \frac{\Omega_1}{(\Omega_1^2 + \Omega_2^2)^{1/2}} & \frac{\Omega_2}{(\Omega_1^2 + \Omega_2^2)^{1/2}} & 0 \\ \frac{\Omega_1}{\Omega} & \frac{\Omega_2}{\Omega} & \frac{\Omega_3}{\Omega} \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\Omega_1 \Omega_3}{(\Omega_1^2 + \Omega_2^2)^{1/2} \Omega} \\ \frac{\Omega_2 \Omega_3}{(\Omega_1^2 + \Omega_2^2)^{1/2} \Omega} \\ \frac{\Omega_3}{\Omega} \end{pmatrix}$$

Comparing this with the Equation (C.5) one chooses the constants as follows:

$$A = P \Omega_2 \Omega_1^{-1} (\Omega_1^2 + \Omega_2^2)^{1/2}$$

$$B = P \Omega_1 (\Omega_1^2 + \Omega_2^2)^{-1/2} \tag{0.0}$$

$$C = \Omega_2 \Omega^{-1}$$

The transpose of the matrix of the equation (0.0) will transform the components of \mathbb{E} from the primed to the unprimed system

$$E'(t) = \begin{pmatrix} \frac{\Omega_1 \Omega_2}{(\Omega_1^2 + \Omega_2^2)^{1/2}} \cos \Omega t & \frac{-\Omega_2}{(\Omega_1^2 + \Omega_2^2)^{1/2}} \sin \Omega t & \frac{\Omega_1}{\Omega} \\ \frac{\Omega_1 \Omega_2}{(\Omega_1^2 + \Omega_2^2)^{1/2}} \sin \Omega t & \frac{\Omega_1}{(\Omega_1^2 + \Omega_2^2)^{1/2}} \cos \Omega t & \frac{\Omega_2}{\Omega} \\ \frac{(\Omega_1^2 + \Omega_2^2)^{1/2}}{\Omega} & 0 & \frac{\Omega_2}{\Omega} \end{pmatrix} \begin{pmatrix} \Omega_1 \Omega_2 \cos \Omega t & \Omega_2 \sin \Omega t \\ \Omega_1 \Omega_2 \sin \Omega t & \Omega_1 \cos \Omega t \\ \Omega_2 & \Omega_1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{-\Omega_1 \Omega_2}{\Omega^2} \cos \Omega t + \frac{\Omega_1}{\Omega} \sin \Omega t + \frac{\Omega_1 \Omega_2}{\Omega^2} \\ \frac{\Omega_1^2 + \Omega_2^2}{\Omega^2} \cos \Omega t + \frac{\Omega_2 \Omega_1}{\Omega} \\ -\frac{\Omega_1 \Omega_2}{\Omega^2} \cos \Omega t - \frac{\Omega_1}{\Omega} \sin \Omega t + \frac{\Omega_1 \Omega_2}{\Omega^2} \end{pmatrix}$$

$$= \frac{1}{\Omega} \begin{pmatrix} \Omega_1 \Omega_2 (1 - \cos \Omega t) + \Omega \Omega_3 \sin \Omega t \\ (\Omega \frac{2}{3} + \Omega \frac{2}{1}) \cos \Omega t + \Omega \frac{2}{2} \\ \Omega_3 \Omega_2 (1 - \cos \Omega t) - \Omega \Omega_1 \sin \Omega t \end{pmatrix} \quad (6.10)$$

In the coordinate system we have chosen $\bar{\Omega}$ is given by

$$\bar{\Omega} = \frac{\mu_0}{20} \left[\frac{1}{8} \Omega_1, \Omega_2, \Omega_3 \right] \quad (6.11)$$

It is seen that if $\bar{\Omega}$ is perpendicular to \bar{p} and $\bar{\Omega}_0$ which are approximately the case in this experiment, then one has

$$\bar{\Omega} = \frac{\mu_0}{20} (0, 0, \Omega) \quad (6.12)$$

and

$$\bar{\Omega}(t) = \bar{\Omega} \begin{bmatrix} \cos \Omega t \\ \sin \Omega t \\ 0 \end{bmatrix} \quad (6.13)$$

which is the same as the equation (II.3.13).

APPENDIX D

THE DISTRIBUTION OF THE EXACT ANGULAR DISTRIBUTION
IN TERMS OF THE ANGLES φ AND ψ

One can write equation (II.4.1) in the following form

$$d\Omega = \frac{1}{4\pi} \left(1 - \alpha \frac{\vec{P} \cdot \vec{P}'_p}{P_p} \right) d\Omega \quad (D.1)$$

where \vec{P} is the polarization vector and \vec{P}'_p is the proton momentum vector in the center of mass and $d\Omega$ is the differential solid angle element. The scalar product can be written using the components in the reference system defined by equation (II.3.3):

$$d(\varphi, \psi) d\varphi d\psi = \frac{1}{4\pi} \left[1 - \alpha (\alpha_1 \cos\psi \sin\varphi + \alpha_2 \cos\psi \cos\varphi + \alpha_3 \sin\psi) \right] \varphi d\varphi d\psi \quad (D.2)$$

One can put this equation into the following form

$$\begin{aligned} d(\varphi, \psi) d\varphi d\psi &= \frac{1}{4\pi} \left[1 - \alpha_1 \sin\psi + \alpha \cos\psi (\alpha_1 \sin\varphi + \alpha_2 \cos\varphi) \right] \varphi d\varphi d\psi \\ &= \frac{1}{4\pi} \left[1 - \alpha_1 \sin\psi + \alpha \cos\psi \alpha_2 (\tan\varphi \sin\varphi + \cos\varphi) \right] \varphi d\varphi d\psi \end{aligned}$$

$$= \frac{1}{4\pi} \left[1 - \frac{a_2 \sin \psi \times \cos \psi}{\cos \psi_0} \cos(\psi - \psi_0) \right] \sin \psi$$

$$= \frac{1}{4\pi} \left[1 - \frac{a_2 \sin \psi \times \cos \psi}{\cos \psi_0} \cos(\psi - \psi_0) \right] \sin \psi \quad (3.3)$$

where

$$= \frac{a_2}{\cos \psi_0} \left[\frac{\sqrt{1 - \frac{a_2^2 \sin^2 \psi}{\cos^2 \psi_0}}}{2} + \frac{\sqrt{1 - \frac{a_2^2 \cos^2 \psi}{\cos^2 \psi_0}}}{2} - \sqrt{1 - \left(\frac{a_2}{\cos \psi_0}\right)^2} \right] \left\{ 1 - \left[\frac{a_2 \sin \psi \times \cos \psi}{\cos \psi_0} \cos(\psi - \psi_0) \right] \right\}^{1/2} \quad (3.4)$$

This is the generalized form of the equation (II.4.6) and reduces to it for $a_2 = 0$.

APPENDIX B

DERIVATION OF THE STATISTICAL ERROR ON THE ANGLE

 φ_0 DUE TO THE ASYMMETRY IN THE DECAY

The final direction of polarization of Δ^0 can be determined by measuring the decay asymmetry with respect to three planes which are perpendicular to each other, in the center of mass system of the particle. Considering an oriented plane, defined by a unit vector \vec{I} normal to the plane, $A(\vec{I})$, the asymmetry with respect to this plane is defined as follows:

$$A(\vec{I}) = \frac{N(+\vec{I}) - N(-\vec{I})}{N(+\vec{I}) + N(-\vec{I})} \quad (B.1)$$

where $N(\pm\vec{I})$ is the number of decays in the half-space corresponding to the direction $\pm\vec{I}$.

Using the equations (II.4.4) and (B.1) one can obtain the angle of precession φ_0 in terms of the asymmetries A_1 , A_2 and A_3 :

$$\tan \varphi_0 = \frac{\sqrt{A_1^2 + A_2^2}}{A_3} \quad (11.2)$$

where

A_1 = forward - backward asymmetry

A_2 = left-right asymmetry

A_3 = up-down asymmetry

Let $u = \tan \varphi_0$. $\delta \varphi_0$, the error in φ_0 , is given in terms of δu , the error in u , as follows:

$$\delta \varphi_0 = \frac{\partial \varphi}{\partial u} \delta u \quad (11.3)$$

One has

$$\frac{\partial \varphi}{\partial u} = \frac{1}{1+u^2} \quad (11.4)$$

and

$$(\delta u)^2 = \left(\frac{\partial u}{\partial A_1}\right)^2 (\delta A_1)^2 + \left(\frac{\partial u}{\partial A_2}\right)^2 (\delta A_2)^2 + \left(\frac{\partial u}{\partial A_3}\right)^2 (\delta A_3)^2 \quad (11.5)$$

One obtains the derivatives of u as follows:

$$\frac{\partial u}{\partial A_1} = \frac{A_1}{A_3 (A_1^2 + A_2^2)^{1/2}} \quad (11.6)$$

$$\frac{\partial u}{\partial A_2} = \frac{A_2}{A_3 (A_1^2 + A_2^2)^{1/2}} \quad (11.7)$$

$$\frac{\partial u}{\partial A_3} = \frac{1}{A_3 (A_1^2 + A_2^2)^{1/2}} \quad (11.8)$$

The statistical errors δA_1 , δA_2 and δA_3 are:

$$(\delta A_1)^2 = \left(\frac{\partial A_1}{\partial N_1(+)}\right)^2 (\delta N_1(+))^2 + \left(\frac{\partial A_1}{\partial N_1(-)}\right)^2 (\delta N_1(-))^2 \quad (8.9)$$

Since $N_1(+)=N_1-N_1(-)$ the derivatives are:

$$\frac{\partial A_1}{\partial N_1(+)} = -\frac{\partial A_1}{\partial N_1(-)} = \frac{1}{N_1} \quad (8.10)$$

The statistical errors on $N_1(+)$ and $N_1(-)$ are:

$$\delta N_1(+)=\sqrt{N_1(+)} \quad (8.11)$$

$$\delta N_1(-)=\sqrt{N_1(-)}$$

Substituting these into (8.9) we get:

$$(\delta A_1)^2 = \frac{1}{N_1^2} N_1(+) + \frac{1}{N_1^2} N_1(-) \quad (8.12)$$

or

$$(\delta A_1)^2 = \frac{1}{N_1} \quad (8.13)$$

The error in a is from equation (8.5)

$$\delta a = \left[\frac{A_1^2}{N_1^2(A_1^2 + A_2^2)} + \frac{A_1^2 + A_2^2}{A_1^4} + \frac{A_3^2}{N_1^2(A_1^2 + A_2^2)} \right]^{1/2} \frac{1}{N_1^{1/2}} \quad (8.14)$$

Simplifying this we get:

$$\delta a = \frac{(A_1^2 + A_2^2 + A_3^2)^{1/2}}{N_1^{3/2} A_1^2} \quad (8.15)$$

The error in φ_0 is from Eqs. (3.3) and (3.4)

$$\delta\varphi_0 = \frac{1}{1 + \frac{A_1^2 + A_2^2}{A_3^2}} \frac{(A_1^2 + A_2^2 + A_3^2)^{1/2}}{A_3^{1/2} \frac{A_1}{A_3}} = \frac{1}{A_3^{1/2} (A_1^2 + A_2^2 + A_3^2)^{1/2}} \quad (3.25)$$

Using the definition $A(\mathbf{I}) = \frac{N(+)-N(-)}{N(+)+N(-)}$ and the formula (2.1.6) to calculate

$N(+)$ and $N(-)$

we obtain:

$$A(\mathbf{I}) = \frac{2}{\pi} \lambda \alpha S_{\mathbf{I}} \quad (3.27)$$

If \mathbf{I} is measured with respect to three planes defined by the three mutually perpendicular unit vectors $\mathbf{i}, \mathbf{j}, \mathbf{k}$, $A(\mathbf{i}), A(\mathbf{j}), A(\mathbf{k})$ are the components of a vector \mathbf{I} such that

$$\mathbf{I} = \frac{2}{\pi} \lambda \alpha \mathbf{I} \quad (3.28)$$

$$\delta\varphi_0 \approx \frac{1}{A_3^{1/2} \frac{2}{\pi} \lambda \alpha F} \quad (3.29)$$

i.e. the error in φ_0 decreases with increasing number of events and increasing polarisation.

APPENDIX F

CHOOSING THE CUT-OFF FOR THE ANGLE ψ_0

The statistical error on the angle φ_0 is given by the equation (II.1.7):

$$\delta\varphi_0 \approx \frac{2}{\lambda \alpha F R^{1/2}}$$

We want to find the cut-off angle ψ_0 for which $\delta\varphi_0$ will be minimum. $\delta\varphi_0$ is a function of ψ_0 through λ and R . To minimize $\delta\varphi_0$ we equate its derivative with respect to ψ_0 to zero:

$$\frac{\partial \delta\varphi_0}{\partial \psi_0} = \frac{\partial \delta\varphi_0}{\partial \lambda} \cdot \frac{\partial \lambda}{\partial \psi_0} + \frac{\partial \delta\varphi_0}{\partial R} \cdot \frac{\partial R}{\partial \psi_0} = 0 \tag{F.1}$$

One has

$$\frac{\partial \delta\varphi_0}{\partial R} = -\frac{2}{\lambda \alpha F R^{3/2}} \tag{F.2}$$

and

$$\frac{\partial \phi}{\partial \lambda} = -\frac{2}{\alpha \sqrt{\lambda}} \quad (7.3)$$

ψ and λ are given by the equations (II.4.5) and (II.4.6) respectively

$$\psi(\varphi/\psi_0) d\varphi = \frac{1}{2\pi} \sin \psi_0 \left\{ 1 - \alpha \sqrt{\lambda} \sin(\varphi - \varphi_0) \right\} d\varphi$$

$$\lambda = \frac{1}{2} \left(\cos \psi_0 + \frac{\psi_0}{\sin \psi_0} \right)$$

Integrating the first equation over φ one gets the total Ω :

$$\begin{aligned} \Omega(\psi_0) &= \frac{1}{2\pi} \sin \psi_0 \left[\varphi + \frac{1}{\lambda \alpha} \cos(\varphi - \varphi_0) \right]_{0}^{2\pi} \\ &= \sin \psi_0 \end{aligned} \quad (7.4)$$

Differentiating Ω and λ with respect to ψ_0 one obtains the following :

$$\frac{d\Omega}{d\psi_0} = \cos \psi_0 \quad (7.5)$$

$$\frac{d\lambda}{d\psi_0} = \frac{1}{2} \left(-\sin \psi_0 + \frac{\sin \psi_0 - \psi_0 \cos \psi_0}{\sin^2 \psi_0} \right) \quad (7.6)$$

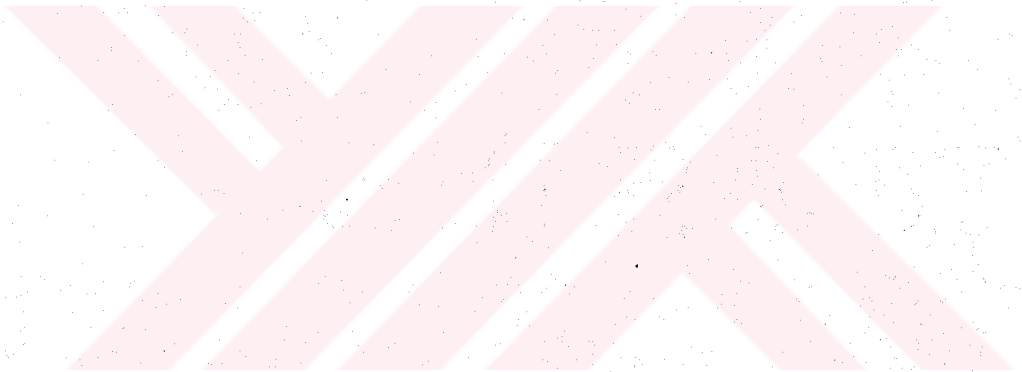
Substituting (7.5), (7.5) and (7.6) into (7.2) one gets

$$\frac{\cos \psi_0}{\sin \psi_0} = \frac{1}{\cos \psi_0 + \frac{\psi_0}{\sin \psi_0}} \left(\frac{1}{\sin \psi_0} - \sin \psi_0 - \psi_0 \frac{\cos \psi_0}{\sin^2 \psi_0} \right) \quad (7.7)$$

$$3 \cos \psi_0 \sin \psi_0 = \psi_0$$

The solution of this equation is

$$\sin \psi_0 = 0.333 .$$



APPENDIX G

OBTAINING AN ANALYTICAL CURVE FOR THE $g^x - \beta$ CALIBRATION

G.1. Fitting of the curve $g^x = a + b/\beta^c$ to the experimental points

One has to minimize the sum of the weighed squares of the deviations between the fitted and measured quantities:

$$\chi^2 = \sum_i \frac{(g_i^x - a - b/\beta_i^c)^2}{(\delta g_i^x)^2} \tag{G.1.1}$$

where g_i^x and β_i are the measured quantities and $(\delta g_i^x)^2$ is the error in the g_i^x measurement. Minimization should be done with respect to the 3 parameters: a, b, and c. But the derivative with respect to c is such that it becomes too complicated to solve for a, b, c simultaneously. Therefore what one does is the following:

First χ^2 of the logarithms of the above equation is minimized with respect to b and c , assuming a constant. Let's

$$y = y_i - a = b/\beta^c \quad (3.1.2)$$

Take the logarithm

$$\log y = \log b - c \log \beta \quad (3.1.3)$$

Let's

$$\chi^2_{\log} = \sum_1 \frac{(\log y_i - \log b + c \log \beta_i)^2}{(\delta \log y_i)^2} \quad (3.1.4)$$

The derivatives of χ^2_{\log} with respect to the parameters $\log b$ and c are equated to zero

$$\frac{\partial \chi^2}{\partial (\log b)} = \sum_1 \frac{2(\log y_i - \log b + c \log \beta_i)}{(\delta \log y_i)^2} = 0 \quad (3.1.5)$$

or

$$\sum_1 \frac{\log b}{(\delta \log y_i)^2} = c \sum_1 \frac{\log \beta_i}{(\delta \log y_i)^2} = \sum_1 \frac{\log y_i}{(\delta \log y_i)^2} \quad (3.1.6)$$

$$\frac{\partial \chi^2}{\partial c} = \sum_1 \frac{2 \log \beta_i (\log y_i - \log b + c \log \beta_i)}{(\delta \log y_i)^2} = 0 \quad (3.1.7)$$

or

$$\log b \sum_1 \frac{\log \beta_i}{(\delta \log y_i)^2} = c \sum_1 \frac{(\log \beta_i)^2}{(\delta \log y_i)^2} = \sum_1 \frac{(\log \beta_i)(\log y_i)}{(\delta \log y_i)^2} \quad (3.1.8)$$

One can write (3.1.6) and (3.1.8) as a matrix equation :

$$\begin{pmatrix} \sum_1 \frac{1}{(\delta \log r_1)^2} & - \sum_1 \frac{\log \beta_1}{(\delta \log r_1)^2} \\ \sum_1 \frac{\log \beta_1}{(\delta \log r_1)^2} & - \sum_1 \frac{(\log \beta_1)^2}{(\delta \log r_1)^2} \end{pmatrix} \begin{pmatrix} \log b \\ c \end{pmatrix} = \begin{pmatrix} \sum_1 \frac{\log r_1}{(\delta \log r_1)^2} \\ \sum_1 \frac{(\log \beta_1)(\log r_1)}{(\delta \log r_1)^2} \end{pmatrix} \quad (11.2.9)$$

Define

$$S_1 = \sum_1 \frac{\log \beta_1}{(\delta \log r_1)^2}$$

$$S_2 = \sum_1 \frac{(\log \beta_1)^2}{(\delta \log r_1)^2} \quad (11.2.10)$$

$$S_3 = \sum_1 \frac{1}{(\delta \log r_1)^2}$$

$$S_4 = \sum_1 \frac{(\log \beta_1)(\log r_1)}{(\delta \log r_1)^2}$$

$$S_5 = \sum_1 \frac{\log r_1}{(\delta \log r_1)^2}$$

(11.2.9) takes the form

$$\begin{pmatrix} S_3 & -S_1 \\ S_1 & -S_2 \end{pmatrix} \begin{pmatrix} \log b \\ c \end{pmatrix} = \begin{pmatrix} S_5 \\ S_4 \end{pmatrix} \quad (11.2.11)$$

Solution of this matrix equation is :

$$\log b = \frac{\begin{vmatrix} g_3 & -g_1 \\ g_4 & -g_2 \end{vmatrix}}{\begin{vmatrix} g_3 & -g_1 \\ g_2 & -g_2 \end{vmatrix}}$$

$$c = \frac{\begin{vmatrix} g_3 & -g_3 \\ g_2 & -g_4 \end{vmatrix}}{\begin{vmatrix} g_3 & -g_1 \\ g_2 & -g_2 \end{vmatrix}}$$

(4.1.12)

Now taking the value of c calculated from (4.1.12) as a constant, X^2 is minimized with respect to a and b :

$$\frac{\partial X^2}{\partial a} = \sum_i \frac{-2(g_i^2 - a - b/\beta_i^2)}{(\delta g_i^2)^2} = 0 \tag{4.1.13}$$

$$\frac{\partial X^2}{\partial b} = \sum_i \frac{-\frac{2}{\beta_i^2} (g_i^2 - a - b/\beta_i^2)}{(\delta g_i^2)^2} = 0 \tag{4.1.14}$$

or :

$$a \sum_i \frac{1}{(\delta g_i^2)^2} + b \sum_i \frac{1}{\beta_i^2 (\delta g_i^2)^2} = \sum_i \frac{g_i^2}{(\delta g_i^2)^2} \tag{4.1.15}$$

$$a \sum_i \frac{1}{\beta_i^2 (\delta g_i^2)^2} + b \sum_i \frac{1}{\beta_i^2 (\delta g_i^2)^2} = \sum_i \frac{g_i^2}{\beta_i^2 (\delta g_i^2)^2} \tag{4.1.16}$$

Since two equations are equivalent to :

$$\begin{pmatrix} \sum_{i=1}^n \frac{1}{(\delta_{i2})^2} & \sum_{i=1}^n \frac{1}{\beta_{i1}^2 (\delta_{i2})^2} \\ \sum_{i=1}^n \frac{1}{\beta_{i1}^2 (\delta_{i2})^2} & \sum_{i=1}^n \frac{1}{\beta_{i1}^2 (\delta_{i2})^2} \end{pmatrix} \begin{pmatrix} \bullet \\ \bullet \end{pmatrix} = \begin{pmatrix} \sum_{i=1}^n \frac{g_i}{(\delta_{i2})^2} \\ \sum_{i=1}^n \frac{g_i}{\beta_{i1}^2 (\delta_{i2})^2} \end{pmatrix}$$

(1.2.27)

Define

$$a_6 = \sum_{i=1}^n \frac{1}{\beta_{i1}^2 (\delta_{i2})^2}$$

$$a_7 = \sum_{i=1}^n \frac{1}{(\delta_{i2})^2}$$

$$a_8 = \sum_{i=1}^n \frac{1}{\beta_{i1}^2 (\delta_{i2})^2}$$

(1.2.28)

$$a_9 = \sum_{i=1}^n \frac{g_i}{(\delta_{i2})^2}$$

$$a_{10} = \sum_{i=1}^n \frac{g_i}{\beta_{i1}^2 (\delta_{i2})^2}$$

(1.2.27) takes the form

$$\begin{bmatrix} c_7 & c_8 \\ c_9 & c_6 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} c_9 \\ c_{10} \end{bmatrix} \quad (3.1.29)$$

The solution is :

$$a = \frac{\begin{vmatrix} c_7 & c_9 \\ c_{10} & c_6 \end{vmatrix}}{\begin{vmatrix} c_7 & c_8 \\ c_9 & c_6 \end{vmatrix}}$$

$$\begin{vmatrix} c_7 & c_8 \\ c_9 & c_6 \end{vmatrix}$$

(3.1.30)

$$b = \frac{\begin{vmatrix} c_7 & c_9 \\ c_8 & c_{10} \end{vmatrix}}{\begin{vmatrix} c_7 & c_8 \\ c_9 & c_6 \end{vmatrix}}$$

The value of a calculated here is substituted as the constant a in (3.1.2) and this procedure is repeated until a small enough χ^2 is obtained.

