

**DEVELOPMENT OF A DECISION SUPPORT SYSTEM FOR
PERFORMANCE-BASED LANDFILL DESIGN**

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I hereby declare that all information in this document has been obtained and presented in accordance with academic rules and ethical conduct. I also declare that, as required by these rules and conduct, I have fully cited and referenced all material and results that are not original to this work.

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ABSTRACT

DEVELOPMENT OF A DECISION SUPPORT SYSTEM FOR PERFORMANCE-BASED LANDFILL DESIGN

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Performance-based landfill design approach is a relatively new design approach adopted recently in solid waste management and applied in USA, European Union countries and some developing-economy countries like South Africa. This approach rejects the strict design criteria and accommodates a design that selects the most appropriate design components of a landfill (final cover, bottom liner, and leachate collection system) and their design details to result in the best overall performance with respect to performance criteria (groundwater contamination and stability) considering the system variables (climatic conditions of the site, site hydrogeology, and size of the landfill). These design components, performance criteria and design variables involved in decision process make performance-based landfill design a complex environmental problem. Decision support systems

(DSS) are among the most promising approaches to confront this complexity. The fact that different tools can be integrated under different architectures confers DSSs ability to confront complex problems, and capability to support decision-making processes. In this thesis study, a DSS to aid in the selection of design components considering the design variables and performance criteria for performance-based landfill design was developed. System simulation models and calculation modules were integrated under a unique DSS architecture. A decision support framework composed of preliminary design and detailed design phases were developed. The decision of appropriate design components leading to desired performance was made based on stability issues and vulnerability of groundwater, using knowledge gathered from DSS. Capabilities and use of the developed DSS were demonstrated by one real and one hypothetical landfill case studies.

Keywords: landfill modeling, performance-based design, decision support system, system simulation models

ÖZ

PERFORMANS-BAZLI KATI ATIK DEPOLAMA SAHASI İÇİN KARAR DESTEK SİSTEMİ GELİŞTİRİLMESİ

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Performans-bazlı katı atık depolama sahası tasarımı, son yıllarda katı atık yönetiminde benimsenen, ABD, AB ülkeleri ve Güney Afrika gibi ekonomisi gelişmekte olan ülkelerde uygulanan yeni bir tasarım yaklaşımıdır. Bu yaklaşım “tek-tip”çi tasarım anlayışını reddetmekte ve katı atık depolama sahası tasarım elemanlarını (üst örtü, depolama tabanı ve sızıntı suyu toplama sistemi) ve bunların tasarım detaylarını, performans ölçütlerine göre (yer altı suyu kirliliği ve stabilite) en iyi performansı sağlayacak şekilde ve sistem değişkenlerine (iklim, saha hidrojeolojisi ve atık yüküne bağlı olarak depolama sahasının boyutu) uygun olarak seçen bir tasarım yaklaşımı sunmaktadır. Karar mekanizmasında yer alan tasarım elemanları, performans ölçütleri ve tasarım değişkenleri performans-bazlı katı atık depolama sahası tasarımını karmaşık bir çevresel problem haline

getirmektedir. Karar destek sistemleri (KDS) bu karmaşıklığı gidermede en çok ümit vaat eden yaklaşımların başında gelmektedir. İstatistiksel/nümerik yöntemler, ve coğrafi bilgi sistemleri gibi araçların farklı mimarilerde entegre edilebiliyor olması da KDS'nin karmaşık problemleri çözme ve karar verme mekanizmalarını desteklemektedir. Bu tez çalışmasında, performans-bazlı katı atık depolama sahası tasarımı için tasarım elemanlarının, sistem değişkenleri ve performans ölçütlerini göz önüne alarak seçimine yardımcı olacak bir KDS geliştirilmiştir. Sistem simülasyon modelleri, tasarım modeli ve hesaplama modülleri özgün bir KDS mimarisinde birleştirilmiştir. Ön tasarım ve ayrıntılı tasarım aşamalarından oluşan iki aşamalı bir KDS geliştirilmiştir. İstenen performansı sağlayacak olan tasarım bileşenlerinin seçimi stabilite ve yer altı suyunun varlığı ve hassasiyetiyle ilgili kaygılar göz önünde bulundurularak, KDS'den elde edilen bilgi ve verilere dayanarak gerçekleştirilecektir, Geliştirilen KDS'nin kullanımı bir gerçek bir de varsayıma dayanan örnek saha üzerinde gösterilmiştir.

Anahtar Kelimeler: katı atık depolama sahası modellemesi, performans-bazlı tasarım, karar destek sistemi, sistem simülasyon modelleri

To my little son ınar and beloved husband Ahmet...

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ABBREVIATIONS

2D	Two-dimensional
3D	Three-dimensional
CCL	Compacted clay liner
CDS	Cover drainage system
Cl ⁻	Chloride ion
CSV	Comma separated value
CX	Final cover design alternatives (C1, C2, C3)
DEM	Digital elevation model
DSS	Decision support system
ET	Evapotranspiration final cover
FS	Factor of safety value
GIS	Geographic information systems
GM	Geomembrane
GUI	Graphical user interface
LCS	Leachate collection system
LFDSS	Landfill Decision Support System
LX	Bottom liner design alternatives (L1, L2, L3, L4, L5, L6)
MacOS	Macintosh Operating System
MS	Microsoft
RDM	Regional data map
SSM	System simulation model
VLF	Virtual Landfill

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CHAPTER 1

INTRODUCTION

1.1. The Landfill System

A sanitary landfill is an engineered waste disposal system. In a broad sense, it is composed of a cover system (to minimize the moisture entrance into the system due to precipitation), waste contained, and a barrier system (to minimize leakage to the underlying soil and aquifer). The landfill is the first component of the landfill system. The other two components are soil (onto which the landfill is constructed) and aquifer (water containing and yielding formation) below the soil layer. Schematic view of a landfill system, together with its processes and components are shown in Figure 1.1.

Because "contamination-causing" or "alien" factor in this system is the sanitary landfill, the engineering properties of the landfill are of highest concern with respect to its impacts to the whole landfill system. Therefore, the components of a sanitary landfill should be identified in the first place.

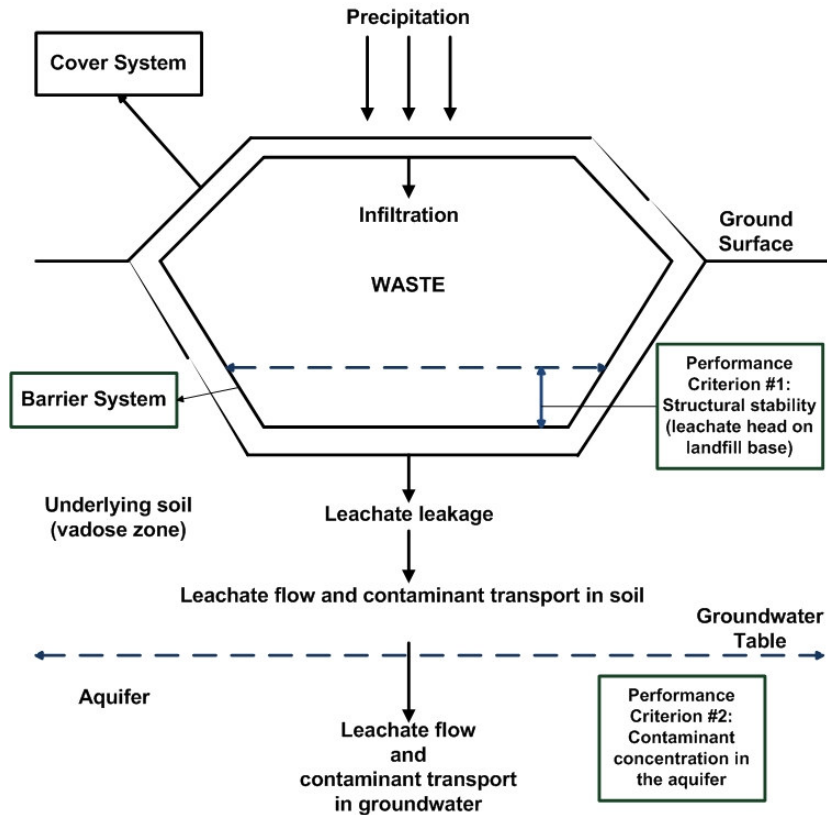


Figure 1. 1 Landfill scheme

Cover system (final cover) aims to minimize/control the moisture entrance to the landfill due to precipitation, as well as it protects the landfill from wind or soil actions and also protects the environment from the nuisance that can be caused by the landfill content. The cover system can be composed of vegetation layers, gas and leachate drainage layers, clay or mineral liners and synthetic liners. *Barrier system* (bottom liner) aims to minimize leakage to the underlying soil or aquifer, as well as providing a strong base to the landfill. It can be composed of leachate collection pipes and layers, clay or mineral liners, and synthetic liners. Soil and aquifer are the “natural” components of the landfill which are prone to the consequences of the landfill processes. Therefore, it is quite important to design a landfill that will result in the minimum possible contamination to the underlying soil and aquifer.

Performance-based solid waste landfill design is an approach that enables the determination of the most appropriate landfill design components for the site and waste conditions providing the desired performance with minimal design details and low cost. With this design approach, the most appropriate design components of a landfill are selected to result in the best overall performance with respect to performance criteria considering the system variables. Design variables are climatic conditions of the site, site hydrogeology, waste thickness and size of the landfill with respect to waste load. Performance criteria are defined as maintaining a desired groundwater quality at the groundwater table, and not exceeding a predefined maximum leachate head on the bottom of the landfill at all times for cover and waste stability reasons. The design components are the final cover, leachate collection and bottom liner systems of the landfill. In this study, layers that do not effect leachate leakage into or from the landfill, such as gas drainage layers or protective liners, are not considered as components of cover (final) or barrier (bottom liner) systems. For the proposed methodology, a cover system can be composed of one of the three alternatives:

- i. natural attenuation/*evapotranspiration* “*ET*” cover –only natural soil;
- ii. intermediate cover –drainage system coupled with compacted clay liner;
- iii. extensive engineering cover –leachate collection system coupled with a compacted clay liner and a geomembrane.

Similarly, a barrier system can consist of one or a combination of the following:

- i. a natural attenuation barrier –only natural soil/aquitard;
- ii. a leachate collection system;
- iii. a geomembrane in the barrier system;
- iv. a compacted clay liner in the barrier system.

1.2. Objectives and Scope

This thesis study aims to develop a decision support system to aid in the selection of design components considering the design variables and performance criteria for a performance-based landfill design. System simulation software models, a landfill base contour design model and calculation modules are aimed to be joined in DSS architecture. The decision of the design components leading to the best performance-based landfill design is made considering the knowledge, data and information gathered from the DSS.

The study is composed of two phases. Phase-I (base line studies) consists of four steps: (i) development of a conceptual model; (ii) selection of the appropriate system simulation models; i.e., final cover design model, and bottom liner design and subsurface transport model; (iii) determination of performance criteria for the evaluation of landfill design alternatives; and (iv) construction of the design component selection matrix. Phase-I intends to propose various landfill design alternatives considering the design variables and the performance criteria. The design component selection matrix is a design guidance and an input for the decision support system, to serve as a knowledge-base.

Phase-II (DSS development studies) also consists of four steps: (i) determination of the level of integration for the simulation models that constitute DSS, (ii) development of the landfill base contour design model (i.e. Virtual Landfill – VLF) and calculation modules (i.e. waste and landfill volume, landfill stability, and major cost estimation modules), (iii) development of a DSS that accommodates system simulation models, landfill base contour design model and calculation modules; and (iv) application of the developed DSS to implement a performance-based landfill design. The purpose of Phase-II is to ease the decision process, which is composed of two steps. At the first step, appropriate design alternatives are identified and proposed by the knowledge-base (design

component selection matrix). Then, the proposed alternatives are analyzed by system simulation software and calculation modules using site-specific values at the final landfill design phase. The selection of the suitable landfill design alternative(s) for the particular site is achieved by utilizing an automated system; namely, the decision support system.

In 2006, "Urban Solid Waste Management Strategic Plan" was prepared by the Ministry of Environment and Forestry in order to propose a solution to the solid waste problems of Turkey. According to the strategic plan, approximately 120 regional solid waste management complexes are proposed to be built in the midterm. The strategic plan clearly demonstrates a major requirement of solid waste landfills and points out that approximately 120 landfills will be constructed. In the context of the Strategic Plan, type-projects are planned to be developed regarding the needs of different regions in Turkey (MIMKO, 2006). The DDS developed in this study can be a useful tool to develop proposed type-projects by allowing the design of well-performing regional landfills at feasible costs.

Performance-based landfill design deals with numerous design variables, and design components to result in the predefined performance criteria. The interactions between these variables make the performance-based landfill design a complex environmental problem. Decision support systems can handle this complexity and guide the user in the selection of the best-performing design components of a landfill, under given design variables. However, as far as the author's knowledge is concerned, a landfill decision support system has not been reported in the literature, yet. Therefore in this study, a holistic landfill DSS is aimed to be designed to: (i) propose various design alternatives with respect to general design variables of a site, (ii) design the landfills starting from waste volume calculation, base contour design, and orienting the landfill with respect to natural in situ clay layer at the landfill base and the position of groundwater and flow direction, and (iii) simulate the proposed landfill designs using site-specific

values to produce performance, cost and stability based evaluations. To the best of our knowledge, the developed DSS is unique in its kind, and distinguished from the other DDS presented in the literature, by being a holistic landfill design system that simultaneously handles the design of final cover system, bottom liner system, and the subsurface contaminant transport; as well as evaluates the results produced by simulation and design models and calculation modules in order to provide the user with guidance on decision making.

The thesis is organized into the following chapters. Chapter 2, Literature Review, presents the literature on modeling and system simulation, decision support systems, particularly environmental decision support systems, system simulation models, stability in landfills, and variables affecting landfill performance. Chapter 3, Methodology, is divided into two sections. In the first part, development of the design methodology and the design component selection matrix are explained. In the second part, development of the decision support system is presented. Chapter 4, Results and Discussion, presents effect of design variables on the performance of landfill designs, performance and stability results of the landfill simulations, the design component selection matrix, and results of two cases. Chapter 5 summarizes the main findings of the study and provides the important conclusions that are drawn from the results of the study. Finally, Chapter 6 offers topics for future research to make further progress along the present study.

CHAPTER 2

LITERATURE REVIEW

2.1. Simulation and Modeling

Simulation and modeling provide a rapid means of investigating the expected response of a system to possible future changes, by undertaking the necessary computations which are commonly complex and data intensive. Model integration is an important goal because environmental management and studies are tending towards more holistic approaches. However, environmental models of different processes are seldom simple to link. To achieve model integration, existing models should be made fully accessible and integration software tools and standards should be provided. Object-oriented design, modular development and remodeling, the use of formalized modeling languages, development of integrated modeling frameworks and drag-and-drop style modeling environments are some of the practices that address to the aforementioned problems.

Specific for the purpose of this thesis study, there are environmental modeling software packages covering almost all environmental problem domains. Their number is growing fast due to the latest advances of computer technologies, allowing more complex models and simulations to be developed and run. These technologies can be complemented and run with geographic information systems (GIS) and expert systems (ES) by integrating them using a decision support

system (DSS) framework (Lukashev et al., 2001). The DSS and the methods for integration under a DSS framework are presented in the following sections.

2.2. Coupling Methodologies

When coupling models, it is important to identify the components required to link, resulting in a systems integration problem. There exist major obstacles to coupling models because of them being geography-specific or machine or library dependent; therefore, models often needed to be coupled in a heterogeneous, networked computing environment (Brandmeyer and Karimi, 2000). There have been many methodologies proposed by many researchers to come over these challenges. For example, Chou and Ding (1992) offered a cubic perspective using a data sharing method, a modeling method, and a user interface as the dimensions of the cube. However, some of the combinations, like shifting user interface and internal modeling cannot exist. A similar cubic approach also proposed by Lilbourne (1996), selecting functionality, interface, and integration as the dimensions. Nyerges (1992) developed four categories of coupling with GIS being isolated, loose, tight, and integrated. Loose coupling is the transfer of data between model and GIS. Tight coupling is the category in which either the model is embedded in GIS or GIS is embedded in the model. This methodology was also identified by Karimi and Houston (1996). Bivand and Lucas (2000) also presented four ways of linking GIS and modeling technologies similarly as loose coupling, tight coupling, system enhancement and full integration, with increasing degree of integration.

The synthesis of all the above approaches is presented by Brandmeyer and Karimi (2000), and this synthesized approach is widely accepted among modelers and researchers. They present five possible levels of integration: (1) one-way data transfer, (2) loose coupling (two-way data transfer), (3) shared coupling (sharing one component, graphical user interface –GUI or data storage), (4) joined

coupling (sharing both components), (5) tool coupling (coupling under a modeling framework) (Brandmeyer and Karimi, 2000; Adenso-Diaz et al., 2005). Figure 2.1 demonstrates the progression of coupling methodologies. In this pyramid, the first level shows that in one-way data transfer, the extent of modeler interaction with component models is at minimum. At the second step (loose coupling), automation of data transfer is achieved. Shared coupling represents the level in which a GUI is constructed on top of the two previous steps. At the fourth step (joined coupling) sharing of data storage is possible, and finally the most advanced level of integration, tool coupling, allows the presence of integration and modeling tools under a framework. The advantages and disadvantages of the five coupling methodologies are presented by Brandmeyer and Karimi (2000).

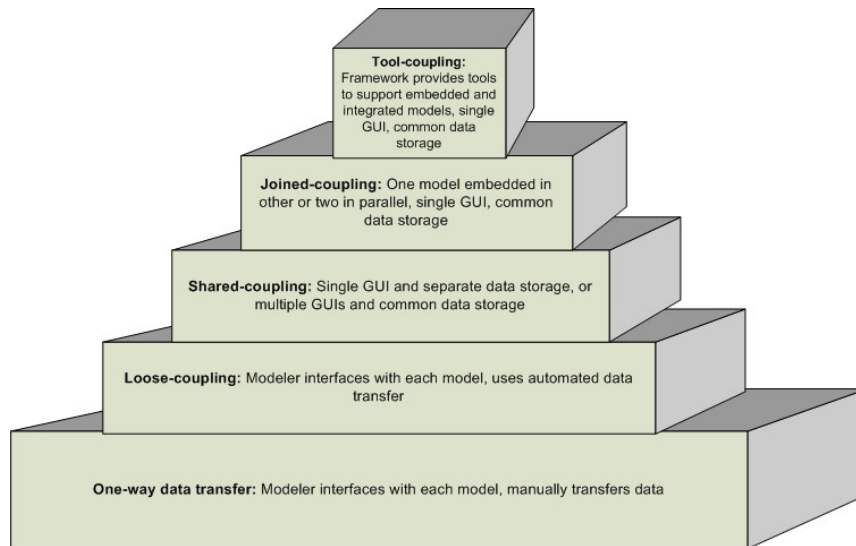


Figure 2.1 Progression of coupling methodologies (Brandmeyer and Karimi, 2000)

2.2.1. One-way Data Transfer

This level is presents a situation in which the only method for passing data is through a series of manual/non-automated transfer if models operate on binary data stored in different formats, are written in incompatible languages, and execute under different operating systems. Models remain completely separate at

this level, and coupling means the transfer of the output data of one model as an input to the other model (Brandmeyer and Karimi, 2000). This method is represented in Figure 2.2.

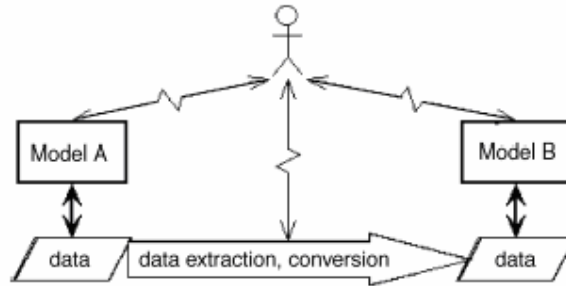


Figure 2. 2 One-way data transfer (Brandmeyer and Karimi, 2000)

2.2.2. Loose Coupling

Data may be interchanged automatically between models in a dynamic feedback during simulation. A series of steps involving extraction from one model's data structure and conversion to the other model's data structure is usually required. There are many examples of loosely coupled models in the literature like interface of GIS to SWAT hydrology model, GIS to CENTURY plant-soil ecosystem model, and a general circulation model (GCM) to a vegetation cover model (Brandmeyer and Karimi, 2000). Modeler interactions in loose coupling are shown in Figure 2.3.

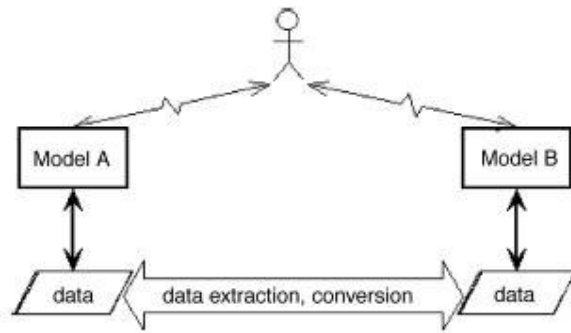


Figure 2. 3 Loose coupling (Brandmeyer and Karimi, 2000)

2.2.3. Shared Coupling

Models share a major component, either the graphical user interface (GUI) or data storage at this level. In GUI coupling, there is a single user interface linking the models, but the data is stored separately for each model. The modeler accesses to a virtual environment which the GUI provides, and does not deal with the locations or configurations of computer systems. The internal coupling method is hidden, making the models less confusing and more widely used. GUI coupling provides a user-friendly method of coupling (Brandmeyer and Karimi, 2000). In a project employing GUI coupling, Visual Basic provided a user interface for a GIS-based model and SWAT (Blodgett et al., 1995). In a Korean water quality study, GUI coupled two models and a spatial database (Kim et al., 1995).

In data coupling on the other hand, the user interacts directly with each model, but data files are shared by the models. This method is not frequently used because it requires models to share data storage and the proprietary nature of some models limit the ability of others to share data files. One way of sharing data is to use a published computer-dependent format such as Network Common Data Form (netCDF) or generic, object-oriented open data exchange system (GOODES). Also, the personal computer industry provides additional methods of data sharing like dynamic data exchange (DDE), Open Database Connectivity (ODBC), and object

linking and embedding (OLE). Unfortunately, none of these data-sharing methods currently supports all types of environmental modeling data, which are attribute data (integer, float, double, etc.), geospatial data (point, vector, volume, raster, etc.) and multimedia data (scanned images etc.) (Brandmeyer and Karimi, 2000). Two methods of shared coupling are demonstrated in Figure 2.4.

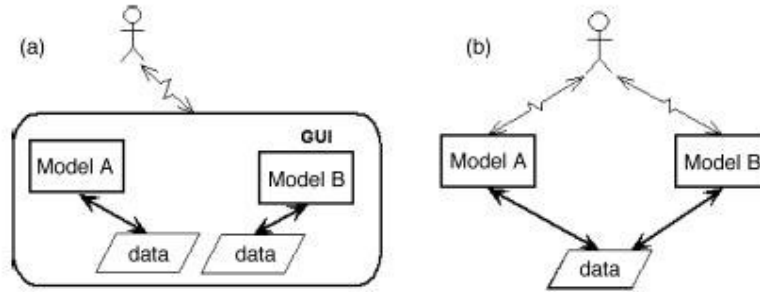


Figure 2. 4 Shared coupling (a) GUI coupling, (b) data coupling (Brandmeyer and Karimi, 2000)

2.2.4. Joined Coupling

The two coupling methodologies available at this level are embedded and integrated coupling. These methodologies use both the common GUI and common data storage but the structure of model interaction is different (Brandmeyer and Karimi, 2000). Methods of joined coupling are shown in Figure 2.5.

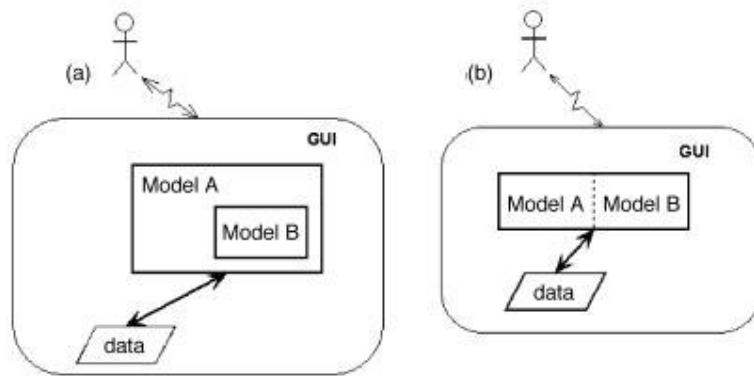


Figure 2. 5 Jointed coupling (a) embedded coupling, (b) integrated coupling (Brandmeyer and Karimi, 2000)

Simple mathematical models may be easily embedded when adequate programming language is available. In embedded coupling, the models are in a master-slave relationship and the master model contains the slave model. Through the GUI, the user only interacts with the master model. Examples of this coupling methodology usually deal with embedding models in GIS (Brandmeyer and Karimi, 2000).

In integrated coupling, each model is integrated (peer of) the other model. The interaction of user with any model is provided through the common GUI. Also, functions and subroutines of one model may be reused between integrated models, by the use of shared libraries (Brandmeyer and Karimi, 2000).

2.2.5. Tool Coupling

Models are coupled using an overall modeling framework, which uses both shared and jointed coupling, presenting a single GUI to the modeler and implementing shared data storage. The framework also provides functions and tools common to multiple models, manages data and computes resources (Brandmeyer and Karimi, 2000). This top-level methodology is presented in Figure 2.6.

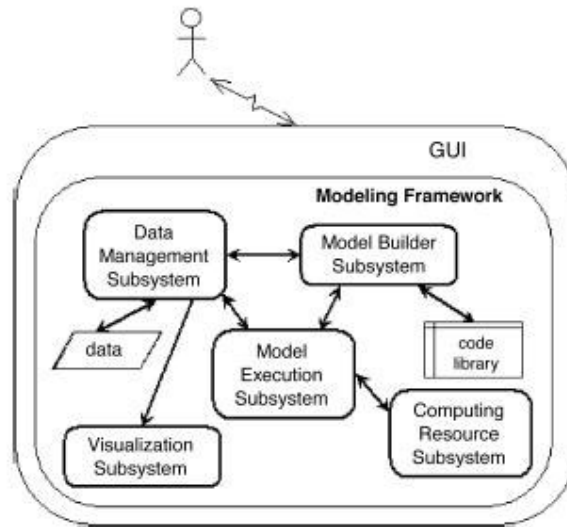


Figure 2. 6 Tool coupling (Brandmeyer and Karimi, 2000)

2.2.6. Challenges in Coupling Environmental Models

To be coupled, environmental models should have the capability with which two or more programs can share and process information regardless of their implementation language and platform. In another words, the models should be interoperable. Moreover, even though the models can share information, results will be meaningless if they do not have the same temporal or spatial scale. In this case, intermediate programs are required for scale conversions (Brandmeyer and Karimi, 2000).

In the framework of models, some models must be implemented to accept the output of another model as input (transformational mode); while in some cases the user may alter the input in an arbitrary manner (reactive mode). Moreover, the models may be originally implemented with different programming languages and software platforms. In this case, a program control that can understand and communicate with all of the models is required (Lam et al., 2004). During model integration, Lam et al. (2004) stated one of the most difficult challenges to hide

information not alterable by the user and to highlight model input parameters that the user may change. They pointed out the requirement of cautions and guards to guide the input by the user to satisfy model assumptions and restrictions.

2.3. Environmental Decision Support Systems (EDSS)

Software systems that integrate models, or databases, or other decision aids, and package them in a way that decision-makers can use are commonly referred to as Decision Support Systems (DSS) (Rizzoli and Young, 1997). A more comprehensive definition for DSS states that it is a computer system that assists decision-makers in choosing between alternative beliefs or actions by applying knowledge about the decision domain to arrive at recommendations for the various options. An Environmental Decision Support System (EDSS) is an intelligent system that reduces the time in which decisions are made in an environmental domain, and improves the consistency and quality of these decisions (Poch et al., 2003). In a closed definition, EDSS is a computer system that combines several technologies to help environmental researchers make environmental decisions. A spatial database represented by the GIS, a knowledge base represented by an expert system (ES), a model base combining several environmental simulation models (SM), and a user interface are components of any EDSS (Lukashev et al., 2001). Schematic of an EDSS shell and the building blocks of EDSS are shown in Figure 2.7 and 2.8 respectively.

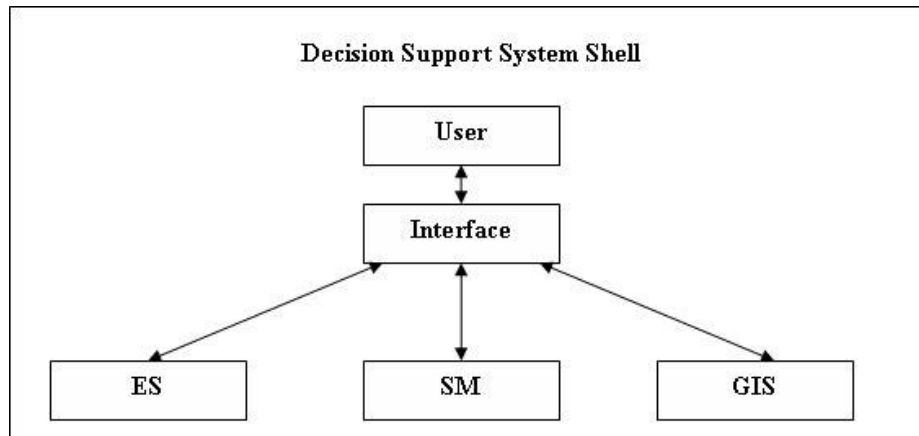


Figure 2. 7 Schematics of EDSS (Lukashev et al., 2001)

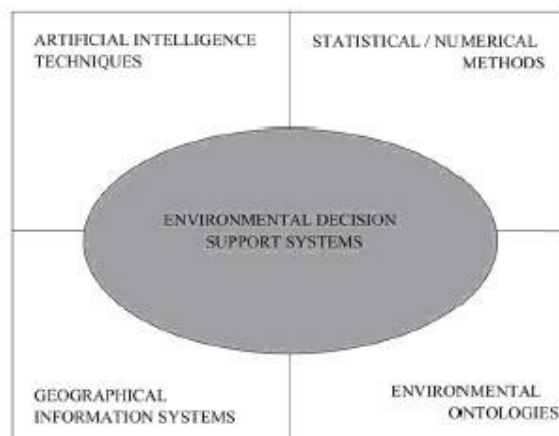


Figure 2. 8 EDSS conceptual components (Poch et al., 2003)

Environmental systems include physical resources of water, land, and air, as well as biological resources; and are characterized by fluxes of energy and materials within and between these physical and biological compartments. Because of environmental modeling systems' multidisciplinary nature, the users of these systems come from a wide range of disciplines. Therefore, software for use in modeling and managing environmental systems must be carefully designed and implemented according to the requirements of the particular type of end-user (Rizzoli and Young, 1997). Rizzoli and Young (1997) define three categories of users of EDSS as (i) Environmental scientist –who defines the problem domain,

develops models and tests them; (ii) Environmental manager –who needs “ready-to-use” models for decision making, integrated in an EDSS; and (iii) Environmental stakeholder –who wants access to understanding about the responses of different parts of the system under proposed management decisions. This categorization brings the concept of “two-level DSS” (Soncini-Sessa et al., 1990), in which the environmental scientist employs EDSS as a modeling environment to develop new models and integrate these, while environmental manager and stakeholder –or, the end-users- can access the DSS knowledge in an easy and structured way.

The EDSS can be divided into two categories: (i) Problem-specific –can be used to solve problems relating to a specific domain of knowledge, and can be applied to different situations in the same problem domain, and (ii) Situation and problem-specific –intended to be applied to a particular problem in a given place, and is not flexible to be modified for use in new locations. The desirable features of an EDSS are the ability to acquire, represent and structure the knowledge; separation of data from models; ability to deal with a database; ability to provide expert knowledge; ability to be used efficiently for diagnosis, planning, management, and optimization; and ability to assist the user during problem formulation and selecting the solution methods (Rizzoli and Young, 1997).

In a review study conducted by Poch et al. (2003), it is observed that the range of environmental problems to which EDSSs have been applied is wide and varied. Most of the EDSSs are dealing with water management issues (25% of the references), and these are followed by EDSSs on risk assessment (11.5%) and forest management (11%). Although landfill design and waste management problems can greatly benefit from the use of a DSS, very few DSSs were actually developed on the area of solid waste management and landfill design (Lukashev et al., 2001).

2.3.1. Architecture and Development of EDSS

The architecture of a DSS is based on the concept of DMM (Data, Dialog, Model). Data is the information that serves as the starting point for decision making, dialog is the information to the user in a user-adapted format, and model enables information that will help the user make decisions to be generated (Adenso-Diaz et al., 2005). Poch et al. (2003) propose an EDSS architecture based on five levels:

1. Data gathering: Original raw data are often defective, requiring a number of pre-processing procedures before being registered in an understandable and interpretable way.
2. Diagnosis: The reasoning models are used to infer the state of the process so that a reasonable proposal of actuation can be reached. This is accomplished with the help of statistical, numerical and artificial intelligence models.
3. Decision support level: The conclusions derived from the knowledge-based and numerical techniques are gathered and merged. Item Plans are formulated and presented as a list of general actions to solve a specific problem.
4. The set of actions to be performed to solve problems in the domain are considered. The system recommends not only the action or a sequence of actions, but also a value that has to be accepted by the decision-maker.

This five-level approach is presented in Figure 2.9 below:

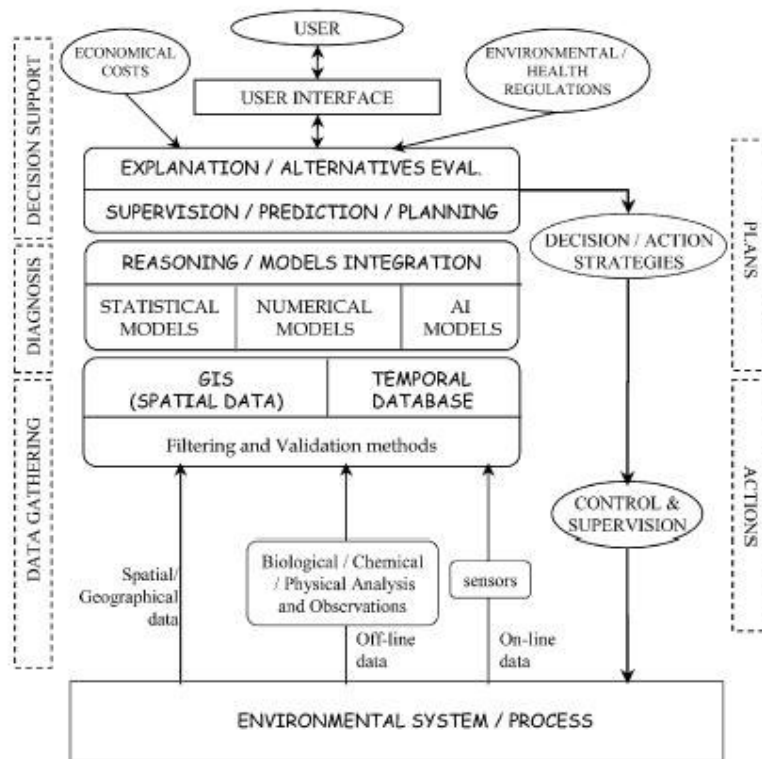


Figure 2. 9 Five-level EDSS architecture (Poch et al., 2003)

There are three generally accepted approaches for EDSS development and delivery. The techniques and their advantages and disadvantages are summarized as follows:

1. Using programming languages: This approach brings flexibility and coupling with techniques from model integration and reuse leads to high quality results with possible future extensions. However, using programming languages should usually be avoided because they require substantial amount of time, financial and human resources.
2. Using modeling and simulation software tools: This approach is very effective for generating EDSS prototypes and these can provide a test-bed for further investigation and development. However this approach is only

achievable only if the software packages are structured to allow the interface to control their functions and access data stored in their files.

3. Using model integration and re-use techniques: A software framework for model integration allows the scientist to prototype several different EDSS using a wider set of software resources to satisfy the requirements of each EDSS. Therefore, it is advantageous over the standard tools of modeling and simulation. However, this approach is still under research (Rizzoli and Young, 1997; Lukashchik et al., 2001; Booty et al., 2001).

The first approach has the benefit of control in the model design and linkage; but as previously stated, it requires longer development time. The second and third approaches save on development time, but they require additional work to link up existing models. Usually, the second approach is used when previously developed models are suitable for the purpose of the system designer (Lam et al., 2004).

2.4. EDSS Applications

In this section, examples of decision support systems recently developed and applied in various environmental research areas are presented. At the end of the section, two particular systems (RAISON and FRAMES) offering an integration platform for environmental models are discussed and presented specifically at the end of this section.

IMPAQT (Integrated Modular Program for Air Quality Tools) is software in the form of a decision support system. It was developed to create a flexible framework which allows communication between various air quality tools with minimal system requirements. The objectives of IMPAQT are to help local authorities by increasing the efficiency of the air quality assessment process. The system links a transportation model, an emissions inventory, a dispersion model and a geographic information system (GIS). Transportation, emission, hourly

meteorological and statistical meteorological data are types of data to be processed by the DSS. Interface modules were developed to process each type of data in the system (Lim et al., 2004). A conceptual model for the DSS is presented in Figure 2.10.

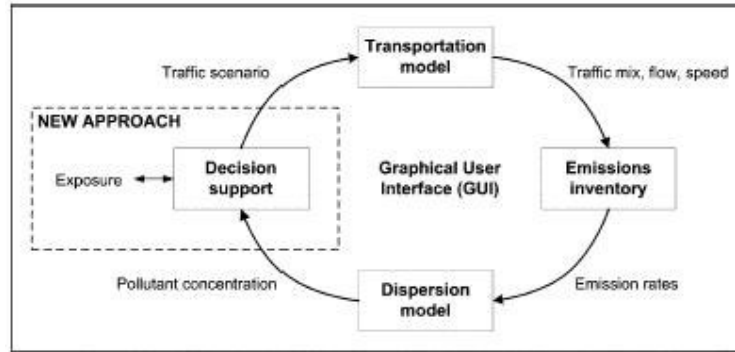


Figure 2. 10 Conceptual model for DSS development of IMPAQT (Lim et al., 2004)

A technical user interface (TUI) which can link meteorological, hydrological, terrestrial, hydrodynamic, and water quality models to simulate complex physical, chemical and biological processes is developed by Lam et al. (2004). The main goal of this TUI is to use the data and models in a simple, step-by-step and effective DSS. The developed DSS is aimed to help watershed managers to evaluate water turbidity and quality consequences of their management practices, prior to application. RAISON Object System (ROS) software, programmed with Visual Basic, is the core of linkage with other systems such as Access for database manipulation, Excel for watershed model, GIS maps, and the surface runoff model. A vital part of TUI is EnSim system, which offers visualization and animation tools for the results from hydrodynamic, transport, and dispersion models. EnSim is connected to ROS via component object model (COM) technologies in software design (Lam et al., 2004). Software linkage in TUI is presented in Figure 2.11.

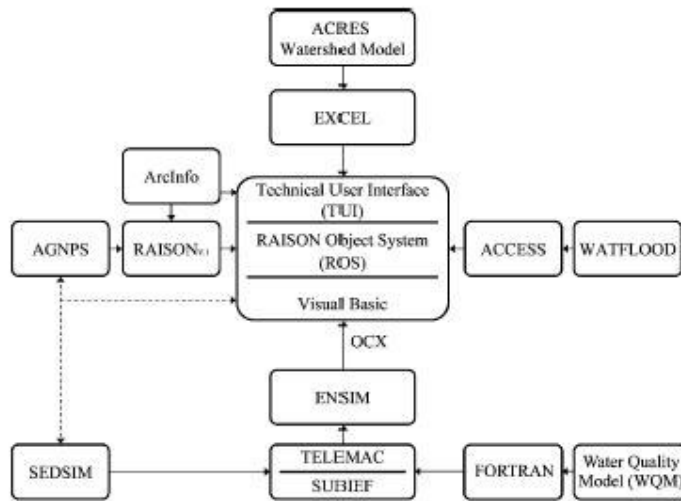


Figure 2. 11 Software linkage in TUI (Lam et al., 2004)

A probabilistic performance-assessment model and software tool was developed for evaluating the total system performance of long term landfill cover systems by Ho et al. (2004). Performance assessment is described by the authors as “an iterative technical analysis aimed at evaluating the performance of a disposal site with respect to regulatory compliance, often using probabilistic models” (Ho et al., 2004). Each scenario identified by the software contains a combination of models that represent process in vadose zone, saturated zone, air, etc. These process models describe water percolation through cover (HELP), radon gas transport through cover (RAECOM), source term release (MEPAS), vadose-zone transport (MEPAS), saturated zone transport (MEPAS), and human exposure (MEPAS). As these models do not originate from the same numerical code, they are integrated under a framework called FRAMES (Framework for Risk Analysis in Multimedia Environmental Systems). FRAMES system employs a GUI that helps user in setting up and simulating each model. A screen capture from FRAMES GUI is presented in Figure 2.12.

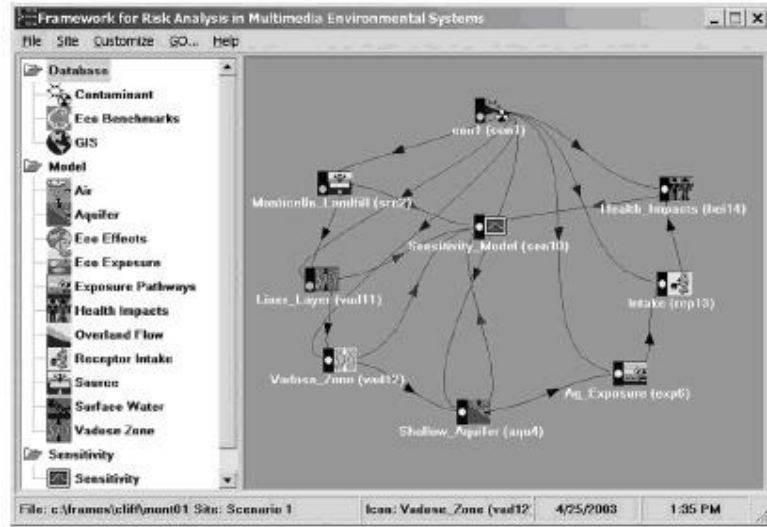


Figure 2. 12 Screen caption from FRAMES (Ho et al., 2004)

Short descriptions of many EDSS were presented in the review paper by Lukashev et al. (2001). An environmental DSS shell system was developed combining ARC/INFO GIS and Nexpert Object expert system for the analysis and preparation of input data for HEC-1 rainfall runoff model by Djokic (1996). This DSS example has the spatial component (mostly characterized by a GIS); however, there are DSSs (like SLEUTH and MSW Management Systems Planning) lacking this spatial component. SLEUTH (Shallow Landfill Evaluation Using Transport and Hydrology) was developed for design and remediation of shallow landfill burial systems (Ascough II et al., 1994). This DSS provides decision support for the design of landfill elements based on a multi-objective decision module embedded in HELP model. The Municipal Solid Waste Management Systems Planning (Barlisen et al., 1994) is a DSS developed in the area of waste management, to assist with the preliminary planning of municipal solid waste (MSW) management systems. It combines optimization, simulation and spreadsheet models to perform waste forecasting, technology evaluation, source separation, facility cost and operational data estimation, facility location, sizing and investment timing, and simulation of an existing or proposed MSW management system.

DEEM (Dynamic Environmental Effects Model) is “a software framework intended to support multi-disciplinary modeling of terrestrial, aquatic and atmospheric processes” (Rizzoli and Young, 1997). It was developed by Argonne Laboratory at the University of Chicago, and if widely adopted, presented to become a standard for model integration and reuse. HYDRA project aims to integrate different existing modeling systems using a federated systems approach to architectural design into a unique EDSS for water quality management. It uses a GIS-based interface, and seeks to develop a GUI. EDSS developed by Environmental Programs Group at North Carolina Supercomputing Center can handle alternative formulations for advection, diffusion, clouds and chemistry models, to work on air quality modeling. The simulation management module of EDSS helps in connecting models to create more complex models (Rizzoli and Young, 1997).

An EDSS was developed by Poch et al. (2003) to supervise wastewater treatment plants (WWTP) and to select wastewater treatment and disposal systems in Catalonia. Rule-based reasoning models (expert system) and case-based reasoning models were selected to acquire knowledge and to form a knowledge-based DSS. The hybrid intelligent approach to supervise WWTP and EDSS operation are presented in Figure 2.13 and 2.14.

A GIS-based DSS was developed by Adenso-Diaz et al. (2005) for the evaluation of alternatives in wastewater collecting systems design. The DSS considers the criteria of cost, environmental quality and social cost as factors. A pseudocode was written for the search algorithm. A structure of the proposed system is given in Figure 2.15.

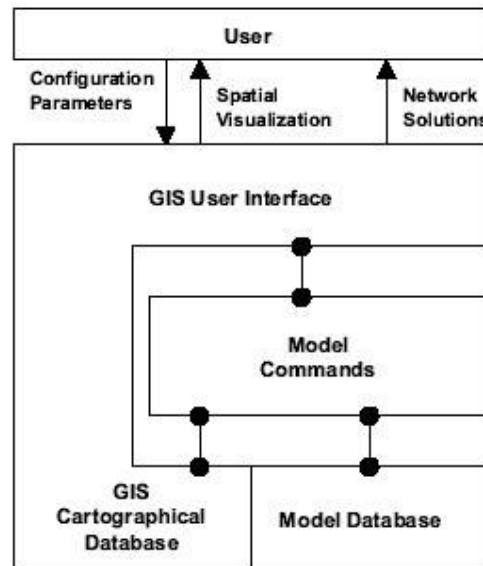


Figure 2. 15 Structure of DSS (Adenso-Diaz et al., 2005)

MODULUS project was developed to integrate research models to produce a tool to support integrated environmental decision making addressing physical, economic and social aspects of land degradation in the Mediterranean. 10 sub-models (climate and weather, hillslope hydrology, plant growth, natural vegetation, groundwater, surface water, crop choice, irrigation and land use) having different spatial and temporal scales were integrated under MODULUS DSS. The DSS was built as an integrated model composed of a number of self-registering COM components (ActiveX) called Model Building Blocks (MBB). Each MBB corresponds to the sub-models. The integration of existing models was achieved by the use of a wrapping technique without having to completely re-code. In this technique, each sub-model is transformed from its native code into a

2.4.1. RAISON for Windows v1.0

RAISON decision support system was designed based upon a knowledge-based approach which incorporates a hierarchy of tools. The system consists of database, spreadsheet, GIS layer, statistics, expert system, contouring, spatial visualization and graphs. RAISON design provides generic software tools for fast prototyping and practical implementation of EDSS. All the modules are directly linked with functions and tools including modeling interfaces, neural network, fuzzy logic, uncertainty analysis, animation, visualization, and optimization procedures. RAISON system imports data, text and graphics; and performs advanced environmental analysis, synthesis and prediction. RAISON database uses Microsoft Access 2.0 (*.mdb) files as the database standard. Worksheet is similar to any other commercial spreadsheets, which is designed to be fully integrated with all other modules. RAISON object system is the GIS module of the system. The statistics module includes basic statistics such as mean, median, mode, percentiles, hypothesis tests, normal and lognormal distribution analysis. RAISON expert system is a rule-based system with fuzzy logic. There are also neural network module, contour module, and visualization module in the system (Booty et al., 2001; Environment Canada, 2003). RAISON system accepts various types of data, text, maps and images from external sources. These are stored in its internal fully-linked database, map system and graphic components (University of Waterloo, Delft Hydraulics, and United Nations University, 2000).

The system is composed of two phases, technical user interface (TUI) and public user interface (PUI). TUIs are used by technical users to connect databases, rule-bases and other information; whereas, PUIs are used by managers and stakeholders, or in public consultation meetings. TUIs, which form the basis for PUIs, are for more technical functions like converting the output of a three-dimensional hydrodynamic model to be used as input to a water quality box model. The main purpose of the TUIs is to provide a human-machine interface to

enable communication with software system. Some of the TUIs required by the RAISON model are an input/output display interface, a data extraction interface, and a control interface for specifying model parameters and initial concentrations to run models. As can be seen in Figure 2.18, these interfaces are implemented in a tool-bar format (University of Waterloo, Delft Hydraulics, and United Nations University, 2000).

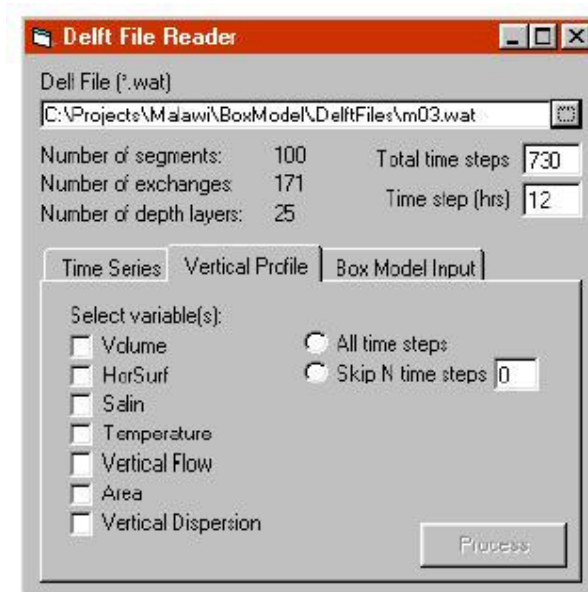


Figure 2. 18 A TUI for extracting results from the hydrodynamic model to be used by box model (University of Waterloo, Delft Hydraulics, and United Nations University, 2000)

RAISON system offers an expert system component, which is a rule-based system to facilitate consensus-building. A rule-base in RAISON system can be created using the Expert System toolbar. When this is selected, a window, divided into three regions, containing the empty rule-base opens (Figure 2.19). The regions are the top table for the parameters of the rule-base, bottom table for the rules of the rule-base, and the decision tree after the rule-base is created. Information on the parameters and rules should be entered by the user. The decision tree is generated automatically after the information is complete. The rules can be entered in a

simple spreadsheet format and saved as a rule-base file (Figure 2.20) (University of Waterloo, Delft Hydraulics, and United Nations University, 2000).

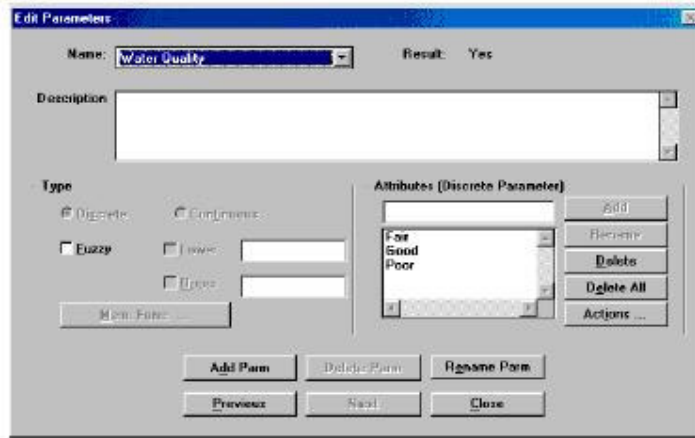


Figure 2. 19 Creating rules in expert system (University of Waterloo, Delft Hydraulics, and United Nations University, 2000)

Parameters	Name	Fuzzy	Type	Attributes
1	DO	No	Continuous	
2	Temperature	No	Continuous	
3	Water Quality	No	Discrete	Fair, Good, Poor
4				

Rules	DO	Temperature	Water Quality	Explanations
1	>= 7	<= 24	Good	
2	>= 7	[24 - 26.5]	Good	
3	[6 - 7]	<= 24	Good	
4	[6 - 7]	[24 - 26.5]	Fair	
5	>= 7	>= 26.5	Fair	
6	<= 6	<= 24	Fair	
7	[6 - 7]	>= 26.5	Poor	
8	<= 6	[24 - 26.5]	Poor	
9	<= 6	>= 26.5	Poor	
10				

Figure 2. 20 A simple rule-base for defining water quality (University of Waterloo, Delft Hydraulics, and United Nations University, 2000)

RAISON system not only integrates the databases, but also links some of the models or their results. There are three methods to incorporate models in RAISON. The first method is to run the model separately from RAISON and feed the model results into RAISON as input. The second method offers linking model to RAISON, by making use of RAISON databases, maps and graphical facilities. The third method is to rewrite the code for the model in a programming language to link to RAISON. One or all of the methods can be used to link models under RAISON system (University of Waterloo, Delft Hydraulics, and United Nations University, 2000).

2.4.2. Framework for Risk Analysis for Multimedia Environment Systems (FRAMES)

The FRAMES system provides a holistic approach to modeling in which source, fate and transport, exposure and health impact models, resolution (analytical, semi-analytical and numerical), and operating platforms can be combined as a part of overall assessment of contaminant fate and transport in the environment (Ho et al., 2004). In a broader sense, it is a software platform for selecting and implementing environmental software models for risk assessment and management problems. There are different types of modules present under FRAMES platform such as air, ecological effects, ecological exposure, exposure pathway, human health impacts, overland, receptor intake, saturated zone, source term, surface water, and vadose zone (Pacific Northwest National Laboratory, 2007). The system provides a user-friendly platform for integrating medium specific computer models, an extensive and editable contaminant database, a sensitivity/uncertainty module, and textual and graphical viewers for presenting model outputs. The disadvantage of this modeling framework is that only the simple, one-dimension, homogeneous and analytical component models run quickly under FRAMES (Ho et al., 2004).

2.5. HELP Model

The Hydrogeologic Evaluation of Landfill Performance (HELP) is a quasi -two-dimensional hydrologic model of water movement across, into, through and out of landfills (EPA, 1994). It is a versatile model for predicting landfill hydrogeologic processes and testing the effectiveness of landfill designs; therefore, enabling the prediction of landfill design failure resulting in groundwater contamination (Waterloo Hydrogeologic, 2002).

The model requires (i) weather –precipitation, solar radiation, temperature, evapotranspiration parameters, (ii) soil –porosity, field capacity, wilting point, and hydraulic conductivity, and (iii) engineering design data –liners, leachate and runoff collection systems, surface slope as input parameters. The profile structure can be multilayered, consisting of natural (soil) and artificial materials (waste, geomembranes) with an option to install horizontal drainage, and change the slope of profile parts like landfill cap, leachate collection and removal systems (Waterloo Hydrogeologic, 2002).

HELP uses numerical solution techniques that account for the effects of surface storage, snowmelt, runoff, infiltration, evapotranspiration, vegetative growth, soil moisture storage, lateral subsurface drainage, leachate recirculation, unsaturated vertical drainage, or leakage through soil, geomembrane, or composite liners. With in the Visual HELP 2.2.0.2 model, built-in database and tools like (i) weather generator, which is a tool for synthetic data generation for up to 100 years of daily values of precipitation, air temperature and solar radiation, and (ii) soil, waste and geomembrane database which contains parameters for 42 materials (Waterloo Hydrogeologic, 2002).

HELP model simulates the landfill as a set of profiles as shown in Figure 2.21. Vertical percolation layer is usually a topsoil, suitable for vegetative growth, or a

waste layer. The primary purpose of a vertical percolation layer is to provide moisture storage. Lateral drainage layer is a material with moderate to high permeability, like sand and gravel, which is underlaid by a liner with a lateral drainage collection and removal system. The primary purpose of a lateral drainage layer is to transport water towards the drainage pipe. Barrier soil liner is a soil with low permeability, like loam or clay, often compacted, which is designed to limit percolation and leakage. Geomembrane liner is a synthetic flexible membrane designed to restrict vertical drainage, and limit leakage. Geotextiles and geonets are synthetic materials designed to drain water laterally (Waterloo Hydrogeologic, 2002). All of the profile properties can be modified, except for the properties of geotextiles and geonets. HELP model has some basic rules to arrange the profiles. Additional details of profile set-up can be found in Waterloo Hydrogeologic (2002).