3.2. Fitting of the curve $\log c^x = a + b \log \beta + c(\log \beta)^2$ to the experimental points:

The sum of the weighted squares of deviations is :

$$\chi^2 = \sum_1 \frac{(\log c_i^x - a - b \log \beta_i - c(\log \beta_i)^2)^2}{(S \log \beta_i)^2} \quad (3.2.1)$$

One minimizes this with respect to the parameters a , b and c :

$$\frac{\partial \chi^2}{\partial a} = \sum_1 \frac{-(\log \sigma_1^2 - a - b \log \beta_1 - c(\log \beta_1)^2)}{(\delta \log \sigma_1^2)^2} = 0 \quad (1.2.2)$$

$$\frac{\partial \chi^2}{\partial b} = \sum_1 \frac{-\log \beta_1 (\log \sigma_1^2 - a - b \log \beta_1 - c(\log \beta_1)^2)}{(\delta \log \sigma_1^2)^2} = 0 \quad (1.2.3)$$

$$\frac{\partial \chi^2}{\partial c} = \sum_1 \frac{-(\log \beta_1)^2 (\log \sigma_1^2 - a - b \log \beta_1 - c(\log \beta_1)^2)}{(\delta \log \sigma_1^2)^2} = 0 \quad (1.2.4)$$

These three equations are equivalent to the matrix equation:

$$\begin{pmatrix} \sum_1 \frac{1}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{\log \beta_1}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{(\log \beta_1)^2}{(\delta \log \sigma_1^2)^2} \\ \sum_1 \frac{\log \beta_1}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{(\log \beta_1)^2}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{(\log \beta_1)^3}{(\delta \log \sigma_1^2)^2} \\ \sum_1 \frac{(\log \beta_1)^2}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{(\log \beta_1)^3}{(\delta \log \sigma_1^2)^2} & \sum_1 \frac{(\log \beta_1)^4}{(\delta \log \sigma_1^2)^2} \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \sum_1 \frac{\log \sigma_1^2}{(\delta \log \sigma_1^2)^2} \\ \sum_1 \frac{(\log \sigma_1^2)(\log \beta_1)}{(\delta \log \sigma_1^2)^2} \\ \sum_1 \frac{(\log \sigma_1^2)(\log \beta_1)^2}{(\delta \log \sigma_1^2)^2} \end{pmatrix} \quad (1.2.5)$$

Define

$$a_1 = \sum_1 \frac{1}{(\delta \log g_1^2)^2}$$

(1.2.1)

$$a_2 = \sum_1 \frac{\log \beta_1}{(\delta \log g_1^2)^2}$$

$$a_3 = \sum_1 \frac{(\log \beta_1)^2}{(\delta \log g_1^2)^2}$$

$$a_4 = \sum_1 \frac{(\log \beta_1)^3}{(\delta \log g_1^2)^2}$$

$$a_5 = \sum_1 \frac{(\log \beta_1)^4}{(\delta \log g_1^2)^2}$$

$$a_6 = \sum_1 \frac{\log g_1^2}{(\delta \log g_1^2)^2}$$

$$a_7 = \sum_1 \frac{(\log g_1^2)(\log \beta_1)}{(\delta \log g_1^2)^2}$$

$$a_8 = \sum_1 \frac{(\log g_1^2)(\log \beta_1)^2}{(\delta \log g_1^2)^2}$$

(1.2.5) takes the form :

$$\begin{pmatrix} a_1 & a_2 & a_3 \\ a_2 & a_3 & a_4 \\ a_3 & a_4 & a_5 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} a_6 \\ a_7 \\ a_8 \end{pmatrix}$$

(1.2.6)

The solution is :

$$a \cdot \begin{vmatrix} s_6 & s_2 & s_3 \\ s_7 & s_3 & s_4 \\ s_8 & s_4 & s_5 \end{vmatrix}$$

$$\begin{vmatrix} s_1 & s_2 & s_3 \\ s_2 & s_3 & s_4 \\ s_3 & s_4 & s_5 \end{vmatrix}$$

$$b \cdot \begin{vmatrix} s_1 & s_6 & s_3 \\ s_2 & s_7 & s_4 \\ s_3 & s_8 & s_5 \end{vmatrix}$$

(3.2.3)

$$\begin{vmatrix} s_1 & s_2 & s_3 \\ s_2 & s_3 & s_4 \\ s_3 & s_4 & s_5 \end{vmatrix}$$

$$c \cdot \begin{vmatrix} s_1 & s_2 & s_6 \\ s_2 & s_3 & s_7 \\ s_3 & s_4 & s_8 \end{vmatrix}$$

$$\begin{vmatrix} s_1 & s_2 & s_3 \\ s_2 & s_3 & s_4 \\ s_3 & s_4 & s_5 \end{vmatrix}$$

The errors $(\delta c_1^2)^2$ and $(\delta \log c_1^2)^2$ are calculated as

follows:

The normalised grain density, $G^{\#}$, is defined as

$$G^{\#} = \frac{N}{N^0} \quad (9.2.9)$$

where N and N^0 are the number of grains counted on equal length of particle and relativistic electron tracks. The error in $G^{\#}$ will be due to the errors on N and N^0 . These errors are quadratically combined to give the error in $G^{\#}$:

$$\frac{\delta G^{\#}}{G^{\#}} = \left(\left(\frac{\delta N^0}{N^0} \right)^2 + \left(\frac{\delta N}{N} \right)^2 \right)^{1/2}$$

or

$$\delta G^{\#} = G^{\#} \left(\left(\frac{\delta N^0}{N^0} \right)^2 + \left(\frac{\delta N}{N} \right)^2 \right)^{1/2} \quad (9.2.10)$$

Assuming a Poisson distribution for the grain counts δN^0 and δN will be proportional to the square root of the number of grains counted. $\delta \log G^{\#}$ is obtained as follows :

$$\frac{\delta \log G^{\#}}{\delta G^{\#}} = \frac{1}{G^{\#}}$$

or

$$\delta \log G^{\#} = \frac{\delta G^{\#}}{G^{\#}} \quad (9.2.11)$$

APPENDIX E

LEAST SQUARES FITTING TO THE Λ^0 DECAY KINEMATICS

For each event which we suspect of being a Λ^0 decay we measure the plane and dip angles and momenta of both tracks. From the plane and dip angles one can calculate the space opening angle. If θ is the space, δ is the dip and α is the plane opening angle, it can be easily shown that:

$$\cos \theta = \sin \delta_p \sin \delta_\pi + \cos \delta_p \cos \delta_\pi \cos \alpha \quad (E.1)$$

In a Λ^0 decay we therefore have only one unknown quantity of the Λ^0 . The number of constraint equations is two: Conservation of momentum and conservation of energy:

$$P_{\Lambda^0}^2 = P_p^2 + P_\pi^2 + 2 P_p P_\pi \cos \theta \quad (E.2)$$

$$\left(E_{\Lambda^0}^2 + m_{\Lambda^0}^2 \right)^{1/2} = \left(P_p^2 + m_p^2 \right)^{1/2} + \left(P_\pi^2 + m_\pi^2 \right)^{1/2} \quad (E.3)$$

One unknown and two constraints gives a 1-0 fit. We can

eliminate P_\wedge . From the two equations above and get the only constraint equation:

$$(P_p, P_\pi, \theta) = \Delta + P_p P_\pi \cos \theta - ((P_p^2 + a_p^2)(P_\pi^2 + a_\pi^2))^{1/2} = 0 \quad (2.4)$$

where

$$\Delta = \frac{a_p^2 - a_\pi^2 - a_\wedge^2}{2}$$

We want to minimize

$$S^2(P_p, P_\pi, \theta) = \frac{(P_p - P_p^0)^2}{(\delta P_p)^2} + \frac{(P_\pi - P_\pi^0)^2}{(\delta P_\pi)^2} + \frac{(\theta - \theta^0)^2}{(\delta \theta)^2} \quad (2.5)$$

subject to the constraint given by (2.4).

In (2.5) the superscript 0 refers to the nominal quantities.

One way to do the minimization as well as satisfying the constraint is to multiply (2.4) by a Lagrange multiplier α , to be determined in the process and add to (2.5); we then minimize

$$S^2(P_p, P_\pi, \theta, \alpha) = \frac{(P_p - P_p^0)^2}{(\delta P_p)^2} + \frac{(P_\pi - P_\pi^0)^2}{(\delta P_\pi)^2} + \frac{(\theta - \theta^0)^2}{\delta \theta^2} + 2\alpha(P_p P_\pi \cos \theta - ((P_p^2 + a_p^2)(P_\pi^2 + a_\pi^2))^{1/2}) \quad (2.6)$$

Compute the derivatives with respect to P_p, P_π, θ to zero:

$$\frac{\partial S^2}{\partial P_p} = 2 \left[\frac{P_p - P_p^0}{(\delta P_p)^2} + \alpha P_\pi \cos \theta - \frac{\alpha P_\pi (P_p^2 + a_p^2)^{1/2}}{(P_p^2 + a_p^2)^{1/2}} \right] = 0 \quad (2.7)$$

$$\frac{\partial \mathcal{L}}{\partial p_\pi} = 2 \left[\frac{p_\pi - p_\pi^0}{(\Delta p_\pi)^2} + \alpha p_\pi \cos \theta - \frac{p_\pi (\pi^2 + p_\pi^2)^{1/2}}{(\pi^2 + p_\pi^2)^{1/2}} \right] = 0 \quad (11.8)$$

$$\frac{\partial \mathcal{L}}{\partial \theta} = 2 \left[\frac{\theta - \theta^0}{(\Delta \theta)^2} - p_\pi \sin \theta \right] = 0 \quad (11.9)$$

From the three equations above we can solve for p_π , θ and θ . In order to reduce \mathcal{L} further we have to repeat the calculations. A superscript γ means that this value has been derived in the γ -th iteration.

$$p_\pi^{\gamma+1} = p_\pi^0 + (\Delta p_\pi)^2 \left(\frac{p_\pi^\gamma}{\pi} \sin \theta^\gamma (\pi^{\gamma+1})^{-1/2} p_\pi^\gamma \cos \theta^\gamma \right) \mathcal{L}^{\gamma+1} \quad (11.10)$$

$$\theta^{\gamma+1} = \theta^0 + (\Delta \theta)^2 \left(\frac{\theta^\gamma}{\pi} \sin \theta^\gamma (\pi^{\gamma+1})^{-1/2} p_\pi^\gamma \cos \theta^\gamma \right) \mathcal{L}^{\gamma+1} \quad (11.11)$$

$$\theta^{\gamma+1} = \theta^0 + (\Delta \theta)^2 \left(\frac{\theta^\gamma}{\pi} \sin \theta^\gamma \right) \mathcal{L}^{\gamma+1} \quad (11.12)$$

where $\mathcal{L} = (\pi^2 + p^2)^{1/2}$ is the energy of each particle.

In order to eliminate $\mathcal{L}^{\gamma+1}$ we expand the constraint equation:

$$f(p_\pi^{\gamma+1}, p_\pi^{\gamma+1}, \theta^{\gamma+1}) = f(p_\pi^\gamma, p_\pi^\gamma, \theta^\gamma) + \frac{\partial f(p_\pi^\gamma, p_\pi^\gamma, \theta^\gamma)}{\partial p_\pi^\gamma} (p_\pi^{\gamma+1} - p_\pi^\gamma) + \frac{\partial f(p_\pi^\gamma, p_\pi^\gamma, \theta^\gamma)}{\partial p_\pi^\gamma} (p_\pi^{\gamma+1} - p_\pi^\gamma) + \frac{\partial f(p_\pi^\gamma, p_\pi^\gamma, \theta^\gamma)}{\partial \theta^\gamma} (\theta^{\gamma+1} - \theta^\gamma) \quad (11.13)$$

or

$$\begin{aligned}
 & \Delta P \frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \\
 & - \frac{V}{p} \sin \theta (\theta^{y+1} - \theta) = 0 \tag{11.14}
 \end{aligned}$$

Substituting for $\frac{V}{p} \frac{\partial \theta}{\partial x}$, $\frac{V}{p} \frac{\partial \theta}{\partial x}$, θ^{y+1} from the equations (11.10), (11.11), (11.12) respectively we get :

$$\begin{aligned}
 & \Delta P \frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) + (\delta P)^2 \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \cos \theta \right) \alpha^{y+1} \\
 & + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \cos \theta \right) \alpha^{y+1} \\
 & - \frac{V}{p} \sin \theta (\theta^{y+1} - \theta) + (\delta P)^2 \frac{V}{p} \sin \theta \alpha^{y+1} = 0 \tag{11.15}
 \end{aligned}$$

From (11.15) we can solve for α^{y+1} :

$$\begin{aligned}
 \alpha^{y+1} &= \left[\Delta P \frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \right. \\
 & \left. + \left(\frac{V}{p} \cos \theta - \frac{V}{p} \frac{\partial \theta}{\partial x} \right) \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \cos \theta \right) - \frac{V}{p} \sin \theta (\theta^{y+1} - \theta) \right] / \\
 & \left[\left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \cos \theta \right)^2 (\delta P)^2 + \left(\frac{V}{p} \frac{\partial \theta}{\partial x} - \frac{V}{p} \cos \theta \right)^2 (\delta P)^2 \right. \\
 & \left. - \frac{V}{p} \sin \theta (\theta^{y+1} - \theta) (\delta P)^2 \right] \tag{11.16}
 \end{aligned}$$

By substituting α^{y+1} back into the equations (11.10), (11.11) and (11.12), $\frac{V}{p} \frac{\partial \theta}{\partial x}$, $\frac{V}{p} \frac{\partial \theta}{\partial x}$ and θ^{y+1} can be calculated.

APPENDIX I

COORDINATES OF THE PRODUCTION POINT OF Λ^0 IN THE TARGET

The coordinates of the decay vertex of Λ^0 were measured in a coordinate system² whose x^* - y^* plane is the emission plane and z^* is the direction perpendicular to it. Let the measurements in such a system whose origin is at the center of the stack be x^*, y^* and z^* (y^* is measured in degrees). In another coordinate system whose origin is at the center of the target and x^* axis along the symmetry axis of the experiment the coordinates of the decay vertex can be written as follows:

$$x^* = (110 + x^*) \cos 20^\circ - z^* \sin 20^\circ \quad (1.1)$$

$$y^* = (110 + x^*) y^* \pi / 180 \quad (1.2)$$

$$z^* = (110 + x^*) \sin 20^\circ + z^* \cos 20^\circ \quad (1.3)$$

y^* is measured along a circular arc whose center is at the target center. The last expression is correct for only the set of

² See Figure 2.

stacks, placed at one side of the initial π beam (positive z' side). For the other set z' is equal to the negative of this expression. In the calculations z' was taken always positive. This means rotating the second stack around z' by 180° . Then the magnetic field in this stack becomes opposite in the direction, which makes the polarization rotate in the opposite direction. Therefore in order to combine the angular distributions of odd and even numbered stacks one has to subtract the angles in one set of stacks from 2π .

The magnitude of the Λ° -momentum at the decay vertex is calculated from the conservation of momentum:

$$P_{\Lambda^\circ} = (P_\pi^2 + P_p^2 - 2 P_p P_\pi \cos \theta)^{1/2} \quad (1.4)$$

where θ is the space opening angle.

From the conservation of momentum in the z' direction one gets:

$$P_{\Lambda^\circ} \sin \delta_{\Lambda^\circ} = P_p \sin \delta_p + P_\pi \sin \delta_\pi \quad (1.5)$$

where δ^* 's are the dip angles and from which one can calculate δ_{Λ° , the dip angle of Λ° .

The projection of Λ° -momentum into the x^*y^* plane is given by:

$$P_{\Lambda^\circ}^* = (P_\pi^2 \cos^2 \delta_\pi + P_p^2 \cos^2 \delta_p - 2 P_p P_\pi \cos \delta_p \cos \delta_\pi)^{1/2} \quad (1.6)$$

where α is the plane opening angle. The total momentum in the x^* direction is:

$$r_x^* = r_p \cos \delta \cos \theta_p + \frac{r_p \cos \delta}{\pi} \cos \theta_\pi \quad (1.7)$$

where θ_p 's are the plane angles. The plane angle of $\hat{\lambda}^\circ$ with respect to the grid line closest to the vertex is

$$\theta^* = \cos^{-1}(r_x^* / r_\lambda^\circ) \quad (1.8)$$

Since the angle between adjacent grid lines is 20° , the plane angle with respect to the central grid line is

$$\theta_{\lambda^\circ} = \frac{\pi}{180} + \theta^* \quad (1.9)$$

We can write a unit vector in the $\hat{\lambda}^\circ$ direction in the double prime system as follows:

$$\begin{aligned} \hat{u}_{\lambda^\circ} = & (\cos \delta_{\lambda^\circ} \cos \theta_{\lambda^\circ} \cos 20^\circ - \sin \delta_{\lambda^\circ} \sin 20^\circ) \hat{i}'' + (\cos \delta_{\lambda^\circ} \sin \theta_{\lambda^\circ}) \hat{j}'' \\ & + (\sin \delta_{\lambda^\circ} \cos 20^\circ + \cos \delta_{\lambda^\circ} \cos \theta_{\lambda^\circ} \sin 20^\circ) \hat{k}'' \quad (1.10) \end{aligned}$$

Let

$$\begin{aligned} u_{\lambda^\circ x} &= \cos \delta_{\lambda^\circ} \cos \theta_{\lambda^\circ} \cos 20^\circ - \sin \delta_{\lambda^\circ} \sin 20^\circ \\ u_{\lambda^\circ y} &= \cos \delta_{\lambda^\circ} \sin \theta_{\lambda^\circ} \\ u_{\lambda^\circ z} &= \cos \delta_{\lambda^\circ} \cos \theta_{\lambda^\circ} \sin 20^\circ + \sin \delta_{\lambda^\circ} \cos 20^\circ \end{aligned} \quad (1.11)$$

Equation of the $\hat{\lambda}^\circ$ direction is given by :

$$\begin{aligned} x &= x'' + \frac{u_{\lambda^\circ x}}{u_{\lambda^\circ x}} (x' - x'') \\ y &= y'' + \frac{u_{\lambda^\circ y}}{u_{\lambda^\circ x}} (x' - x'') \end{aligned} \quad (1.12)$$

The production point (x_0, y_0, z_0) is estimated as being the point of closest approach of the \wedge° path to the control ray of the incident π° beam. The distance of a point on the \wedge° path, (x, y, z) to the control π° ray (x -axis) is given by :

$$d = (y^2 + z^2)^{1/2} = (y^2 + z^2 + \frac{u_{\wedge^\circ y}^2 + u_{\wedge^\circ z}^2}{u_{\wedge^\circ x}^2} (x - x^\circ)^2 + \frac{2}{u_{\wedge^\circ x}^2} (u_{\wedge^\circ z} z^\circ + u_{\wedge^\circ y} y^\circ)(x - x^\circ))^{1/2} \quad (2.13)$$

We want this distance to be a minimum :

$$\frac{d}{dx} d^2 = 2(x - x^\circ) \frac{u_{\wedge^\circ y}^2 + u_{\wedge^\circ z}^2}{u_{\wedge^\circ x}^2} + \frac{2}{u_{\wedge^\circ x}^2} (u_{\wedge^\circ z} z^\circ + u_{\wedge^\circ y} y^\circ) = 0 \quad (2.14)$$

The solution of this equation is:

$$x_0 = x^\circ - \frac{u_{\wedge^\circ x}^2}{u_{\wedge^\circ y}^2 + u_{\wedge^\circ z}^2} (u_{\wedge^\circ z} z^\circ + u_{\wedge^\circ y} y^\circ) \quad (2.15)$$

From (2.12) we get y_0 and z_0 :

$$y_0 = y^\circ - \frac{u_{\wedge^\circ y}^2}{u_{\wedge^\circ y}^2 + u_{\wedge^\circ z}^2} (u_{\wedge^\circ z} z^\circ + u_{\wedge^\circ y} y^\circ) \quad (2.16)$$

$$z_0 = z^\circ - \frac{u_{\wedge^\circ z}^2}{u_{\wedge^\circ y}^2 + u_{\wedge^\circ z}^2} (u_{\wedge^\circ z} z^\circ + u_{\wedge^\circ y} y^\circ)$$

Since we now know the coordinates of the production and decay vertices we can calculate the length l of the path travelled in the field :

$$z = (z_1 \cos \theta)^2 + (z_2 \sin \theta)^2 + (z_3 \cos \theta)^2 \quad (2.2.1)$$

$$z = (z_1 \cos \theta)^2 + (z_2 \sin \theta)^2 + (z_3 \cos \theta)^2 \quad (2.2.2)$$



APPENDIX J

EFFECTS CAUSED BY THE CURVATURE OF THE INCIDENT BEAM
AS IT STRIKES THE TARGET*

Let d be the vertical displacement of the beam with respect to the axis of the beam channel and x the variable distance along the axis ($x = 0$ at the front end of the target) d is given by :

$$d = \frac{1}{2} a t^2 \quad (J.1)$$

where a is the acceleration of the particle due to the magnetic field and t is the time spent in the field. Since incoming pions have a momentum of 1.05 GeV/c they are relativistic and the force on them is given in the laboratory frame by:

$$F = \frac{d\mathbf{p}}{dt} \quad (J.2)$$

and their acceleration is :

* See Figure 29.

$$a = \frac{1}{\gamma} = \frac{v}{c} \quad (3.3)$$

The distance travelled by the particles in the magnetic field is $\frac{x}{\gamma}$ therefore the time spent is :

$$t = \frac{x}{\gamma v} \quad (3.4)$$

Substituting (3.3) and (3.4) into (3.1) we get:

$$d = \frac{1}{2} = \frac{eB}{2\gamma m_0 c^2} \left(\frac{x}{\gamma}\right)^2 \approx \frac{eB}{2\gamma m_0 c^2} x^2 \quad (3.5)$$

γ is given by :

$$\gamma = \frac{(\sqrt{2.7} + p^2)^{\frac{1}{2}}}{m_0 c^2} \approx \frac{1050}{140} = 7.5 \quad (3.6)$$

Therefore d is :

$$d = \frac{4.8 \times 10^{-10} \times 200 \times 10^3}{2 \times 7.5 \times 140 \times 1.6 \times 10^{-6}} x^2 = 0.0205 x^2 \text{ cm} \quad (3.7)$$

The beam was aligned such that d was zero at the center of the target. Therefore we have :

$$d = 0.0205 (x^2 - 1.6^2) \text{ cm} \quad (3.8)$$

i.e. d changes between -0.075 cm and $+0.32$ cm.

Since an incident π^+ now has the direction AB^* instead of AB the production angle of the Λ^0 produced by the π^+ is changed by $\Delta\theta = \theta_1 - \theta_0$. θ_0 is taken to be 20° . θ_1 is given by :

$$\theta_1 = \tan^{-1} \frac{x}{\delta} \quad (5.7)$$

The maximum value θ_1 takes is therefore $22^{\circ}40'$.

The production plane ACB' (defined by \vec{E}_λ^0 and $\vec{E}_{\pi/2}^0$) is inclined with respect to the horizontal median plane of the coil ACB by the angle ψ . From Fig. 29 we see that

$$\sin \psi = \frac{BC}{\cos \psi} = AC \tan \theta_1 = BC \frac{\tan \theta_1}{\tan \theta_0} \quad (5.8)$$

Therefore

$$\cos \psi = \tan \theta_0 / \tan \theta_1 \quad (5.9)$$

$\cos \psi$ changes between 0.87 and 1.

The direction of the λ^0 polarization vector is inclined by the same angle ψ with respect to the plane of the emission polaroids. The effect of this on the φ distribution is to reduce the observed value of $\alpha \mathcal{P}$ by the factor $\cos \psi$. This introduces an error of $\sim 3\%$ into the estimate of M_λ^0 .

Another effect the beam tilt has is on the winding cone distribution. This effect depends on the angle δ which measures the angle of deviation of the beam in the vertical plane. It is equal to :

$$\delta = \sin^{-1} (\sin \theta_1 \cdot \sin \psi) \quad (5.10)$$

The maximum value it takes is 10° .

In calculating the missing mass we had assumed $\delta = 0$ neglecting the perpendicular component of \vec{P}_{miss} . The error this introduces into the missing mass is:

$$\delta\Delta = (P_{\text{miss}} \sin \delta)^2 \cong (1050 \times \sin 10^\circ)^2 = 0.02 (\text{GeV}/c^2)^2$$

This is in agreement with our missing mass distribution.²



² See Figure 11.

APPENDIX K

CALCULATION OF THE ANGLE φ

φ is the angle between \vec{s}_0 , the initial polarization vector of Λ^0 and the projection of the proton momentum vector onto the (\vec{e}_x, \vec{e}_y) plane, in the c.o.m. system of Λ^0 . The analysis is done in the coordinate system given by the 2q. (K.5.0) :

$$\vec{I} = \frac{\vec{s}_0}{|\vec{s}_0|}, \quad \vec{J} = \frac{\vec{p}_p}{|\vec{p}_p|}, \quad \vec{K} = \vec{I} \times \vec{J} \quad (\text{K.5.0})$$

In terms of the double primed coordinate system defined in Appendix F, \vec{I} , \vec{J} , \vec{K} is given as:

$$\vec{I} = u_{\Lambda_z} \vec{I}'' + u_{\Lambda_y} \vec{J}'' + u_{\Lambda_x} \vec{K}'' \quad (\text{K.1})$$

$$\vec{J} = -\frac{\vec{I}'' \times \vec{s}_0}{|\vec{I}'' \times \vec{s}_0|} = (u_{\Lambda_y}^2 + u_{\Lambda_z}^2)^{-1/2} (u_{\Lambda_z} \vec{J}'' - u_{\Lambda_y} \vec{K}'') \quad (\text{K.2})$$

$$\vec{K} = \vec{I} \times \vec{J} = (u_{\Lambda_y}^2 + u_{\Lambda_z}^2)^{-1/2} \left[-(u_{\Lambda_y}^2 + u_{\Lambda_z}^2) \vec{I}'' + u_{\Lambda_z} u_{\Lambda_y} \vec{J}'' + u_{\Lambda_x} u_{\Lambda_y} \vec{K}'' \right] \quad (\text{K.3})$$

\vec{P}_p , the proton laboratory momentum vector, in the double primed system is given in terms of the measured quantities as follows :

$$\vec{P}_p = P_{p_x}'' \vec{i}'' + P_{p_y}'' \vec{j}'' + P_{p_z}'' \vec{k}'' \quad (2.4)$$

where $P_{p_x}'' = (\cos \delta_p \cos \theta_p \cos 20^\circ - \sin \delta_p \sin 20^\circ) P_p$

$$P_{p_y}'' = (\cos \delta_p \sin \theta_p) P_p \quad (2.5)$$

$$P_{p_z}'' = (\cos \delta_p \cos \theta_p \sin 20^\circ + \sin \delta_p \cos 20^\circ) P_p$$

δ_p is the dip angle, θ_p the plane angle of the proton with respect to the primed coordinate system whose origin is at the center of the collision stack and P_p is the fitted proton momentum.

In the unprimed system x, y components of \vec{P}_p is given

by:

$$P_{p_x} = P_p \cdot \vec{i} = u_{\wedge x} P_{p_x}'' + u_{\wedge y} P_{p_y}'' + u_{\wedge z} P_{p_z}'' \quad (2.6)$$

$$P_{p_y} = P_p \cdot \vec{j} = (u_{\wedge x} P_{p_y}'' - u_{\wedge y} P_{p_x}'') (u_{\wedge y}^2 + u_{\wedge z}^2)^{-1/2} \quad (2.7)$$

These components transform into the c.m.s. system of \wedge as follows:

$$P_{p_x}' = \gamma (P_{p_x} - \beta E_p) \quad (2.8)$$

and

$$P_{p_y}' = P_{p_y} \quad (2.9)$$

where

$$\beta = v^{\wedge} / (c^{\wedge} + v^{\wedge})^{1/2}, \quad \gamma = 1 / (1 - \beta^2)^{1/2}$$

and

$$E_p = (c_p^2 + v_p^2)^{1/2}.$$

The angle φ is given by :

$$\varphi = \tan^{-1} \frac{v_p^2}{c_p^2}$$

(1.20)



TABLE 1
SOME THEORETICAL VALUES OF THE HADRONIC NUMBER OF
THE Λ^0 HYPERON

Model	Reference	μ_{Λ^0}
Free SU_3	(33, 34)	-0.75
Free SU_3 (free μ_{Λ^0})	(35)	-0.53
Free-connected SU_6	(33)	-0.73
Broken SU_3 (depends on $z=1/2$)	(36)	-0.66
Broken SU_3 (photo production amplitudes)	(37)	-0.75
Broken SU_3 (current algebra)	(38)	-0.33
Broken SU_6 ($\omega = \varphi$ mixing)	(39)	-0.76
Broken SU_3	(40)	-0.40
Broken SU_3 (asymptotic symmetry) ²	(41)	-0.52, 0.03
Broken SU_3 (current algebra)	(42)	-0.74
Quark model ²	(43)	-0.52, 0.03
Quark model	(44)	-0.33
Partial symmetry	(45)	-0.53
Isotropy	(46)	0.00
The triplets of fundamental particles	(47)	-1.57

² The "errors" show the effect of varying the parameters within a reasonable range.

TABLE 2

THE LABORATORY VELOCITY, MOMENTA, ENERGY AND ANGLE OF THE Λ^0
 PRODUCED IN THE REACTION $\pi^- + p \longrightarrow \Lambda^0 + \pi^0$ AS A FUNCTION
 OF THE C.M.S. ANGLE (FOR $p = 1.05$ GeV/c)

CM ANGLE	β	p (MeV/c)	E (MeV)	θ^0
0	0.667	998.3	1497.1	0.0
10	0.666	994.8	1494.7	3.9
20	0.662	984.4	1487.8	5.0
30	0.655	967.2	1476.9	7.4
40	0.646	943.6	1461.1	9.7
50	0.634	914.0	1442.2	12.0
60	0.619	879.0	1420.3	14.2
70	0.601	839.3	1395.0	16.2
80	0.581	795.6	1370.2	17.9
90	0.557	748.7	1343.5	19.4
100	0.531	699.7	1316.9	20.9
110	0.503	649.7	1291.0	21.1
120	0.474	600.1	1266.8	21.0
130	0.444	552.3	1244.8	20.2
140	0.415	508.2	1225.9	18.9
150	0.388	470.0	1210.5	17.3
160	0.367	440.1	1199.3	14.1
170	0.353	420.8	1192.3	9.9
180	0.348	414.2	1190.0	0.0

TABLE 3

THE LABORATORY MOMENTA AND ANGLES OF THE PROTON AND PION FROM THE
DECAY $\Lambda^0 \longrightarrow p + \pi^-$ AS A FUNCTION OF THE CMS ANGLE

(1) For $\beta_{\Lambda^0} = \beta_{\text{MAX}} = 0.667$

CMS ANGLE	θ_p	P_p (Mev/c)	θ_{π^-}	P_{π^-} (Mev/c)
0	0.0	800.9	0.0	287.1
10	1.3	799.2	4.1	288.8
20	2.6	794.2	8.2	292.1
30	3.7	785.9	12.3	297.0
40	4.8	774.6	16.5	303.0
50	5.8	760.6	20.8	310.0
60	6.7	744.2	25.2	317.7
70	7.8	725.7	29.7	326.7
80	8.1	705.7	34.3	337.3
90	8.4	684.6	39.1	349.2
100	8.6	663.2	44.1	362.1
110	8.5	641.9	49.3	375.5
120	8.1	621.5	54.7	389.6
130	7.3	602.7	60.3	404.6
140	6.3	586.1	66.2	420.7
150	5.0	572.3	72.0	438.0
160	3.5	562.1	78.2	456.1
170	1.8	555.7	84.7	475.6
180	0.0	553.5	173.4	0.0

(11) $\beta_{10} = \beta_{011} = 0.543$

CRS ANGLE	θ_p	P_p (Nev/c)	θ_{π}	P_{π} (Nev/c)
0	0.0	536.7	0.0	107.0
10	1.0	535.5	5.4	107.1
20	2.0	531.2	10.7	107.5
30	3.0	524.5	16.2	108.0
45	4.2	515.0	21.7	108.5
50	5.0	505.2	27.4	109.0
60	10.2	490.4	33.2	109.0
70	11.5	475.7	39.3	109.1
80	12.5	461.5	45.6	109.3
90	13.5	448.2	52.3	109.6
100	15.7	439.2	59.4	109.8
110	15.7	430.1	67.0	109.6
120	12.4	421.5	75.4	109.0
130	11.1	413.9	84.9	108.0
140	10.7	408.1	95.0	107.0
150	8.6	394.8	105.6	106.0
160	6.1	384.0	116.9	105.0
170	3.1	375.5	128.4	104.4
180	0.0	376.5	140.0	104.0

TABLE 4

THE RESULTS OF SOME OF THE REORGANIZATIONS

Event No	θ_p			δ_p			σ_p		
	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$
1	10°.6	10°.6	0°.0	0°.915	0°.688	0°.227	2.50	2.57	-0.07
2	1°.9	1°.8	0°.1	1°.600	1°.600	0°.000	2.52	2.53	-0.01
3	6°.1	6°.3	-0°.2	0°.693	0°.915	-0°.227	1.40	1.50	-0.10
4	9°.5	9°.6	0°.1	0°.239	0°.457	-0°.227	2.31	2.31	0.00
5	356°.6	356°.4	0°.2	2°.750	2°.750	0°.000	2.14	2.04	0.10
6	351°.9	351°.9	0°.0	0°.457	0°.693	-0°.236	2.13	2.31	-0.18
7	16°.4	16°.0	0°.4	3°.200	3°.650	-0°.450	2.74	2.39	0.35
8	8°.9	9°.8	-0°.9	0°.915	0°.915	0°.000	2.52	2.53	-0.01

Event No	θ_π			δ_π			σ_π		
	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$	Mean. 1	Mean. 2	$\Delta \sigma_{1-2}$
1	323°.3	323°.3	0°.0	0°.457	0°.457	0°.0	1.40	1.40	0.00
2	155°.3	155°.2	0°.1	26°.20	25°.0	1°.20	Black	Black	-
3	29°.0	29°.0	0°.0	12°.00	10°.50	1°.50	Black	Black	-
4	343°.4	343°.4	0°.0	1°.84	1°.60	0°.24	1.00	1.29	-0.29
5	26°.0	26°.1	-0°.1	7°.18	7°.45	-0°.27	1.32	1.34	-0.02
6	22°.0	22°.0	0°.0	0°.457	0.227	0°.230	1.06	0.69	0.37
7	316°.0	316°.0	0°.0	8°.25	8°.13	0°.12	1.12	1.07	0.05
8	332°.3	332°.9	-0°.6	8°.13	7°.18	0°.95	0.62	1.13	-0.51

TABLE 5
THE σ^2 - β CALIBRATION
DATA

σ^2 Name/o	β	δ		$\delta \sigma^2$
		Name: 5	Name: 6	
400	.354	3.14	3.37	3.25
500	.486	2.49	2.73	2.60
600	.360	1.93	1.93	2.04
700	.515	1.74	1.61	2.18
800	.666	1.49	1.50	2.23
900	.700	1.36	1.42	2.21
	.350	1.33	(Normal)	2.21

TABLE 6

PARAMETERS OF THE FITTED $g^2-\beta$ CURVES OF THE HIGHER ORDER

$$\log g^2 = a + b \log \beta + c (\log \beta)^2$$

Order	a	b	c	r^2	r^2_{adj}
5	-0.202	-1.866	-0.553	2.270	4
6	-0.209	-1.467	0.066	9.286	4
5.6	-0.209	-1.643	-0.178	20.742	11

$$g^2 = a + b/\beta^c$$

Order	a	b	c	r^2	r^2_{adj}
5	-0.201	0.949	1.564	7.57	4
6	0.071	0.737	1.665	9.258	4
5.6	-0.051	0.825	1.497	22.756	11

$r^2_{adj} = \text{No. of experimental points} - \text{No. of parameters}$
 adjusted r^2 .

TABLE 7

REPEAT MEASUREMENTS IN THE GRAIN CONINGS OF A MEASUREMENT

Flute No	\bar{C}_p	
	1st Measurement	2nd Measurement
140/3	24.60 ± .5	24.99 ± .5
140/4	26.24 ± .5	27.51 ± .5
140/5	25.84 ± .5	26.30 ± .5
140/6	26.33 ± .5	26.98 ± .5
140/3	27.07 ± .5	26.74 ± .5
140/4	27.39 ± .5	26.52 ± .5
140/5	27.71 ± .5	27.76 ± .5

TABLE 8
THE NUMBER OF EVENTS LEFT (IN ANSADA) AFTER SOME
CUT OFF

Installation	No. of events left
$0.05 < z < 0.55$	430
$z^2 < 25$	375
$ n_1 < 20, n_2 < 8, n_3 < 2$	235
$450 < E_{\lambda} < 800$	211
$\sin \psi_0 < 0.91$	200

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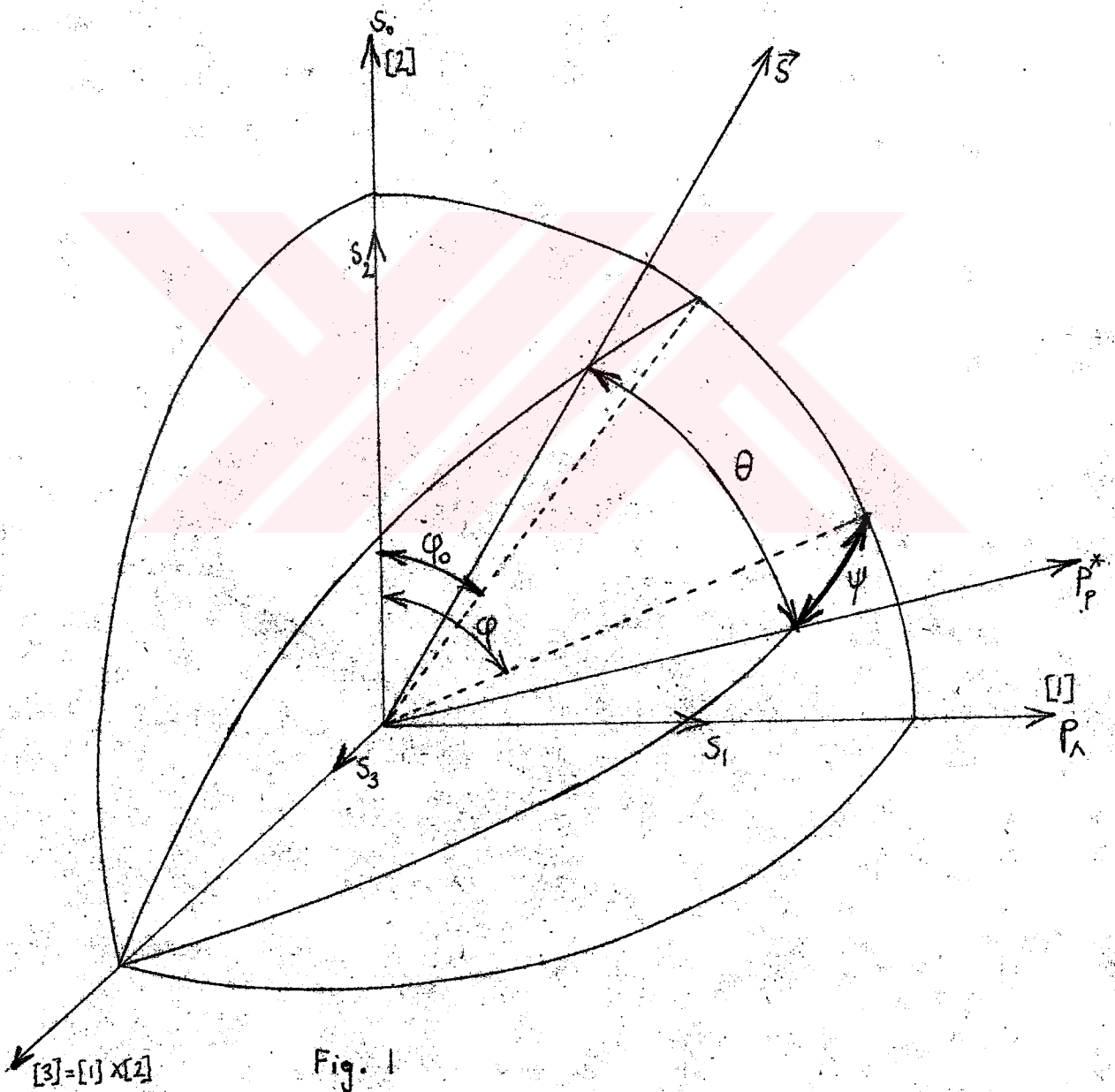


Fig. 1

1:1

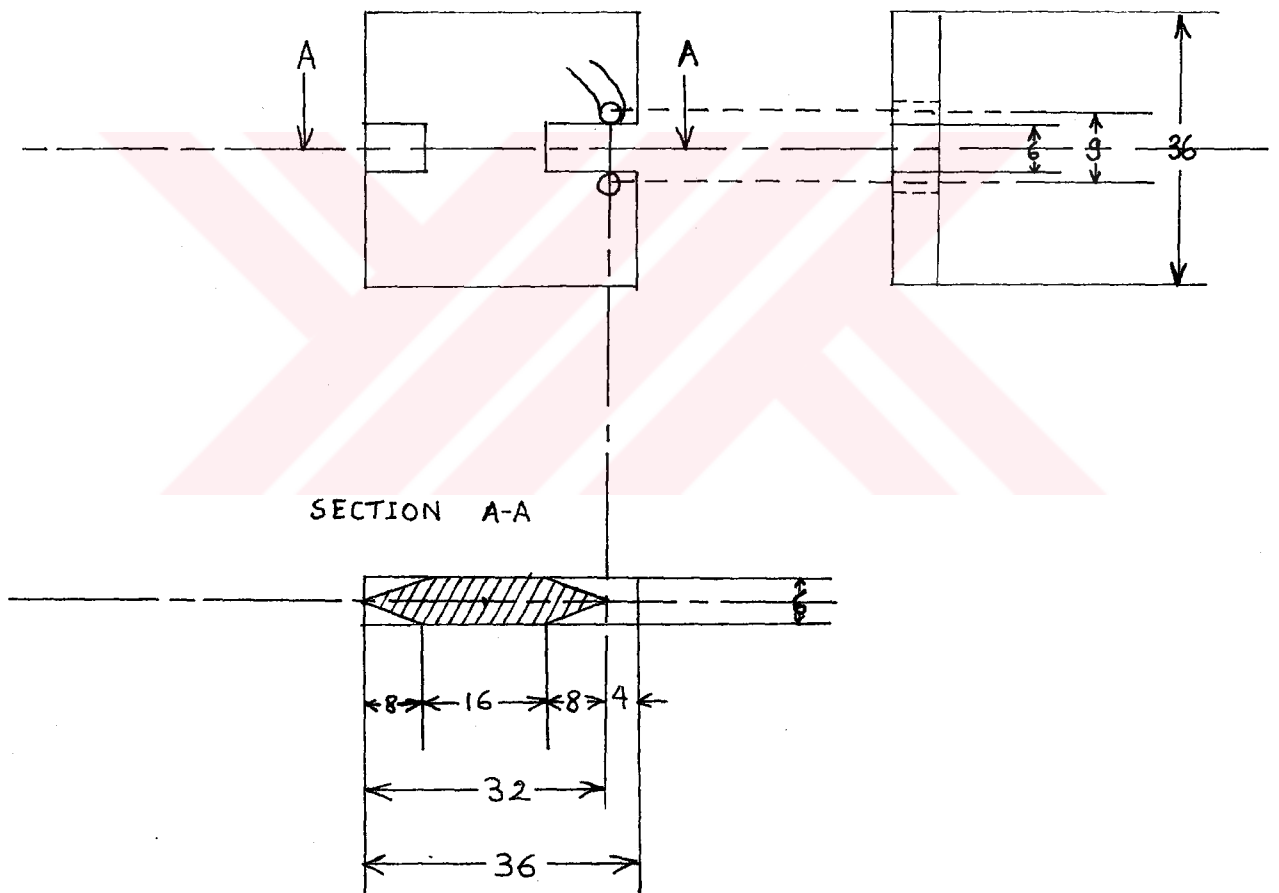
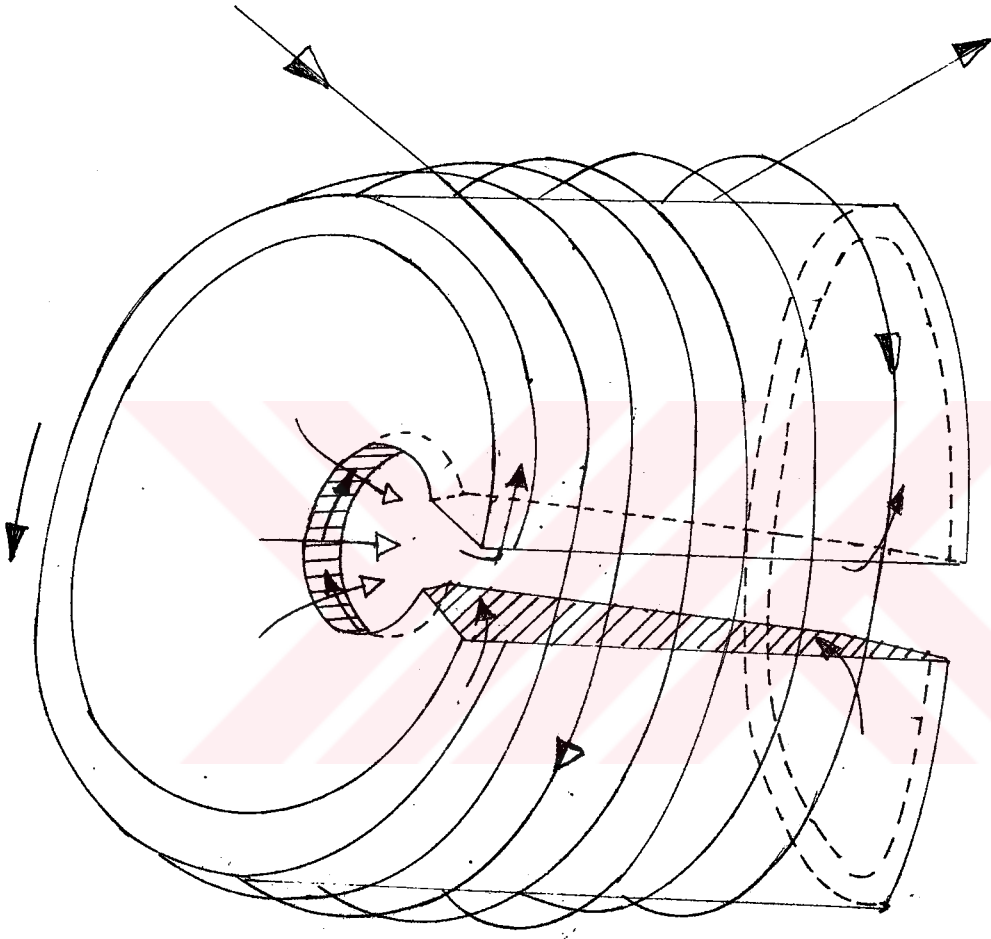