2.6. POLLUTE v7.0

POLLUTE is a semi-analytical, finite-layer contaminant migration model used for landfill design and comprehensive contaminant migration analysis (Rowe, 1990). The model implements “1.5-dimensional” solution to the advection-dispersion equation. Landfill designs that can be considered range from simple systems, on a natural clayey aquitards to composite liners with multiple barriers and multiple aquifers. The model also considers adsorption, radioactive and biological decay, phase changes, and transport through fractures. It also has a graphical user interface for user-friendly editing, execution and printing of data (Scientific Software Group, 1998).

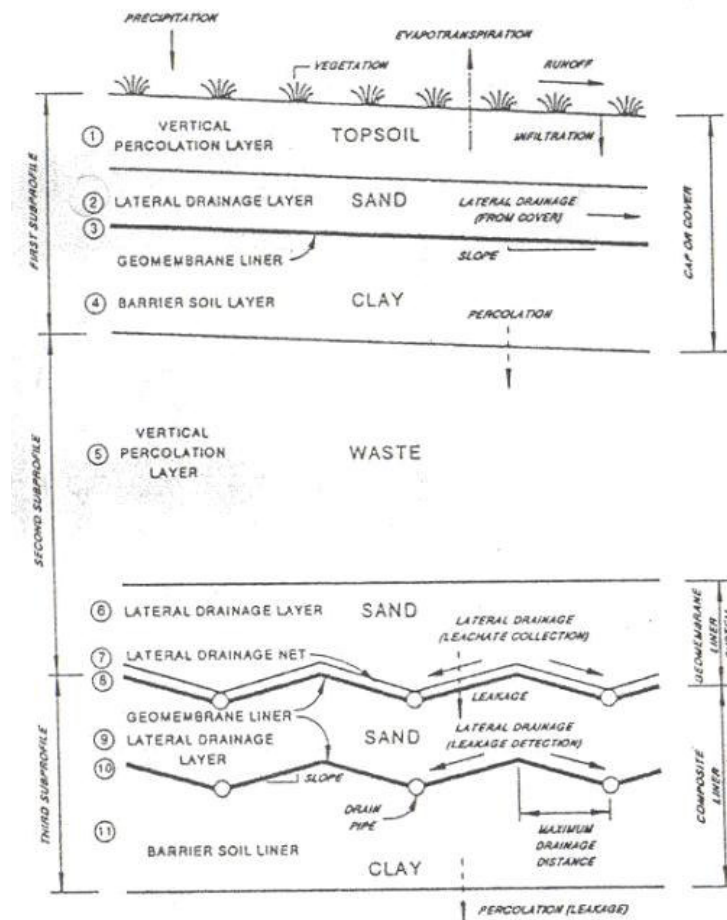


Figure 2. 21 Profiles in HELP model (Waterloo Hydrogeologic, 2002)

POLLUTE model can be applied to model contaminant migration from composite liner and single-liner landfills, as well as contaminant transport from spills, lagoons, and buried waste deposits, either vertically or horizontally through multiple aquitards and aquifers. The model can calculate maximum and temporal concentrations at any depth and time, model 1D, 2D or 3D fractures, vary source and layer properties with time to simulate effects of a failure of engineered systems, and assess uncertainty in parameter values using Monte Carlo simulation. Two boundary conditions, either finite mass boundary to represent a contaminant source such as a landfill or fixed outflow velocity to represent an

aquifer below the layers in the dataset can be defined. The concentration of the contaminant can be calculated at any number of specific depths or the maximum concentration can be determined automatically at any selected depth. The results of the simulations can be obtained graphically for concentration versus time, concentration versus depth, and flux versus time. Moreover, the model outputs a color concentration plot (Scientific Software Group, 1998).

2.7. Stability in Landfills

Stability in landfills are controlled by properties of the supporting soil, strength characteristics and weight of refuse, inclination of the slope, leachate levels and movements within the landfill, type of cover, and cover resistance to erosion. In all cases, water acts as a destabilizing agent for reducing the strength. The unit weight of refuse and its strength are difficult to determine and vary over a wide range. Therefore, the assessment of these variables is based on case histories and site-specific investigations (Daniel, 1995).

Stability in landfills can be assessed using two methods; limit-equilibrium and finite-element analyses. However, as the parameters required for finite-element analysis (strength, stress-strain, and modulus) are poorly defined in refuse, limit-equilibrium analyses are preferred to assess stability in landfills (Sharma and Lewis, 1994).

Potential instability can occur in the foundation soil, the refuse, or the cover. The safety margin for all cases is expressed in terms of factor of safety, FS (Sharma and Lewis, 1994):

$$FS = \frac{\sum \text{Resisting forces, moments}}{\sum \text{Driving forces, moments}} \quad (2.1)$$

In waste disposal sites, the driving force causing the development of a slip surface is the weight of the waste and leachate. The resisting (or restoring) forces occur due to the shear strength of waste and soil and the weights of soil, water and waste located near the toe of slope (Daniel, 1995). A factor of safety of 1 indicates imminent slippage, and a factor of safety below 1 indicates unstable conditions. The slope is stable if the factor of safety value is greater than 1 (Sharma and Lewis, 1994). Typical factor of safety values are given in Table 2.1:

Table 2. 1 Recommended minimum values of factor of safety for slope stability analyses (Sharma and Lewis, 1994)

Consequences of Slope Failure	Uncertainty of Strength Measurements^a	
	Small^b	Large^c
No imminent danger to human life or major environmental impact if slope fails	1.25 (1.2)	1.5 (1.3)
Imminent danger to human life or major environmental impact if slope fails	1.5 (1.3)	2.0 or greater (1.7 or greater)

^a numbers without parentheses apply for static conditions and those within parentheses apply to seismic conditions.

^b uncertainty of strength measurements is smallest when soil conditions are uniform and high-quality strength test data provide a consistent, complete and logical picture of strength characteristics.

^c uncertainty of strength measurements is largest when soil conditions are complex and when available strength data do not provide a consistent, complete and logical picture of strength characteristics.

Three common types of limit equilibrium analyses are infinite slope, wedge method and the method of slices. Infinite slope analyses deal with one-directional failures and movements parallel to the slope; i.e. final cover soils placed on a refuse slope. Wedge methods are used when the failure mass has a simple geometry, which can be divided into wedge-shape sections. This approach is less conservative and more realistic than infinite slope. The method of slices is used

for circular or wedge/block-type slip surfaces. Circular slip surfaces occur in homogeneous soils; whereas, wedge/block-type surfaces occur when a weak plane, such as a geomembrane liner, is present (Sharma and Lewis, 1994).

The stability analyses for landfills are divided into excavation slope, refuse fill, and cover systems (Sharma and Lewis, 1994). Potential slip mechanisms, analytical parameters and factor of safety for each of the analyses are given in the following sections.

2.7.1. Excavation Slope Stability

Excavation slope stability analyses, which are thought to be most critical in the preliminary site development and layout stages, are required to estimate acceptable grades for slopes. Typical excavation slopes for covered pit and trenched landfills are approximately 3:1 (horizontal:vertical), as the clay liners may be constructed on the side slopes at this grade. Potential slip surfaces in excavation slopes are presented in Figure 2.22 (Sharma and Lewis, 1994).

Limit-equilibrium analysis is performed using a circular slip surface. Block-type surface is preferred if a potential weak plane exists. Usually, as the water table is significantly below the base of the landfill, slope stability analyses do not include water table. If a non-flowing water table exists, effect of water table should be included in the form of a hydrostatic pressure distribution. If seepage conditions exist, internal pore pressures should be determined. Strength parameters of soils, like effective friction angle (ϕ') and unit weight (γ_t), should be considered. Typical factor of safety values range between 1.3 and 1.5 (Sharma and Lewis, 1994).

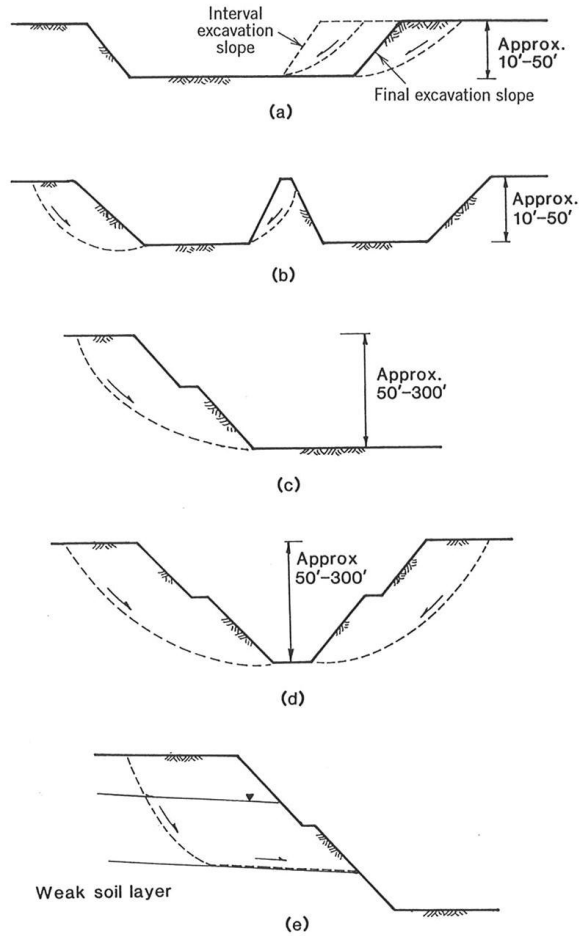


Figure 2. 22 Potential slip surfaces in excavation slopes (Sharma and Lewis, 1994)

2.7.2. Refuse Fill Stability

Refuse fill stability analyses are important for both final and interim landfill configuration. Critical stability concerns may occur, especially when liner systems using geomembranes are used. Potential slip surfaces may occur through refuse, along the liner system, or may be a composite surface through refuse and along liner (Figure 2.23). Refuse fill stability analyses are performed using circular surfaces. If a geosynthetic liner system is placed in landfill, translational block surface along the liner system or a composite slip surface through refuse and along liner may be of concern (Sharma and Lewis, 1994).

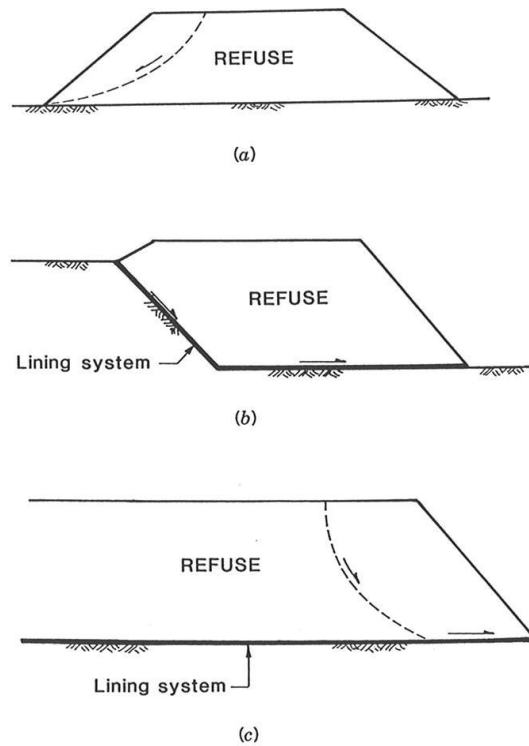


Figure 2. 23 Potential slip surfaces in landfills: (a) failure through refuse alone, (b) failure along liner system, (c) composite surface through refuse and liner system (Sharma and Lewis, 1994).

Refuse fill analyses employ limit equilibrium approach using a circular slip surface through refuse. When the landfill is lined with geosynthetic materials, limit equilibrium methods using composite or block-type surfaces are required. Refuse material properties, i.e. refuse shear strength, moisture content, and density, liner material strength properties, and interface strength properties are required. The material strengths of clay, granular soils, geotextiles and geomembranes should be considered to select the weak plane. Shear strength values of clay and granular soils exceed interface material strengths; therefore, do not represent a weak plane. Geotextile-soil interfaces have strengths that are approximately equal to or greater than 70 percent of the adjacent soil; therefore, they do not represent a weak plane, either. Weak planes occur between geomembranes and clays, and between geomembranes and other geosynthetics. Subgrade soil strengths should be known for assessing subgrade landfill

stabilities. For refuse fill stability analyses, factor of safety values greater than 1.5 are recommended (Sharma and Lewis, 1994).

2.7.3. Cover System Stability

Stability of the landfill final cover system is important for the final landfill grades. Landfills are constructed with final grades of 3:1, which are stable for soil cover systems. However, the soil cover systems may deform with underlying refuse settlements. To increase their flexibility, geosynthetics are used; however, they create stability concerns. Potential slip mechanisms are generally planar in final cover systems, between material interfaces or through the material itself. Therefore, infinite-slope analyses of limit equilibrium approach are suitable. The stability of each material type and/or interface strength should be considered separately. As the final cover system is easily repairable, factor of safety values less than refuse fills (i.e. between 1.3 and 1.5) are acceptable (Sharma and Lewis, 1994).

2.7.4. Effect of Moisture in Landfills

Moisture in waste affects the stability in landfills. Typically, incoming waste is at a moisture content of 20-40%. But, depending on the nature of waste, the moisture content may increase. As the moisture content in the refuse increases, unit weight of the waste also increases. This results in a decrease in factor of safety, namely unstabilizes the landfill. Therefore, leachate head above the landfill liner is regarded as one of the most important indicators for assessing the moisture-related landfill stability. Typically, 30 cm of leachate head on landfill liner is acceptable to maintain stability in landfills. The effect of leachate head over waste thickness ratio on the factor of safety is demonstrated in Figure 2.24 (Koerner and Soong, 2000).

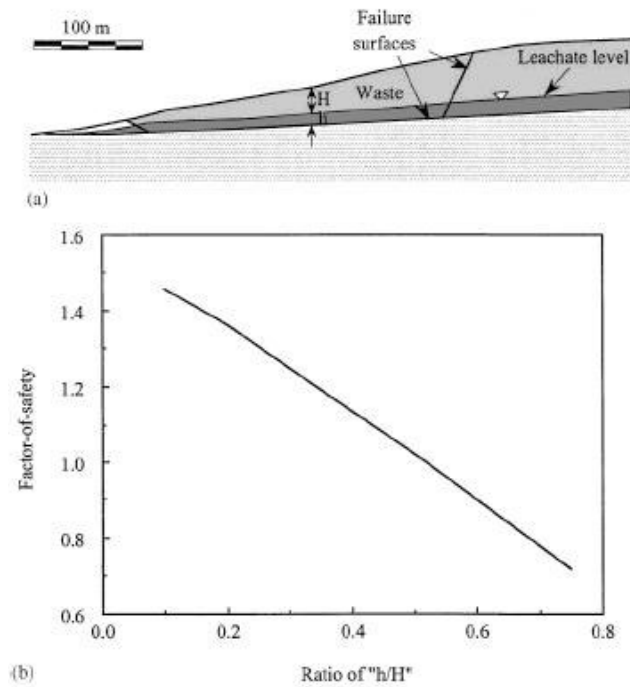


Figure 2. 24 Effect of leachate head on liner at lined landfill site on FS value (Koerner and Soong, 2000).

2.8. Effect of Groundwater Velocity on Contaminant Concentrations

The groundwater flow velocity, seepage velocity, is referred to as one of the most significant factors affecting solute transport in the subsurface for both organic and conservative pollutants, and growth and decay of microorganisms suspended in liquid (Mohammed and Allayla, 2000). The groundwater velocities occurring in natural aquifers are reported to be in the range of 0.01 – 10 m/d, 0.1 – 1 m/d being typical (Maekawa et al., 2002; Hudak, 2005; Hazardous Substances Research Centre, 2002). For example, a typical sandy aquifer with a hydraulic conductivity of 10 cm/s, hydraulic gradient of 0.005, and a porosity of 0.3 has a seepage velocity of 0.144 m/d (Wu and Tang, 2004). For organic contaminants, higher contaminant removal is observed at lower velocity values due to high detention time, and high detention of microorganisms. Biodegradation rate constant (e.g. for BTX compounds) is strongly dependent on seepage velocity (Mohammed and

Allayla, 2000). For inorganic compounds (e.g. chloride), as the seepage velocity increases, retardation rate constant decreases due to shortened reaction time between chloride and the medium; however, the dispersion coefficient increases due to mechanical dispersion. For velocity values higher than 0.086 m/d, mechanical dispersion prevails (Visudmedanukul et al., 2007). Due to dispersion, the contaminants received by the aquifer are diluted, and this phenomenon affects the concentrations observed at the receptor points.

CHAPTER 3

METHODOLOGY

Regarding the two-phase structure of the study, the methodology is presented in two parts. In the first part, development of the design methodology and design component selection matrix is explained. In this context, the conceptual model integrating the related sub-models and modules, landfill design variables, performance criteria, design components and landfill design alternatives, and design component selection matrix are described. The second part is dedicated to the development of the decision support system (DSS). DSS design, architecture, and framework, coupling methodology of system simulation models (SSMs), preliminary and detailed design phases, and models and modules used for the DSS are explained under this part. The chapter is completed by the presentation of the decision mechanism and decision analysis methodology of the DSS.

3.1. Development of Design Methodology and the Design Component Selection Matrix

3.1.1. Development of Design Methodology

3.1.1.1. Conceptual Model

A *conceptual model* was developed to effectively integrate preliminary knowledge-base, simulation models, landfill base contour design model, and calculation modules. The conceptual model is composed of physical and functional components. Physical components are preliminary design knowledge-base, landfill base contour design model, cover design evaluation model, waste and bottom liner evaluation and subsurface contaminant transport model, volume calculation module, stability module, and major design component approximate cost estimation module. Cover design evaluation model, and waste and bottom liner evaluation and subsurface contaminant transport model are referred to as system simulation models (SSM). Volume calculation module, stability module, and major design component approximate cost estimation module are referred to as calculation modules. Functional components are design variables, design components and the performance criteria. Design variables are climate (i.e. total annual precipitation rate), waste load (i.e. landfill area and waste thickness), and hydrogeology of the site (i.e. groundwater seepage velocity, porosity and hydraulic conductivity of the vadose zone). Design components are the final cover system, leachate collection and drainage system, and bottom liner system. Performance criteria are defined as meeting prespecified groundwater quality at a downgradient receptor point such as a well or water table and a maximum allowable leachate head on the bottom of the landfill at all times, the latter being adopted for cover and waste stability reasons. In the conceptual model, functional components are defined as the tasks that physical components perform (Figure 3.1).

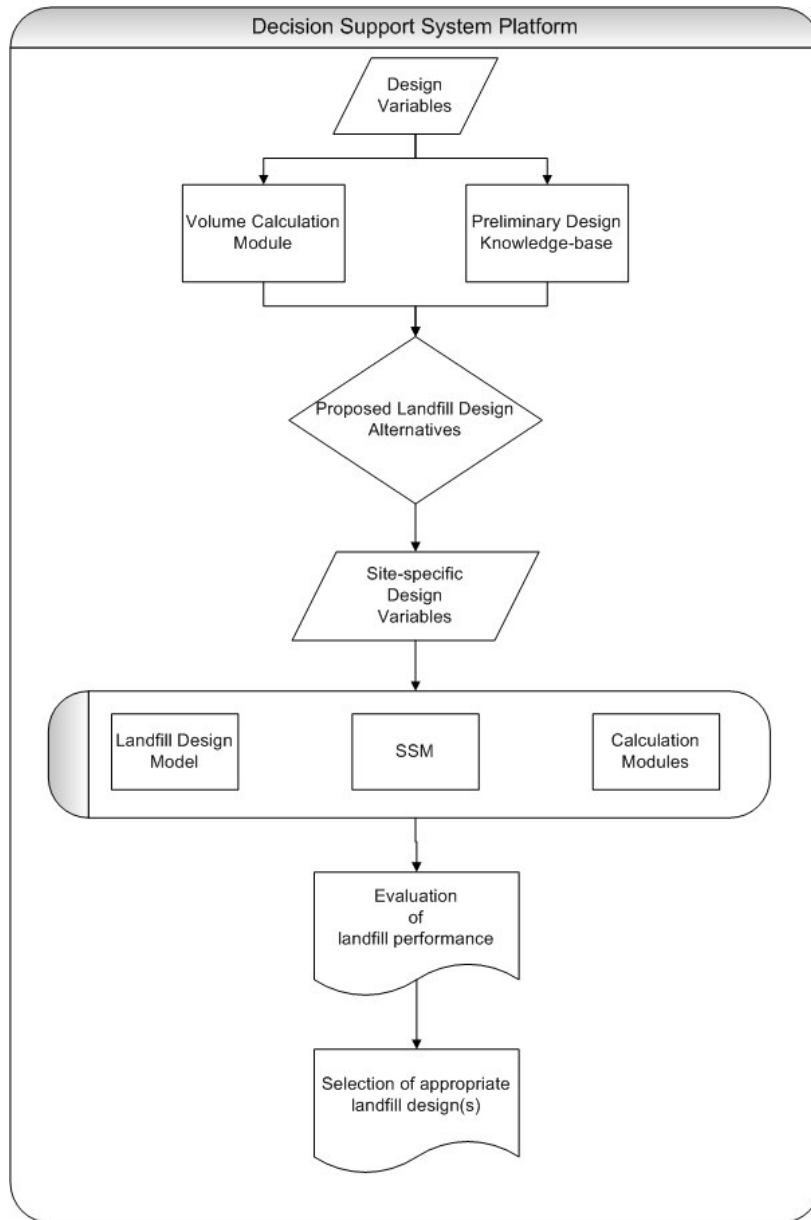


Figure 3. 1 Conceptual model for the DSS

Volume calculation module and landfill base contour design model (Virtual Landfill) handle and analyze site specific geographic, hydrogeologic, climatic and waste data associated with the design variables; and SSMs and other calculation modules (i.e. stability and major design component approximate cost estimation)

evaluate the performance of the landfill design alternatives with respect to the performance criteria. Therefore, the physical components of the conceptual model help in the selection of the most appropriate design components.

3.1.1.2. Design Variables

The basic design variables that should be considered for the design of landfills were defined as:

- i. climate (i.e. annual total precipitation rate)
- ii. waste loading rate (i.e. size of landfill)
- iii. waste thickness
- iv. groundwater seepage velocity
- v. hydrogeologic properties of the landfill site (i.e. porosity, hydraulic conductivity, and vadose zone thickness)

The climate variable was defined by annual total precipitation amount; and, classified as arid (annual precipitation amount ≤ 500 mm/yr), moderate (annual precipitation amount between 500 and 1000 mm/yr) and humid (annual precipitation amount ≥ 1000 mm/yr) (Kampf et al, 2002). As the climate is the major variable affecting leakage, the classification of the design alternatives was based primarily on annual total precipitation amount. All of the climatic parameters for the region (temperature, evapotranspiration, solar radiation, wind speed, humidity, growing season start and end day, and maximum leaf area index) were obtained from the weather generator module of Visual HELP 2.2.0.2. To represent the arid, moderate and humid climatic conditions, the simulations were performed using the meteorological data of Afyon (annual precipitation, $P = 340$ mm/y), İstanbul ($P = 660$ mm/y) and Zonguldak ($P = 1150$ mm/y), respectively. Also, climate sensitivity analyses were performed to assess whether the determined ranges are suitable for evaluating and classifying design alternatives.

As waste loading rate affects the landfill size directly, this variable is represented by the landfill area. Landfill area (or the landfill length in the direction of groundwater flow) is one of the most important parameters affecting contaminant concentrations in leachate. Landfills were classified as *communal* ($A \leq 2$ ha), *small* ($2 < A \leq 15$ ha), *medium* ($15 < A \leq 50$ ha), and *large* ($A > 50$ ha), with respect to size. For the calculations of landfill capacity, the operational lifetime of landfill was taken as 20 years. The landfill size is related to the maximum rate of waste deposition (MRD) that the landfill receives. The MRD and the related landfill sizes were calculated as (RSA DWAF, 1998):

$$MRD = IMRD \times (1 + d)^t \quad (3.1)$$

$$A = \frac{MRD \times t}{\rho_w \times T_w} \quad (3.2)$$

where *IMRD* is initial maximum rate of deposition [M/T]; *d* is projected population growth rate; *t* is the operational time of landfill [T]; ρ_w is the density of in-situ compacted waste and taken as 550 kg/m³ (İller Bankası, 2000); and *T_w* is the thickness of waste in landfill and taken as 20 m. The average waste production rate in Turkey is accepted as 1 kg/cap/day (DİE, 2001 TURKAY REFS). Using equation 3.1 and 3.2, landfill sizes were classified according to the MRD as shown in Table 3.1.

Table 3. 1 Classification of landfills with respect to Maximum Rate of Deposition (MRD) and population

Landfill Class	Population	MRD (tons/day)	Landfill Size (ha)
Communal (C)	≤ 25000	<25	≤ 2
Small (S)	25001-150000	25 – 150	2 – 15
Medium (M)	150001-500000	150 – 500	15 – 50
Large (L)	> 500000	> 500	> 50

A previously formed database (Tarhan, 2003) was used to evaluate the hydrogeologic conditions. The hydrogeologic formations were classified according to their suitability for serving as a barrier for landfill bottom. Generally, clays, silts, clay stones, marlstones, and unfractured igneous and metamorphic rocks are considered to be potential barrier geologic materials that a landfill can be constructed on (Dörhöfer and Siebert, 1997). Therefore, these geologic formations were classified as suitable (S), and the rest of them, like sand and gravel, were classified as unsuitable (U) formations for landfill construction (Figure 3.2).

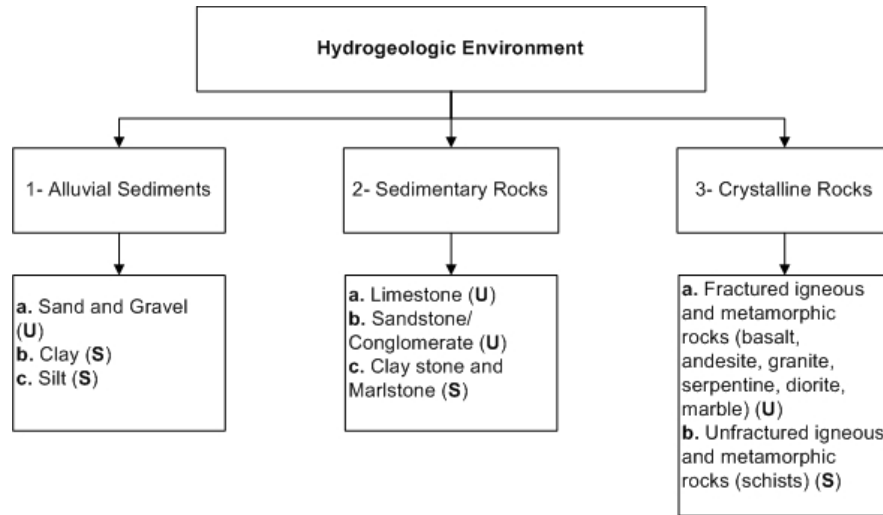


Figure 3. 2 Hydrogeologic environment classes. S and U denote hydrogeologic environment subclasses that are suitable or unsuitable for landfill siting, respectively

The main geologic formations used in the model were selected on the basis of their suitability for being a barrier material and their hydraulic conductivities. The hydraulic conductivities of water yielding U-class formations are obtained from the database (Tarhan, 2003) and values for the non-water-yielding S-class formations were obtained from Newell et al. (1990), and Domenico and Schwartz (1990), as seen in Table 3.2. Accordingly, they are classified into two groups as low conductivity ($10^{-8} - 10^{-6} m/s$) and high conductivity ($> 10^{-5} m/s$).

Waste thickness, seepage velocity and vadose zone parameters are other three important parameters affecting design of landfills. Detailed analyses of these effects are given in Sections 3.1.1.2.1 and Section 3.1.1.2.2.

Table 3. 2 Hydraulic conductivity values for different hydrogeologic environment subclasses

HGE Subclasses	Maximum Value (m/s)	Minimum Value (m/s)
Clay –Silt	5×10^{-6}	1×10^{-9}
Clay stone –Marl	5×10^{-9}	1×10^{-11}
Unfractured metamorphic and igneous rocks	2×10^{-10}	4×10^{-14}
Sand and Gravel	4×10^{-2}	2×10^{-6}
Limestone	6×10^{-6}	1×10^{-9}
Sandstone and Conglomerate	6×10^{-6}	4×10^{-10}
Fractured metamorphic and igneous rocks	4×10^{-4}	8×10^{-9}

3.1.1.2.1. Vadose Zone Effect on Steady-state Leakage Rates

To evaluate the effect of vadose zone on steady-state leakage rates, a landfill barrier system having a compacted clay liner underlain by a vadose zone of varying thickness is modeled using SEEP/W seepage analysis software. The vadose zone is modeled to be composed of either coarse textured or fine textured soil. Simulations of both models are performed assuming steady state conditions. Coarse textured vadose zones are represented by sandy soils, and fine textured vadose zones are represented by silty soils for both model configurations. Effect of uniform saturated hydraulic conductivity values and unsaturated soil hydraulic conductivity functions, texture and thickness of vadose zone, and compacted clay liner hydraulic conductivity on leakage rates is assessed.

To describe the landfill barrier system in numerical unsaturated flow model SEEP/W, two specified head boundary conditions are defined.

As the top boundary condition, 0.3-m-pressure head is defined to describe a design leachate head of 0.3 m in the drainage layer over the compacted clay liner (CCL) (i.e. a typical design leachate head (Rowe, 2005)). For conditions where

leachate head above the CCL increases significantly beyond the typical design value of 0.3 m due to clogging of drainage layer, a coarse gravel drainage layer was selected because of its excellent long-term performance (Rowe, 2005; Ont. Reg. 232/98) and hence, a drastic increase in the leachate leakage rate through the CCL should not be expected. Since there is a significant hydraulic conductivity contrast between the CCL and the vadose zone, unsaturated moisture flow conditions will prevail in the vadose even under relatively high leachate head conditions above the CCL.

Zero pressure head is defined at the bottom boundary to represent the groundwater table at the bottom of the vadose zone. It is possible to model unsaturated flow conditions with SEEP/W, assigning soil hydraulic conductivity functions to the vadose zone. As hydraulic conductivity is defined as the capacity of soil to conduct water, it is dependent on the water content and is a function of pore-water pressure. SEEP/W estimates the hydraulic conductivity function from a soil-water characteristic function by using the Green and Corey (1971) procedure. When the hydraulic conductivity is defined for negative pore-water pressure regions, it is possible to analyze both unsaturated and saturated flow problems (SEEP/W, 2002). Therefore, simulations are performed both by using soil hydraulic conductivity functions and uniform saturated hydraulic conductivity values to assess the implications of using saturated hydraulic conductivity values. Uniform sand, sand, and fine sand hydraulic conductivity functions and uniform silt, silt, and silt tailings hydraulic conductivity functions are chosen to represent coarse and fine textured soils, respectively. The respective saturated hydraulic conductivity values of uniform sand, sand and fine sand are specified as 1×10^{-4} m/s, 5×10^{-5} m/s, and 4×10^{-6} m/s; whereas, those of uniform silt, silt and silt tailings are specified as 1×10^{-8} m/s, 2.5×10^{-7} m/s, and 5.8×10^{-8} m/s, respectively. The hydraulic conductivity versus pressure curves of these functions are given in Figure 3.3. The configuration of the landfill barrier system in SEEP/W model is given in Table 3.3. In order to evaluate the effect of the

compacted clay liner hydraulic conductivity on the performance of the overall landfill barrier system, barrier systems having compacted clay liner of one order of magnitude lower hydraulic conductivity (i.e. 1×10^{-10} m/s) than the common practice (i.e. 1×10^{-9} m/s) are also simulated.

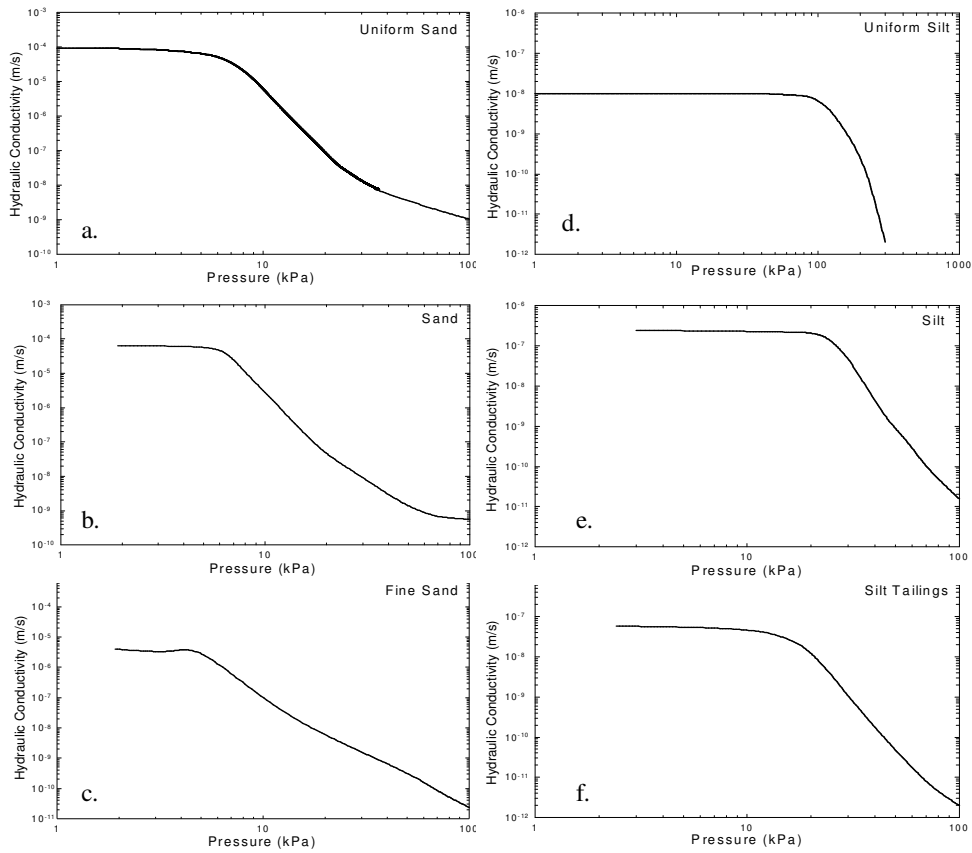


Figure 3.3 Hydraulic conductivity functions for (a) uniform sand (b) sand, (c) fine sand, (d) uniform silt, (e) silt, and (f) silt tailings.

Table 3. 3 Landfill barrier system configuration in SEEP/W model

Barrier System Design	Compacted Clay		Vadose Zone	
	Liner (CCL)		(VZ)	
	$K_{sat}^{(a)}$ (m/s)	Thickness (m)	$K_{sat}^{(a)}$ (m/s)	Thickness (m)
Vadose zone under CCL –uniform sand (US)	1×10^{-9}	0.6	1×10^{-4}	1, 5 or 10
Vadose zone under CCL –sand (S)	1×10^{-9}	0.6	5×10^{-5}	1, 5 or 10
Vadose zone under CCL –fine sand (FS)	1×10^{-9}	0.6	4×10^{-6}	1, 5 or 10
Vadose zone under CCL – uniform silt (USi)	1×10^{-9}	0.6	1×10^{-8}	1, 5 or 10
Vadose zone under CCL –silt (Si)	1×10^{-9}	0.6	2.5×10^{-7}	1, 5 or 10
Vadose zone under CCL –silt tailings (SiT)	1×10^{-9}	0.6	5.8×10^{-8}	1, 5 or 10
Vadose zone under CCL –sand (S)	1×10^{-10}	0.6	5×10^{-5}	5 or 10
Vadose zone under CCL –silt (Si)	1×10^{-10}	0.6	2.5×10^{-7}	5 or 10

^(a) Stands for the uniform saturated hydraulic conductivity.

To check the accuracy of SEEP/W results, steady state leakage rates into the aquifer are hand calculated using the effective hydraulic conductivity of the overall barrier system, following Darcy's Law. The effective hydraulic conductivity of the barrier system is taken as the harmonic mean of the compacted clay hydraulic conductivity and vadose zone harmonic mean hydraulic conductivity (Eq.3.3); and, the steady state leakage rate (Eq.3.5) is calculated simply by multiplying the gradient occurring across the barrier system (Eq.3.6) by the effective hydraulic conductivity:

$$\bar{k} = \frac{D_{VZ} + D_{CCL}}{\left(\frac{D_{VZ}}{\bar{k}_{VZh}}\right) + \left(\frac{D_{CCL}}{k_{CCL}}\right)} \quad (3.3)$$

where \bar{k} is the effective (combined harmonic mean) hydraulic conductivity of the vadose zone and CCL; D_{VZ} is the thickness of the vadose zone underlying the CCL; D_{CCL} is the thickness of the CCL; \bar{k}_{VZh} is the harmonic mean hydraulic conductivity of the vadose zone; k_{CCL} is the hydraulic conductivity of the CCL. The value of \bar{k}_{VZh} was calculated using the hydraulic conductivity values corresponding to each of the nodes (elements) across the vadose zone as

$$\bar{k}_{VZh} = \frac{n}{\frac{1}{k_1} + \frac{1}{k_2} + \dots + \frac{1}{k_n}} = \frac{n}{\sum_{i=1}^n \frac{1}{k_i}} \quad (3.4)$$

where k_i is the hydraulic conductivity value corresponding to the finite element node i , and n is the number of nodes, or number of hydraulic conductivity values. The \bar{k}_{VZh} value calculated from Eq. 3.4 is used in Eq. 3.3 to calculate \bar{k} . In Eq. 3.3, the thicknesses of CCL and vadose zone were taken into account separately, as this would have an impact on the value \bar{k} , which was used as a representative hydraulic conductivity value for the overall barrier system.

Steady state leakage rates into the aquifer were also hand calculated following the Darcy's Law:

$$q_{ss} = i \times \bar{k} \quad (3.5)$$

where

$$i = \frac{z_T + h}{z_T} \quad (3.6)$$

and q_{SS} is the steady-state leakage rate through the CCL and the vadose zone into the aquifer; i is the hydraulic gradient across the CCL and vadose zone; z_T is the combined thickness of the CCL and vadose zone; and h is the pressure head on the top of the CCL.

3.1.1.2.2. Waste Thickness and Seepage Velocity Effect on Steady-State Leakage Rates

To determine the effect of waste thickness and groundwater seepage velocity on the contaminant concentrations at the receptor, 3 sets of sensitivity analyses were performed. In the *first set*, waste thickness was held constant and simulations were performed with 5 different seepage velocity values. In the *second set*, seepage velocity was held constant and simulations were performed with 5 different waste thickness values. *Set 3* was performed to demonstrate the combined effect. The simulations were performed for a communal landfill ($A < 2$ ha) placed on a sandy vadose zone of 10 m and having a mean hydraulic conductivity of 10^{-7} m/s. The climate was set as moderate ($500 \text{ mm/yr} < P < 1000 \text{ mm/yr}$). The simulations were performed with the major design alternatives (Table 3.4). The configurations of the three sets were given in Table 3.5. The infiltration rates obtained by HELP model simulations for some major design alternatives, namely natural attenuation landfill, extensive engineering design and intermediate engineering design are 0.249 m/yr, 0.00423 m/yr and 0.245 m/yr, respectively.

Table 3. 4 Design details of major design alternatives used for waste thickness and seepage velocity calculations

Design	Final Cover	Bottom Liner
Natural attenuation landfill	0.6-m-thick natural topsoil	Natural aquitard below waste
Extensive engineering design	0.6-m-thick natural topsoil	0.3-m-thick leachate collection layer
	0.3-m-thick cover	2-mm-thick geomembrane
	drainage layer	0.6-m-thick compacted clay liner
	1-mm-thick geomembrane	Vadose zone/aquitard
	0.6-m-thick clay layer	
Intermediate engineering design	0.6-m-thick natural topsoil	0.3-m-thick leachate collection layer
	0.3-m-thick cover	0.6-m-thick compacted clay liner
	drainage layer	Vadose zone/aquitard
	0.6-m-thick clay layer	

Table 3. 5 Configurations of sensitivity simulations

Set Number	Waste Thickness (m)	Seepage Velocity (m/d)
1 <i>(15 runs)</i>	20	0.01
	20	0.05
	20	0.1
	20	0.5
	20	1
2 <i>(15 runs)</i>	5	1.2
	10	1.2
	15	1.2
	20	1.2
	30	1.2
3 <i>(75 runs)</i>	5	0.01
	10	0.05
	15	0.1
	20	0.5
	30	1

3.1.1.3. Performance Criteria

The performance of the landfill is evaluated on the basis of compliance to contamination and stability criteria.

Leachate head on the liner acts hydrostatically and can readily be incorporated into stability analyses. Therefore, as the stability criterion, leachate head above the landfill liner should not exceed 1 m due to landfill stability concerns (Koerner and Soong, 2000).

As a conservative approach, chemicals in leachate are modeled by chloride (Cl⁻), often used as a conservative environmental tracer to estimate groundwater recharge rates in arid and semiarid regions (O'Green et al., 2002). Chloride concentrations in the leachate and solid waste were assumed as 1000 mg/L and 1000 mg/kg, respectively (İller Bankası, 2000). The contamination criterion was specified such that the maximum chloride (Cl⁻) concentration at the groundwater table should not exceed 25 mg/L.

3.1.1.4. Design Components and Landfill Design Alternatives

Selection of design components is based on the design variables of the landfill and the performance criteria. Three final cover and six bottom liner options were identified. These cover and liner options were composed of different combinations of design components shown in Table 3.6.

Three types of final covers (evapotranspiration cover –C1, extensive engineering final cover –C2, and intermediate design final cover –C3) were considered. *Evapotranspiration final cover (C1)* is composed of only natural topsoil on top of waste (Hauser et al., 2001). *Extensive engineering final cover (C2)* is composed of

natural topsoil, drainage layer, geomembrane, and clay liner. *Intermediate design final cover* (C3) is composed of natural topsoil, drainage layer, and clay liner.

Six different types of bottom liner systems were used. *Natural attenuation bottom liner* (L1) is composed of only natural aquitard below waste; *extensive engineering bottom liner* (L2) is composed of leachate collection system, geomembrane, and compacted clay liner over vadose zone; *L3* bottom liner is composed of leachate collection system placed over low conductivity aquitards; *L4* bottom liner is composed of leachate collection system and geomembrane over vadose zone; *intermediate engineering bottom liner* (L5) is composed of leachate collection system and compacted clay liner over vadose zone; and finally *L6* bottom liner is composed of compacted clay liner over vadose zone.

Table 3. 6 Final Cover and Bottom Liner Alternatives

Final Cover	Design Components
C1	Natural soil
C2	Natural soil +CDS ^a + geomembrane + clay liner
C3	Natural soil + CDS + clay liner
Bottom Liner	Design Components
L1	Only aquitard below waste
L2	LCS ^b + geomembrane + CCL ^c + aquitard/unsaturated zone
L3	LCS + aquitard
L4	LCS + geomembrane + aquitard/unsaturated zone
L5	LCS + CCL + aquitard/unsaturated zone
L6	CCL + aquitard/unsaturated zone

^aCover Drainage System

^bLeachate Collection System

^c Compacted Clay Liner

The developed methodology was applied to 18 design alternatives formed using different combinations of final cover and bottom liner options. Appendix-A

presents the schematic drawings of 18 possible landfill design profiles obtained from various combinations of final cover and bottom liner selections. Three of these designs among 18 alternatives, C1L1, C2L2 and C3L5, were selected as major designs and the design details are given in Table 3.7. The combinations of 18 design alternatives are presented in Table 3.8. These alternatives are produced using different combinations of the design components described in Table 3.7.

Table 3. 7 Design Details of Major Design Alternatives

Design Alternative	Design Details	
	Final Cover	Bottom Liner
C1L1		
Natural attenuation	- 60cm fine sandy loam	- Natural aquitard (clay, $k=10^{-8}$ m/s)
C2L2	- 60cm fine sandy loam - 30cm coarse sand (drainage)	- 30cm gravel (drainage) - 2mm high density polyethylene (HDPE)
Extensive engineering	- 1mm low density polyethylene (LDPE) - 60cm silty clay, $K=1 \times 10^{-8}$ m/s	- 60 cm compacted clay, $k=1 \times 10^{-9}$ m/s - Natural soil ($k_{\text{mean}}=10^{-7}$ m/s)
C3L5	- 60cm fine sandy loam	- 30cm gravel (drainage)
Intermediate design	- 30cm coarse sand (drainage) - 60cm silty clay, $K=1 \times 10^{-8}$ m/s	- 60 cm compacted clay, $k=1 \times 10^{-9}$ m/s - Natural soil ($k_{\text{mean}}=10^{-7}$ m/s)

Table 3. 8 Combinations of Landfill Design Alternatives Ranging from Minimal Engineering to Extensive Engineering

Design	Design Combination	
	Final Cover	Bottom Liner
C1L1^a	Natural soil	Only natural aquitard below waste
C1L2	Natural soil	LCS ^e + geomembrane + compacted clay liner + unsaturated zone
C1L3	Natural soil	LCS + aquitard
C1L4	Natural soil	LCS + geomembrane + aquitard/unsaturated zone
C1L5	Natural soil	LCS + compacted clay liner + aquitard/unsaturated zone
C1L6	Natural soil	compacted clay liner + aquitard/unsaturated zone
C2L1	Natural soil + CDS ^d + geomembrane + clay liner	Only aquitard below waste
C2L2^b	Natural soil + CDS + geomembrane + clay liner	LCS + geomembrane + compacted clay liner + unsaturated zone
C2L3	Natural soil + CDS + geomembrane + clay liner	LCS + aquitard
C2L4	Natural soil + CDS + geomembrane + clay liner	LCS + geomembrane + aquitard/unsaturated zone
C2L5	Natural soil + CDS + geomembrane + clay liner	LCS + compacted clay liner + aquitard/unsaturated zone
C2L6	Natural soil + CDS + geomembrane + clay liner	compacted clay liner + aquitard/unsaturated zone
C3L1	Natural soil + CDS + clay liner	Only aquitard below waste
C3L2	Natural soil + CDS + clay liner	LCS + geomembrane + compacted clay liner + unsaturated zone
C3L3	Natural soil + CDS + clay liner	LCS + aquitard
C3L4	Natural soil + CDS + clay liner	LCS + geomembrane + aquitard/unsaturated zone
C3L5^c	Natural soil + CDS + clay liner	LCS + compacted clay liner + aquitard/unsaturated zone
C3L6	Natural soil + CDS + clay liner	compacted clay liner + aquitard/unsaturated zone

^(a) natural attenuation landfill, ^(b) extensive engineering landfill, ^(c) intermediate landfill design, ^(d) cover drainage system, ^(e) leachate collection system

3.1.2. Development of Design Component Selection Matrix

A design component selection matrix was built in order to develop a knowledge-base for the decision support system and to propose different design alternatives that are supposed to comply with the performance criteria under different site (design) conditions. It is used as guidance for the selection of most appropriate design components for a given site and waste conditions. The matrix accommodates all the design variables (i.e. climate –total annual precipitation rate, waste load –landfill area and waste thickness, and site hydrogeology – hydraulic conductivity, porosity and thickness of vadose zone, and groundwater seepage velocity) and is beneficial in selecting a preliminary design alternative among the feasible designs listed, when the ranges of design variables are known (Table 3.9). The alternative design combinations presented in the matrix were selected based on simulated landfill performance evaluations.

Table 3. 9 Design variable sets for the design component selection matrix

Climate	Area	Waste Thickness	Seepage Velocity	Site Hydrogeology
Arid (P < 500 mm/yr)	2 ha (L=200 m)	5 m 20 m	0.05 m/d 0.1 m/d	<i>Sandy vadose zone:</i>
Moderate (500 < P < 1000 mm/yr)	15 ha (L=500m)		0.5 m/d 1 m/d	T = 10 m K _{mean} ^(a) = 10 ⁻⁷ m/s φ = 0.35
Humid (P > 1000 mm/yr)	50 ha (L=1000m)			<i>Clayey vadose zone:</i> T = 10 m K _{mean} = 10 ⁻⁸ m/s φ = 0.45

^(a) The mean hydraulic conductivity of the vadose zone.

As climate is the major variable affecting leachate production, classification is based primarily on total annual precipitation rate. Waste loading rate directly affects the landfill area; therefore, these variables were combined to represent the size of the landfill. Contaminant loading rate coming to the aquifer increases with waste thickness. Groundwater seepage velocity dilutes the contaminants; therefore, lower contaminant concentrations in the aquifer are observed under faster velocities. Therefore, waste thickness and seepage velocity were added to the matrix as design variables. As sandy soils demonstrate a similar hydraulic behavior to silty soils under unsaturated conditions, the type and hydrogeology of the vadose zone was implicitly included in the design component selection matrix. This distinction appears in the configuration of the design alternatives. For example, natural attenuation landfills are only allowed to be constructed over silty-clay aquitards; whereas, extensive engineering landfills are appropriate to be constructed on sandy vadose zones (Table 3.10).

Table 3. 10 Required site hydrogeology with respect to landfill design alternatives

Bottom Liner Design	Hydrogeology of Vadose Zone (VZ)
L1: Only aquitard below waste	Low conductivity, silty-clay soils
L2: LCS ^a + GM ^b + CCL ^c + VZ ^d	High conductivity, sandy soils
L3: LCS + VZ	Low conductivity, silty-clay soils
L4: LCS + GM + VZ	High conductivity, sandy soils
L5: LCS + CCL + VZ	High conductivity, sandy soils / Low conductivity, silty-clay soils
L6: CCL + VZ	High conductivity, sandy soils / Low conductivity, silty-clay soils

^a leachate collection system ^b geomembrane ^c compacted clay liner ^d vadose zone

As incorporation of all five design variables would make design component selection matrix too complicated to use, three different matrices were formed with respect to three different climatic conditions (i.e. arid, moderate, and humid).

Moreover, as site hydrogeology is implicitly identified within the design alternatives, three design variables (i.e. waste thickness, seepage velocity, and size of landfill –landfill area) were accommodated in each matrix.

To construct the matrix, over 1300 simulations of 18 landfill design alternatives were performed using system simulation models considering the aforementioned design variables. Visual HELP 2.2.0.2 was selected as landfill final cover design model, and POLLUTE v7 was selected as landfill bottom liner design and subsurface contaminant transport model.

Visual HELP was used to calculate annual total leachate production rate (infiltration rate to waste layer) by simulating final covers of design alternatives under different design conditions. The leachate production rate produced by HELP was used as input for infiltration rate in POLLUTE. The final cover design parameters used in HELP simulations are given in Table 3.11.

Table 3. 11 Final cover design parameters used in HELP simulations

Design component	T^b	Slope	Slope length	Total porosity	Field capacity	Wilting point	K_{sat}^c
	(m)	(%)	(m)	(vol/vol)	(vol/vol)	(vol/vol)	(m/s)
Natural top soil	0.60	3	30	0.473	0.222	0.104	5×10 ⁻⁶
Drainage layer	0.30	2	30	0.417	0.045	0.018	1×10 ⁻³
Clay liner	0.60	-	-	0.479	0.371	0.251	1×10 ⁻⁷
Design component	T	Slope	Slope length	Hole frequency	Defects	Placement quality	K_{sat}
	(m)	(%)	(m)	(#/ha)	(#/ha)	(-)	(m/s)
LDPE ^a	0.001	-	-	2	4	4	4×10 ⁻¹⁵

^alow density polyethylene,

^blayer thickness,

^csaturated hydraulic conductivity

POLLUTE was used to model waste layer, landfill bottom liner, and the subsurface below the landfill bottom liner. The hydraulic head value on top of the landfill barrier liner (either compacted clay liner or natural low conductivity aquitard) was evaluated by POLLUTE model and the compliance of the design alternatives to the first performance criterion (*i.e. hydraulic head on top of landfill barrier should be less than 1 m*) was determined. The design alternatives complying with the first performance criterion were further simulated by POLLUTE and the contaminant concentrations at the groundwater table were obtained. By this way, the compliance of design alternatives with the second performance criterion (*i.e. the contaminant concentration (CI) at the groundwater table should be less than 25 mg/L*) were determined. The design parameters used in POLLUTE simulations are given in Table 3.12.

Sensitivity analysis on climate and landfill area were carried out in order to confirm the compliance of the selected design alternatives presented in the design selection matrix under whole determined range of conditions. Further HELP and POLLUTE simulations for the design alternatives, yielding contaminant concentration close to the maximum contaminant level at the point of compliance (*i.e. groundwater table*) ($C_{\max} = 10\text{-}25 \text{ mg CI/L}$), were performed under higher end of arid climate range ($P = 450 \text{ mm/yr}$) and for a wetter moderate climatic condition ($P = 760 \text{ mm/yr}$). The results of the sensitivity runs were also included in the design selection matrix considering different landfill sizes. For example, the intermediate-engineering design alternative (C3L5) yielding a maximum chloride concentration of *21.1 mg CI/L* at the compliance point, under moderate climate with an annual precipitation amount of 660 mm/y and for a landfill size of 50 ha, was not included in the relevant section of the matrix. This is due to the fact that, as a result of climate sensitivity analyses, this alternative will not comply with the contamination criteria at the wetter range of that climate. All the design alternatives were tested and evaluated in the same manner, and the matrix was refined considering the wetter edges of the climate ranges.

Table 3. 12 Landfill design and subsurface hydraulic parameters used in POLLUTE simulations

Source	Value	Geomembrane	Value
Contaminant concentration	1000 mg/L	Thickness	2 mm
Landfill length ^a	2 ha → 200m 15 ha → 500m 50 ha → 1000m	Wrinkle frequency	10/ha
Waste thickness	5 m 20 m	Wrinkle width	0.3 m
Infiltration rate	<i>HELP output</i>	Wrinkle spacing	10 m
Waste density	550 kg/m ³	Wrinkle length	100 m
Percent of contaminant	0.1	Hole radius	0.00564 m
Hydraulic head		Diffusion coefficient	3x10 ⁻⁵ m ² /y
Hydraulic head on top of barrier	0.3m	Transmissivity	1x10 ⁻¹⁰ m ² /s
Groundwater level with respect to the top of aquifer	0m	Hydraulic conductivity of the drainage layer	0.001 m/s
Compacted clay liner		Vadose zone	
Thickness	0.6 m	Thickness	0.6 m
Density	1.9 g/cm ³	Density	1.9 g/cm ³
Hydraulic conductivity	1x10 ⁻⁹ m/s	Hydraulic conductivity	1x10 ⁻⁷ m/s (sand) 1x10 ⁻⁸ m/s (clay)
Diffusion coefficient	0.02 m ² /y	Diffusion coefficient	0.02 m ² /y
Dispersion coefficient	0 mL/g	Dispersion coefficient	0 mL/g
Porosity	0.4	Porosity	0.35 (sand) 0.45 (clay)
Aquifer		Aquifer	
Thickness	3 m	Seepage velocity	0.05 m/d 0.1 m/d 0.5 m/d 1 m/d

^aLandfil length in the direction of groundwater flow

3.2. Development of the Decision Support System

3.2.1. Decision Support System (DSS) Design

The design of a “landfill system” involves the interaction and simultaneous consideration of many variables and processes, which makes it a complex engineering problem. As stated before, decision support systems (DSS) can

handle this complexity and can lead to the solution of this complex environmental problem. Therefore, a two-step DSS was developed for performance-based landfill design.

The architecture of DSS is composed of *data gathering*, *diagnosis* and *decision support stages*. In *data gathering* stage, data required for design variables are compiled by the DSS as input to the preliminary design knowledge-base. In the *diagnosis* stage, the gathered data are evaluated by the preliminary design knowledge-base (design component selection matrix) and feasible landfill alternatives are proposed by the DSS. Proposed landfill design alternatives are simulated using site-specific design data by the models and modules running under DSS, and finally, the performance, stability, and cost evaluation of the landfill design alternatives are presented to the user in the final *decision support* stage (Figure 3.4).

Two approaches were evaluated for the development of DSS for landfill design – using readily available DSS platforms to integrate system simulation models (SSMs), and developing a new code and platform for integration.