Fig. 3



- Primary Current
- Secondary Current
- Magnetic field

Fig. 4

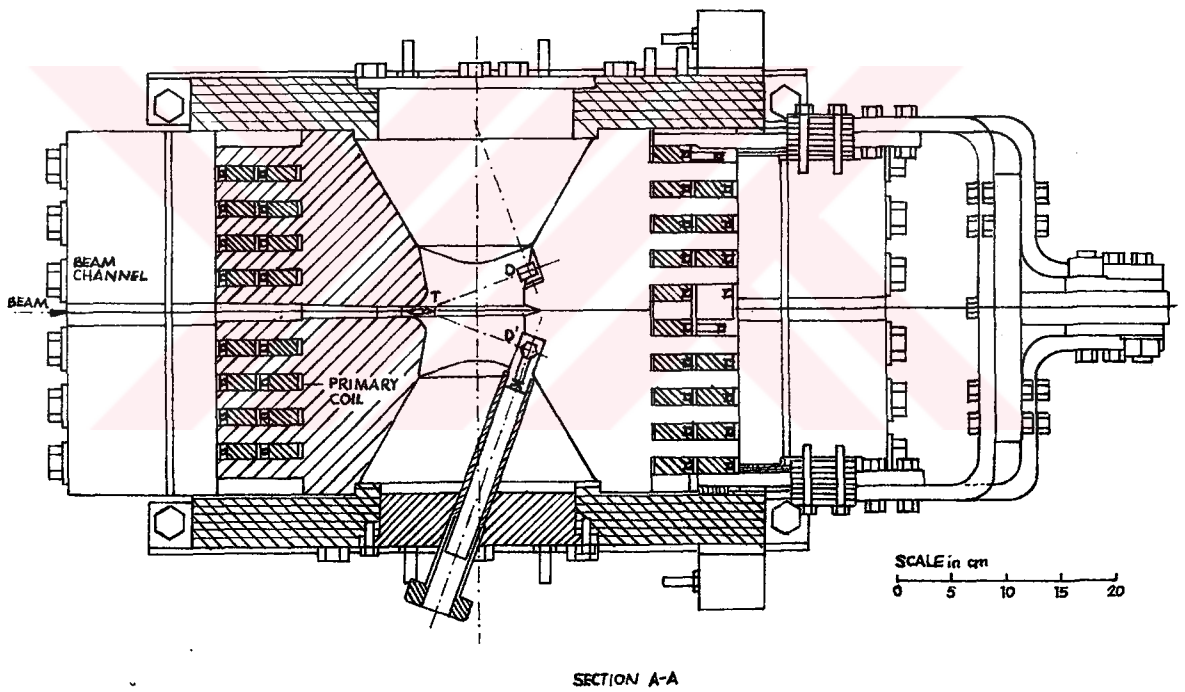


Fig. 5

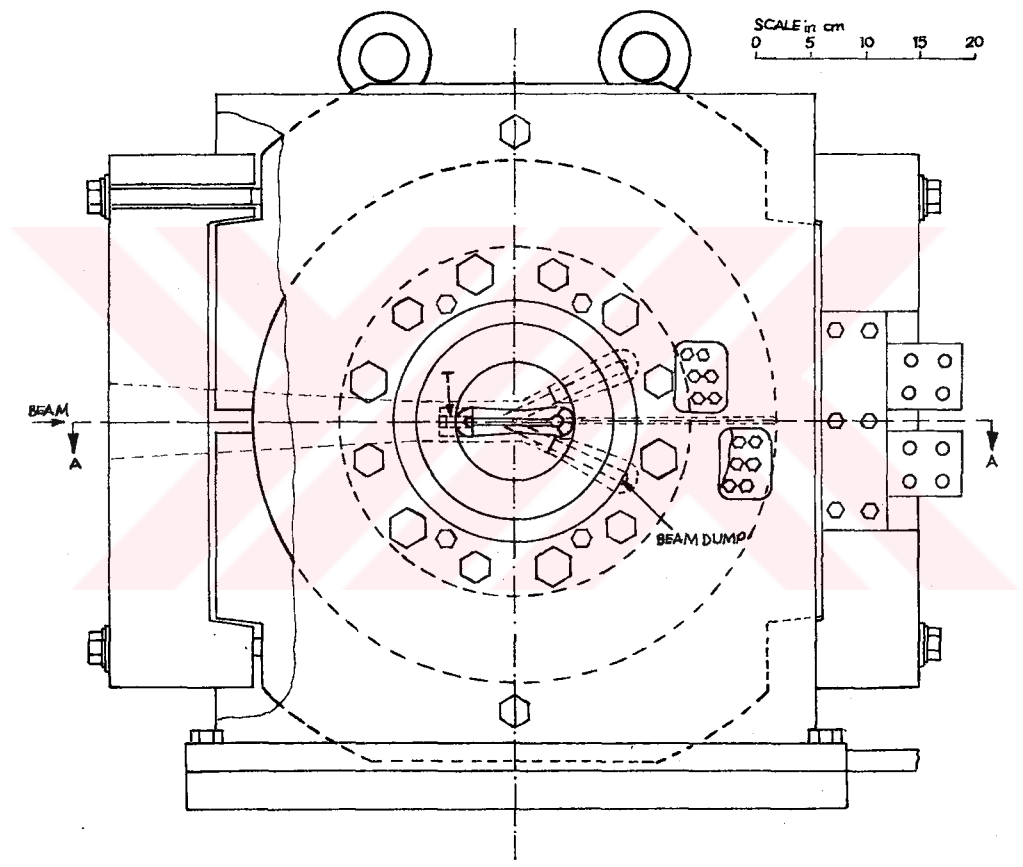


Fig. 6

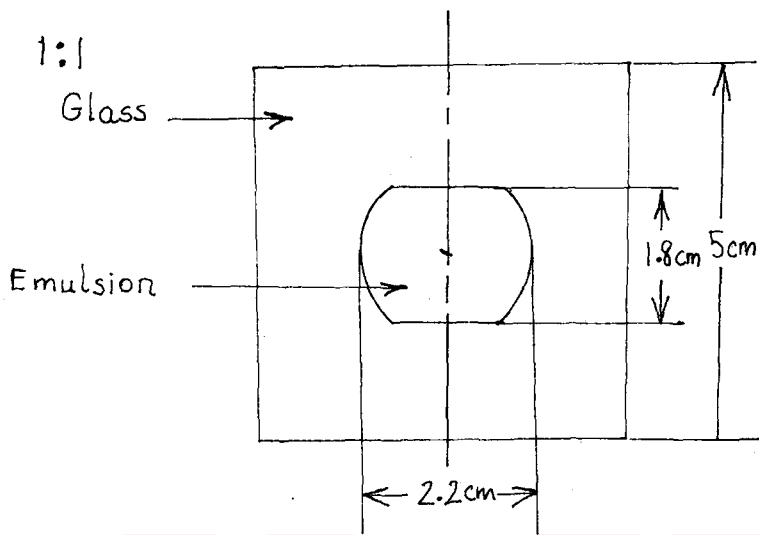


Fig. 7

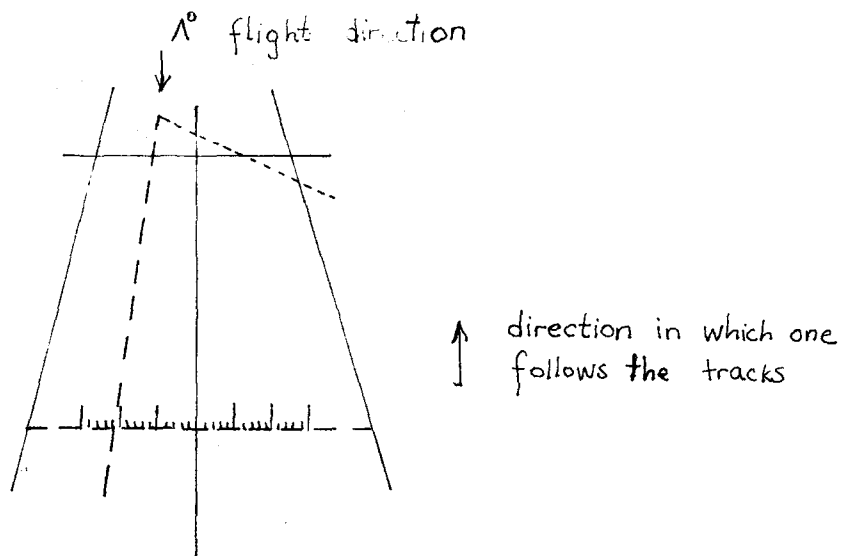


Fig. 8

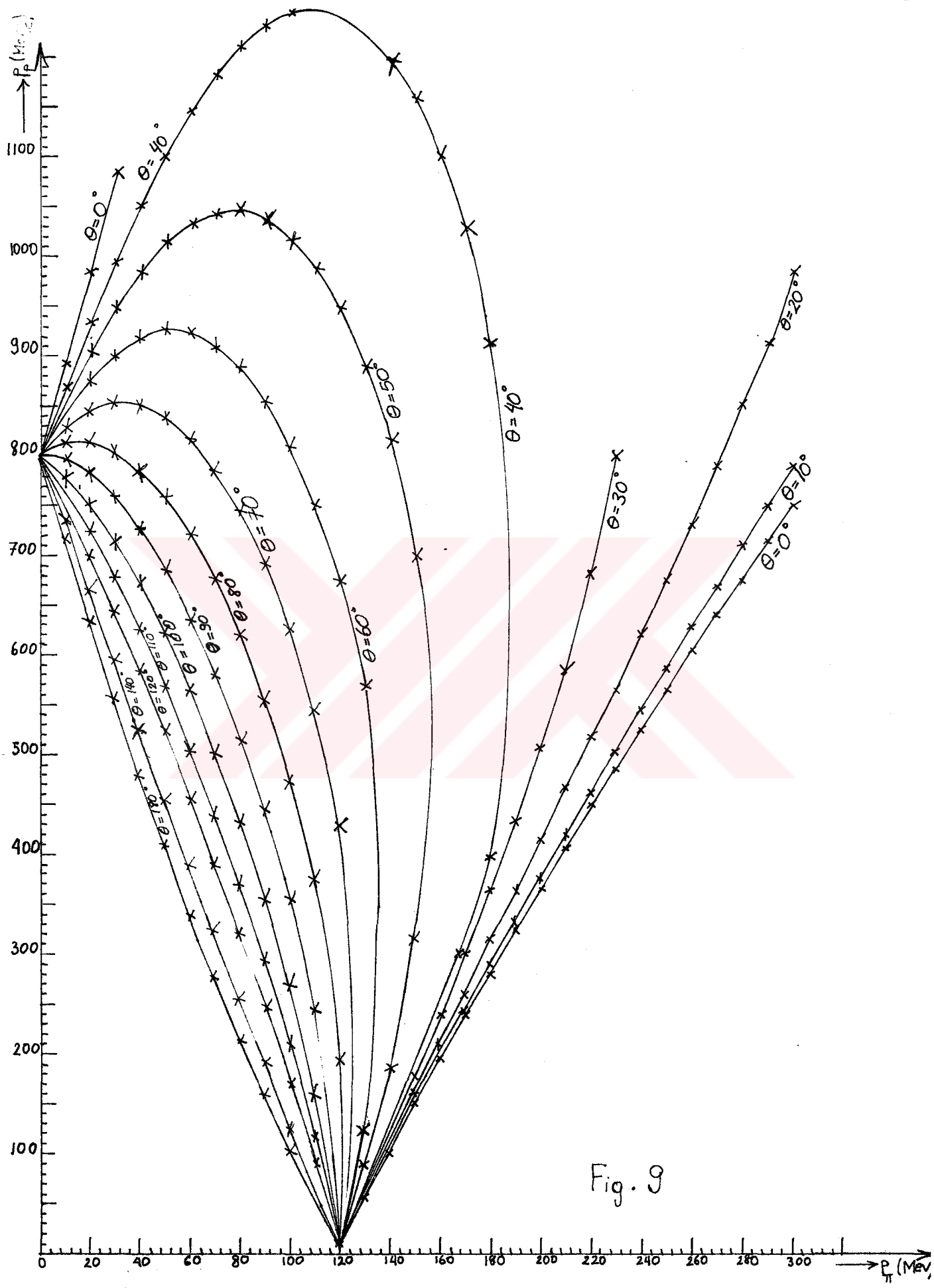


Fig. 9

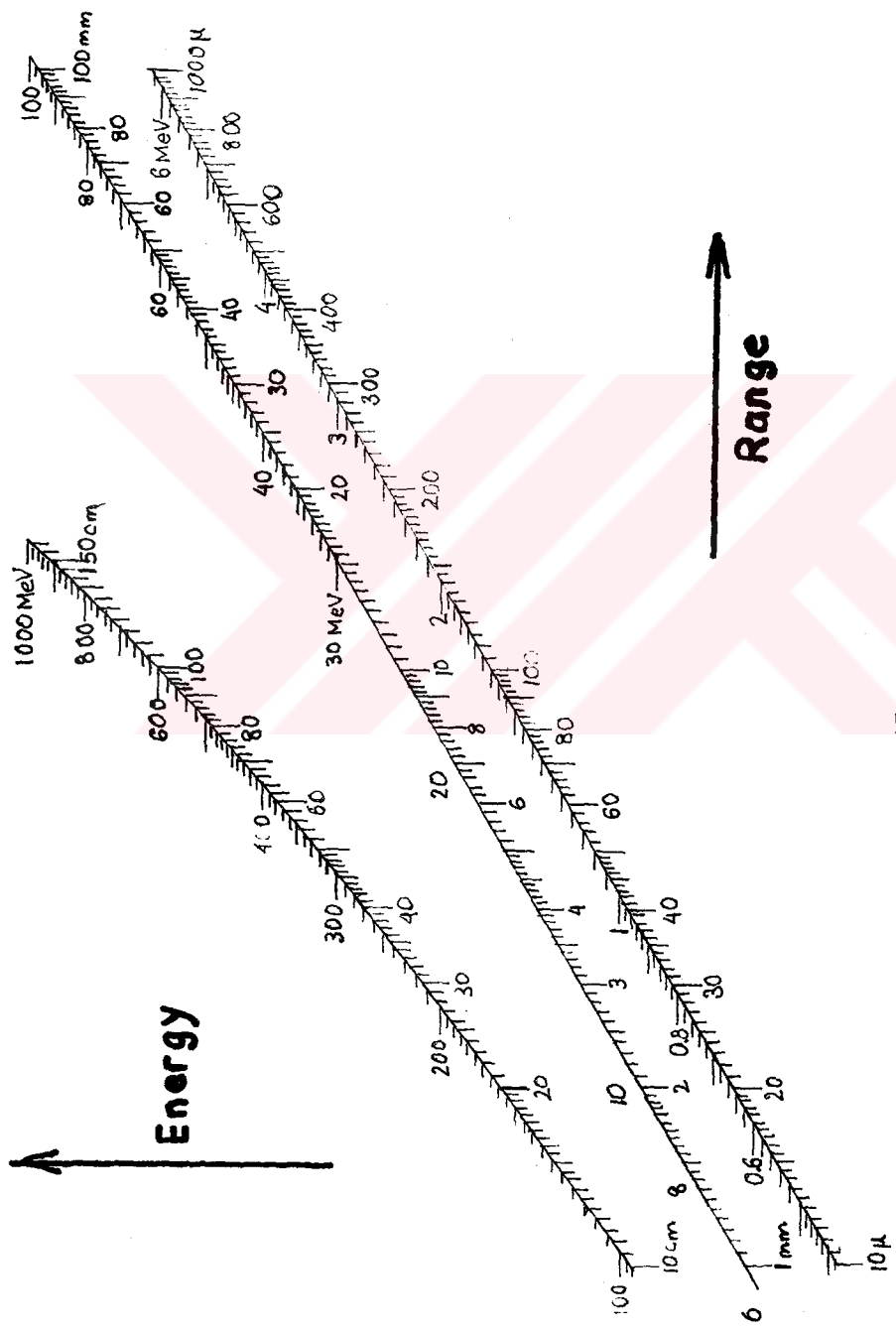


Fig-10

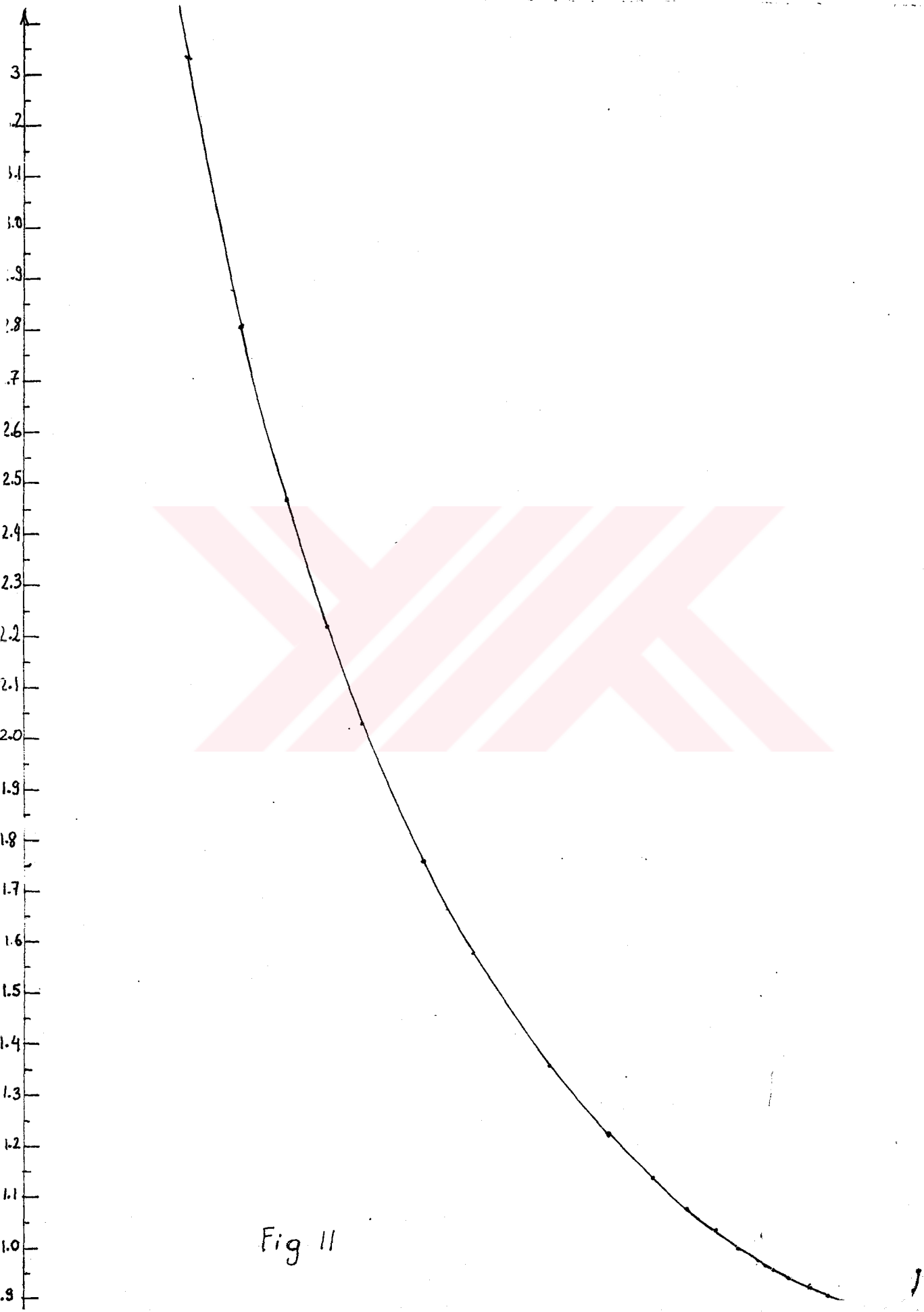
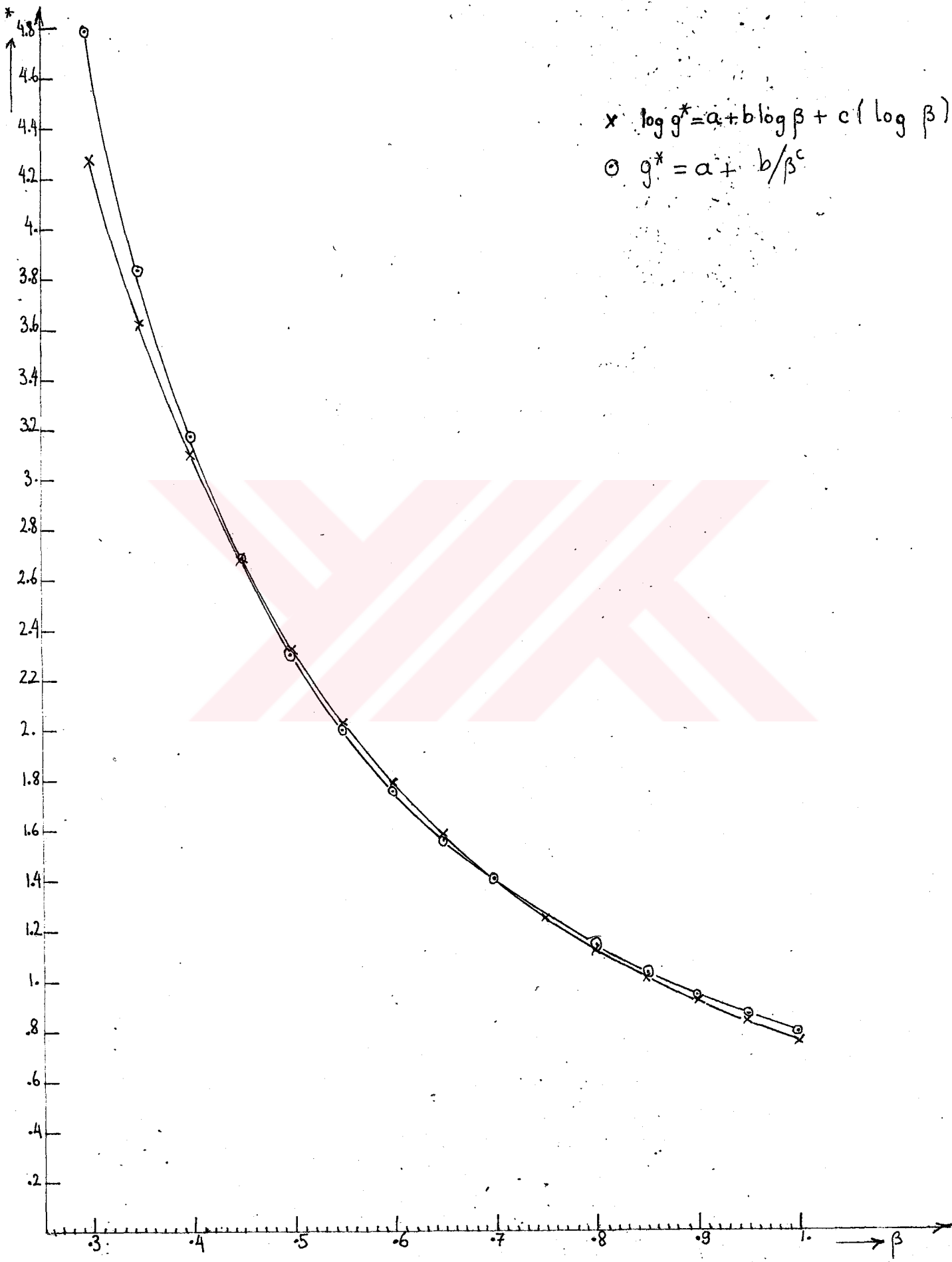