For the first approach, two DSS platforms for model integration (i.e. RAISON, FRAMES) were evaluated. RAISON had seemed to be the most promising platform because the object system can process GIS maps and databases and it is suitable for the application of technical user interfaces to link models. However, based on the communications with the developers of the program (Environment Canada), although the RASION object system (ROS) is the only system that offers a rule-based expert system component for decision making, ROS is not a “shrink-wrapped” system and it lacks flexibility to easily integrate external models for challenging tasks. Moreover, the platform is not user-friendly, and integrating external models requires assistance of the developers. Therefore, RAISON has been excluded from the list of alternative DSS platforms.

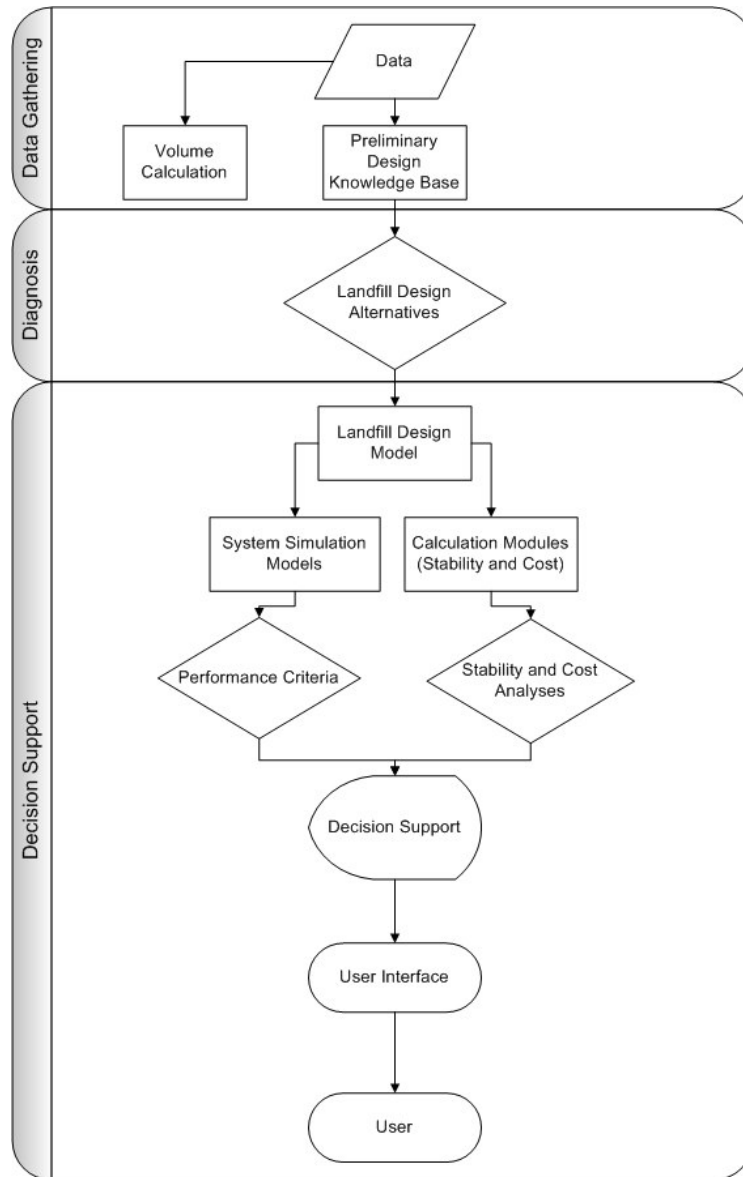


Figure 3. 4 Architecture of decision support system

The second DSS platform, FRAMES, on the other hand, is an open-architecture framework, which allows for the seamless communication of disparate models and databases, using pre-determined file formats. However, FRAMES not only lacks the expert system module, which is required during the preliminary design phase and to interpret the results of the detailed design phase, but also the

platform is not capable of interfacing new external models under the framework to run the SSMs or linking SSMs for data transfer. Therefore, FRAMES has also been excluded from the alternative DSS platform list.

Besides RAISON and FRAMES, opportunity of integration under another platform, ARGUS ONE, was investigated. ARGUS ONE is an intelligent GIS having an open numerical environment to link models and databases. Using the plug-in extensions (PIEs) of ARGUS ONE, it is possible to link external codes to the platform and to couple models running under the platform. PIEs do not require algorithms of the models to be interfaced. The models are linked as DLLs/Shared-Libraries, and saved into a special directory from which they are seamlessly linked to Argus ONE. Instructions to ARGUS ONE to format the output of a particular model in the required input format for a second model can be created by a simple export script language. ARGUS ONE does not offer a decision-making component; however, it is possible to plug-in a rule-base expert system component using PIEs. Although ARGUS ONE seemed to be a promising platform, the communications with the developers showed that, due to its numerical nature, the platform is too complicated to be used for the purposes of the conceptual model developed for the thesis study.

Detailed examination of the readily available DSS platforms exposed that the most robust technique to integrate the SSMs, design model, and modules is to develop a new DSS from the ground up, which would run based on the requirements of the conceptual model and would also be flexible enough to incorporate new models or algorithms when necessary. Thus, a new DSS named as **LFDSS**, abbreviation for “*Landfill Decision Support System*”, was developed with the assistance of a technical staff on code writing. LFDSS integrates four main components; design component selection matrix, a custom landfill base contour design model (Virtual Landfill –VLF), system simulation models (SSMs; HELP model and POLLUTE model), and calculation modules (i.e. stability,

volume, cost). The integration of these components and the design of the platform adhere to the conceptual model.

The new DSS consists of a common user interface which runs without using the interfaces of HELP or POLLUTE models. LFDSS runs under Microsoft .NET platform, and is developed using C# programming language. The technical details of LFDSS are presented in Appendix-B. All components except VLF are unified under a common user interface application, accessible from LFDSS, in order to give the user flexibility of performing landfill base contour designs independently. The components are further divided into one or multiple modules that encapsulate core functionality or interaction with the user. In particular, a special attention is paid to ease of use and the number of parameters that need to be entered by the user is minimized as much as possible without compromising functionality. Consequently, this also led to a simplified user interface providing a user-friendly SSM input platform. Under the LFDSS, HELP, POLLUTE, and Virtual Landfill directories are defined at the beginning of the DSS setup. This prevents the operation corruptions when the directories of either of the SSMs change. The unified set of parameters is stored in XML format, which facilitates portability and also allows editing them even on a computer that does not have LFDSS installed (for example, using an XML editor).

3.2.2. Coupling System Simulation Models (SSM)

Coupling of models, which are not directly inter-operable, under a DSS platform requires the exchange and/or processing of input and/or output data among them and also other components of the system. Availability of the models for data exchange/process can be understood by accessing the codes of the models and their input/output data format. The major models (SSMs) to be integrated under LFDSS platform are HELP and POLLUTE models. The landfill base contour design model, namely Virtual Landfill –VLF, is embedded in the platform.

Therefore, input parameters of the SSMs (i.e. HELP, and POLLUTE) were analyzed, categorized, and feasible data-exchange possibilities were investigated to design a compatible data flow (Figure 3.5). The data flow to and from calculation modules and landfill base contour design model (i.e. Virtual Landfill – VLF) are also investigated and explained in Sections 3.2.4 and 3.2.5.

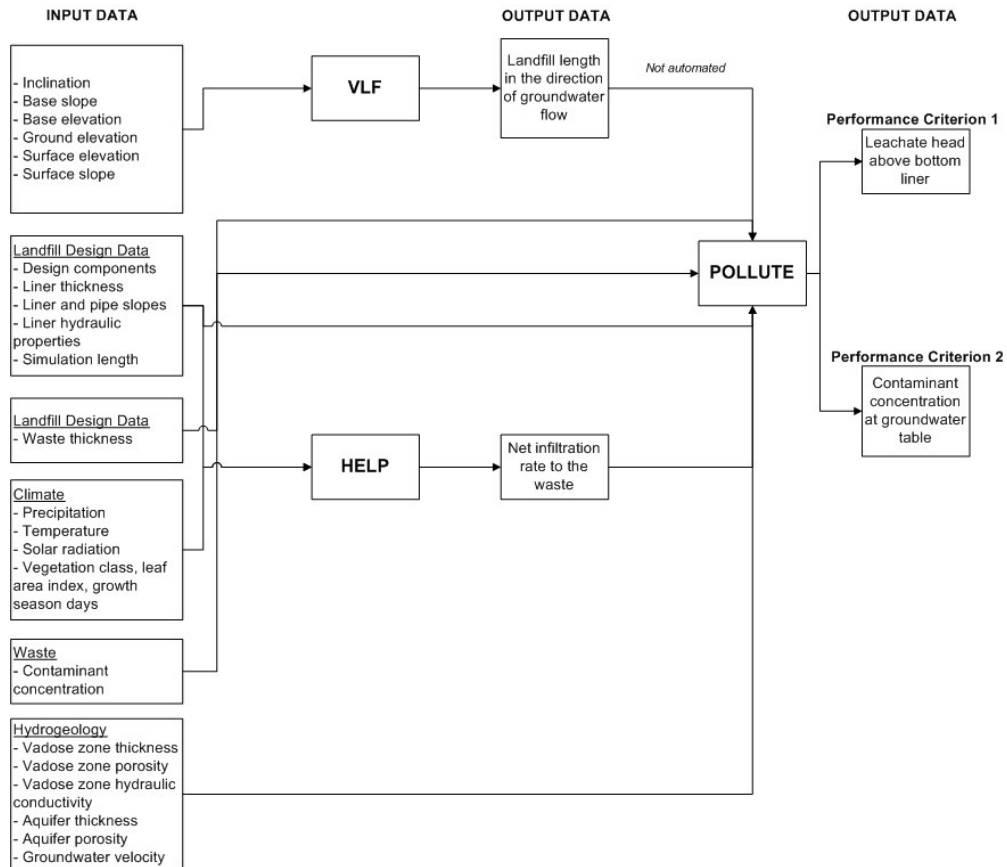


Figure 3. 5 Data flow between SSMs

3.2.2.1. Exploring Codes of HELP Model

HELP version 3.0, cover design model, was developed using FORTRAN programming language. All of the source codes of the program are available and, the output data format can be accessed by using these codes.

As can be seen from Figure 3.5, HELP uses the climatic and final cover liner property data. All of these data are either defined or present in the model's databases, or can be specified by the user. Therefore, HELP model does not require input data from the waste and bottom liner design and subsurface transport model (i.e. POLLUTE). However, the model creates an important output; infiltration below the final cover to the waste. This output is used by POLLUTE, as input data. Therefore, the output data format of HELP model needs to be compatible with the input data format of POLLUTE, or acceptable by the DSS platform. HELP model gives output in ASCII format. This format is acceptable by POLLUTE and also by the DSS platform.

HELP model is operated under 5 submenus: soil and design, evapotranspiration, temperature, precipitation, and solar radiation. The model is executed within the LFDSS via another submenu called "Run". Details for the input/output requirements and operation of the model under LFDSS are provided in Section 3.2.5.2.

3.2.2.2. *Exploring Codes of POLLUTE Model*

POLLUTE is the waste and bottom liner design and subsurface transport model. The model was also developed using FORTRAN programming language. Source codes of the program are available and, the output data format can be accessed by using these codes.

Figure 3.5 demonstrates that, POLLUTE requires the landfill design (e.g. waste thickness, liner and soil properties, etc.), hydrogeologic and net infiltration rate data. Landfill design data (i.e. landfill length in the direction of groundwater flow and waste thickness) are either specified by the user or obtained from landfill base contour design model –Virtual Landfill (VLF). Leakage rate to the waste data from the HELP model is used by POLLUTE model as net infiltration rate.

POLLUTE first determines the compliance to the first performance criterion, stability criterion, as soon as the input data are entered. The simulations are carried out for the landfill design alternatives which satisfy the stability criterion. As POLLUTE is the last SSM used in the DSS, output of the model is not transferred. Output data of POLLUTE, which is also in ASCII format, either indicate the maximum contaminant concentration at the groundwater table or at specified depths throughout the landfill profile, or contaminant concentrations at specified times at the groundwater table or at all depths. These results are directly processed by the DSS to evaluate the overall landfill design.

POLLUTE model is operated under three tabs separated into subsections for proper data entry. First tab is the *Parameters* tab, where waste and bottom liner design parameters are specified. Second tab is the *Maximum Concentrations* tab, where the run parameters are specified and results of maximum concentration and time of occurrence of maximum concentration are presented to the user. In the third tab, *Concentrations at Specified Times*, contamination trend with time can be observed, if required. The model is simulated by cursor touches via a macro, as if the user is clicking on the mouse. Therefore, when POLLUTE model is run under LFDSS, the macro executes the main execution module of POLLUTE outside the LFDSS. Therefore, this integration requires the POLLUTE model to be a registered software in the computer that LFDSS is located. Further details for the input/output requirements and operation of the model under LFDSS are provided in Section 3.2.5.3.

3.2.2.3. *Coupling Methodology*

HELP and POLLUTE are implemented by third-party applications. For the integration of these SSMs to the DSS platform, Graphical User Interface (GUI) coupling method is used (Figure 3.6). In this method, a common interface integrates the models. The user does not directly interacts with the models and

corresponding applications, but rather the provided user interface acts as a bridge between the user and models, effectively hiding the details of complex configurations and operations that need to be set and executed. This level of integration is a robust, simple and user-friendly way of modeling.

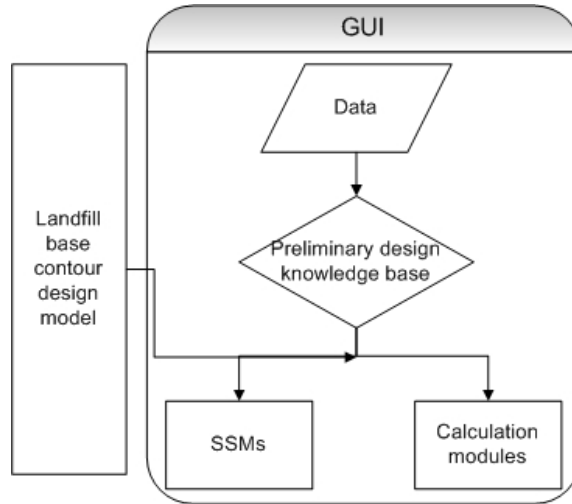


Figure 3. 6 Graphical user interface (GUI) coupling methodology

In order to realize this method, special modules that interface with the aforementioned SSMs were developed. The version of HELP model used is a command line (DOS) application, which requires input as a series of text files and similarly produces output as a text file. Therefore, the module for the HELP model (i) creates the specially formatted text files based on the parameters entered by the user, (ii) runs the model, (iii) parses the resulting output file generated by the model and extracts the information required for further calculations (in particular, the value of “*maximum leakage rate through the final cover*”), and finally (iv) transfers extracted information back to LFDSS. POLLUTE model, on the other hand, is a graphical application, which requires the user to enter the model parameters and export the results interactively by filling several forms and editing dialog boxes. For the POLLUTE module, scripted macros were used. The macros allowed defining a combination of simulated keystrokes, mouse

movement and window/control manipulation in order to automate Windows GUI tasks (Appendix-B). The POLLUTE module generates a set of parameters required by the POLLUTE model based on the parameters entered by the user, saves them in the form of text files which can be loaded by the scripts, starts the POLLUTE model and executes the scripts. The scripts are responsible for (i) automatically transferring the generated parameters to the POLLUTE model as if the user is entering them manually, (ii) running the model, and (iii) transferring the results back to LFDSS or in some cases commanding the model to display them visually to the user.

3.2.3. Decision Support System (DSS) Framework

A framework was defined in order to describe the model interactions and the function of DSS. Performance based landfill design is composed of two steps; *preliminary landfill design phase* and *detailed/final landfill design phase*.

In the *preliminary design phase*, ranges or classes of design variables are determined; i.e. the design variable is classified to be in arid climate range if it indicates a precipitation amount less than 500 mm/y. All the design variables (climate, landfill size, seepage velocity, waste thickness and hydraulic conductivity) are classified according to the defined ranges (Table 3.13) and classes are entered to the rule base. The matching results are selected from the design selection matrix decision tree via rule base. Therefore, the preliminary design phase requires the expert system rule base involvement. Communication between SSMs and calculation modules are not necessary at this stage. This phase is completed by the list of landfill design alternatives which are expected to result in desired acceptable performance.

Table 3. 13 Defined ranges of design variables

	Value
Climate	
Arid	$P \leq 500$ mm/y
Moderate	$500 < P \leq 1000$ mm/y
Humid	$P > 1000$ mm/y
Landfill Size	
Communal	$A \leq 2$ ha
Small	$2 < A \leq 15$ ha
Medium	$15 < A \leq 50$ ha
Large	$A > 50$ ha
Hydrogeology	
Sandy vadose zone	10 m, 10^{-7} m/s
Clayey vadose zone	10 m, 10^{-8} m/s
Waste Thickness	
Shallow	5 m
Deep	20 m
Seepage Velocity	
Very slow	$v \leq 0.05$ m/d
Slow	$0.05 < v \leq 0.1$ m/d
Medium	$0.1 < v \leq 0.5$ m/d
Fast	$0.5 < v \leq 1$ m/d

In the *detailed design phase* each of the proposed design alternatives is evaluated by using site-specific parameter values. This phase requires the communication between HELP and POLLUTE models, and between landfill base contour design model (Virtual Landfill –VLF) and POLLUTE models. Selected design alternatives are simulated using site-specific data as input to the SSMs. The value of design variable can be selected from the databases or literature, in case site-specific data are not available. Data are entered to HELP model first and transferred to POLLUTE. POLLUTE model uses the infiltration rate output generated by HELP model and exported to the GUI (graphical user interface) and produces leachate head over bottom liner and groundwater contaminant concentration results. If the design satisfies the performance criteria (i.e. maximum leachate head over bottom liner and maximum groundwater contaminant concentration under the selected landfill base contour design), stability analyses are carried out and costs of major design components are

calculated. The procedure would be repeated for each of the proposed design alternative in the preliminary design phase. The DSS evaluates the results of all contamination, stability, and cost analyses, and proposes the comparative results of each evaluated landfill design alternative to the user in tables. By this way, it is possible to conduct performance, stability, and cost-based comparison among different landfill designs.

3.2.4. Preliminary Design Phase

As previously stated, the DSS framework consists of two steps; *preliminary design phase* and *the final/detailed design phase*. The preliminary design phase enables the user to calculate the volume of landfill required for the anticipated amount of waste and to enter the design variable classes of a site of concern. It is possible to calculate approximate waste thickness and landfill area regarding the calculated landfill volume. When the approximate values of the design variables are entered to the system, the DSS proposes the user a selection of appropriate design alternatives, using the knowledge-base (i.e. design component selection matrices). There are two modules in the preliminary design phase: volume calculation module and preliminary design knowledge base. Data flow scheme of the modules in preliminary landfill design phase is given in Figure 3.7. These modules are explained in the following sections.

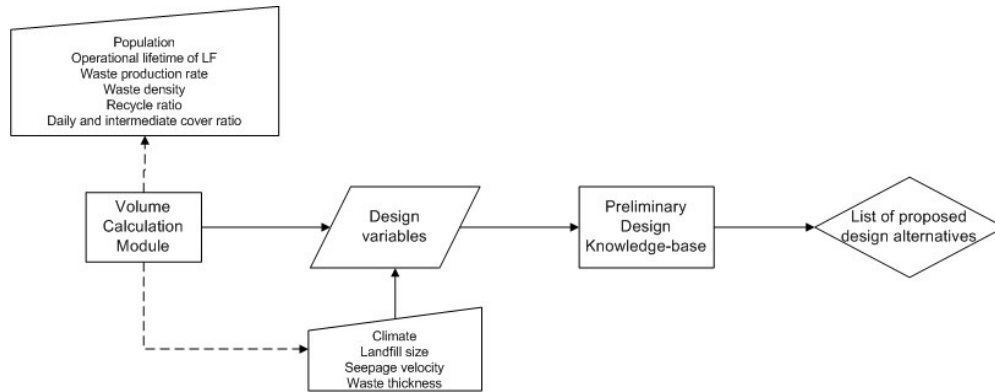


Figure 3. 7 Data flow in preliminary design phase in LFDSS

3.2.4.1. Volume Calculation Module

Volume calculation module was developed as an MS Excel spreadsheet to calculate the required volume of landfill when the projected design population, operational lifetime of landfill, waste production rate, waste density, recycle ratio, and daily and intermediate cover ratio are known. Turkish guidance values for waste production rate (0.5 – 2.0 kg/cap/day; typical being 1.04 kg/cap/day (DIE, 2001)) and reference values for waste density (İller Bankası, 2000) are provided within the module (Table 3.14).

Table 3. 14 Waste density values (İller Bankası, 2000)

Waste Type	Waste Density (kg/m ³)
Municipal waste, uncompacted	90 - 200
Municipal waste, compacted in truck	180 - 450
Municipal waste, compacted in landfill	360 - 510
Municipal waste, well compacted in landfill	600 - 750
Municipal waste, shredded but uncompacted	120 - 270
Municipal waste, shredded and compacted	660 - 1080

The amount of waste to be disposed in the landfill (V_{waste}) is calculated using Eq. 3.7.

$$V_{waste} = \frac{P \times t_{LF} \times 365 \times r_w}{\rho_w} \quad (3.7)$$

Where P is projected design population, t_{LF} is operational lifetime of landfill (years), r_w is waste production rate (kg/cap/day), and ρ_w is waste density (kg/m³). The required volume of landfill is then calculated by considering recycling ratio – if applicable, and daily and intermediate cover ratio (Eq. 3.8):

$$\begin{aligned} V_{waste_after_recycling} &= V_{waste} - r_{recycle} \times V_{waste} \\ V_{LF} &= V_{waste(or_waste_after_recycling)} + r_{d\&i} \times V_{waste(or_waste_after_recycling)} \end{aligned} \quad (3.8)$$

Where $V_{waste_after_recycling}$ is the volume of waste after recycled materials are removed from waste stream (m³), $r_{recycle}$ is the recycling ratio (%), V_{LF} is the volume of landfill (m³), and $r_{d\&i}$ is the daily and intermediate cover ratio (in decimals).

The calculated landfill volume can be divided into expected waste thickness in order to obtain an approximate landfill base area to be used as input to the preliminary knowledge base. Moreover, the calculated landfill volume can be compared with the volume calculated by the landfill base contour design model (Virtual Landfill –VLF) to check whether the landfill orientation applied by the user in VLF is fulfilling the volume requirements. The input data requirements and output data supplied by the module are presented in Table 3.15.

Table 3. 15 Input data requirement and output data supplied by Volume Calculation Module

Input	From Model/Module	Output	To Model/Module
Design population	User defined	Required landfill volume	Virtual Landfill
Waste production rate	User defined	Landfill base area	Preliminary knowledge base
Operational lifetime of landfill	User defined		
Waste density	User defined		
Recycling ratio	User defined		
Daily and intermediate cover ratio	User defined		

MS Excel spreadsheet accommodating the volume calculation formulae was used as basis for the formation of Volume Calculation Module in LFDSS. It is possible to input data manually or via copy and paste from other sources (e.g. MS Excel) in a tabular form using the *DataGridView* property of *Visual C#*. This property creates a user-friendly environment for data input, and also, eases multiple calculations under a single menu in LFDSS (Figure 3.8).

LFDSS v1.0

File

Virtual Land Fill Save Results

Preliminary Design Help Pollute Stability Cost Volume Calculation

Design Population: 100000

Operational Lifetime of Land Fill (year): 15

Waste Production Rate (kg/cap/day): 1.5 (Turkish guidance value, 0.5 - 2.0 kg/cap/day, typical = 1.04 kg/cap/day*)

Waste Density (kg/m3): 600 (see guidance values)

Total Waste Volume (m3): 1368750

Calculate

Recycling Rate (%): 25

Waste Volume to be Landfilled (m3): 1026562.5

Daily and Intermediate Cover Ratio: 0.2

Total Landfill Volume (m3): 1231875

Waste Density - Reference Values

Waste Type	Waste Density (kg/m3)
municipal waste, uncompacted	90 - 200
municipal waste, compacted in truck	180 - 450
municipal waste, compacted in landfill	360 - 510
municipal waste, well compacted in landfill	600 - 750
municipal waste, shredded but uncompacted	120 - 270
municipal waste, shredded and compacted	660 - 1080

(*) Reference: İller Bankası, Katı Atık Tesisi Projesi: Proje Yapım İşine Ait Genel Teknik Şartnamesi, 2000.

Figure 3. 8 Screenshot of LFDSS for the Volume Calculation Module

3.2.4.2. Preliminary Design Knowledge Base

Preliminary design knowledge base was developed from the design component selection matrices. The rules of the matrices were defined (Appendix-C) to construct a decision tree (Figure 3.9).

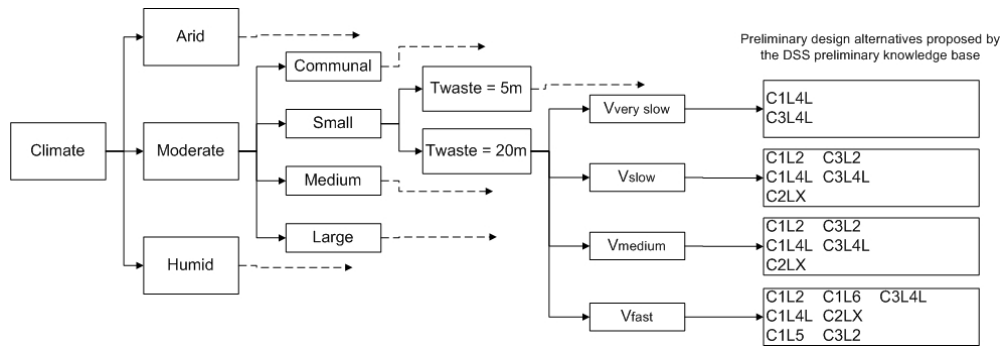


Figure 3. 9 Structure of decision tree to construct the rule base in preliminary design (Only a part of the branches are demonstrated due to space limitation)

As the LFDSS platform is coded in C# language under .NET platform, the rules and the user interface for the user to enter design variable ranges were also defined using C# code. The user interface is a form to select the design variable (i.e. climate, landfill area, seepage velocity, and waste thickness) ranges. The design component selection matrices are text files defined in CSV (comma-separated values) format in MS Excel. Each cell was separated by a semicolon (;), and if a cell included multiple values (e.g. more than one design alternative) then these values were separated by commas (,) (e.g. presentations of the columns A8-A12 and A15-A18 are as follows: *C1L2, C1L4L, C2LX, C3L2, C3L4L; C1L2, C1L4L, C3L2, C3L4L*).

A parser is a part of software that processes the rules of the matrices and separates them into sub-rules, and prepares the rules in a form that the computer can read and understand. Therefore, a parser was written to identify definitions and the rules of the matrix in a text file. Using this parser, the related columns in the matrix could be read by the DSS, or, warnings to the user could be displayed on the screen. For example, for a humid climate, to present the design alternatives for a shallow waste thickness (i.e. 5 m), slow seepage velocity (i.e. 0.05 - 0.1 m/d), and a small landfill size (i.e. 2 – 15 ha), the definitions in the text file are defined as:

climate>1000,thickness=5,velocity>0.05,velocity<=0.1,size>2,size<=15;
sample.csv:K8-K12

And the design alternatives between columns K8 and K12 are presented to the user. Or, to display the warning “USE DOUBLE LINER SYSTEMS” on the screen when the selected ranges are –for example, for moderate climate, deep waste thickness (i.e. 20 m), very slow seepage velocity (i.e. ≤ 0.05 m/d), and large landfill size (i.e. > 50 ha), the definitions in the text file were defined as:

climate>500,climate<=1000,thickness=20,velocity>0,velocity<=0.05,size>50;
"USE DOUBLE LINER SYSTEMS; OR EXTENSIVE ENGINEERING LANDFILL
DESIGN ON CLAYEY SOILS"

And the warning “USE DOUBLE LINER SYSTEMS; OR EXTENSIVE ENGINEERING LANDFILL DESIGN ON CLAYEY SOILS” is displayed on the screen. Therefore, the component of the DSS to perform preliminary design assessments was completed. This component enables the user to enter the design variable ranges into the DSS via a user interface and the DSS proposes a list of best-performing preliminary design alternatives for the given site conditions. When any of the landfill designs from the list is clicked, a schematic drawing is presented to the user as an illustration of the design conditions (Figure 3.10).

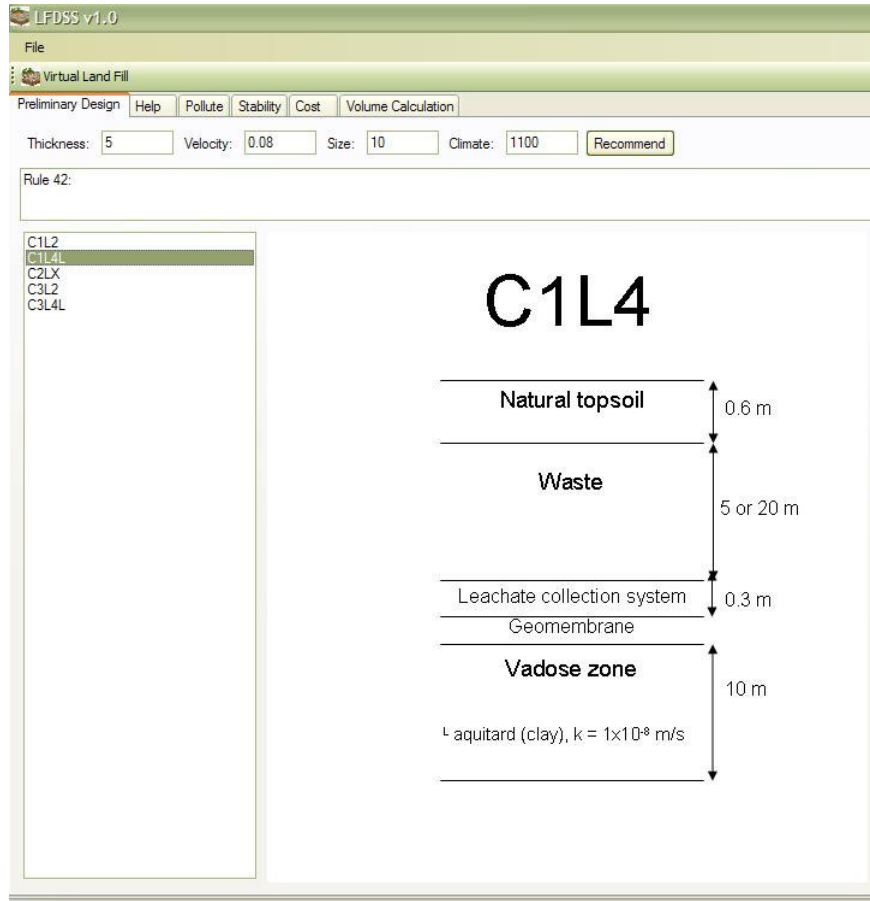


Figure 3. 10 Screenshot of LFDSS for the Preliminary Design Knowledge Base

3.2.5. Detailed Design Phase

After the landfill design alternatives are proposed by the preliminary design knowledge base in the preliminary design phase, these proposed alternatives are further simulated using site-specific parameter values obtained by site investigations (e.g. well logs, hydrogeologic and geotechnical investigations, etc.). The purpose of the detailed design phase is to compare the proposed landfill design alternatives performance-wise, stability-wise, and cost-wise; and, to aid in the decision making process for the optimum design under the given site conditions.

A landfill base contour design model (Virtual Landfill –VLF) to orientate and design the landfill for a given site, two SSMs (HELP and POLLUTE) to simulate the landfill design alternatives for evaluating their compliance to performance criteria, and two calculation modules (stability and cost) to evaluate the stability of landfill design alternatives and to calculate the costs of major design components are used at this stage. The output data supplied by models and modules are presented to the user to aid in the decision making process. The data flow scheme of detailed design phase is given in Figure 3.11. In the following sections, the input data requirements of models and modules and output data supplied by the models and modules, data transfer methods, and integration methods to the LFDSS are explained in further detail.

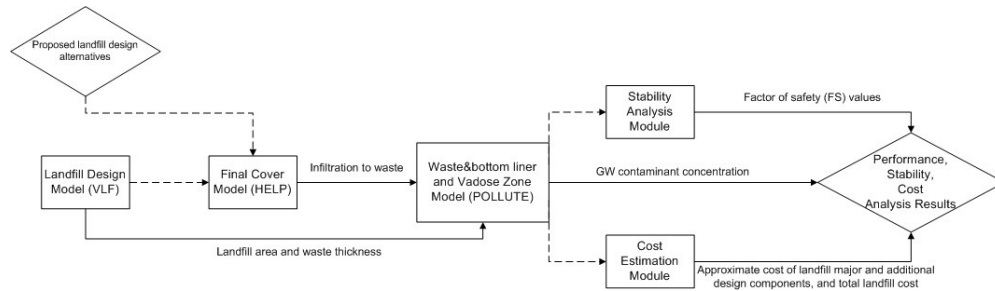


Figure 3. 11 Data flow in detailed/final design phase in LFDSS

3.2.5.1. Landfill Base Contour Design Model (Virtual Landfill)

Instead of integrating commercial GIS packages into the developed DSS, a specific code for performing required landfill calculations was conceptualized. The new code was designed to perform map digitization, 3D image viewing, and length, area and volume calculations on the digital maps. The programme was required to be capable of presenting the coordinates of the landfill placed on a topographic map, available clay layer beneath the landfill, location of groundwater and direction of groundwater flow, excavation and fill volumes calculated according to the given excavation depth and landfill area, and 3D views

of landfill (with or without final cover). The programme was designed to be flexible enough to test desired base grades and landfill orientations as many times as needed with respect to the topography and recalculate excavation and fill volumes and landfill area according to the new orientation. After the conceptual requirements were defined, the virtual landfill base contour design programme, called Virtual Landfill (VLF) was developed. The technical details of VLF are presented in Appendix-D.

The primary function of VLF is to help user in the selection of base grade and orientation of the landfill on the site considering the site topography, available clay layer beneath the landfill, and groundwater depth and flow direction. The model is capable of calculating excavation and fill volumes once the landfill base area, base elevation, side slopes, and ground elevation of the landfill are given as input. Moreover, to be included to the volume calculations, the surface (final cover) of the landfill can be identified to the model by entering surface elevation and surface slope. The model is capable of visually demonstrating the landfill – both with or without final cover- in 3D.

To design a landfill of specific volume and base area (e.g. volume and area may be specified using volume calculation module), first the Base-DEM (digital elevation model) file of the topography of concern is required to be uploaded to the model. If available, clay layer and groundwater layer DEM files are also required to be uploaded for orientation purposes. The base area is drawn on the topography, and the size of the base in hectares (ha) is followed from the *base area box* in the *knowledge sheet* on the left hand side. The depth of excavation, base slope and the value of side slopes (inclination) must be determined by user to calculate and define base and ground elevations. For the situations where the topography is rough, maximum excavation depths and maximum waste heights can be defined in the model using margin functions for stability reasons. Besides the base slope, base slope directions can also be defined. To model the final cover,

surface slope and height of waste from ground elevation to the top of the landfill should be determined by user to calculate the horizontal surface length and to define the surface elevation and surface slope to the model. Finally, the ground offset parameter can be defined to identify the anticipated thickness of final cover over the landfill. After defining the input parameters, the excavation, fill, surface volumes are calculated by hitting “calculate” button and the results are presented in the *knowledge sheet* in cubic decameters. The excavated areas are shown with light blue, whereas the parts required to be filled are shown with dark blue on the map (Figure 3.12). The 3D views of the landfill with and without surface cover are also presented to the user (Figure 3.13).

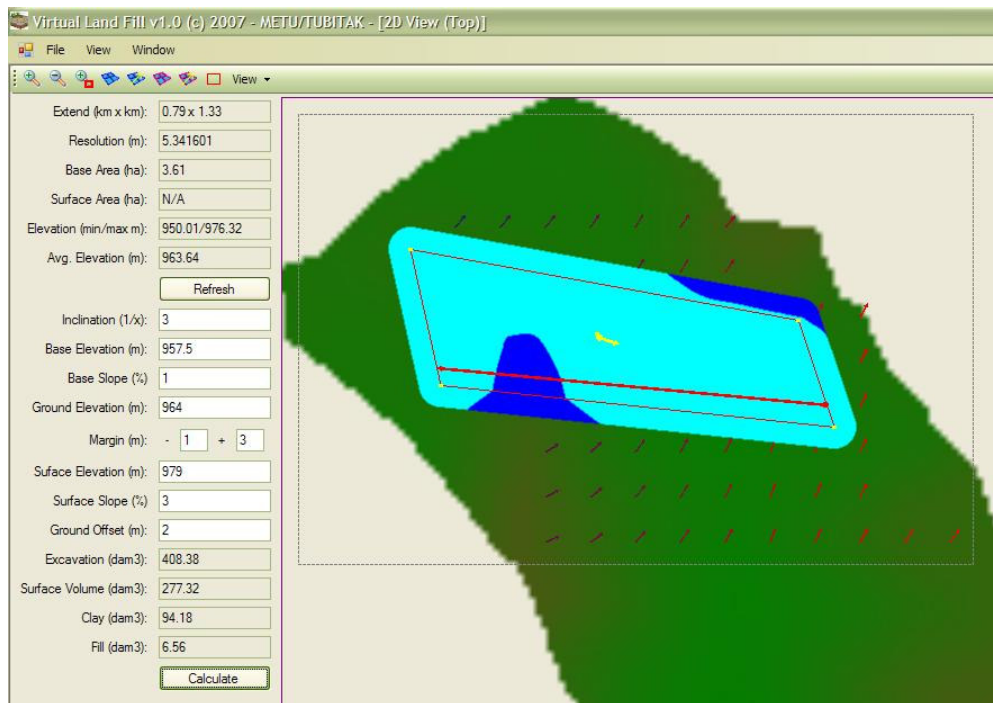


Figure 3. 12 2D demonstration and excavation, fill, and surface volumes of a specified landfill on Virtual Landfill -VLF

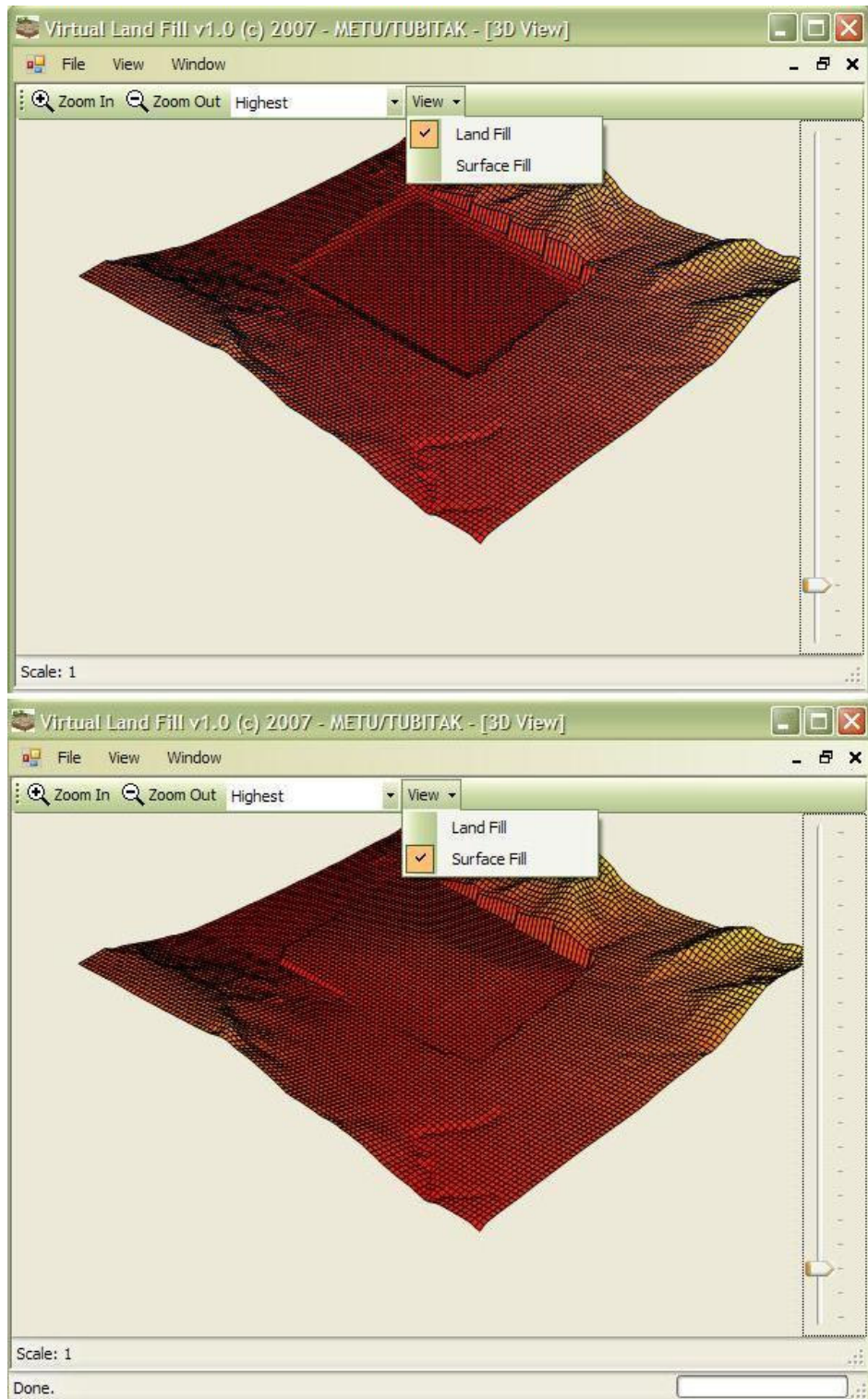


Figure 3. 13 3D representation of landfill excavation and final cover in Virtual Landfill –VLF

If available, DEM files of in situ clay present at the site can be added to the model. To represent the clay layer, DEM files of top and bottom of the clay profile are uploaded from the “Layers” dialog box. The layer is represented by user-defined colors and the thickness is indicated with a color scale (darker color indicates thicker layers, whereas lighter color thinner layers) on the topographic map. When the “Clay Layer” option in the ‘View’ menu is turned on, the relation between the landfill base and the clay layer is presented to the user. The areas shown by red indicate the absence of the clay layer, areas shown by green indicate that the clay layer begins below the vadose zone beneath the landfill (i.e. there is a non-clay material between the landfill base and the top of the clay layer), and the areas shown by blue indicate that the base of the landfill intersects with the clay layer (i.e. the landfill sits on top of the clay layer). Available clay volume remaining at the base of the landfill after excavation is shown in the *knowledge sheet* in cubic decameters (Figure 3.14).

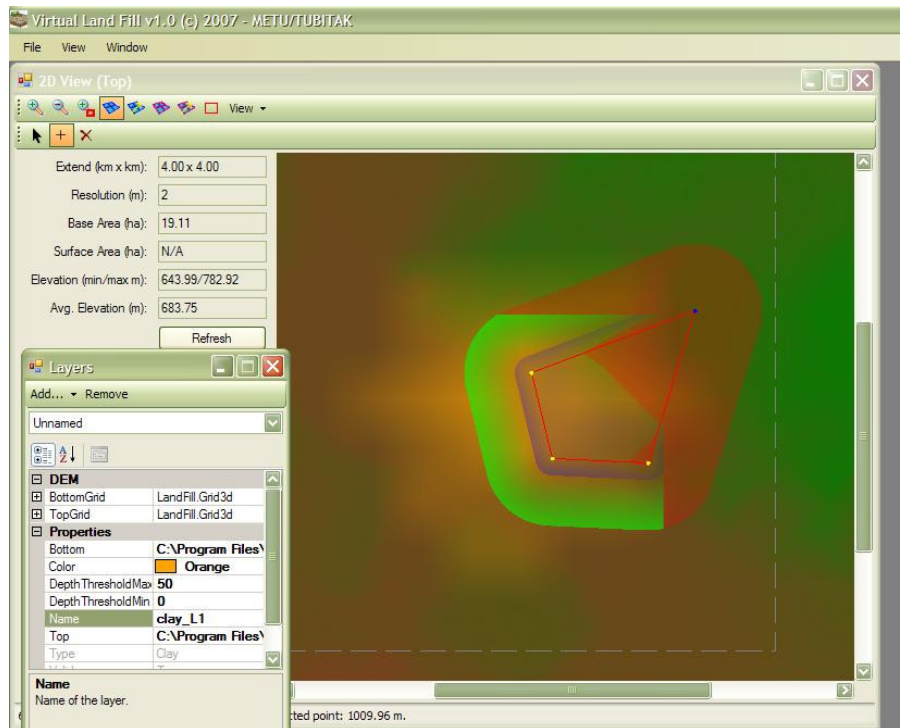


Figure 3. 14 Presenting the available clay layer beneath the landfill in Virtual Landfill –VLF

If also available and present at the site, groundwater depth and flow direction can be specified on the topographic map in VLF using Groundwater-DEMs. Two DEM files, depth and direction, must be defined and uploaded to represent groundwater layers. Groundwater DEMs are uploaded from “Layers” dialog box. Minimum and maximum depth thresholds of the aquifer, and color scale to represent these thresholds are specified by the user in Layers dialog box. The groundwater flow direction and depth of aquifer (e.g. deeper side of the aquifer is represented by midnight blue, whereas shallower side is represented by red on the figure) are presented to the user on the topographic map (Figure 3.15).

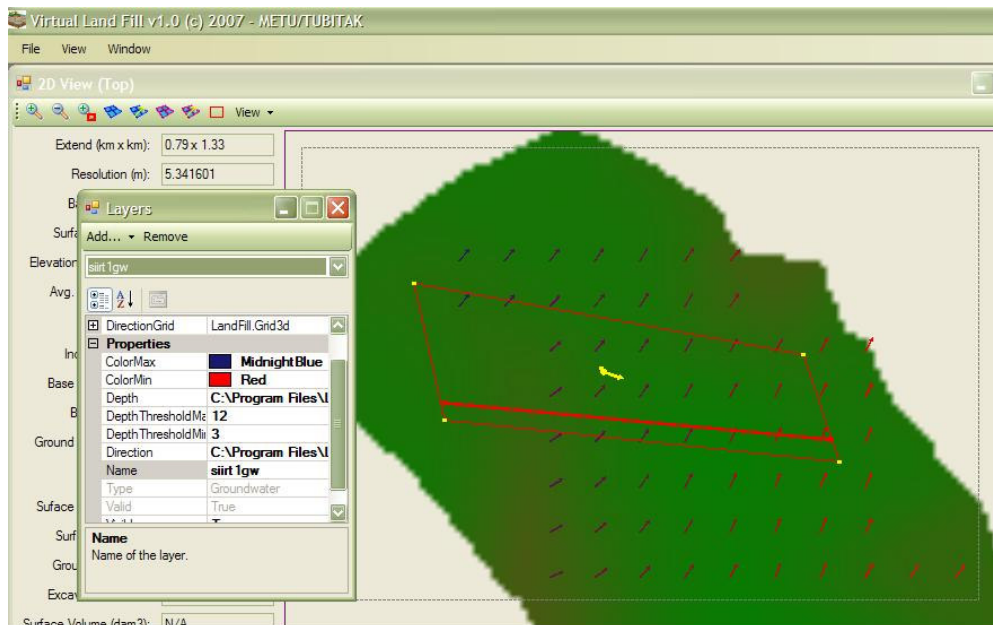


Figure 3. 15 Presenting the groundwater flow direction and aquifer depth in Virtual Landfill –VLF

The input data requirements and output data supplied by the model are presented in Table 3.16.

Table 3. 16 Input data requirement and output data supplied by Virtual Landfill –VLF

Input	From Model/Module	Output	To Model/Module
Base DEM	User defined	Required landfill volume	Volume Calculation Module
Clay DEM	User defined	Landfill base area (Landfill length in the direction of groundwater flow)	POLLUTE
Groundwater DEM	User defined	Waste thickness	POLLUTE
Inclination (side slope)	User defined		
Base elevation	User defined		
Base slope	User defined		
Ground elevation	User defined		
Margins	User defined		
Surface elevation	User defined		
Surface slope	User defined		
Ground offset	User defined		

The base area (landfill length in the direction of groundwater flow) and average waste thickness obtained by using VLF are used as design specific values for POLLUTE simulations. The transfer of these data is achieved manually.

Virtual Landfill (VLF) is embedded into LFDSS platform as an externally operating tool, and it is run by clicking on the Virtual Landfill button at the top menu. As the LFDSS platform is based on .NET, any open-coded software can be added to the platform as a tool and run under it. To locate VLF in the LFDSS, the

directory of the model is required to be defined at the start-up of the DSS platform.

3.2.5.2. *Cover Design Evaluation Model (HELP)*

HELP model was included within the LFDSS to obtain the infiltration rate from the final cover reaching the waste. Performance of different final cover types (i.e. evapotranspiration cover –C1, extensive engineering final cover –C2, and intermediate design final cover –C3) composed of different design components (i.e. natural top soil, cover drainage system, geomembrane, and clay liner) are evaluated and net infiltration rate leaving the final cover is calculated by the model.

HELP model is operated under five submenus: soil and design, evapotranspiration, precipitation, temperature, and solar radiation. Input data requirements of each submenu are given in Table 3.17. The input data can either be defined by the user regarding the specific properties of the landfill final cover design, or HELP databases for soil properties can be used (Figure 3.16).

Table 3. 17 Input data requirement and output data supplied by HELP model

Input Data^a	Input Data^a	Output	To Model/Module
<i>Soil&design data</i>	<i>Evapotranspiration</i>	Infiltration rate	POLLUTE
Landfill area	Latitude		
% of area where runoff is possible	Evaporative zone depth		
Initial moisture	Max. leaf area index		
Amount of water or snow on surface	Growing season start day		
Layer type (natural soil (1)/geomembrane (4) /barrier-clay (3)/drainage (2))	Growing season end day		
Layer thickness	Average wind speed		
Soil type (numbers defining soil codes are given in HELP database)	1 st quarter relative humidity		
Total porosity	2 nd quarter relative humidity		
Field capacity	3 rd quarter relative humidity		
Wilting point	4 th quarter relative humidity		
Initial moisture Saturated hydraulic conductivity	<i>Climatic data</i>		
Drainage length	Daily precipitation		
Drain slope	Daily temperature		
Leachate recirculation	Daily solar radiation		
Recirculation to layer # (number of the layer)			
Subsurface inflow			
Geomembrane pinhole density			
Geomembrane installation defects			
Geomembrane placement quality			
Geotextile transmissivity			

^a Defined by user, or obtained using HELP database

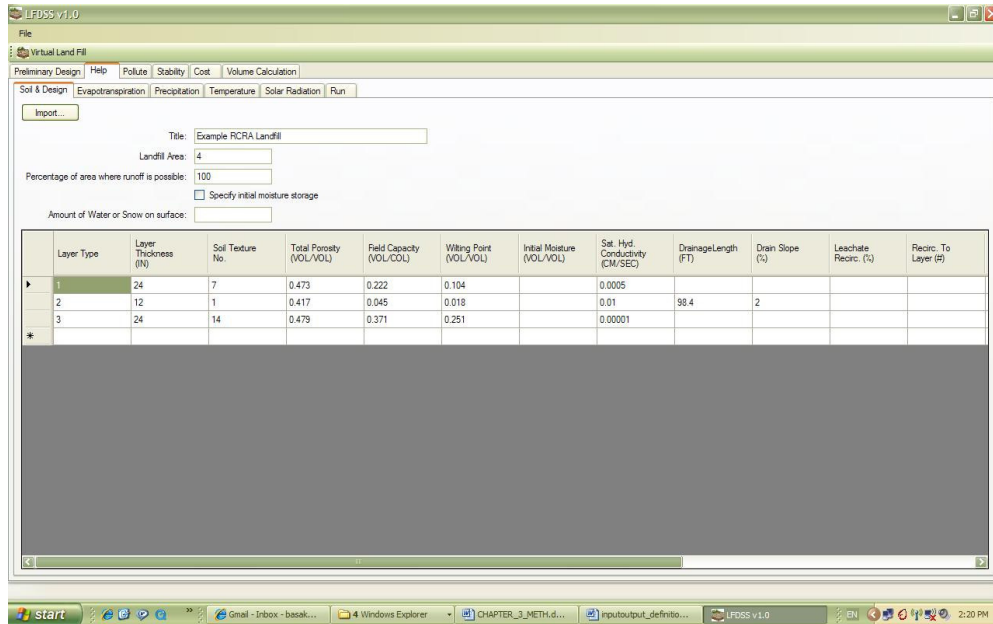


Figure 3. 16 Soil and design input window for HELP model in LFDSS

The sixth submenu (Run) is used to execute the HELP model. Units to display the results, number of years for simulation, and output type are required to be defined by the user (Figure 3.17). HELP model is executed within the LFDSS (Figure 3.18). The simulation is completed by the presentation of annual values of precipitation, evapotranspiration, surface runoff, drainage from, percolation to, and average head over final cover layers, water budget and the “Infiltration” rate under the Run menu (Figure 3.19). The infiltration value is automatically transferred to POLLUTE dialog box. The integration of HELP model and data transfer method to POLLUTE was previously given in Section 3.2.2.3.