Fig 11



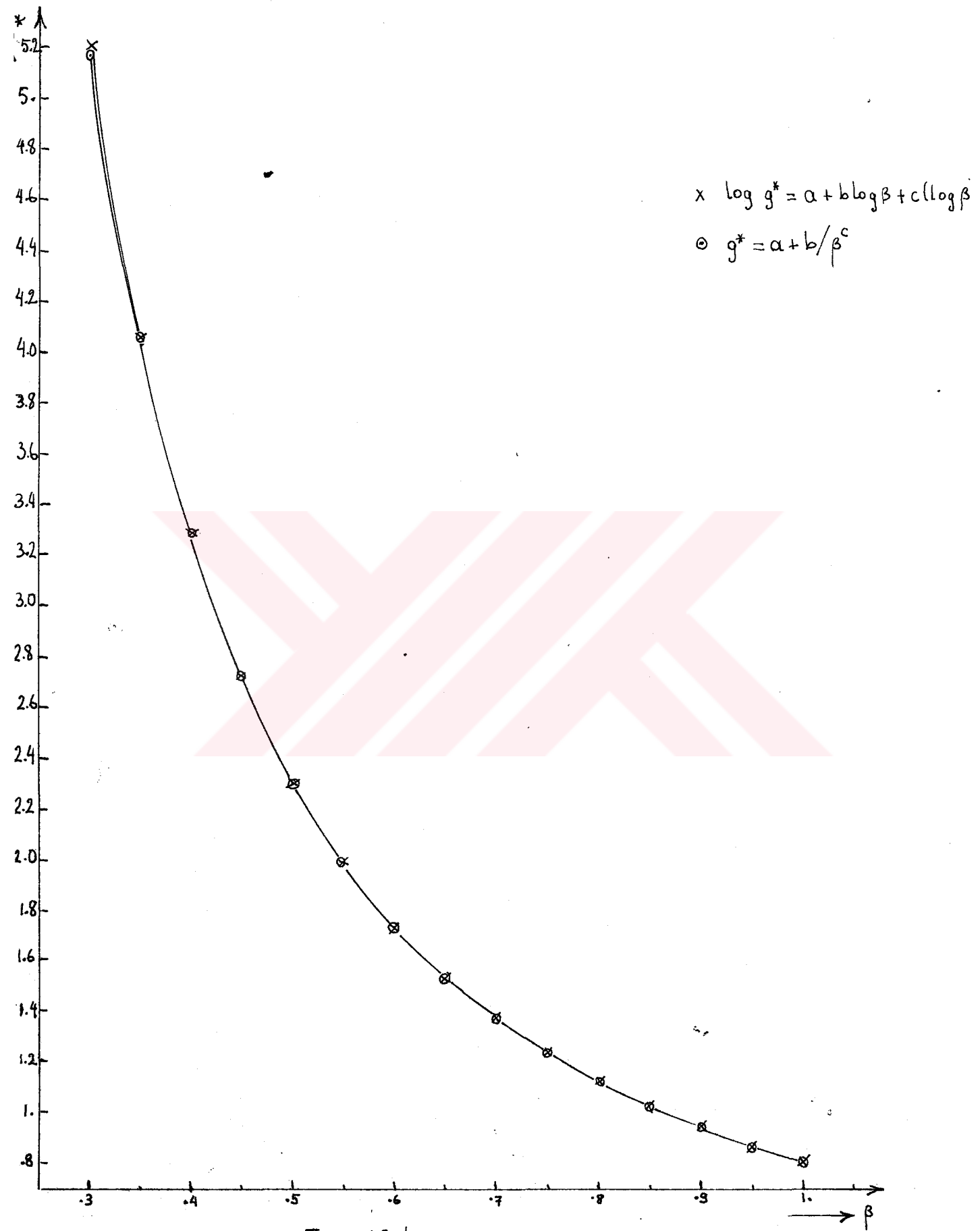


Fig 12 b

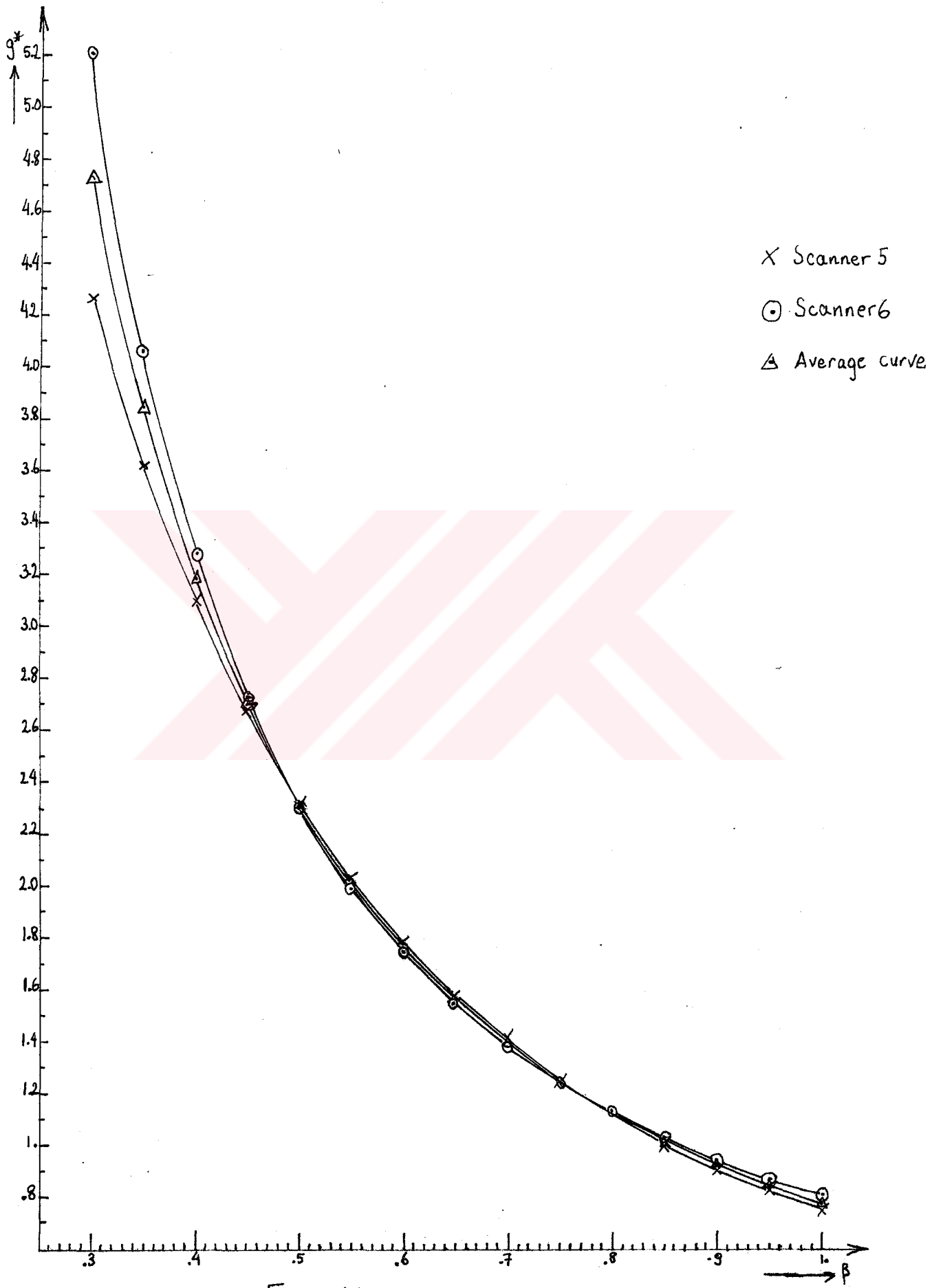


Fig. 13

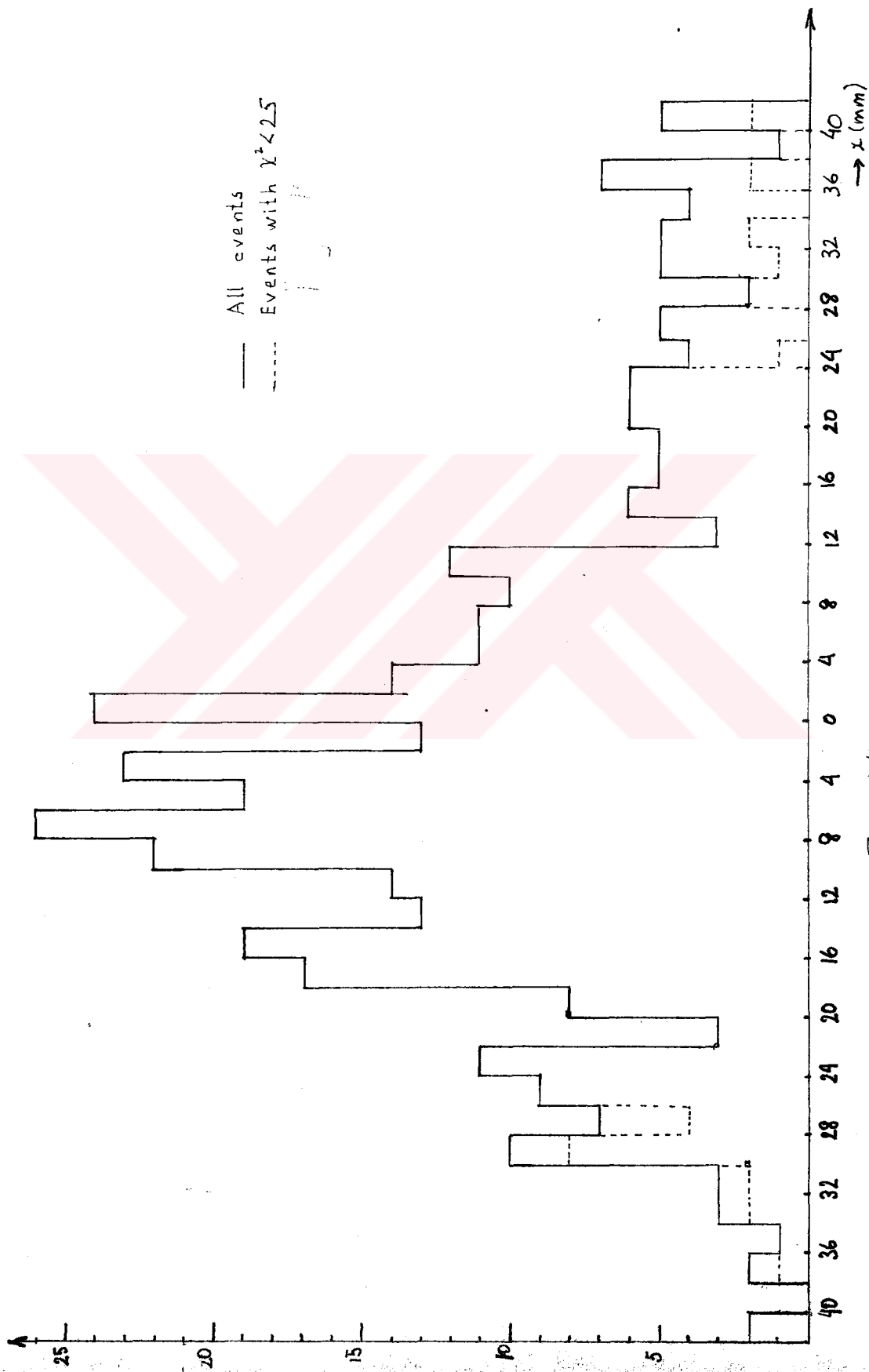


Fig. 14

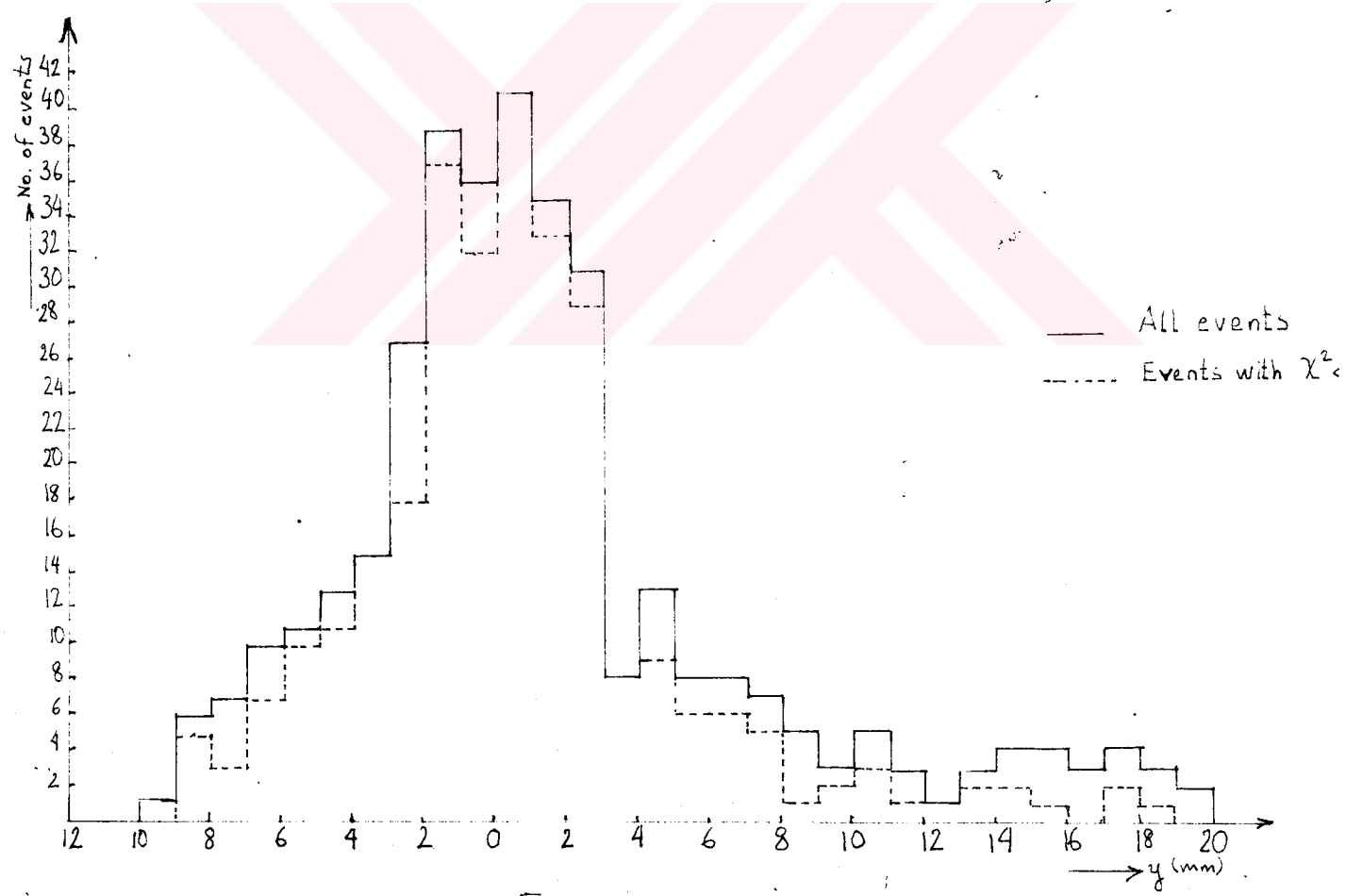


Fig. 15

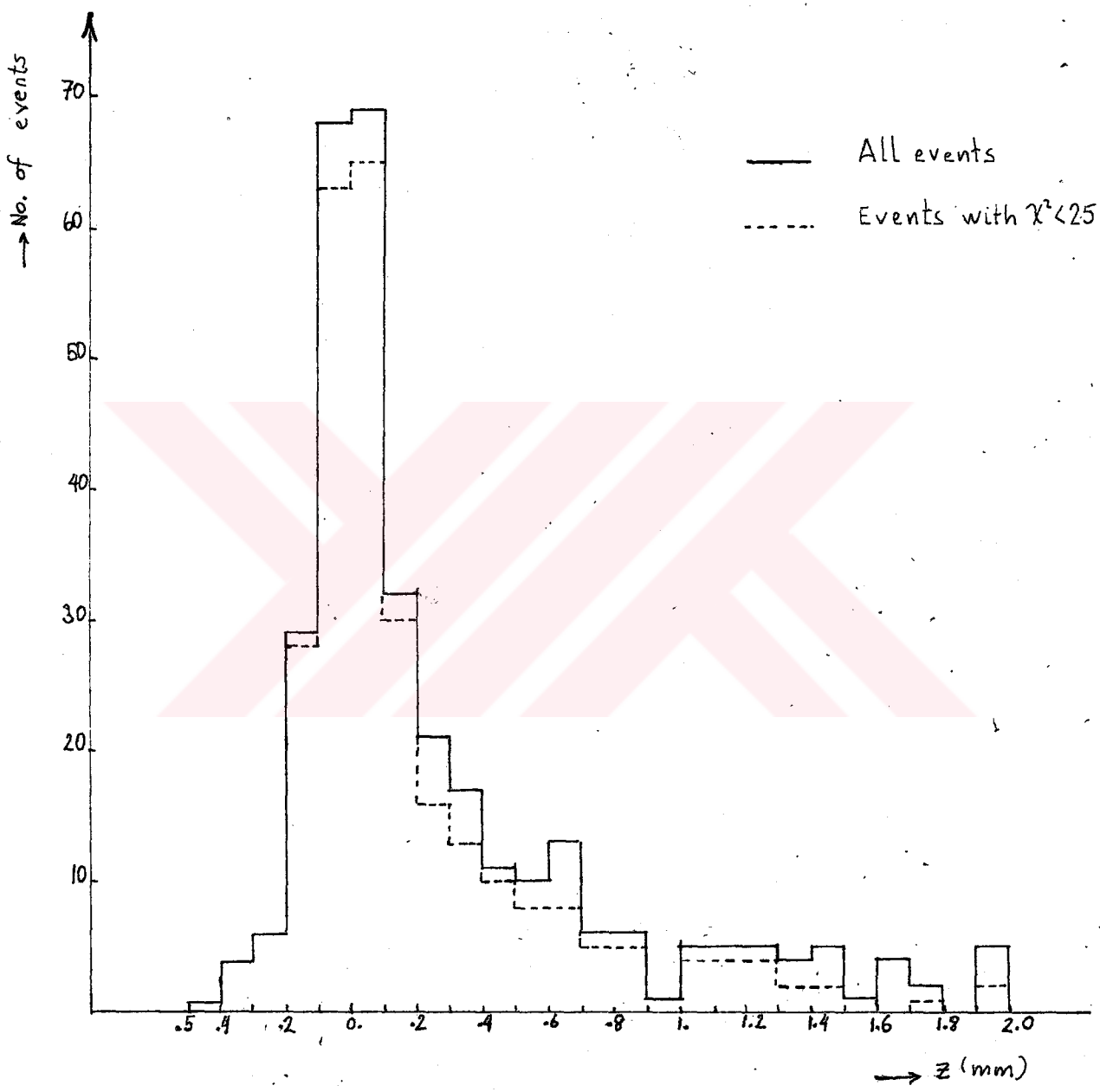


Fig. 16

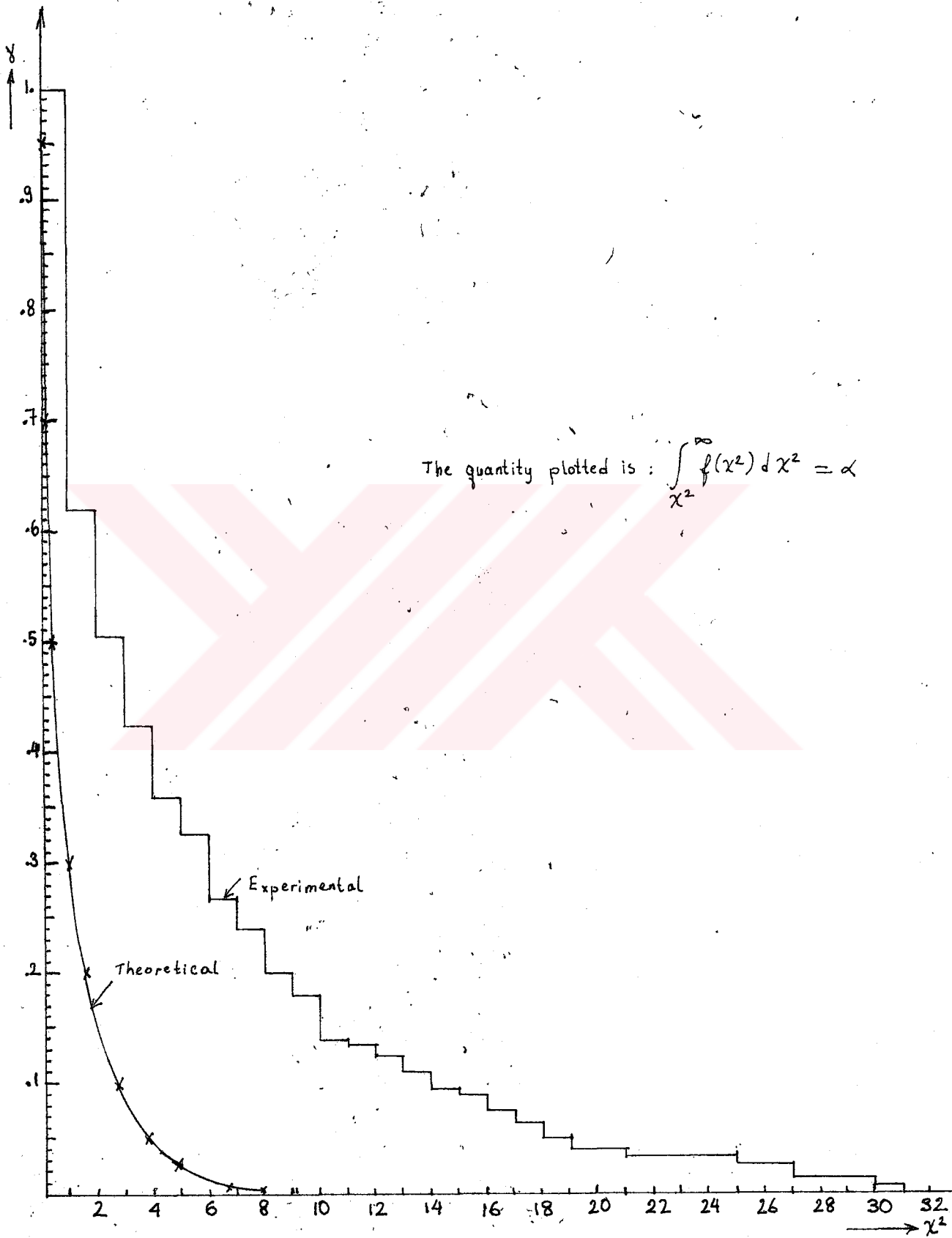


Fig. 17

— Selected events
- - - Non-selected events

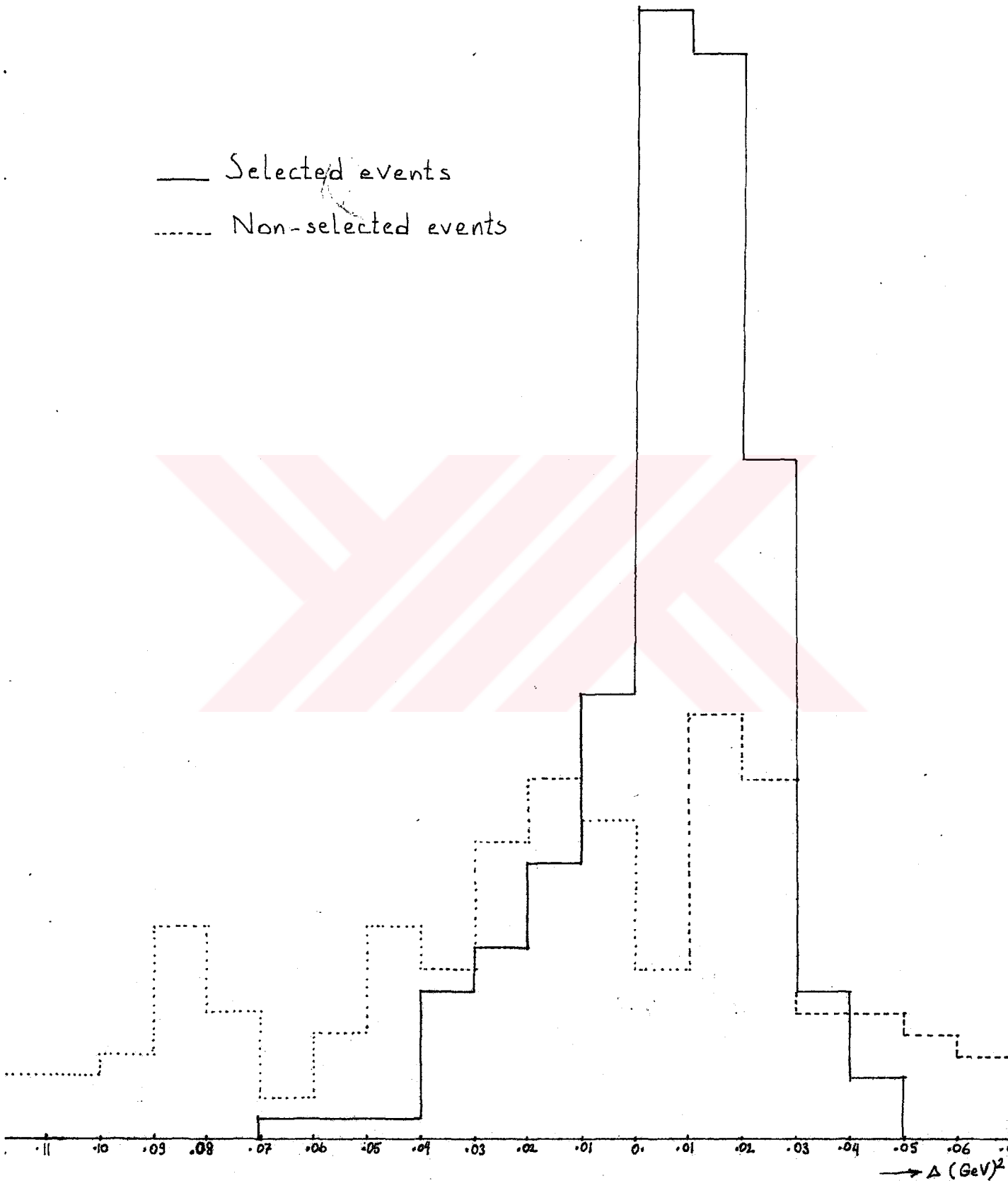


Fig. 18

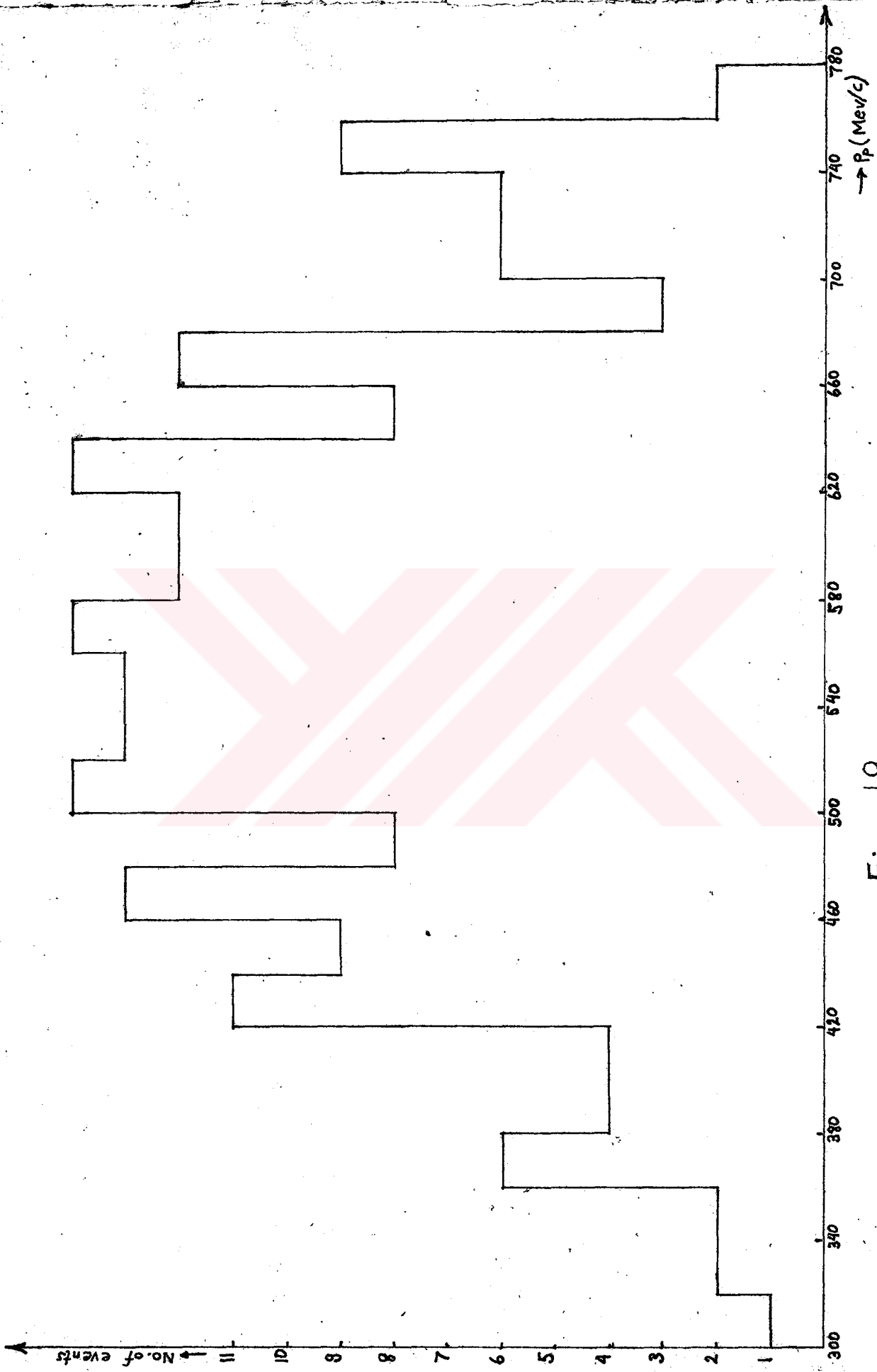


Fig. 19

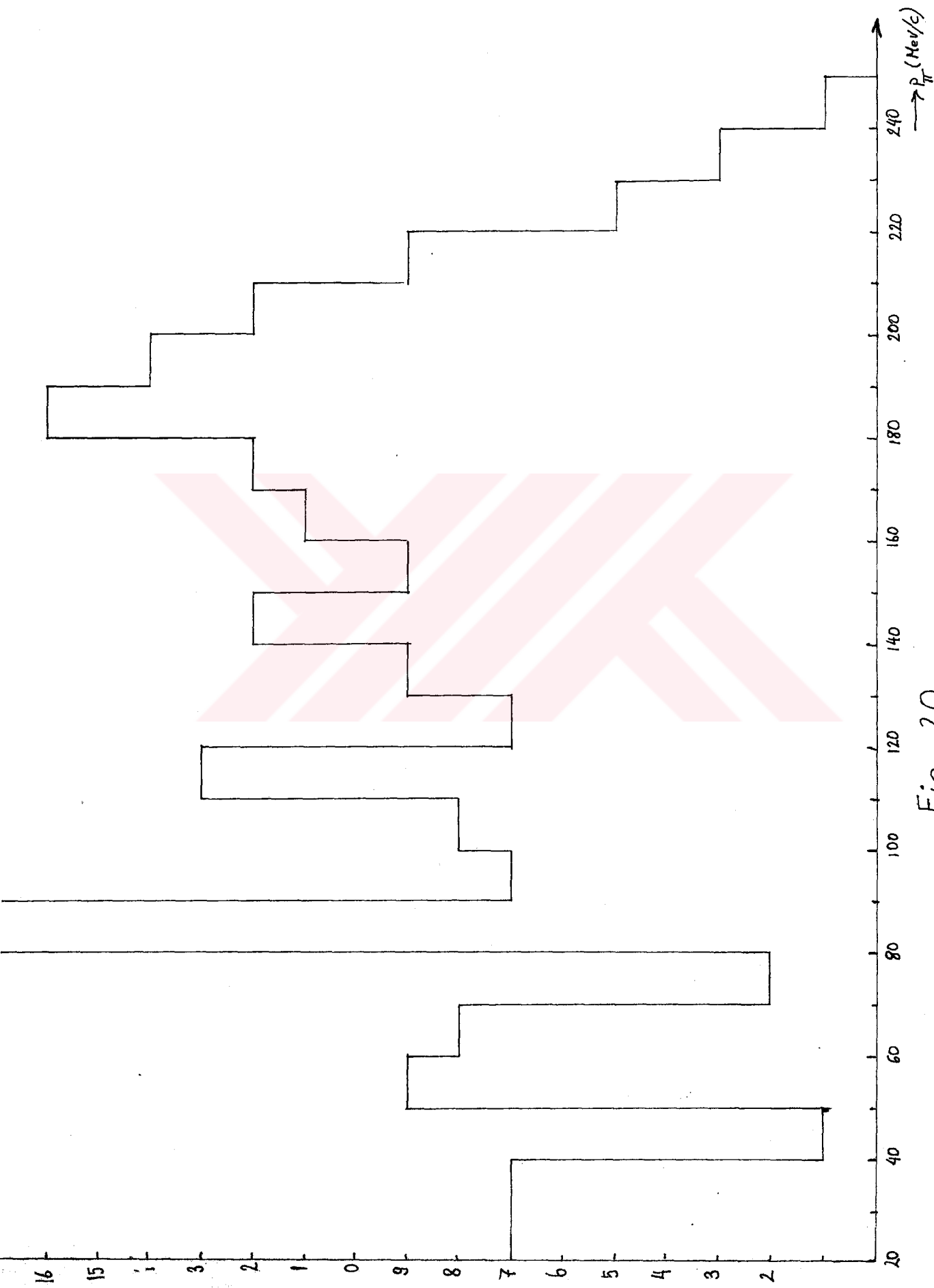


Fig. 20

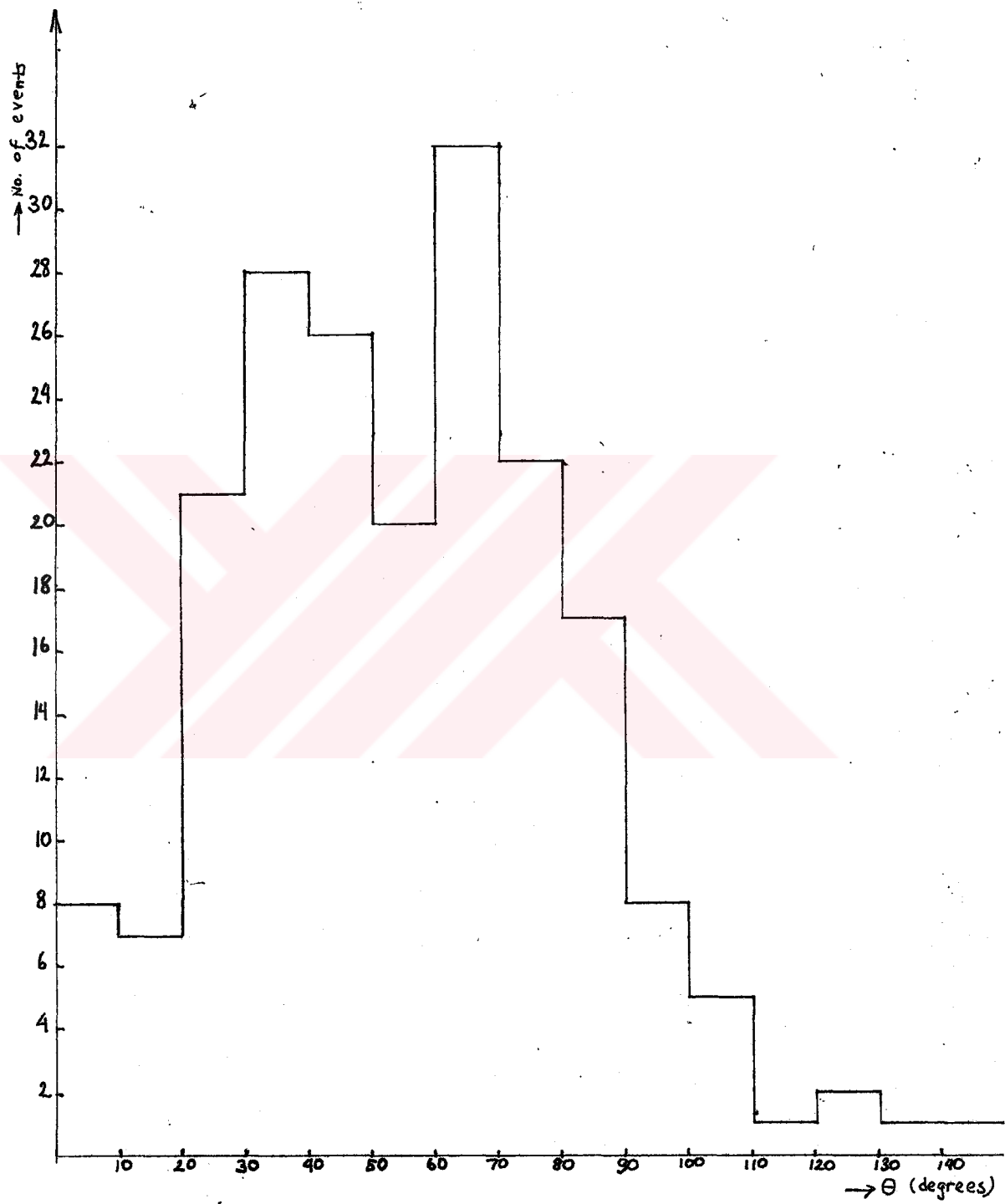


Fig. 21

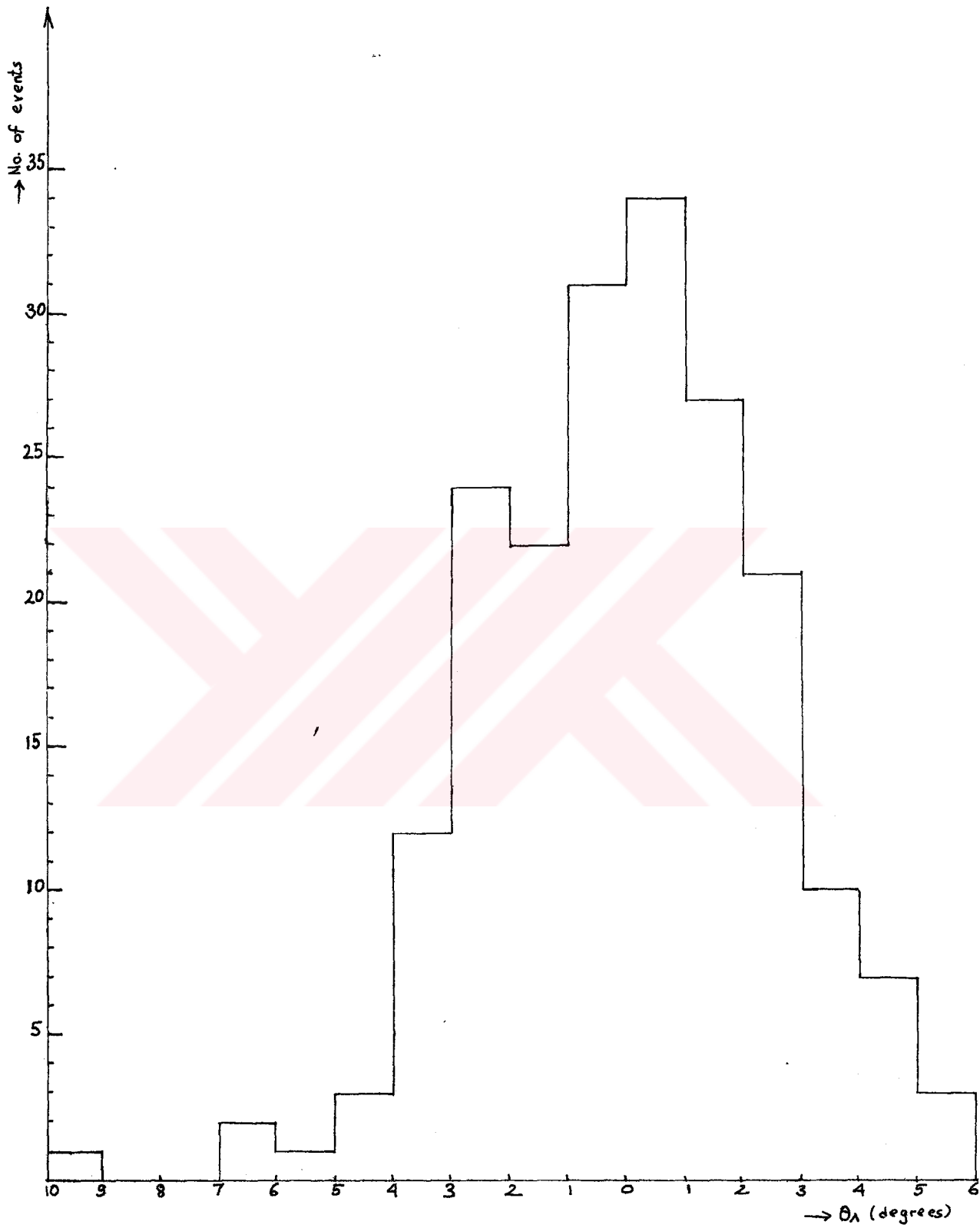


Fig. 22

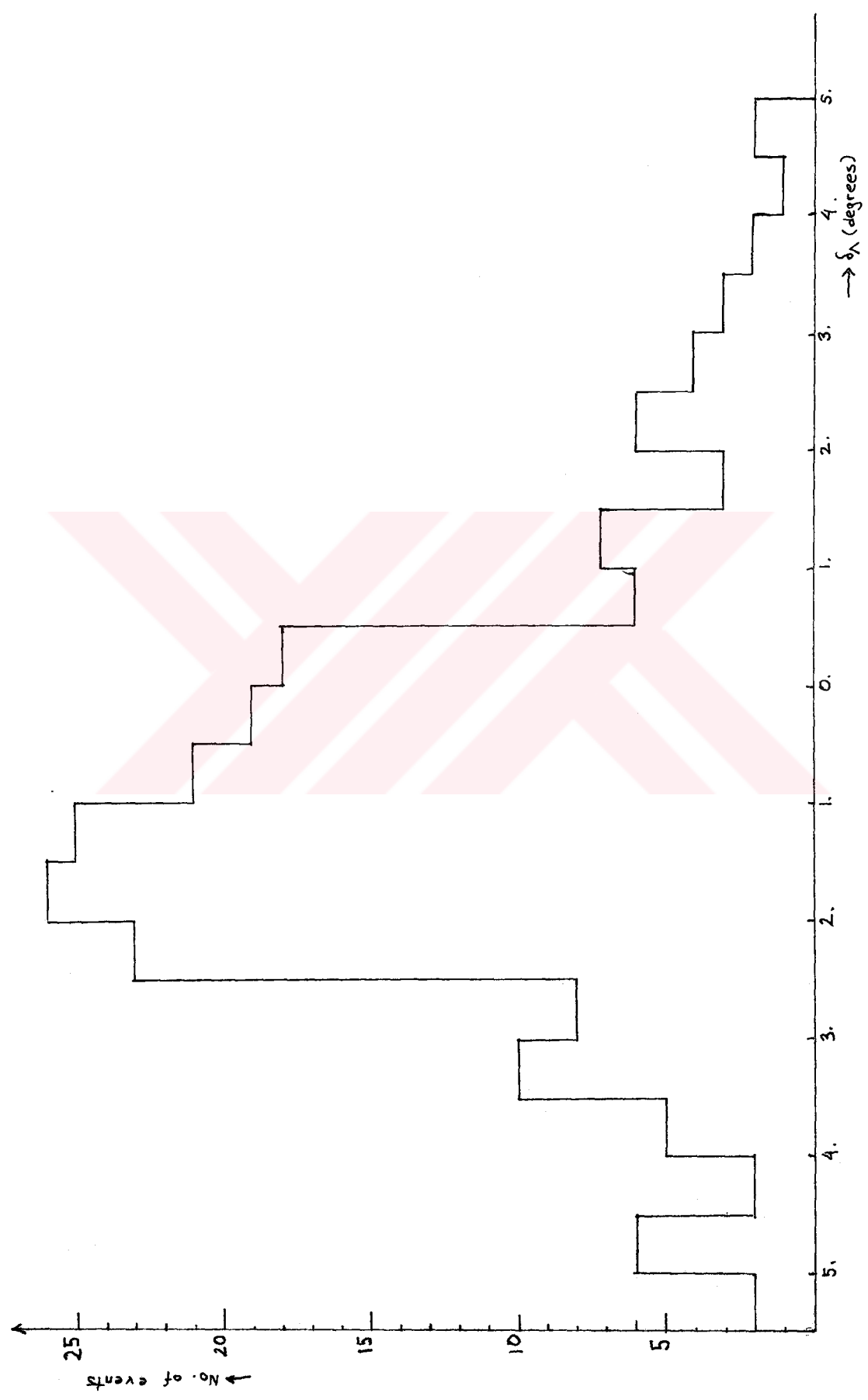


Fig. 23

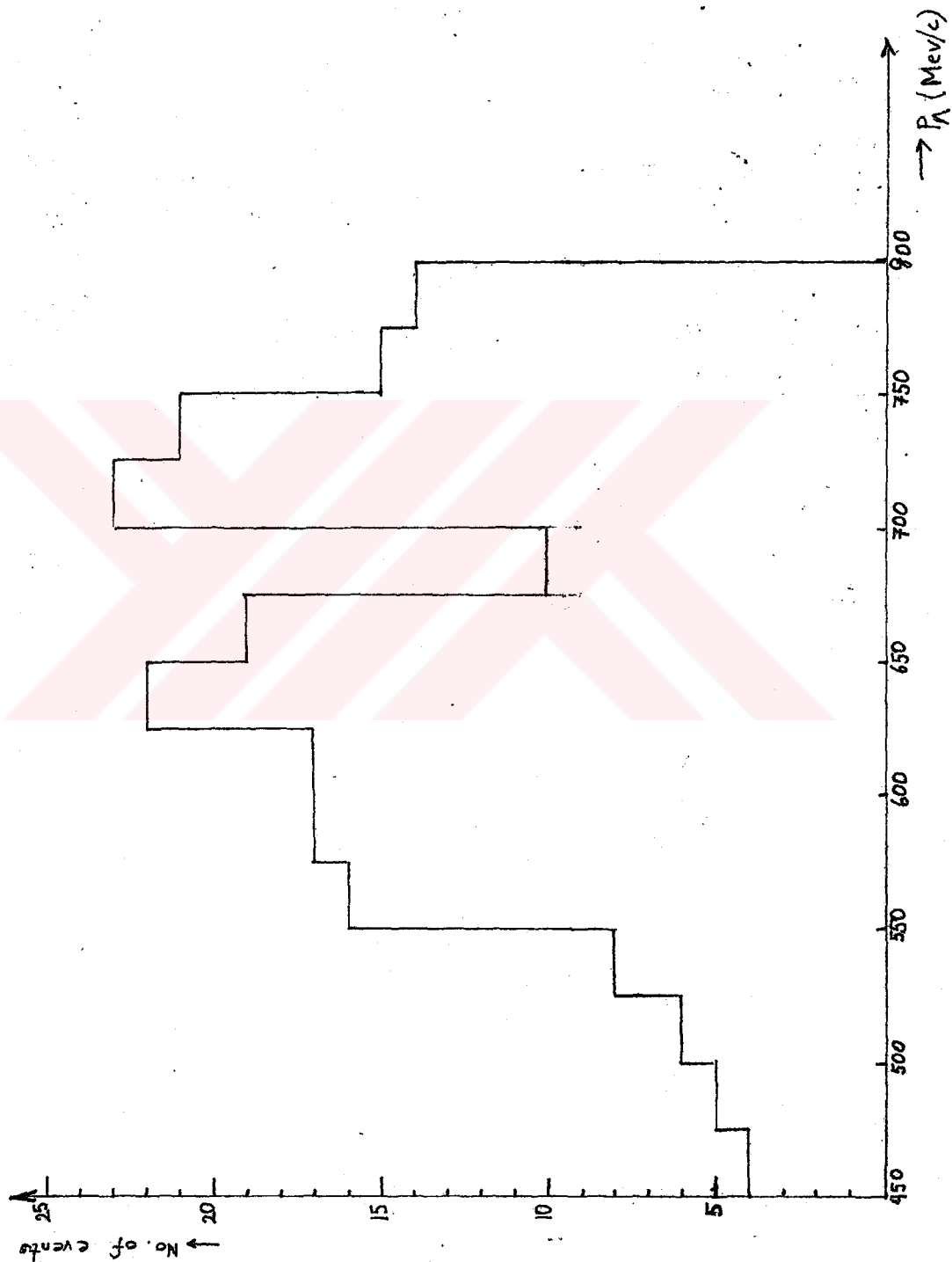


Fig. 24

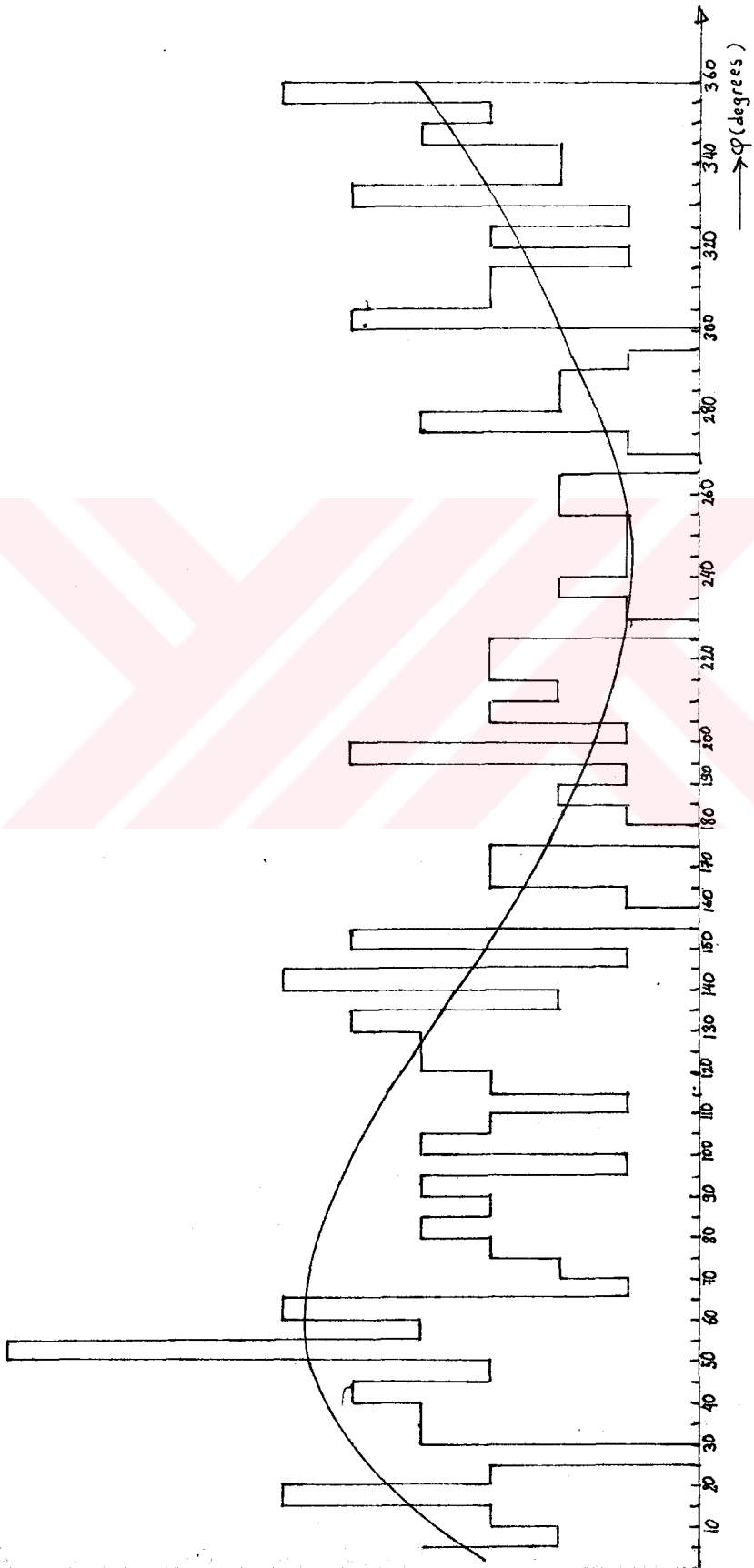


Fig. 25

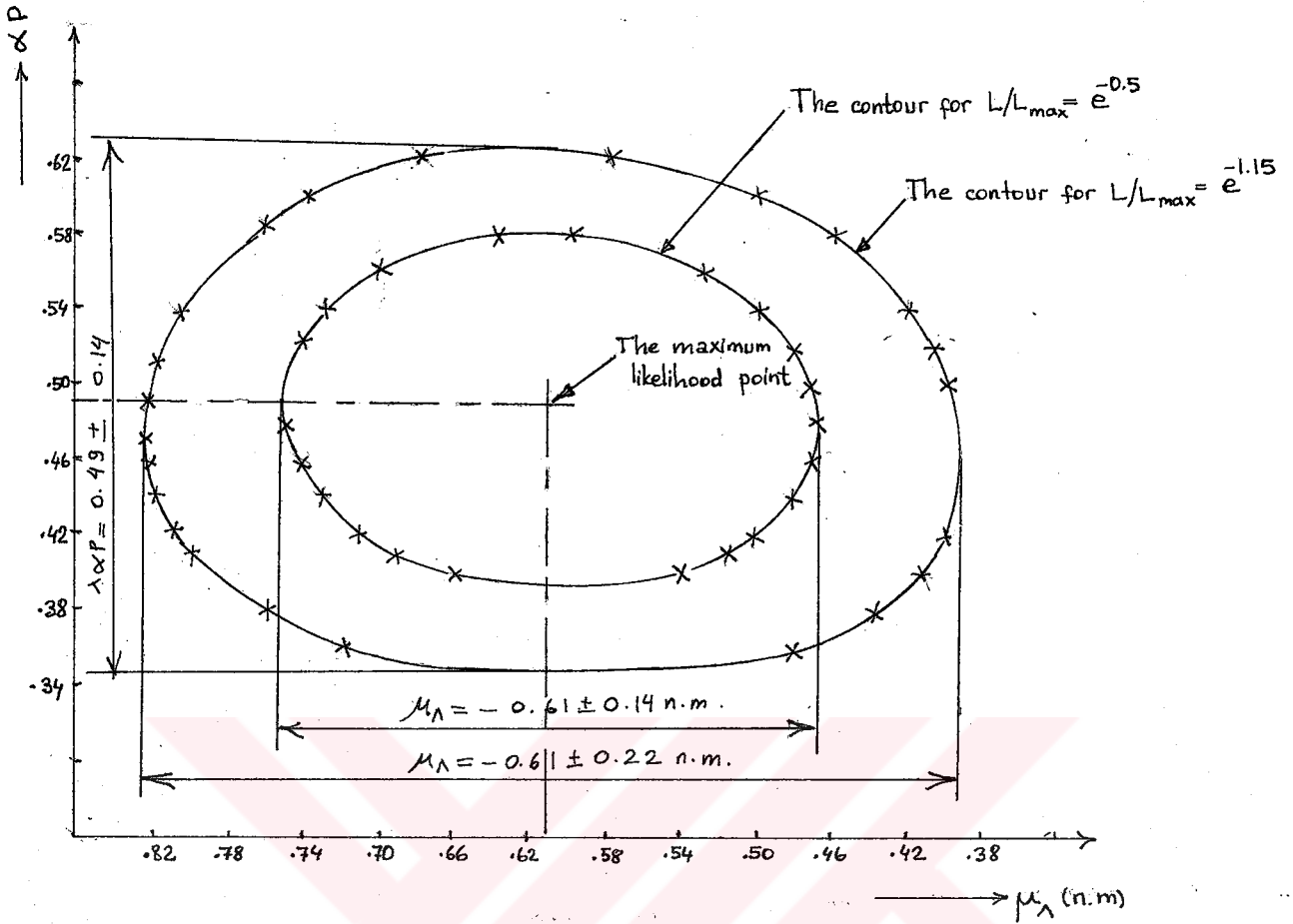


Fig. 26 a

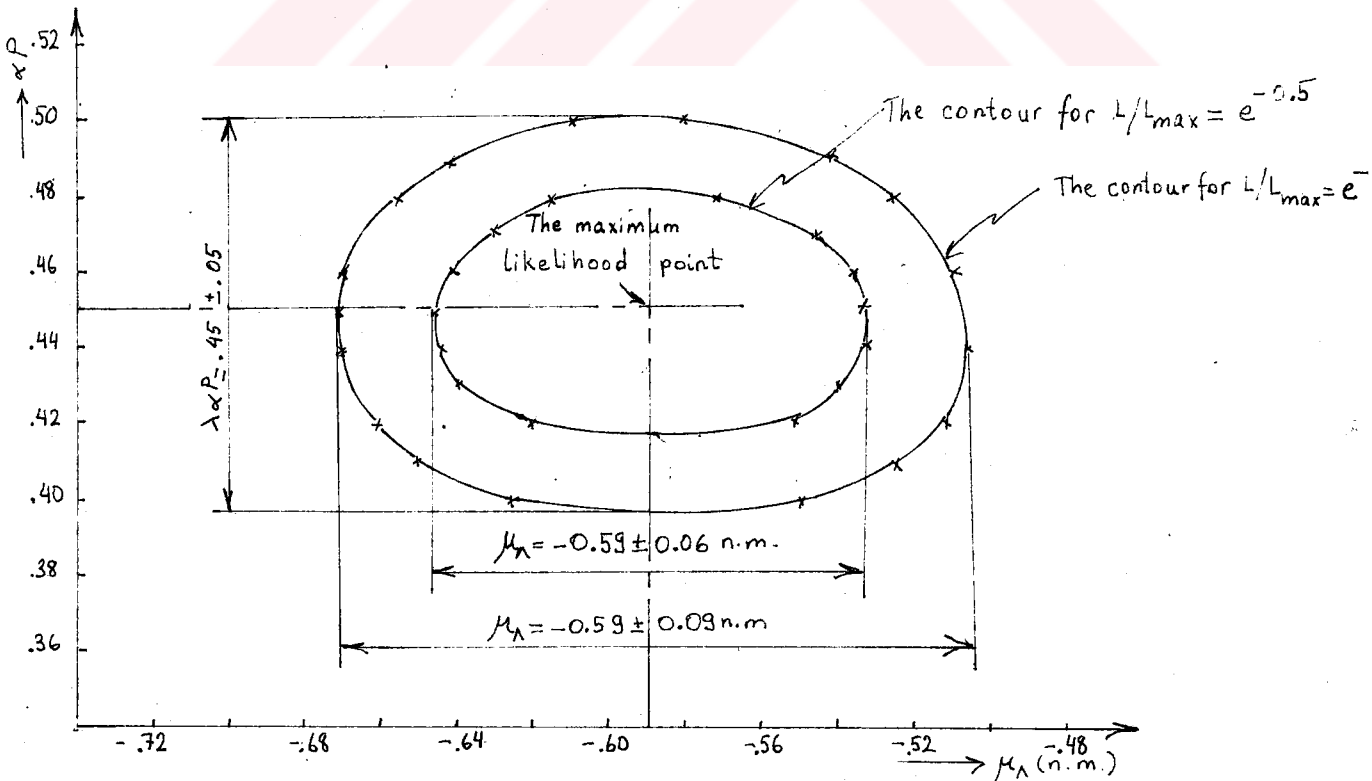


Fig. 26 b

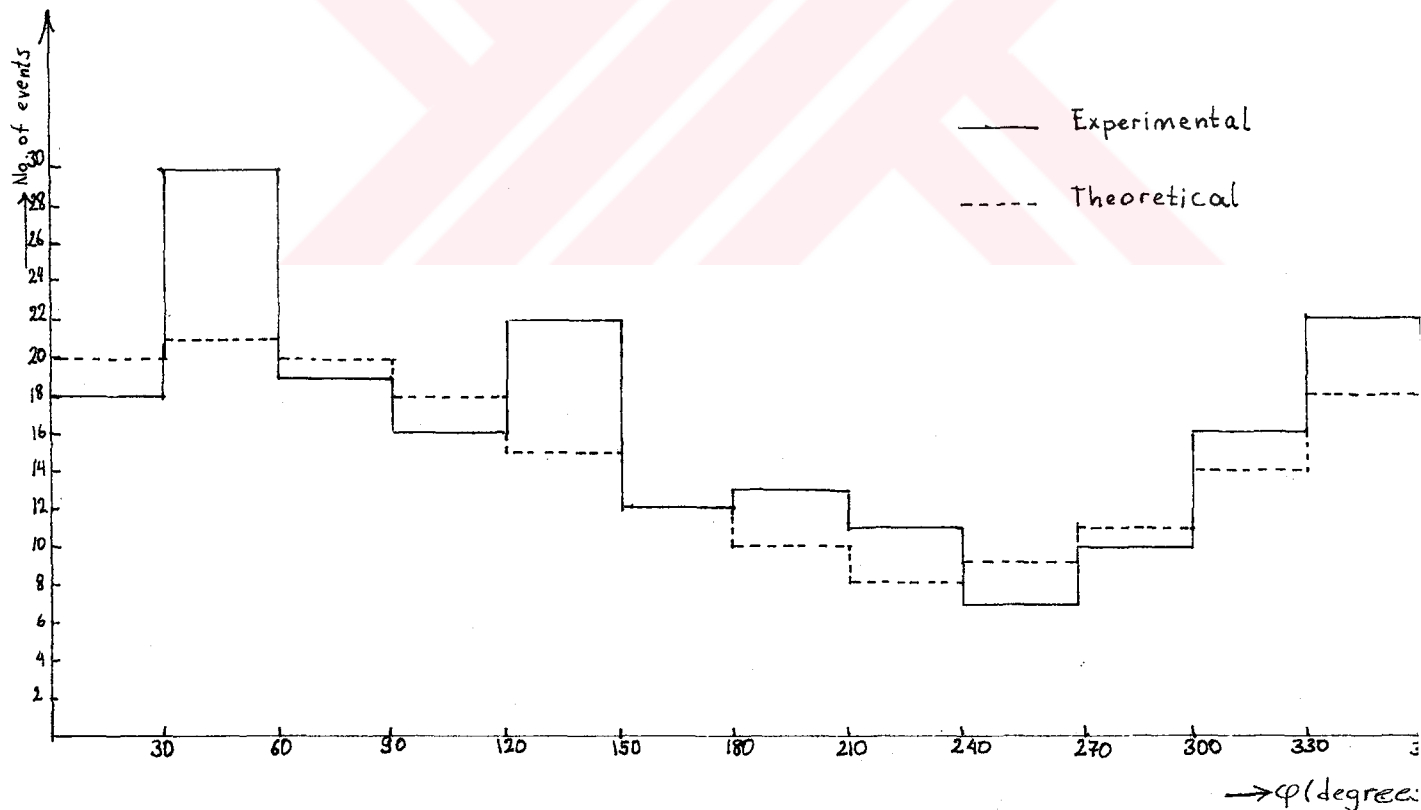


Fig. 27

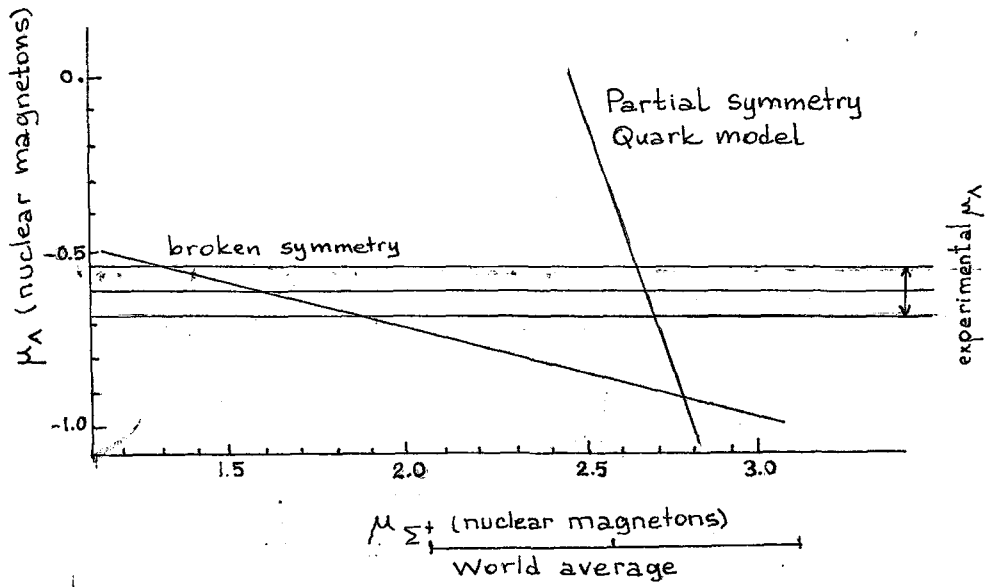


Fig. 28

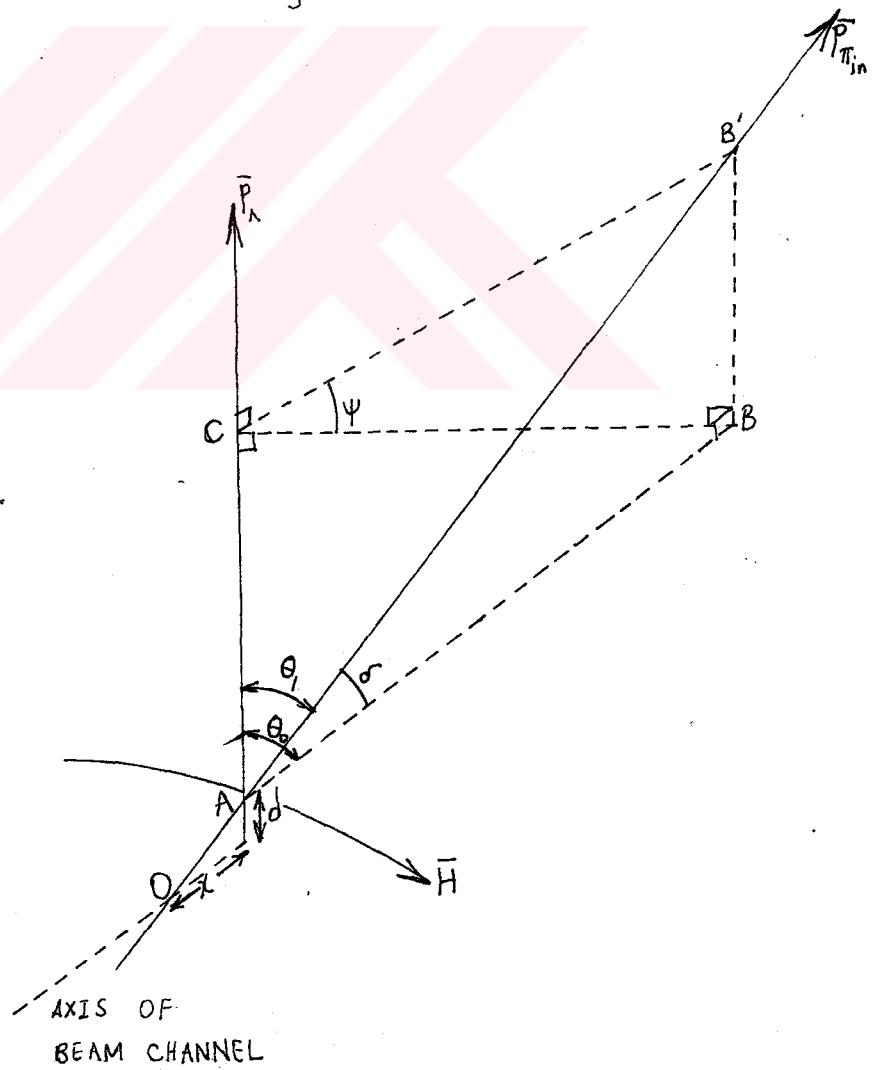


Fig. 29

```

DIMENSION SA(25),X(19),Y(19),APS(3),ORD(3),TITLE(20)
1,Z(19)
6 READ(1,4) SF,BL
4 FFORMAT (2F5.2)
DD 3 K=1,20
3 SA(K)=0.
1 READ(1,2) ID,J,JA,JB,KO,GA,LO,MO,KA,KA,IZO,NO,IGA,IGB,IGC,IA,ZJ,
1ZABM
2 FORMAT(I3,I2,2I1,I2,F2.0,I4,I2,I3,I4,4X,I3,I4,4I2,2F3.0,I1)
J=J+100
IF (IA) 35,35,50
50 IF (IA-4) 10,10,51
51 IF (IA-7) 11,11,52
52 IF (IA-10) 12,12,53
53 IF (IA-13) 13,13,54
54 IF (IA-16) 14,14,55
55 IF (IA-19) 15,15,56
56 IF (IA-22) 16,16,57
57 IF (IA-25) 17,17,58
58 IF (IA-28) 18,18,59
59 IF (IA-31) 19,19,60
60 IF (IA-34) 20,20,61
61 IF (IA-37) 21,21,62
62 IF (IA-40) 22,22,63
63 IF (IA-43) 23,23,64
64 IF (IA-46) 24,24,65
65 IF (IA-49) 25,25,66
66 IF (IA-52) 26,26,67
67 IF (IA-55) 27,27,28
10 SA(1)=SA(1)+1.
GO TO 1
11 SA(2)=SA(2)+1.
GO TO 1
12 SA(3)=SA(3)+1.
GO TO 1
13 SA(4)=SA(4)+1.
GO TO 1
14 SA(5)=SA(5)+1.
GO TO 1
15 SA(6)=SA(6)+1.
GO TO 1
16 SA(7)=SA(7)+1.
GO TO 1
17 SA(8)=SA(8)+1.
GO TO 1
18 SA(9)=SA(9)+1.
GO TO 1
19 SA(10)=SA(10)+1.
GO TO 1
20 SA(11)=SA(11)+1.
GO TO 1
21 SA(12)=SA(12)+1.
GO TO 1
22 SA(13)=SA(13)+1.

```



```
      GD TO 1
23 SA(14)=SA(14)+1.
      GD TO 1
24 SA(15)=SA(15)+1.
      GD TO 1
25 SA(16)=SA(16)+1.
      GD TO 1
26 SA(17)=SA(17)+1.
      GD TO 1
27 SA(18)=SA(18)+1.
      GD TO 1
28 SA(19)=SA(19)+1.
      GD TO 1
35 WRITE(3,7) J
      7 FORMAT (/8H STACK=,I3)
36 WRITE(3,8) JA