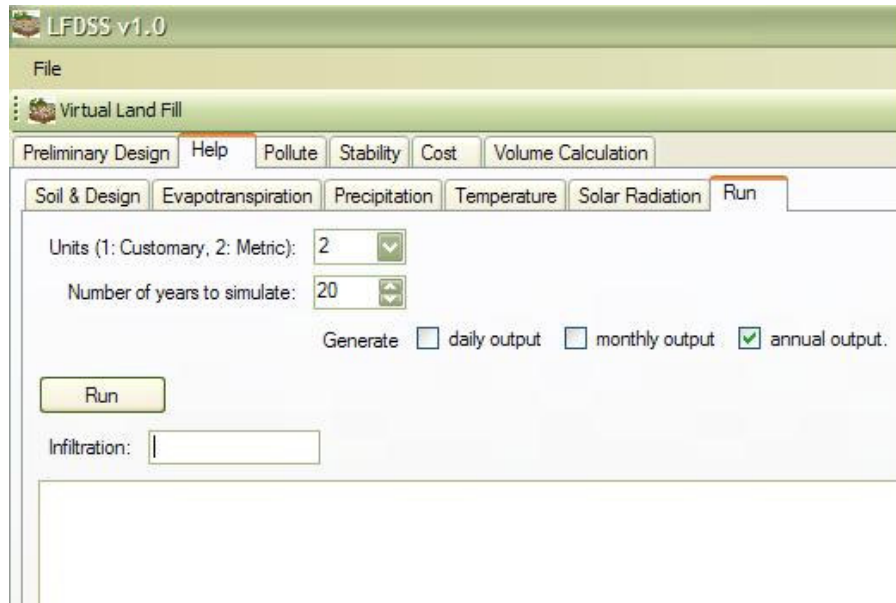


Figure 3. 17 Run menu for HELP model in LFDSS

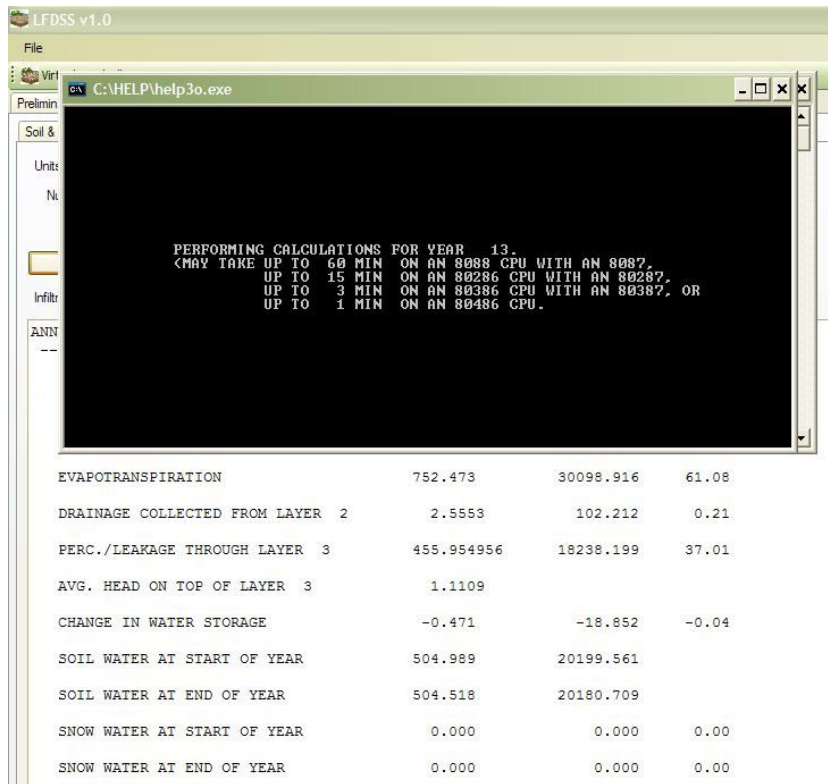


Figure 3. 18 Execution of HELP model within the LFDSS

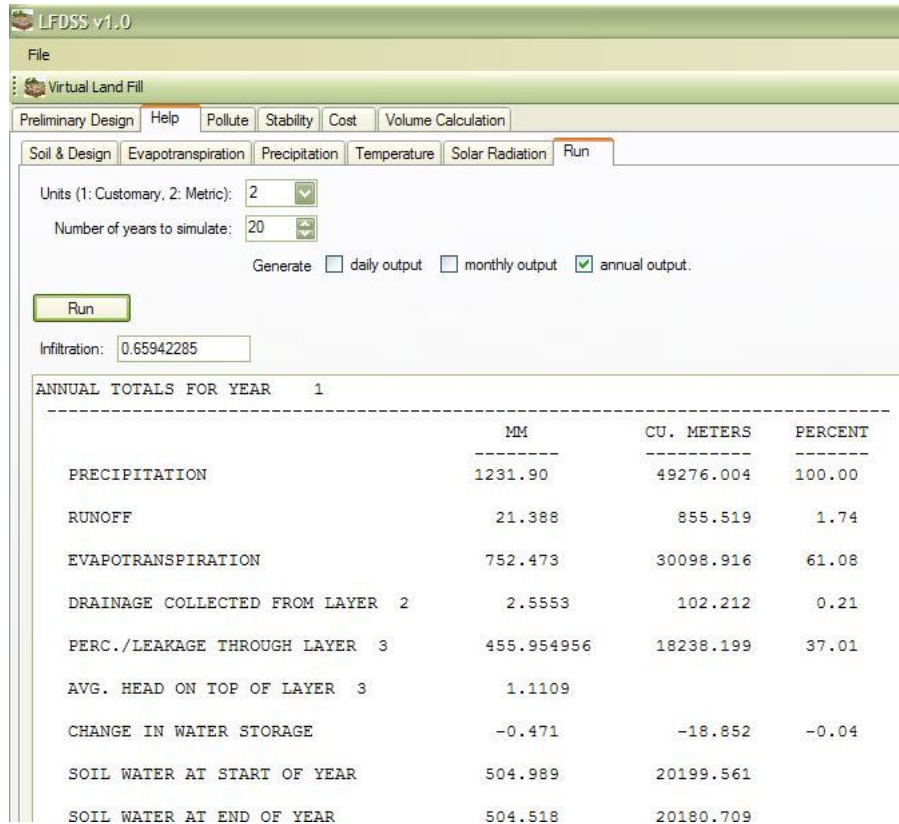


Figure 3. 19 Presentation of infiltration rate and HELP output data in LFDSS

3.2.5.3. Waste and Bottom Liner Design and Subsurface Transport Model (POLLUTE)

POLLUTE model is used to model waste and bottom liner of the landfill, as well as the vadose zone beneath the bottom liner. The model evaluates the compliance of the design alternative to the first performance criterion (i.e. leachate head on top of bottom liner should be less than 1 m for stability reasons). Also, POLLUTE uses infiltration rate data from HELP model to calculate the contaminant concentration at the groundwater table or in soil beneath the landfill, where groundwater is not present. The model results are evaluated by the LFDSS to assess the compliance of the landfill design alternative with the second

performance criterion (i.e. maximum contaminant (CI) concentration at the groundwater table should be less than 25 mg/L).

POLLUTE functions were simplified regarding the input requirements of the performance evaluations under LFDSS; therefore, the model is operated under three tabs, divided into sections related with different design components. First tab is the *Parameters* tab, where waste and bottom liner design parameters are specified (Figure 3.20.a). Second tab is the *Maximum Concentrations* tab, where the run parameters are specified and results of maximum concentration and time of occurrence of maximum concentration are presented to the user (Figure 3.20.b). In the third tab, *Concentrations at Specified Times*, contamination trend with time can be observed, if required (Figure 3.20.c). In the Parameters tab, the design components that would be used for the specific landfill design are selected from the General section. Waste type is defined by the “concentration” and “density” value under Source section. Dimensions of the landfill (i.e. waste thickness and landfill length in the direction of groundwater flow) are also defined by the user considering the output of Virtual Landfill model in the Source section. Infiltration rate is transferred from HELP model automatically (see Section 3.2.2.3 for details). The technical properties of design components (e.g. leachate collection system, geomembrane, compacted clay liner, vadose zone) and the aquifer are also defined under relevant sections. When any of the design components are unchecked (e.g. compacted clay liner), the technical properties entered for the component would not be taken into consideration during the simulations. In the Maximum Concentrations tab, lower and upper time limits are defined by the user to determine the simulation time. Search depth is the total length of the design components used in the bottom liner design (excluding the waste layer but including the vadose zone thickness) and required to obtain the maximum concentration at the groundwater table. In the Concentrations at specified times tab, the user can define specific times (in hours, days, years, or seconds) to observe the contaminant concentrations that would occur at the groundwater table

at the selected times. The results are not transferred to LFDSS, demonstrated from POLLUTE main programme.

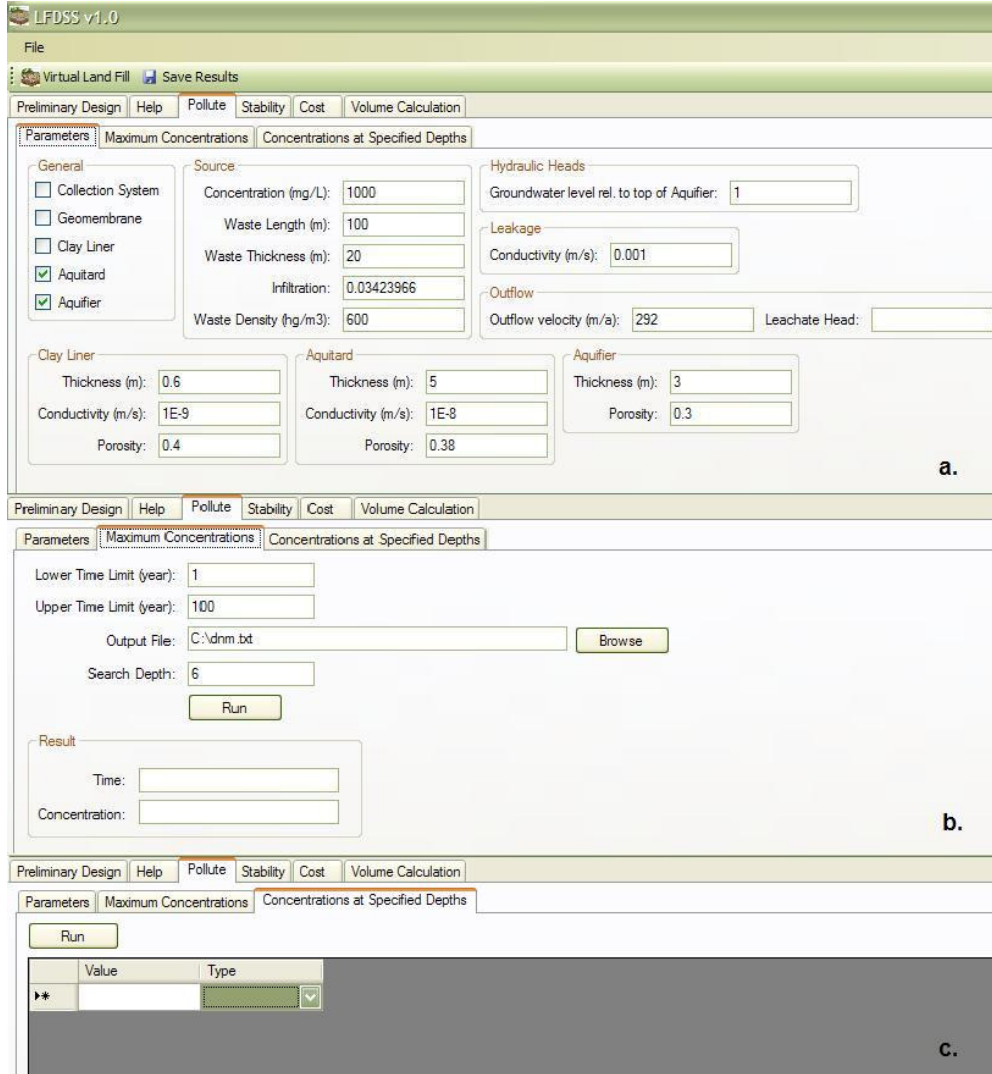


Figure 3. 20 POLLUTE tabs in LFDSS. a) Parameters tab, b) Maximum concentrations tab, c) Concentrations at specified times

When the model is executed from Maximum Concentrations tab, results for maximum concentrations and time of occurrence of maximum concentration are given in *Result* subsection. If the maximum concentration exceeds the predefined contaminant concentration at the groundwater table (i.e. 25 mg/L) the

concentration values is highlighted with red to warn the user. Also, after the execution, if the “Leachate head” box in the parameter menu should be controlled by the user for the designs without leachate collection systems, in order to determine whether the design satisfies the first performance criterion (i.e. leachate head over bottom liner should be less than 1 m) (Figure 3.21).

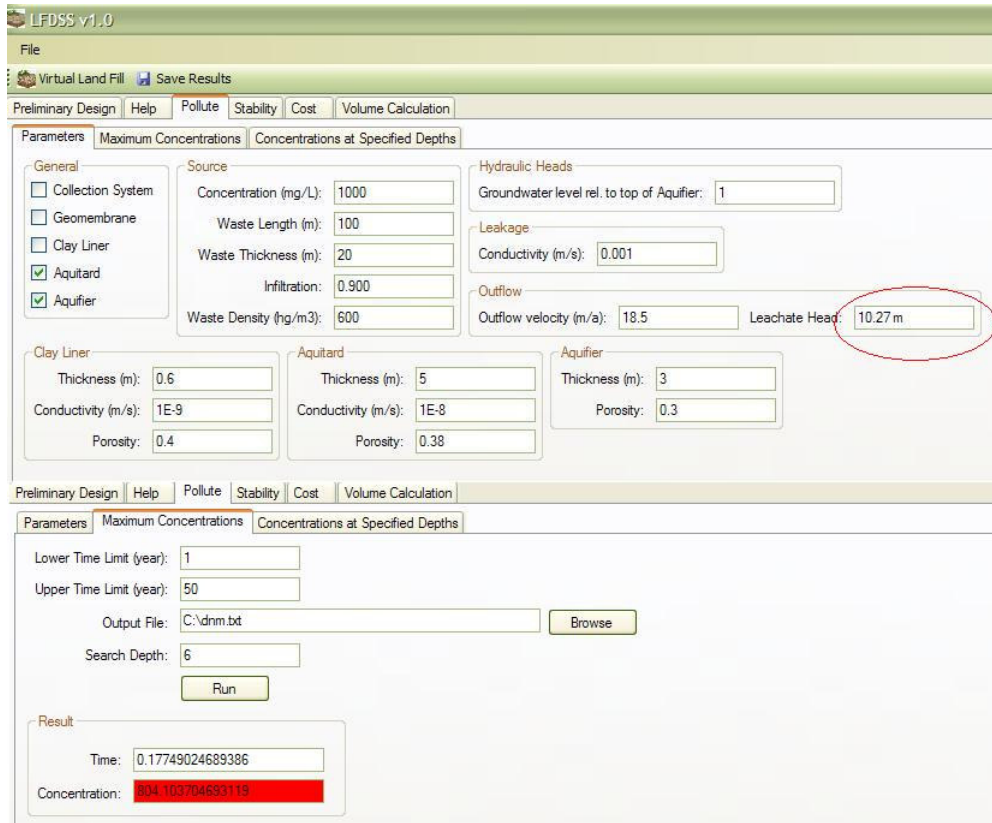


Figure 3. 21 POLLUTE execution from Maximum Concentrations tab in LFDSS

The input data requirements and the output data supplied by POLLUTE model are given in Table 3.18.

Table 3. 18 Input data requirement and output data supplied by POLLUTE model

Input	From Model/Module	Output	To Model/Module
Waste length	Observed from VLF	Contaminant concentration at the groundwater table	LFDSS decision interface
Waste thickness	Observed from VLF	Leachate head on landfill bottom liner	User
Infiltration	Transferred from HELP		
Waste density	User defined		
Groundwater level relative to the top of aquifer	User defined		
Leachate head on primary liner	default as 0.3m for designs including LCS ^b <i>OR</i> automatically calculated by POLLUTE for designs excluding LCS ^b		
Hydraulic conductivity (of drainage material)	User defined		
Thickness of CCL ^a	User defined		
Hydraulic conductivity of CCL ^a	User defined		
Porosity of CCL ^a	User defined		
Thickness of vadose zone	User defined		
Hydraulic conductivity of vadose zone	User defined		
Porosity of vadose zone	User defined		
Thickness of the aquifer	User defined		
Porosity of the aquifer	User defined		
Outflow velocity (groundwater seepage velocity)	User defined		
Lower and upper time limits	User defined		
Search depth	User defined		
Contaminant concentration	User defined		
Search year	User defined		

^a Compacted clay liner

^b Leachate collection system

As previously stated, once the landfill design is simulated from Maximum Concentrations tab, for the designs not having leachate collection system, POLLUTE calculates the leachate head on bottom liner to help in the assessment of the landfill design to the stability criterion. The user should be aware that if the value of the leachate head on primary liner is calculated to be greater than 1 m, the landfill design alternative is not appropriate for the given site conditions. Also, maximum contaminant concentration, and the time of occurrence of maximum concentration are indicated in Result subsection. When the landfill design does not satisfy the contamination criterion (i.e. Cl⁻ concentration below 25 mg/L), the concentration box is highlighted with red. Therefore, the user is guided that the landfill design violates the design criterion.

The LFDSS executes the POLLUTE model outside the platform using a macro (see Section 3.2.2.2). The output file in text file format is saved to the specified destination from the Maximum Concentrations tab. The final concentration record in Results subsection is read by the LFDSS decision interface and written on the *results file*. The details of decision interface are explained in Section 3.2.5.6.

3.2.5.4. *Stability Analysis Module*

Stability Analysis Module was developed to assess the stability of the landfill design alternatives complying with the performance criteria. After the landfill design alternatives are simulated by LFDSS, the geotechnical data related with the design alternatives are entered to the stability analysis module to obtain factor of safety (FS) values. Stability analysis module does not require data transfer from any other module. It is an independent and/or optional module for the performance evaluation of the landfill design alternatives. The equations used in stability calculations, and hence the input data requirement, are explained in this section.

In the literature, the stability analyses for the landfills cover three main issues, which are *excavation slope stability*, *refuse fill stability*, and *cover system stability*. Besides the three main analyses, *geomembrane stability* and *seismic stability* components are included in the Stability Module. The module is developed using MS Excel spreadsheet. The module consists of 5 submenus; each is capable of calculating one of the five stability issues occurring in landfills.

The equations used for factor of safety calculations for each of the stability issues are summarized in Table 3.19.

In the “*excavation slope menu*” the analyses are performed using the method of slices (Eq. 3.9). The total weight (W_T) includes vertical and horizontal seismic loads; and the surcharge (Eq. 3.10). For a first degree seismic zone, horizontal seismic parameter, k_h , is accepted as 0.15, and vertical seismic parameter, k_v , is accepted as 0.08 (Kramer, 1996). According to the common practice, for excavation slope stability calculations, it is accepted that no leakage will be observed at the base during construction; therefore, pore water pressure, u , is accepted as zero. Equation 3.9 and 3.10 are also used for the “*refuse fill stability menu*”; however, *surcharge is excluded* from the total weight.

$$FS = \frac{\sum c(\delta l) + \sum \tan \phi (W \cos \alpha - u(\delta l))}{\sum W_T \sin \alpha} \quad (3.9)$$

$$\begin{aligned} F_v &= k_v \times W \\ F_h &= k_h \times W \end{aligned} \quad (3.10)$$

Table 3. 19 The formulae used in stability calculations

Stability Issue	Formulae
Excavation slope	$FS = \frac{\sum c(\delta) + \sum \tan \phi (W \cos \alpha - u(\delta))}{\sum W_T \sin \alpha}$ $\alpha = \frac{\gamma_c T_c^2}{\sin 2\beta} \left[\left(\frac{2H \cos \beta}{T_c} - 1 \right) \frac{\sin(\beta - \phi_i)}{\cos \phi_i} - \frac{\sin \phi_i}{\cos(\beta + \phi_c)} \right]$ $H_{\max} = \frac{T_c}{2 \cos \beta} \left[1 + \frac{\sin \phi_c \cos \phi_c}{\cos(\beta + \phi_c) \sin(\beta - \phi_i)} \right]$
Refuse fill	$FS = \frac{\sum c(\delta) + \sum \tan \phi (W \cos \alpha - u(\delta))}{\sum W_T \sin \alpha}$ $\alpha = \frac{\gamma_c T_c^2}{\sin 2\beta} \left[\left(\frac{2H \cos \beta}{T_c} - 1 \right) \frac{\sin(\beta - \phi_i)}{\cos \phi_i} - \frac{\sin \phi_i}{\cos(\beta + \phi_c)} \right]$ $H_{\max} = \frac{T_c}{2 \cos \beta} \left[1 + \frac{\sin \phi_c \cos \phi_c}{\cos(\beta + \phi_c) \sin(\beta - \phi_i)} \right]$
Cover system	$FS = \frac{\tan \phi}{\tan \beta} \quad \text{cohesionless, dry}$ $FS = \frac{\gamma_b \tan \phi'}{\gamma_i \tan \beta} \quad \text{cohesionless, seepage}$ $FS = \frac{c' + \sigma' \tan \phi'}{\tau_r'} = \frac{c' + \gamma_b H \cos^2 \beta \tan \phi'}{\gamma_i t \sin \beta \cos \beta} \quad \text{cohesive}$
GM ^a	$FS = \frac{F_{net}}{T} = \frac{(\gamma H \tan^2(45 + \phi_c / 2)) - (\gamma H \tan^2(45 - \phi_c / 2))}{(W \sin \phi_i - W \sin \phi_i \tan \phi_i)}$
Seismic Stability	$FS = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$ $a = (C_s W_A + N_A \sin \beta) \cos \beta + C_s W_p \cos \beta$ $b = -[(C_s W_A + N_A \sin \beta) \sin \beta \tan \phi + (N_A \tan \delta + C_a) \cos^2 \beta + (C + W_p \tan \phi) \cos \beta]$ $c = (N_A \tan \delta + C_a) \cos \beta \sin \beta \tan \phi$

^a Geomembrane

Usually, *planar slip surfaces* occur in final covers; therefore, *infinite slope analysis* of limit equilibrium approach is implemented in “*Cover system stability menu*”. The method has different analysis techniques for cohesionless and cohesive soils. Cohesionless soils are also divided into two, as dry or seepage conditions. Factor of safety calculations are summarized below for each of the aforementioned cases (Sharma and Lewis, 1994):

- Cohesionless soils, dry conditions:

$$FS = \frac{\tan \phi}{\tan \beta} \quad (3.11)$$

Parameters that should be defined are ϕ , angle of internal friction; and β , slope angle.

- Cohesionless soils, seepage conditions:

$$FS = \frac{\gamma_b \tan \phi'}{\gamma_t \tan \beta} \quad (3.12)$$

Parameters that should be defined are ϕ' , effective friction angle; γ_b , buoyant unit weight of soil; γ_t , total unit weight of soil; and β , slope angle. Usually, the slope angle with seepage is half of the one without seepage.

- Cohesive soils:

$$FS = \frac{c' + \sigma' \tan \phi'}{\tau_r'} = \frac{c' + \gamma_b H \cos^2 \beta \tan \phi'}{\gamma_t t \sin \beta \cos \beta} \quad (3.13)$$

Parameters that should be defined are c' , effective cohesion; σ' , effective normal stress; ϕ' , effective friction angle; γ_b , buoyant unit weight of soil; γ_t , total unit weight of soil; H, vertical depth to slip plane; t, soil thickness; and β , slope angle. τ_r is the Mohr envelope.

For “*the geomembrane menu*”, factor of safety values are calculated based on the determined anchorage height (Eq. 3.14). In equation 3.14, γ is the unit weight of soil, H is anchorage height, ϕ_i is interface friction angle between geomembrane and geotextile, ϕ_c is the friction angle of granular soil.

$$FS = \frac{F_{net}}{T} = \frac{(\gamma H \tan^2(45 + \phi_c / 2)) - (\gamma H \tan^2(45 - \phi_c / 2))}{(W \sin \phi_i - W \sin \phi_i \tan \phi_i)} \quad (3.14)$$

In “*the seismic stability menu*” seismic forces were taken into account for the evaluation of seismic stability of final covers. Especially for places with high earthquake risk (e.g. western and eastern regions of Turkey), this type of stability analysis appears to be important. A factor of safety value is calculated by adding the horizontal force acting at the centroid of the cover soil cross-section. The horizontal force is in proportion to the anticipated seismic activity, which is indicated by an average seismic coefficient (C_s). C_s is the ratio of bedrock acceleration to gravitational acceleration, and can be obtained from a seismic zone map (Koerner and Soong, 2005). Guidance values for C_s presented to the users are given in Table 3.20.

Table 3. 20 Guidance values for average seismic coefficient (C_s) (Koerner and Daniel, 1997)

Modified Mercalli Scale	Remark	C_s
-	No damage	0
V and VI	Minor damage	0.3 – 0.7
VII	Moderate damage	0.13
VII and higher	Major damage	0.27

The factor of safety value is then calculated according to Eq. 3.15 (Koerner and Soong, 2005):

$$FS = \frac{-b + \sqrt{b^2 - 4ac}}{2a}$$

$$a = (C_s W_A + N_A \sin \beta) \cos \beta + C_s W_p \cos \beta \quad (3.15)$$

$$b = -[(C_s W_A + N_A \sin \beta) \sin \beta \tan \phi + (N_A \tan \delta + C_a) \cos^2 \beta + (C + W_p \tan \phi) \cos \beta]$$

$$c = (N_A \tan \delta + C_a) \cos \beta \sin \beta \tan \phi$$

Where C_s is the average seismic coefficient, W_A is the weight of active wedge, N_A is the effective force normal to the failure plane of the active wedge, β is the soil slope angle, W_p is the total weight of the passive wedge, ϕ is the friction angle of the cover soil, δ is the interface friction angle between cover soil and geomembrane, and C_a is the adhesive force between cover soil of the active edge and the geomembrane. The relation between the FS value and the average seismic coefficient (C_s) are presented in Figure 3.22. The curve presented in Figure 3.22 is drawn for the parameters given in the legend of the figure. This curve is also presented as guidance to the user (Koerner and Soong, 2005).

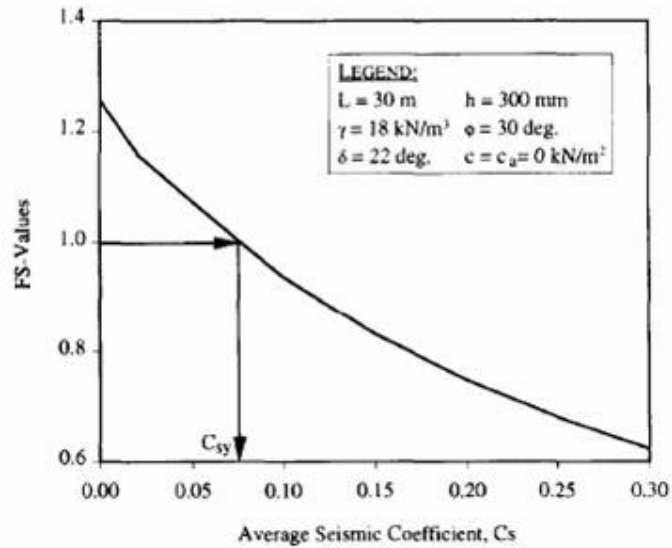


Figure 3. 22 FS values vs. average seismic coefficient (C_s) as guidance in LFDSS (Koerner and Soong, 2005)

MS Excel spreadsheet accommodating the stability formulae was used as basis for the formation of Stability Analysis Module in LFDSS. It is possible to input data manually or via copy and paste from other sources (e.g. MS Excel) in a tabular form using the *DataGridView* property of *Visual C#*. This property creates a user-friendly environment for data input, and also, eases multiple calculations under a single menu in LFDSS (Figure 3.23).

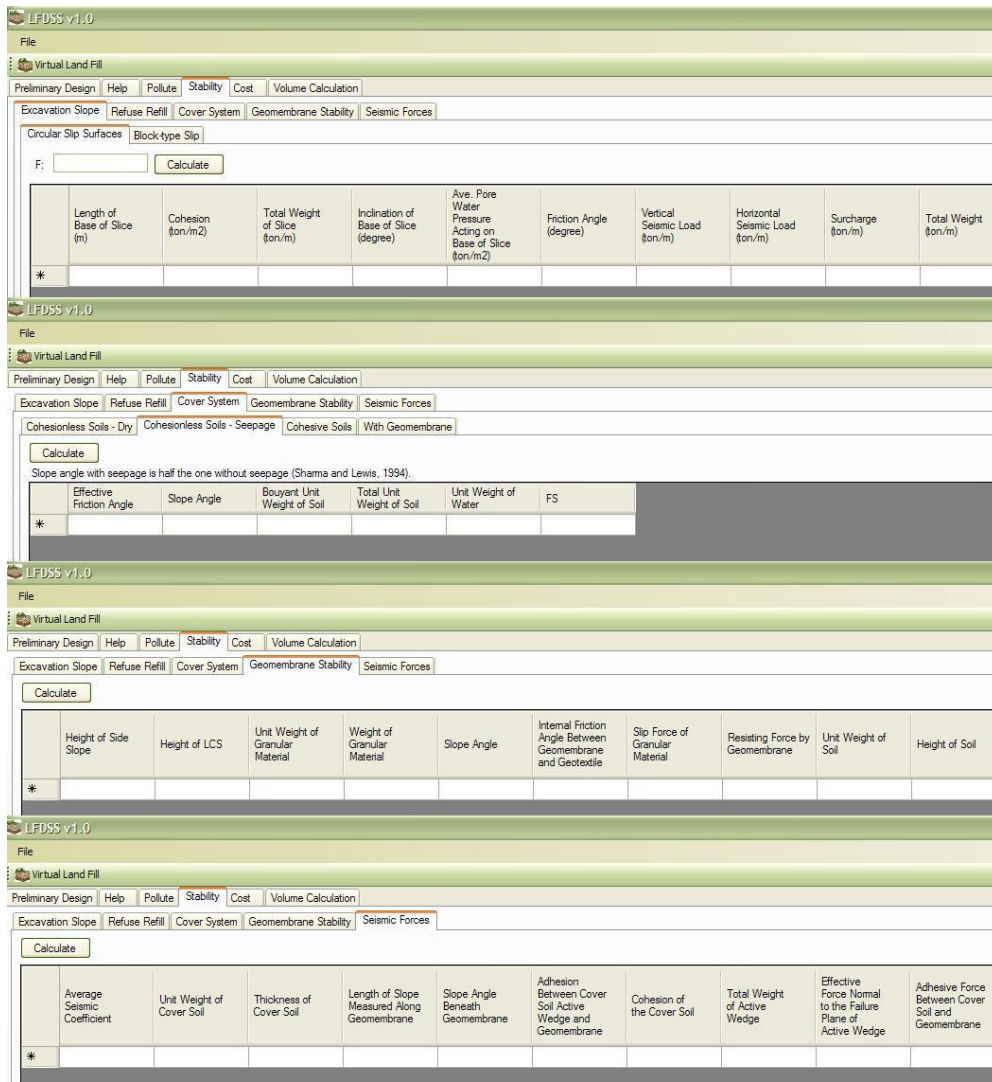


Figure 3. 23 Screenshots of Stability Analysis Module in LFDSS

The factor of safety (FS) values calculated under each submenu are read by the LFDSS decision interface and written on the *results file*. The details of decision interface are explained in Section 3.2.5.6.