      8 FORMAT (/8H PLATE=,I2)
37 WRITE(3,9) JB
      9 FORMAT (/11H TRAVERSE=,I2)
      XZ=3.
      DO 40 I=1,19
      X(I)=SA(I)
      Y(I)=XZ
      Z(I)=PLUS
40 XZ=XZ+3.
      I=JA
      N=19
      NL=19
      NS=1
      IYFORM=1
      IYRGHT=3
      IXFORM=1
      IXRGTH=3
      READ(1,41) ORD,APS,TITLE
41 FORMAT(2(3A4/),20A4)
      CALL GRAPH(X,Y,Z,N,ORD,APS,TITLE,I,NL,NS,IYFORM,IYRGHT,IXFORM,IXRG
      HT)
      GD TO 6
70 STOP
      DATA PLUS /'+'/
      END
```

```

DIMENSION DA(19),X(19),Y(19),APS(3),ORD(3),TITLE(20)
1,Z(19)
6 READ(1,4) SF,BL
4 FORMAT(2F5.2)
DD 3 K=1,20
3 DA(K)=0.
1 READ(1,2) IO,J,JA,JB,KO,GA,LO,MO,KA,IKA,IZO,NO,IGA,IGB,IGC,IA,ZU,
1ZA,M
2 FORMAT(I3,I2,2I1,I2,F2.0,I4,I2,I3,I4,4X,I3,I4,4I2,2F3.0,I1)
J=J+100
IF(ZU-ZA) 91,90,90
91 D=ATAN((ZU-ZA)*SF/BL)
GO TO 92
90 D=-ATAN((ZA-ZU)*SF/BL)
92 D=D*180./3.1416
IF(IA) 30,30,50
50 IF(D+26.) 10,10,51
51 IF(D+23.) 11,11,52
52 IF(D+20.) 12,12,53
53 IF(D+17.) 13,13,54
54 IF(D+14.) 14,14,55
55 IF(D+11.) 15,15,56
56 IF(D+8.) 16,16,57
57 IF(D+5.) 17,17,58
58 IF(D+2.) 18,18,59
59 IF(D-1.) 19,19,60
60 IF(D-4.) 20,20,61
61 IF(D-7.) 21,21,62
62 IF(D-10.) 22,22,63
63 IF(D-13.) 23,23,64
64 IF(D-16.) 24,24,65
65 IF(D-19.) 25,25,66
66 IF(D-22.) 26,26,67
67 IF(D-25.) 27,27,28
10 DA(1)=DA(1)+1.
GO TO 1
11 DA(2)=DA(2)+1.
GO TO 1
12 DA(3)=DA(3)+1.
GO TO 1
13 DA(4)=DA(4)+1.
GO TO 1
14 DA(5)=DA(5)+1.
GO TO 1
15 DA(6)=DA(6)+1.
GO TO 1
16 DA(7)=DA(7)+1.
GO TO 1
17 DA(8)=DA(8)
GO TO 1
18 DA(9)=DA(9)
GO TO 1
19 DA(10)=DA(10)
GO TO 1

```

```
20 DA(11)=DA(11)
   GO TO 1
21 DA(12)=DA(12)
   GO TO 1
22 DA(13)=DA(13)
   GO TO 1
23 DA(14)=DA(14)
   GO TO 1
24 DA(15)=DA(15)
   GO TO 1
25 DA(16)=DA(16)
   GO TO 1
26 DA(17)=DA(17)
   GO TO 1
27 DA(18)=DA(18)
   GO TO 1
28 DA(19)=DA(19)+1.
   GO TO 1
30 WRITE(3,7) J
   7 FORMAT (/8H STAVK=,I3)
36 WRITE(3,8) JA
   8 FORMAT (/8H PLATE=,I2)
37 WRITE(3,9) JB
   9 FORMAT(/11H TRAVERSE=,I2)
   XZ=-27.
   DO 40 I=1,19
   X(I)=DA(I)
   Y(I)=XZ
   Z(I)=PLUS
40 XZ=XZ+3.
   I=JA
   N=19
   NS=1
   NL=19
   READ(1,41) ORD,APS,TITLE
   IYFORM=1
   IYRGHT=3
   IXFORM=1
   IXRGHT=3
41 FORMAT(2(3A4/),20A4)
   CALL GRAPH(X,Y,Z,N,ORD,APS,TITLE,I,NL,NS,IYFORM,IYRGHT,IXFORM,IXRG
   HT)
   GO TO 6
70 STOP
   DATA PLUS /'+'/
   END
```

```

DIMENSION DI(25),X(25),Y(25)
1,Z(19)
6 READ(1,4) SF,BL
4 FORMAT(2F5.2)
DD 3 K=1,20
3 DI(K)=0.
1 READ(1,2) JO,J,JA,JB,KO,GA,LO,MO,KA,IKA,IZO,NO,IGA,IGB,IGC,IA,ZU,
ZA,M
2 FORMAT(13,12,2I1,12,F2.0,14,12,13,16,4X,13,14,4I2,2F3.0,I1)
J=J+100
GB=GA*BL
IF(IA) 35,35,50
50 IF(IGA-47) 10,10,51
51 IF(IGA-50) 11,11,52
52 IF(IGA-53) 12,12,53
53 IF(IGA-56) 13,13,54
54 IF(IGA-59) 14,14,55
55 IF(IGA-62) 15,15,56
56 IF(IGA-65) 16,16,57
57 IF(IGA-68) 17,17,58
58 IF(IGA-71) 18,18,59
59 IF(IGA-74) 19,19,60
60 IF(IGA-77) 20,20,61
61 IF(IGA-80) 21,21,62
62 IF(IGA-83) 22,22,63
63 IF(IGA-86) 23,23,64
64 IF(IGA-89) 24,24,65
65 IF(IGA-92) 25,25,66
66 IF(IGA-95) 26,26,67
67 IF(IGA-98) 27,27,28
10 DI(1)=DI(1)+1.
GO TO 1
11 DI(2)=DI(2)+1.
GO TO 1
12 DI(3)=DI(3)+1.
GO TO 1
13 DI(4)=DI(4)+1.
GO TO 1
14 DI(5)=DI(5)+1.
GO TO 1
15 DI(6)=DI(6)+1.
GO TO 1
16 DI(7)=DI(7)+1.
GO TO 1
17 DI(8)=DI(8)+1.
18 DI(9)=DI(9)+1.
GO TO 1
19 DI(10)=DI(10)+1.
GO TO 1
20 DI(11)=DI(11)+1.
GO TO 1
21 DI(12)=DI(12)+1.
GO TO 1
22 DI(13)=DI(13)+1.

```

```
GO TO 1
23 DI(14)=DI(14)+1.
GO TO 1
24 DI(15)=DI(15)+1.
GO TO 1
25 DI(16)=DI(16)+1.
GO TO 1
26 DI(17)=DI(17)+1.
GO TO 1
27 DI(18)=DI(18)+1.
GO TO 1
28 DI(19)=DI(19)+1.
GO TO 1
35 WRITE(3,7) J
7 FORMAT(/8H STACK=,I3)
36 WRITE(3,8) JA
8 FORMAT(/8H PLATE=,I2)
37 WRITE(3,9) JB
9 FORMAT(/11H TRAVERSE=,I2)
38 WRITE(3,43) GA
43 FORMAT(/9H G MIN =,F3.0)
39 WRITE(3,44) GB
44 FORMAT(/12H G MIN/BOX=,F3.0)
XZ=46.
DO 40 I=1,19
Y(I)=XZ
X(I)=DI(I)
Z(I)=PLUS
40 XZ=XZ+3.
I=JA
N=19
NL= 9
NS=1
IYFORM=1
IYRGHT=3
IXFORM=1
IXRGHT=3
READ(1,41) ORD,APS,TITLE
41 FORMAT(2(3A4/),20A4)
CALL GRAPH(X,Y,Z,N,ORD,APS,TITLE,I,NL,NS,IYFORM,IYRGHT,IXFORM,IXRG
IHT)
GO TO 6
70 STOP
DATA PLUS /'+'/
END
```



```

DIMENSION G(50), V(50), DG(50)
1 READ 2,A,N
2 FORMAT (F5.3,I4)
PRINT 3
3 FORMAT (//12H          INPUT)
DO 5 I=1,N
READ 4,V(I),G(I),DG(I)
4 FORMAT (3F5.3)
PRINT 14,V(I),G(I),DG(I)
14 FORMAT (3F8.3)
5 CONTINUE
PRINT 21
21 FORMAT (//51H          C          B          B          A          CHI)
IT=1
6 S1=0.
S2=0.
S3=0.
S4=0.
S5=0.
DO 10 I=1,N
Y=G(I)-A
ELY=ALOG(Y)
RDY=Y*Y/(DG(I)*DG(I))
ELV=ALOG(V(I))
S1=S1+ELV*RDY
S2=S2+ELV*ELV*RDY
S3=S3+RDY
S4=S4+ELY*ELV*RDY
10 S5=S5+ELY*RDY
DET=S1*S1-S2*S3
ELB=(S4*S1-S2*S5)/DET
B1=EXP(ELB)
C=(S4*S3-S5*S1)/DET
S6=0.
S7=0.
S8=0.
S9=0.
S10=0.
DO 20 I=1,N
VC=V(I)**C
RDG=1./(DG(I)*DG(I))
R=1./(DG(I)*DG(I)*VC)
S6=S6+R/VC
S7=S7+RDG
S8=S8+R
S9=S9+G(I)*RDG
20 S10=S10+G(I)*R
DET=S6*S7-S8*S8
A=(S6*S9-S8*S10)/DET
B2=(S7*S10-S8*S9)/DET
S11=0.
DO 30 I=1,N
T=G(I)-A-B2/(V(I)**C)
RDG=1./(DG(I)*DG(I))

```

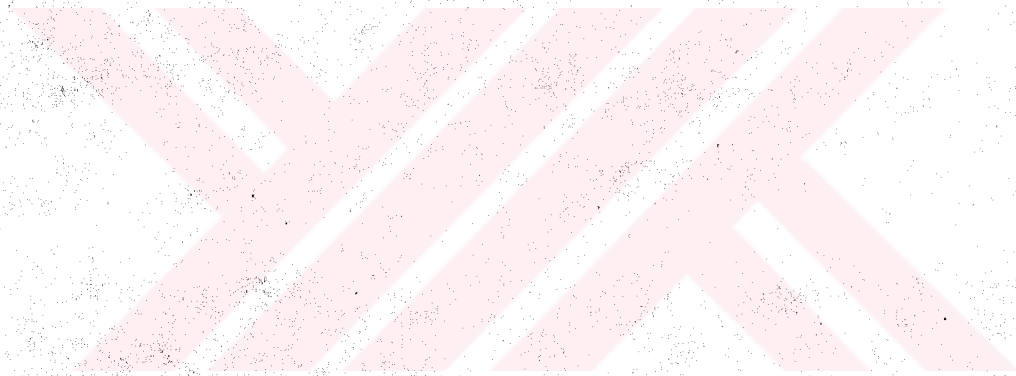
```
T=T*T*RDG
30 S11=S11+T
   PRINT 40,C,B1,B2,A,S11
40 FORMAT (//4F10.3,5X,F10.3)
   IT=IT+1
   IF (IT-15) 6,6,15
15 PRINT 55
55 FORMAT (//24H           FITTED CURVE)
   V(1)=.3
   DO 50 I=1,15
   GF=A+B2/(V(I)*C)
   ELV=ALOG(V(I))
   ELG=ALOG(GF)
   RGM=SQRT(1.-V(I)*V(I))
   IF (RGM) 51,52,51
51 PP=938.21*V(I)/RGM
   GO TO 54
52 PP=9999.
54 PRINT 56, V(I),GF,ELV,ELG,PP
56 FORMAT (2F10.3,2F10.4,F10.0)
50 V(I+1)=V(I)+.05
   GO TO 1
END
```

```

    DIMENSION G(50), V(50), DG(50)
  1 READ 2, EX, N
  2 FORMAT (F5.3,I4)
    PRINT 3
  3 FORMAT (//12H          INPUT)
    DO 5 I=1,N
    READ 4,V(I),G(I),DG(I)
  4 FORMAT (3F5.3)
    ELV=ALOG(V(I))
    ELG=ALOG(G(I))
    PRINT 14,V(I),G(I),DG(I),ELV,ELG
14 FORMAT (5F8.3)
  5 CONTINUE
  6 S1=0.
    S2=0.
    S3=0.
    S4=0.
    S5=0.
    S6=0.
    S7=0.
    S8=0.
    DO 10 I=1,N
    ELG=ALOG(G(I))
    ELV=ALOG(V(I))
    ELV2=ELV*ELV
    RDG=G(I)*G(I)/(DG(I)*DG(I))
    S1=S1+RDG
    S2=S2+ELV*RDG
    S3=S3+ELV2*RDG
    S4=S4+ELV*ELV2*RDG
    S5=S5+ELV2*ELV2*RDG
    S6=S6+ELG*RDG
    S7=S7+ELG*ELV*RDG
10 S8=S8+ELG*ELV2*RDG
    DET=S1*S3*S5-S1*S4*S4+S2*S4*S3-S2*S2*S5+S3*S2*S4-S3*S3*S3
    A=S6*S3*S5-S6*S4*S4+S2*S4*S8-S2*S7*S5+S3*S7*S4-S3*S3*S8
    B=S1*S7*S5-S1*S4*S8+S6*S4*S3-S6*S2*S5+S3*S2*S8-S3*S7*S3
    C=S1*S3*S8-S1*S7*S4+S2*S7*S3-S2*S2*S8+S6*S2*S4-S6*S3*S3
    A=A/DET
    B=B/DET
    C=C/DET
    S10=0.
    DO 20 I=1,N
    ELG=ALOG(G(I))
    ELV=ALOG(V(I))
    RDG=G(I)*G(I)/(DG(I)*DG(I))
    X=ELG-A-B*ELV-C*ELV*ELV
20 S10=S10+X*X*RDG
    PRINT 21
  21 FORMAT (//38H          A          B          C          CHI)
    PRINT 30,A,B,C,S10
  30 FORMAT (//4F10.3,5X,E10.0)
    PRINT 55
  55 FORMAT (//24H          FITTED CURVE)

```

```
V(1)=.3
DO 50 I=1,15
ELV=ALOG(V(I))
ELG=A+8*ELV+C*ELV*ELV
GF=EXP(ELG)
RGM=SQRT(1.-V(I)*V(I))
IF (RGM) 51,52,51
51 PP=938.2I*V(I)/RGM
GO TO 54
52 PP=9999.
54 PRINT 56,V(I),GF,ELV,ELG,PP
56 FORMAT (2F10.3,2F10.4,F10.0)
50 V(I+1)=V(I)+.05
GO TO 1
END
```



JOB H26106 GULSEN ONENGUT

EXEC FFORTRAN

IMPLICIT REAL*8 (A-H,O-Z)

DIMENSION EP(10),EPI(10),PP(11),PPI(11),TETA(11),B(10),C(10),
 ID(10),DELPP(10),DELPP(10),E(10),DELT(10),ALPHA(11),SKI(11),
 ZA(10),AA(10),AB(10),AC(10),SA(11),SB(11),SC(11),SD(11),CT(10),
 3ST(10),TE(10),TET(11)

12 READ(1,1) W,K,S,P,Y,X,Z,L,M,V,T,EG,PAP,PAPI,DELXP,DELZP2,PG,PGZ,
 IDELXPI,DEZPI2,PIG,PIGZ,RAN,EN

1 FORMAT (A1,I1,F3.0,F1.0,2F3.1,F3.3,I1,I1,F4.0,F3.0,F4.2,2F4.1,
 IF3.0,3F4.0,F3.0,3F4.0,F5.0,F9.0)

IF(Z-0.05) 12,901,901

01 IF(Z-0.95) 902,902,12

02 IF(K-5) 80,80,12

41 READ(1,144) W,K,S,P,Y,X,Z,L,M,V,T8,EG8,PAP8,PAPI8,DELXP8,DELZP8,PG
 18,PGZ8,ELXPI8,ELZPI8,PIG8,PIGZ8,RAN,EN

44 FORMAT(A1,I1,F3.0,F1.0,2F3.1,F3.3,I1,I1,F4.0,F3.0,F4.2,2F4.1,F3.0,
 13F4.0,F3.0,3F4.0,F5.0,F9.0)

IF(K-5) 146,80,80

46 T=T8

EG=EG8

PAP=PAP8

PAPI=PAPI8

DELXP=DELXP8

DELZP2=DELZP8

PG=PG8

PGZ=PGZ8

DELXPI=ELXPI8

DEZPI2=ELZPI8

PIG=PIG8

PIGZ=PIGZ8

80 IF (PAP-PAPI) 2,2,3

2 ALPH=PAPI-PAP

GO TO 311

3 ALPH=PAP-PAPI

11 IF(180.0-ALPH) 50,50,51

50 ALP=(360.0-ALPH)*3.1416/180.

GO TO 15

51 ALP=ALPH*3.1416/180.

15 SHR FAC=1260./T

CALP=DCOS(ALP)

SALP=DSIN(ALP)

DELZP=DELZP2*SHR FAC

DELZPI=DEZPI2*SHR FAC

IF(DELZP) 25,26,26

25 DIVP=DABS(DELZP/DELXP)

DELP=DATAN(DIVP)

SIP=-DSIN(DELP)

GO TO 24

26 DELP=DATAN(DELZP/DELXP)

SIP=DSIN(DELP)

24 IF(DELZPI) 27,28,28

27 DIVPI=DABS(DELZPI/DELXPI)

DELPI=DATAN(DIVPI)

SIPI=-DSIN(DELPI)

GO TO 30

E 1

```

28 DELPI=DATAN(DELZPI/DELXPI)
   SIPI=DSIN(DELPI)
30 RA=SIP*SIPI
   COPI=DCOS(DELPI)
   COP=DCOS(DELPI)
   RAB=RA+COPI*COP*CALP
   IF(RAB) 31,32,32
31 ABSRA=DABS(RAB)
   TETAZ=3.1416-DARCOS(ABSRA)
   GO TO 34
32 TETAZ=DARCOS(RAB)
34 GP=COP*PG/(PGZ*(EG/100.))
59 AL=DLOG(GP)
   ALBP=-((2.157-DSQRT(2.157*2.157+4.*0.554*(-0.311-AL)))/(2.*0.554)
   BP=DEXP(ALBP)
   PPZ=938.3*BP/(DSQRT(1.-BP*BP))
   AS=((1115.58*1115.58-938.256*938.256-139.579*139.579)/2.
   PP(1)=PPZ
   TETA(1)=TETAZ
64 ERGP=1./PG+1./(100.*EG)
66 ERBP=ERGP/((-2.157-1.108*DLOG(BP))*(-2.157-1.108*DLOG(BP)))
   ERP=ERBP/((1.-BP*BP)*(1.-BP*BP))
   ERX=(2./126.)*(2./126.)
   ERZP=(4./DELZP)*(4./DELZP)
   YP=DELXP*DELXP+DELZP*DELZP
   YPNA=DELXP*DELXP*DELXP*DELXP*DELZP*DELZP
   YPNB=DELP*DELP*COP*COP
   YPNC=YP*YP*YP
   ERDELP=YPNA*(ERZP+ERX)/(YPNC*YPNB)
   ERZPI=(4./DELZPI)*(4./DELZPI)
   YPI=DELXPI*DELXPI+DELZPI*DELZPI
   YPINA=DELXPI*DELXPI*DELXPI*DELXPI*DELZPI*DELZPI
   YPINC=YPI*YPI*YPI
   YPINB=DELPI*DELPI*COPI*COPI
   ERDEPI=YPINA*(ERZPI+ERX)/(YPINC*YPINB)
   ERA=(0.1*3.1416/180.)/ALP
   ERAL=ERA*ERA
   ABA=SIP*COPI*CALP-COP*SIPI
   IF(TETAZ-3.1416/2.) 35,35,36
35 SITEZ=DSIN(TETAZ)
   GO TO 37
36 SITEZ=DSIN(3.1416-TETAZ)
37 A1=DELP*ABA/(TETAZ*SITEZ)
   ACA=COP*SIPI*CALP-SIP*COPI
   A2=DELP*ACA/(TETAZ*SITEZ)
   ADA=ALP*COP*COPI*SALP
   A3=ADA/(TETAZ*SITEZ)
   IF(K-5) 176,151,715
76 IF(PIG) 12,141,161
51 GPI8=COPI*PIG8/(PIGZ8*(EG8/100.))
   GPI=(GPI*PIGZ+GPI8*PIGZ8)/(PIGZ+PIGZ8)
   GO TO 162
61 GPI=COPI*PIG/(PIGZ*(EG/100.))
62 APL=DLOG(GPI)
   ALBI=-((2.157-DSQRT(2.157*2.157+4.*0.554*(-.311-APL)))/(2.*.554)
E 2

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BPI=DEXP(ALBI)
IF(1.-BPI*BPI) 12,12,13
13 PPIZ=139.58*BPI/(DSQRT(1.-BPI*BPI))
C2=-2.157-1.108*DLOG(BPI)
IF(K-5) 168,167,12
67 ERGPI=1./(PIG+PIG8)+1./(100.*EG)
GO TO 169
68 ERGPI=1./PIG+1./(100.*EG)
69 ERBPI=ERGPI/(C2*C2)
ERPI=ERBPI/((1.-BPI*BPI)*(1.-BPI*BPI))
ERP I=ERPI*PPIZ*PP IZ
GO TO 720
15 ARAN=DLOG10(RAN)
EV=0.58*ARAN-0.947
ENER=10.**EV
PPIZS=ENER*(ENER+2.*139.579)
PPIZ=DSQRT(PPIZS)
ERR=(1./63.)*(1./63.)
ERRO=0.58*(ENER+139.579)/PPIZS
ERPI=ERRO*ERRO*ERR
20 ERT=A1*A1*ERDEL P+A2*A2*ERDEPI+A3*A3*ERAL
ERT=ERT*TETAZ*TETAZ
PPI(1)=PPIZ
DO 8 I=1,10
EP(I)=DSQRT((PP(I))* (PP(I))+938.256*938.256)
EPI(I)=DSQRT((PPI(I))* (PPI(I))+139.579*139.579)
CT(I)=DCOS(TETA(I))
ST(I)=DSIN(TETA(I))
B(I)=(PPI(I))* (CT(I))- (PP(I))* (EPI(I))/EP(I)
C(I)=(PP(I))* (CT(I))- (PPI(I))* EP(I)/EPI(I)
D(I)=(PP(I))* (PPI(I))
20 DELPPI(I)=PPIZ-PPI(I)
DELPP(I)=PPZ-PP(I)
DELT(I)=TETAZ-TETA(I)
22 E(I)=(EP(I))* (EPI(I))
A(I)=AS+(D(I))* (CT(I))-E(I)+(B(I))* (DELPP(I))
AA(I)=(C(I))* (DELPPI(I))- (D(I))* (ST(I))* (DELT(I))
AB(I)=(B(I))* (B(I))* ERP+(C(I))* (C(I))* ERPI
AC(I)=(D(I))* (D(I))* (ST(I))* (ST(I))* ERT
ALPHA(I+1)=(A(I)+AA(I))/(AB(I)+AC(I))
PP(I+1)=PPZ-ERP*(ALPHA(I+1))* (B(I))
PPI(I+1)=PPIZ-ERPI*(ALPHA(I+1))* (C(I))
TETA(I+1)=TETAZ+ERT*(D(I))* (ST(I))* (ALPHA(I+1))
TET(I+1)=(TETA(I+1))*180./3.1416
SA(I+1)=(PP(I+1)-PPZ)*(PP(I+1)-PPZ)/ERP
SB(I+1)=(PPI(I+1)-PPIZ)*(PPI(I+1)-PPIZ)/ERPI
SC(I+1)=(TETA(I+1)-TETAZ)*(TETA(I+1)-TETAZ)/ERT
SD(I+1)=2.*(ALPHA(I+1))* (AS+(D(I))* (CT(I))-E(I))
8 SKI(I+1)=SA(I+1)+SB(I+1)+SC(I+1)
PPIP=COPI*PPI(11)
PPP=(PP(11))*COP
DETPLP=PPIP*PPIP+PPP*PPP+2*PPIP*PPP*CALP
PLP=DSQRT(DETPLP)
PAPI2=3.1416*PAPI/180.
PAP2=3.1416*PAP/180.
CPAPI=DCOS(PAPI2)

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SPAPI=DSIN(PAPI2)
SPAP=DSIN(PAP2)
CPAP=DCOS(PAP2)
PX=PPP*CPAP+PPI*CPAPI
PY=PPP*SPAP+PPI*SPAPI
J=Y
YI=J
PIT=(YI-90.)*3.1416/180.
CTEL=PX/PLP
IF(CTEL-1.) 181,182,182
181 TELI=DARCOS(CTEL)
GO TO 183
182 TELI=0.
183 IF(PY) 180,185,185
180 TEL=PIT-TELI
GO TO 190
85 TEL=PIT+TELI
90 DETPL=(PPI(11))*(PPI(11))+(PP(11))*(PP(11))
DETPL=DETPL+2.*(PPI(11))*(PP(11))*(CT(10))
PL=DSQRT(DETPL)
SDELL=((PP(11))*SIP+(PPI(11))*SIPI)/PL
TW=20.*3.1416/180.
CTW=DCOS(TW)
STW=DSIN(TW)
DELL=DARSIN(SDELL)
CDELL=DCOS(DELL)
CTEL=DCOS(TELI)
STEL=DSIN(TELI)
ULX=CDELL*CTEL*CTW-SDELL*STW
ULY=CDELL*STEL
ULZ=SDELL*CTW+CDELL*CTEL*STW
ZZ=(P-5.5+Z)*1.26
XZA=110.+2.*(X-55.)
XZ=XZA*CTW-ZZ*STW
YZ=(Y-90.)*(3.1416/180.)*XZA
ZZ=ZZ*CTW+XZA*STW
BCD=ULZ*ZZ+ULY*YZ
BC=ULY*ULY+ULZ*ULZ
XF=XZ-ULX*BCD/BC
YF=YZ-ULY*BCD/BC
ZF=ZZ-ULZ*BCD/BC
TEL=TEL*180./3.1416
DELL=DELL*180./3.1416
IF(PIT) 200,205,205
00 PIT=-PIT
CPIT=DCOS(PIT)
SPIT=-DSIN(PIT)
GO TO 210
05 CPIT=DCOS(PIT)
SPIT=DSIN(PIT)
10 COP2=CPIT*CPAP-SPIT*SPAP
SIP2=CPIT*SPAP+SPIT*CPAP
PX=(COP2*COP*CTW-SIP*STW)*(PP(11))
PY=COP*SIP2*(PP(11))
PZ=(SIP*CTW+COP2*COP*STW)*(PP(11))
PXP=ULX*PX+ULY*PY+ULZ*PZ

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PPD=ULZ*ULZ+ULY*ULY
PPD=DSQRT(PPD)
PYP=(PY*ULZ-PZ*ULY)/PPD
PZP=-PX*PPD+(PY*ULX*ULY+PZ*ULX*ULZ)/PPD
EPS=(PP(11))*(PP(11))+938.256*938.256
EP2=DSQRT(EPS)
ELS=PL*PL+1115.58*1115.58
EL=DSQRT(ELS)
BEL=PL/EL
GALDS=1.-BEL*BEL
GALD=DSQRT(GALDS)
GAL=1./GALD
PXP=GAL*(PXP-BEL*EP2)
CPP=PXP*PXP+PYP*PYP+PZP*PZP
CPP=DSQRT(CPP)
SSI=PZP/CPP
SSI=DABS(SSI)
TT=PXP/PYP
IF(TT) 230,235,235
230 IF(PYP) 240,245,245
240 TCM=3.1416-DATAN(-TT)
GO TO 250
245 TCM=2.*3.1416-DATAN(-TT)
GO TO 250
235 IF(PYP) 255,260,260
255 TCM=3.1416+DATAN(TT)
GO TO 250
260 TCM=DATAN(TT)
250 TCM=TCM*180./3.1416
EI=1050.*1050.+139.579*139.579
EI=DSQRT(EI)
DE2=EI+938.256-EL
DE2=DE2*DE2
P4=1050.-PL*ULX
P5=P4*P4+PL*PL*(ULY*ULY+ULZ*ULZ)
DEL=DE2-P5-497.87*497.87
204 IF(SKI(11)-25.) 501,142,142
201 YF=DABS(YF)
ZF=DABS(ZF)
XF=DABS(XF)
IF(XF-24.) 506,142,142
206 IF(YF-8.) 502,142,142
202 IF(ZF-1.) 503,142,142
203 IF(PL-450.) 142,505,505
205 IF(800.-PL) 142,561,561
261 IF(SSI-0.91) 562,562,142
262 D7=0.1*BCD/BC
P7=20.*4.80298*D7/(BEL*938.256*1.6021)
WRITE(2,7) S,X,Y,Z,P7,TCM,EN
7 FORMAT(F5.0,2F5.1,F6.3,F8.4,F10.4,F5.0)
242 IF(PIG-400.) 141,12,12
END
ID OF DATA
IE 5

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      READ(1,1) N
1  FORMAT(I4)
      DIMENSION S(1360),P7(1360),TCM(1360),FLE(1360),FLO(1360),A(45),
1 FL(1360),C(55),C2(55)
      DO 5 I=1,N
      READ(1,3) S(I),P7(I),TCM(I)
3  FORMAT(F5.0,16X,F8.4,F10.4)
5  TCM(I)=TCM(I)*3.1416/180.
      A(I)=0.40
      C(I)=0.40
      DO 20 J=1,40
      WRITE(3,6) A(J)
6  FORMAT(8H      AP=,F5.2,20H      MU      LLF  )
      DO 19 K=1,50
      FFLLE=0.
      FFLLO=0.
      DO 18 I=1,N
22 C2(K)=C(K)*P7(I)
      L=S(I)/2.
      P=S(I)/2.
      E=L
      IF(P-E) 11,11,12
11 FL(I)=1.+A(J)*COS(TCM(I)+C2(K))
      FLE(I)=FL(I)/(2.*3.1416)
      FFLLE=FFLLE+ALOG(FLE(I))
      GO TO 18
12 FL(I)=1.+A(J)*COS(TCM(I)-C2(K))
21 FLO(I)=FL(I)/(2.*3.1416)
      FFLLO=FFLLO+ALOG(FLO(I))
18 CONTINUE
      FFLL=FFLLE+FFLLO
      WRITE(3,15) C(K),FFLLO,FFLLE,FFLL
15 FORMAT(10X,F6.2,5X,F12.4,5X,F12.4,5X,F12.4)
19 C(K+1)=C(K)+.01
20 A(J+1)=A(J)+.01
      STOP
      END
    
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DIMENSION ALPHA(181),TETA(181),PLLAB(181),ELLAB(181),BETAL(18
11),GAMA(181)
AKM=497.76
ALM=1115.6
PM=938.259
PIP=1050.
PIM=139.579
PIE=PIP*PIP+PIM*PIM
PIE=SQRT(PIE)
BETA=PIP/(PIE+PM)
BETAS=BETA*BETA
BETAS=1.-BETAS
BETAS=SQRT(BETAS)
GAMMA=1./BETAS
CMSE=GAMMA*(PIE+PM-BETA*PIP)
CMSES=CMSE*CMSE
AKMS=AKM*AKM
ALMS=ALM*ALM
ELCMS=(CMSES+ALMS-AKMS)/(2.*CMSE)
PLCMS=SQRT(ELCMS*ELCMS-ALMS)
WRITE(3,1) BETA,GAMMA,CMSE
1 FORMAT(1X,5HBETA=,F5.3,3X,6HGAMMA=,F6.3,3X,11HCMS ENERGY=,F8.3)
WRITE(3,2) ELCMS,PLCMS
2 FORMAT(/1X,15HLAMBDA CMS EN.=,F8.3,3X,16HLAMBDA CMS MOM.=,F7.3)
ALPHA(1)=0.
DO 3 I=1,181
CA=COS(ALPHA(I))
SA=SIN(ALPHA(I))
PLCMSY=PLCMS*SA
PLCMSX=GAMMA*(PLCMS*CA+BETA*ELCMS)
TANT=PLCMSY/PLCMSX
TETA(I)=ATAN(TANT)
CT=COS(TETA(I))
PLLAB(I)=PLCMSX/CT
PLLABS=PLLAB(I)*PLLAB(I)
ELLAB(I)=SQRT(ALMS+PLLABS)
BETAL(I)=PLLAB(I)/ELLAB(I)
BETS=BETAL(I)*BETAL(I)
BETS=SQRT(1.-BETS)
GAMA(I)=1./BETS
3 ALPHA(I+1)=ALPHA(I)+3.1416/180.
WRITE(3,4)
4 FORMAT(/62H ALPHA TETA LAMBDA MOMENTUM LAMBDA ENERGY BETA
1 GAMMA)
DO 5 I=1,181
TETA(I)=TETA(I)*180./3.1416
ALPHA(I)=ALPHA(I)*180./3.1416
WRITE(3,6) ALPHA(I),TETA(I),PLLAB(I),ELLAB(I),BETAL(I),GAMA(I)
6 FORMAT(2X,F7.3,5X,F7.3,2X,F8.3,2X,F8.3,2X,F5.3,3X,F6.3)
WRITE(2,6) ALPHA(I),TETA(I),PLLAB(I),ELLAB(I),BETAL(I),GAMA(I)
5 CONTINUE
END

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DIMENSION ALPHA(182),TETAP(181),PPLAB(181),TETAPI(181),PPILAB(181)
ALM=1115.6
PM=938.259
PIM=139.579
ALMS=ALM*ALM
PMS=PM*PM
PIMS=PIM*PIM
EPCM=(ALMS+PMS-PIMS)/(2.*ALM)
EPICM=ALM-EPCM
EPCMS=EPCM*EPCM
EPICMS=EPICM*EPICM
PPCMS=EPCMS-PMS
PPCM=SQRT(PPCMS)
PPICMS=EPICMS-PIMS
PPICM=SQRT(PPICMS)
WRITE(3,2) EPCM,EPICM,PPCM,PPICM
2 FORMAT(1X,18HPROTON CMS ENERGY=,F6.2,2X,16HPION CMS ENERGY=,F6.2,2
1X,15HPROTON CMS MOM=,F6.2,2X,13HPION CMS MOM=,F6.2)
WRITE(3,5)
5 FORMAT(/69H ALPHA PR. ANG. PR. MOM. PI. ANG.
1 PI. MOM )
8 READ(1,1) GAMMA,BETA
1 FORMAT(1X,F5.3,1X,F5.3)
ALPHA(1)=0.
DO 4 I=1,181
CA=COS(ALPHA(I))
SA=SIN(ALPHA(I))
PPCMY=PPCM*SA
PPCMX=GAMMA*(PPCM*CA+BETA*EPCM)
TANTP=PPCMY/PPCMX
TETAP(I)=ATAN(TANTP)
CTP=COS(TETAP(I))
PPLAB(I)=PPCMX/CTP
PPICMY=PPICM*SA
PPICMX=GAMMA*(PPICM*CA+BETA*EPICM)
TANTPI=PPICMY/PPICMX
IF (PPICMY) 3,3,20
20 IF (PPICMX) 6,6,9
9 TETAPI(I)=ATAN(TANTPI)
GO TO 10
6 TANTPI=-TANTPI
TETAPI(I)=3.1416-ATAN(TANTPI)
GO TO 10
3 IF(PPICMX) 11,11,12
11 TETAPI(I)=3.1416+ATAN(TANTPI)
GO TO 10
12 TANTPI=-TANTPI
TETAPI(I)=2.*3.1416-ATAN(TANTPI)
10 CTPI=COS(TETAPI(I))
PPILAB(I)=PPICMX/CTPI
TETAP(I)=TETAP(I)*180./3.1416
TETAPI(I)=TETAPI(I)*180./3.1416
ALPHA(I)=ALPHA(I)*180./3.1416
WRITE(3,7) ALPHA(I),TETAP(I),PPLAB(I),TETAPI(I),PPILAB(I)

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7 FORMAT(4X,F5.1,7X,F7.3,8X,F8.3,7X,F7.3,7X,F8.3)

4 ALPHA(I+1)=(ALPHA(I)+1.)*3.1416/180.

GO TO 8

END