3.2.5.5. Major Design Component Approximate Cost Estimation Module

A Major Design Component Approximate Cost Estimation Module (referred to as cost estimation module from now on throughout the thesis) was included in the LFDSS to calculate the approximate costs of major landfill design components (i.e. natural soil, surface drainage and leachate collection system, (compacted) clay liner, and geomembrane). Besides the major design component costs, it is also possible to calculate the costs of some additional components (i.e. not directly affecting the performance of the design, such as geotextiles, and vegetative cover requirements). Similar to the other calculation modules, Cost Estimation Module was prepared using MS Excel spreadsheets. The module is also an independent module for the performance evaluation of the landfill design alternatives, and it does not require data from any other model within the LFDSS.

The quantity of the design component used for the landfill design alternative of concern is required to be provided by the user. LFDSS is able to offer guidance values for unit costs of major and additional design components; therefore, the user can either define specific unit costs, or use the guidance values. Input data for the module are presented in Table 3.21.

Table 3. 21 Major and additional design components for cost analyses in Cost Estimation Module in LFDSS

Design Component	Processes
<i>Major design components</i>	
Natural soil	Excavation Loading Hauling Spreading Compaction
Top soil	Purchase Hauling Spreading Compaction
Drainage	Gravel purchase Hauling Spreading the gravel
Drainage system	Pipes Hauling Trenching
Clay (Onsite/Offside)	Clay purchase Excavation Processing onsite clay Loading Hauling Spreading Compaction
Geomembrane	60mil (2mm) HDPE –High density polyethylene 40mil PVC -polyvynlchloride 40mil VFPE –very flexible polyethylene Installation and testing
<i>Additional design components</i>	
Geotextiles/geonets	Purchase Installation
Geosynthetic clay liner	Bentomat purchase
Vegetative topsoil	Hydroseeding

MS Excel spreadsheet accommodating the stability formulae was used as basis for the formation of Cost Estimation Module in LFDSS. It is possible to input data manually or via copy and paste from other sources (e.g. MS Excel) in a tabular form using the *DataGridView* property of *Visual C#*. This property creates a user-

friendly environment for data input, and also, eases multiple calculations under a single menu in LFDSS (Figure 3.24).

The screenshot displays the LFDSS v1.0 software interface. At the top, there is a menu bar with 'File', 'Virtual Land Fill', and 'Save Results'. Below the menu bar is a toolbar with a 'Calculate' button. The main area is divided into several sections, each containing a table of cost estimates for different components. The sections are: Native Soil, Top Soil, Drainage, Clay Onsite and Offsite, Drainage Tile, Synthetic Membrane, Geotextile Filter, Geonet, Geosynthetic Clay Liner, and Vegetative Cover. Each table has columns for Item, Description, Cost (USD), Unit, Amount, and Total Cost. The 'Total Main Component Cost (USD)' and 'Total Additional Component Cost (USD)' are both shown as 0. The 'Total Landfill Construction Cost (USD)' is also shown as 0. A note at the bottom states 'Cost means cost per unit given (guidance values)'.

Figure 3. 24 Screenshot of cost estimation module in LFDSS

The cost calculated for each major design component are read by the LFDSS decision interface and written on the *results file*. The details of decision interface are explained in Section 3.2.5.6.

3.2.5.6. Decision Mechanism and Presentation of Decision Analyses

After the performance, stability, and cost analyses are completed, the results of the simulations are saved to a text file (i.e. *results file*) by the “Save Results” button (Figure 3.25).

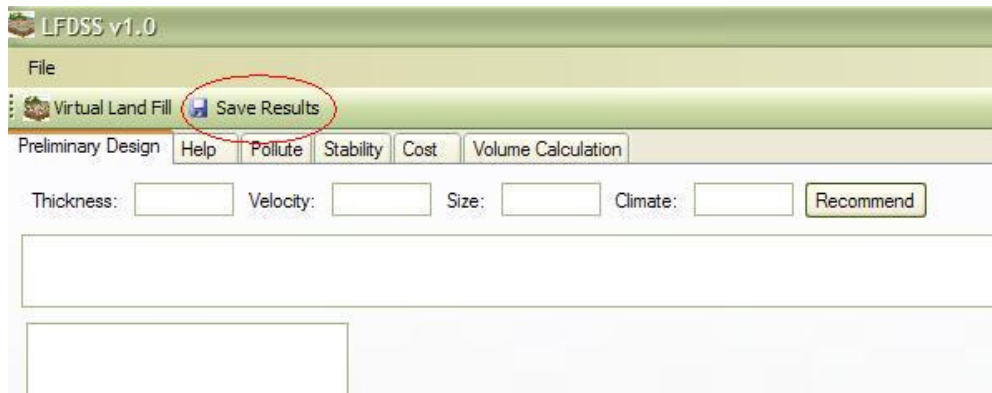


Figure 3. 25 Saving the results in LFDSS

Once the button is clicked (at any stage of the LFDSS simulations), the results of preliminary design module, POLLUTE (maximum concentration and time of occurrence), stability module (FS), and cost estimation module (major, additional, and total costs) are recorded on the results file, separated with commas (.). If either of the model/modules is not run, then the place reserved for the result belonging to that model/module is left blank between commas. If more than one value is calculated for a specific parameter (e.g. factor of safety), then these calculated values are separated with colons (:). The order of records are as follows: design alternative, maximum concentration, time of occurrence of maximum concentration, factor of safety value for excavation slope circular slip surfaces, factor of safety value for excavation slope block type slip, factor of safety value for refuse fill circular slip surfaces, factor of safety value for refuse fill block type slip, factor of safety value for final cover cohesionless dry soils,

factor of safety value for final cover cohesionless soils with seepage, factor of safety value for final cover cohesive soils, factor of safety value for final cover stability with geomembrane, factor of safety value for geomembrane stability, factor of safety value for seismic stability for final covers, major cost, additional cost, and total landfill cost (Figure 3.26). Figure 3.26 shows that two design alternatives, C3L4^L and C2L1, were simulated using LFDSS. Factor of safety value for excavation slope block type slip, factor of safety values for final cover cohesionless soils, and with geomembrane, and factor of safety value for seismic forces were not calculated for C3L4^L design alternative. Moreover, the report demonstrates that four different factor of safety values were calculated for geomembrane stability for the same design.

<p>C3L4L, 1.21587401637304, 135.54014234375, 3.19753280971486, , 3.48939250033159, , , , 45.6805678449124, , 2.41804742076412:1.61203161384274:5.44060669671926:3.62707113114617, , 2097873.51, 30450, 2128323.51 C2L1, 27.300851078987, 91.7644375, 3.19753280971486, , 3.48939250033159, , , , 9.16546829404725, , , 2224323.51, 43500, 2267823.51</p>

Figure 3. 26 Records in results file.

The results file is not in a proper format to be evaluated easily by the user; however, it can be imported to results template (MS Excel file) provided with the LFDSS software. The format of the template in MS Excel is similar to the one demonstrated in Table 3.22.

Table 3. 22 Format of results template provided to the user by LFDSS (*produced from Figure 3.26*)

Design	Performance		Stability		Cost (USD)		
	CI_{max} (mg/L)	T_{max} (yr)	FS values		Major Cost	Additional Cost	Total Cost
C3L4 ⁺	1.22	136	Excavation slope		2097873.5	30450	2128323.5
			Circular slip	3.20			
			Block-type slip	-			
			Refuse-fill				
			Circular slip	3.49			
			Block-type slip	-			
			Cover system				
			Cohesionless –dry	-			
			Cohesionless –	-			
			seepaage	45.68			
			Cohesive	-			
			W/ geomembrane				
			Geomembrane	2.42:			
			Geomembrane	1.61:			
Geomembrane	5.44:						
Geomembrane	3.63						
C2L1	27.3	92	Seismic	-	2224323.5	43500	2267823.5
			Excavation slope				
			Circular slip	3.20			
			Block-type slip	-			
			Refuse-fill				
			Circular slip	3.49			
			Block-type slip	-			
			Cover system				
			Cohesionless –dry	-			
			Cohesionless –	-			
			seepaage	-			
			Cohesive	9.17			
			W/ geomembrane				
			Geomembrane	-			
Seismic	-						

LFDSS does not select an optimum design; the platform offers guidance to the user by providing performance, stability, and cost analyses. Observing the outcomes of simulations for different design alternatives, the user should decide on the particular design/designs depending on the case-specific concerns. For example, for a site where groundwater is not present, stability issues present a much more important decision mechanism on the selection of the most appropriate design. The importance of decision mechanism is demonstrated in two case studies, presented in Chapter 4, Sections 4.5.1 and 4.5.2.

CHAPTER 4

RESULTS AND DISCUSSION

In the first part of the previous chapter, the conceptual model for designing a performance-based landfill was developed and presented. Design variables, performance criteria, and design components were identified to be the main components of the conceptual model. Design variables were identified to be site conditions that affect the performance of a landfill design, performance criteria were the pre-defined limits that a landfill design should satisfy, and design components were the parts of a landfill design to reach the desired performance. A design methodology, and consequently a design component selection matrix, identifying the relations between these components were developed. In the second part, based on the developed methodology, the development of a decision support system was explained.

Chapter 4 is organized under two main parts: results of simulations of the landfill design alternatives, and case studies performed using LFDSS.

First, the results demonstrating the effect of design variables, vadose zone, waste thickness, and seepage velocity, on steady-state leakage rates from landfill barrier systems are presented and discussed. Then the performance-based evaluation of the 18 landfill design alternatives and their compliances with the performance criteria are discussed. The results of the performance-based simulations of the 18

landfill design alternatives are coalesced to develop the design component selection matrices. The discussion is completed with the presentation of the design component selection matrices, which are used as knowledge base in the preliminary design phase of the developed DSS. .

The capabilities and the use of the developed DSS for landfill design (LFDSS) were demonstrated by one hypothetical and one real landfill case studies.

4.1. Effect of Vadose Zone on Steady-State Leakage Rates from Landfill Barrier Systems

To understand the effect of vadose zone on the steady-state leakage rates, a barrier system composed of a compacted clay liner underlain by a vadose zone is simulated by SEEP/W model by using both unsaturated soil hydraulic conductivity functions and uniform saturated hydraulic conductivity values, for both coarse textured and fine textured vadose zones. In the present analysis, the focus was on the case of a single low conductivity CCL underlain by a vadose zone. With respect to leakage rates, this case represents a more conservative situation compared to the case of composite liner, involving a geomembrane and a compacted clay liner (CCL), underlain by a vadose zone, since the geomembrane would further reduce the overall leakage rates through the CCL. As long as the flux through the CCL is not increased significantly (i.e. several orders of magnitude), the underlying vadose zone would not be fully saturated and its barrier function would not be impaired. Therefore, the findings of this work are also expected to be conservative for the case of composite liners. The results are discussed under the relevant headings.

4.1.1. Barrier System: Compacted Clay Liner underlain by Coarse Textured Vadose Zones

According to the simulations performed using unsaturated soil hydraulic conductivity functions, the hydraulic conductivity values in the coarse grained vadose zone was as low as 9×10^{-9} m/s at the top of the vadose zone, near the compacted clay liner; and, reached 8×10^{-5} m/s at the bottom of the vadose zone, near the water table (Figure 4.1). This phenomenon occurred as the suction decreased with the depth of the vadose zone. As the unsaturated hydraulic conductivity is a function of pore-water pressures, the decreased suction resulted in increased hydraulic conductivity in the vadose zone towards the water table. As the thickness of the vadose zone increased, the portion of the vadose zone having lower hydraulic conductivity values also increased; therefore, the harmonic mean hydraulic conductivity of the vadose zone decreased. The decrease in the hydraulic conductivity reaches an asymptotic value for the vadose zone thicknesses greater than 5 m (Figure 4.2).

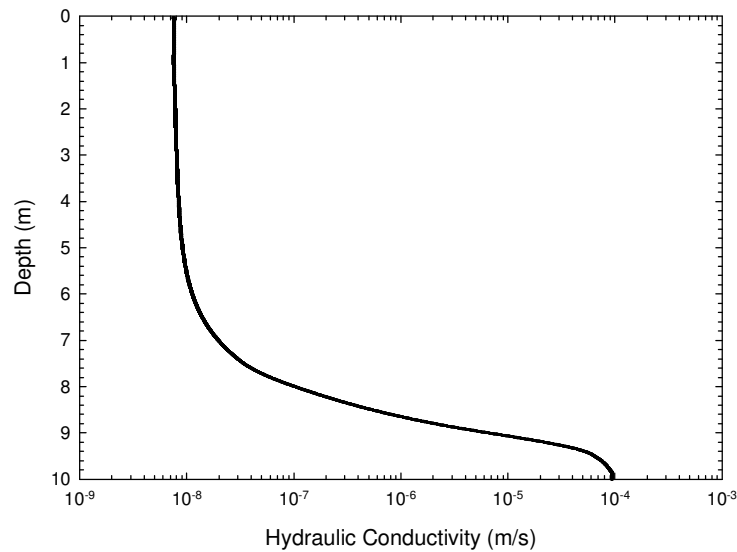


Figure 4. 1 Hydraulic conductivity change with depth for a uniform sand (US)

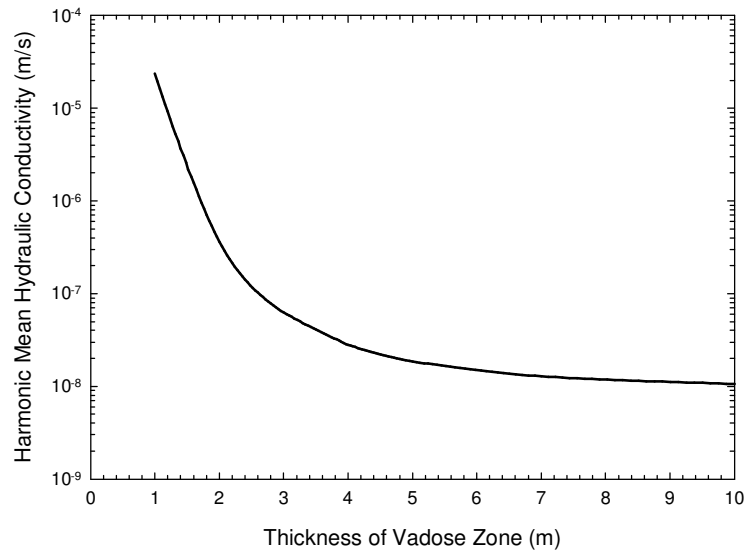


Figure 4. 2 Change in the harmonic mean hydraulic conductivity of the vadose zone with varying sandy (S) vadose zone thickness

Although the harmonic mean hydraulic conductivity of the vadose zone decreased when the thickness of the vadose zone increased, the overall effective hydraulic conductivity of the combined clay barrier and unsaturated sandy soil system increased (Table 4.1). This occurred because the thickness of higher hydraulic conductivity material (i.e. vadose zone) increased relative to the thickness of lower hydraulic conductivity material (i.e. compacted clay liner). The increased effective hydraulic conductivity of the overall barrier system resulted in a gradual increase in the steady-state leachate leakage rates into the aquifer. As the thickness of the overall barrier system increases, the steady-state leakage rates increase gradually; however, similar to the hydraulic conductivity, they reach an asymptotic value between the vadose zone thicknesses of 5 – 10 m and do not change much beyond 10 m (Figure 4.3). Steady-state leakage rate results obtained from SEEP/W model are verified using the results obtained from hand calculations. It is shown that model results are in agreement with the hand-calculated steady-state leakage rates (Table 4.2).

Table 4. 1 Harmonic mean hydraulic conductivity values of the coarse-textured vadose zones, effective hydraulic conductivity values of the overall barrier system and steady-state leakage rates

Soil type	Thickness of Vadose Zone	\bar{k}_{vz} ^(a)	\bar{k}_{vzcl} ^(b)	q_{hc} ^(c)	q_{mc} ^(d)
	(m)	(m/s)	(m/s)	(m/a)	(m/a)
US	1	3.48x10 ⁻⁵	2.67x10 ⁻⁹	0.0999	0.0999
US	5	2.37x10 ⁻⁸	6.91x10 ⁻⁹	0.229	0.229
US	10	1.20x10 ⁻⁸	7.40x10 ⁻⁹	0.240	0.239
S	1	2.35x10 ⁻⁵	2.67x10 ⁻⁹	0.0999	0.0999
S	5	1.86x10 ⁻⁸	6.45x10 ⁻⁹	0.214	0.214
S	10	1.06x10 ⁻⁸	6.87x10 ⁻⁹	0.222	0.223
FS	1	9.17x10 ⁻⁷	2.66x10 ⁻⁹	0.0997	0.0997
FS	5	8.91x10 ⁻⁹	4.82x10 ⁻⁹	0.160	0.160
FS	10	6.86x10 ⁻⁹	5.15x10 ⁻⁹	0.167	0.167

^(a) Harmonic mean of vadose zone hydraulic conductivity

^(b) Harmonic mean of vadose zone and compacted clay liner hydraulic conductivity

^(c) Steady-state leakage rate as a result of hand calculations

^(d) Model calculated steady-state leakage rate

When the barrier system is simulated using uniform saturated hydraulic conductivities for the vadose zone, steady-state leakage rates (denoted by $q_{K_{uni}}$) are 2.0 to 3.5 times greater than the leakage rates simulated using soil hydraulic conductivity functions (denoted by $q_{K_{fn}}$) (Figure 4.4). When the uniform saturated hydraulic conductivities are used, the steady-state leakage rates are overestimated for coarse textured vadose zones; therefore, unsaturated conditions and thus soil hydraulic conductivity functions should be considered when a barrier system having a CCL is underlain by a coarse textured vadose zone.

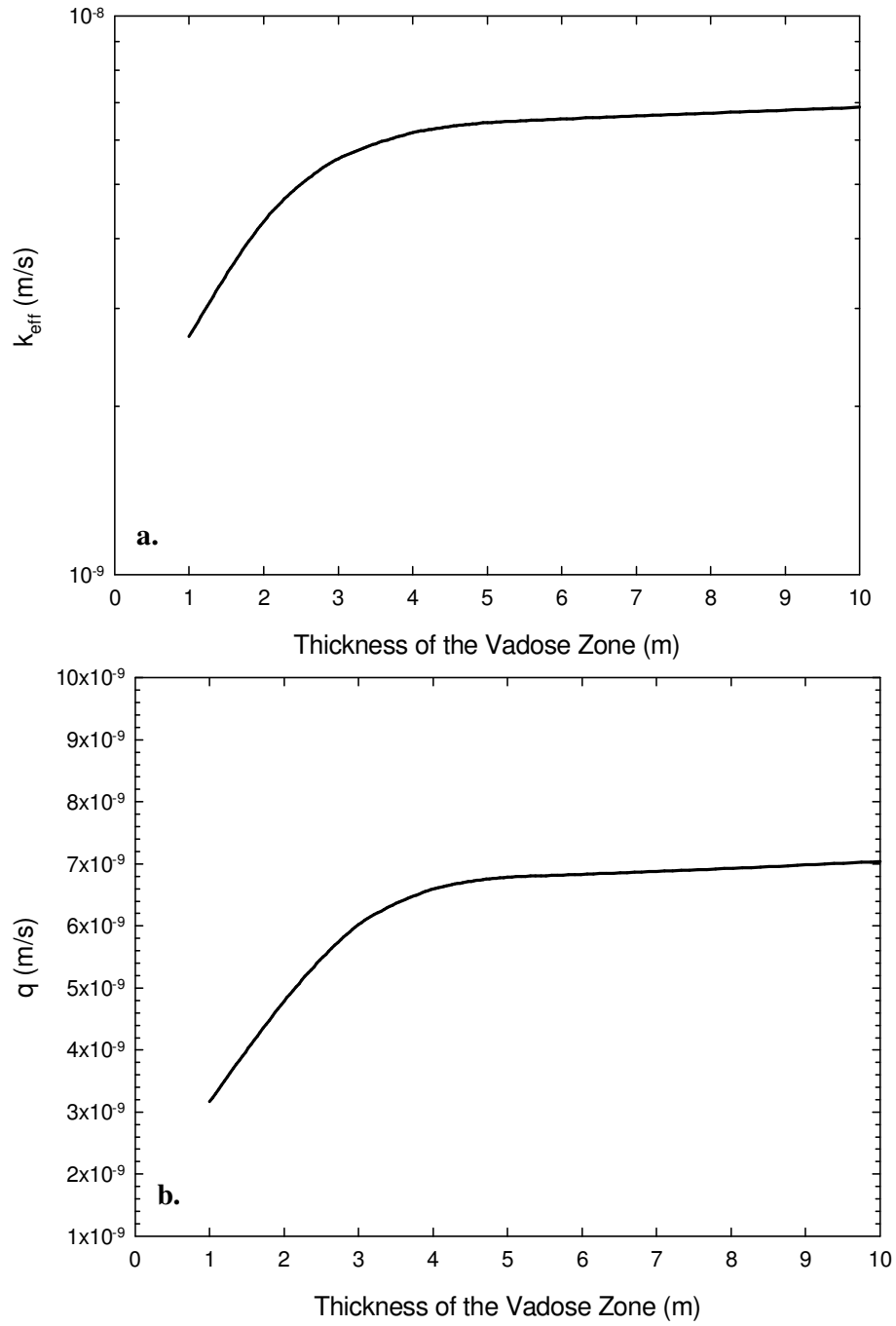


Figure 4. 3 Change in (a) the effective hydraulic conductivity of the overall barrier system and (b) the steady-state leakage rates with varying sandy (S) vadose zone thickness

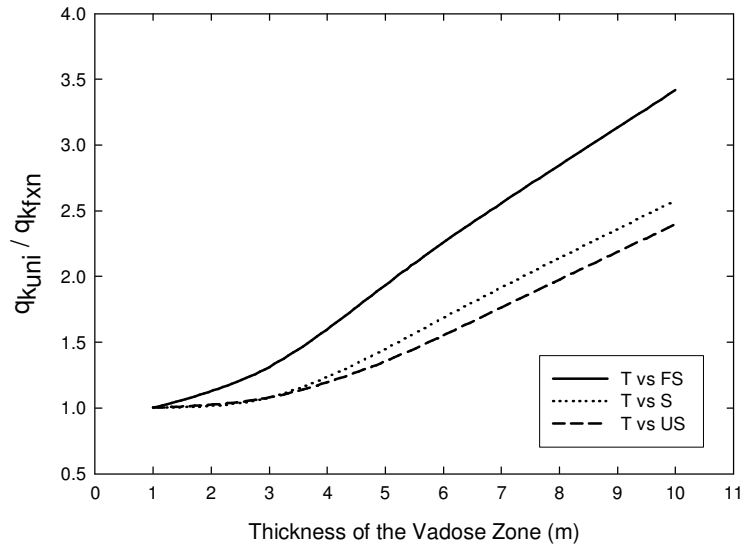


Figure 4. 4 Normalized steady-state leakage rates with varying coarse textured vadose zone thickness (T stands for vadose zone thickness, FS stands for fine sand, S stands for sand, and US stands for uniform sand)

4.1.2. Barrier System: Compacted Clay Liner underlain by Fine Texture Vadose Zones

Hydraulic conductivity profile of the fine textured vadose zones is not affected much by the pore-water pressure change within the vadose zone. According to Figure 3.3 (d), the hydraulic conductivity of the uniform silt shows a significant change after 100 kPa. Up to a thickness of 10 m, the pressure within the vadose zone does not reach 100 kPa, and it is observed to be around 35 kPa. Therefore, for vadose zones composed of uniform silt and that are shallower than 10 m, the hydraulic conductivity values and therefore the steady state leakage rates do not change with varying thickness of the vadose zone. The hydraulic conductivity values for silt and silt tailings change in the range of $6 \times 10^{-8} - 5 \times 10^{-9}$ m/s between the bottom of the compacted clay liner and the top of water table (Figure 4.5). The harmonic mean hydraulic conductivity of the vadose zone also does not show a substantial difference with varying vadose zone thickness. It decreases

only almost half order of magnitude when the thickness is changed from 1 m to 5 m, and reaches an asymptotic value for vadose zones thicker than 5 m (Figure 4.6).

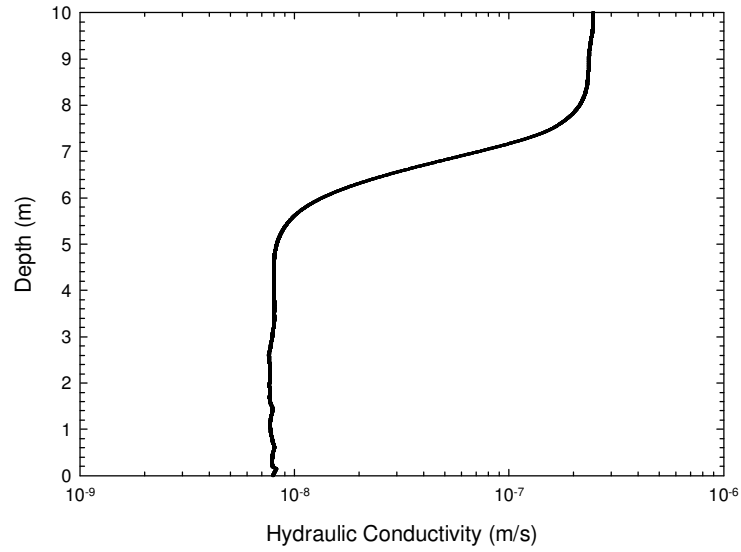


Figure 4. 5 Hydraulic conductivity change with depth for a silt (Si)

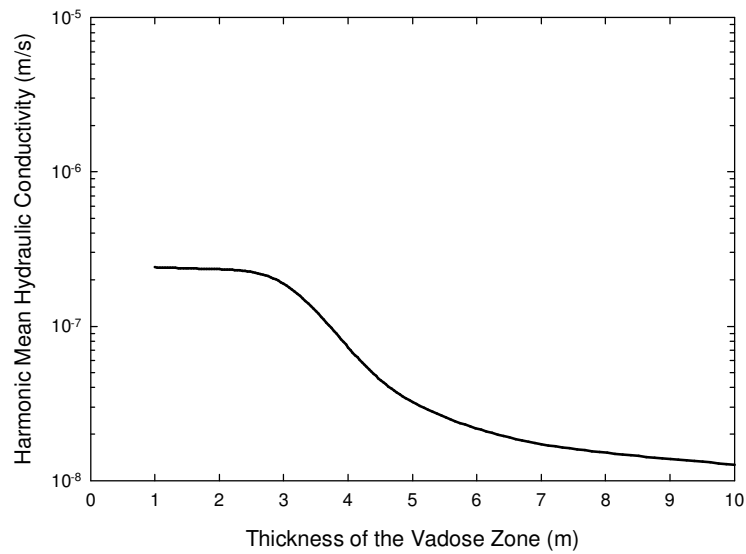


Figure 4. 6 Change in the harmonic mean hydraulic conductivity of the vadose zone with varying silty (Si) vadose zone thickness

Similar to the coarse textured vadose zones, the effective hydraulic conductivity of the barrier system increased with the thickness of the fine textured vadose zone (Table 4.2). The increased effective hydraulic conductivity of the overall barrier system resulted in a gradual increase in the steady-state leakage rates into the aquifer, which reach a constant value beyond 5 m. (Figure 4.7). Hand-calculated steady-state leakage rates also agree with the SEEP/W model results for fine textured vadose zones (Table 4.2).

Table 4. 2 Harmonic mean hydraulic conductivity values of the fine textured vadose zones, effective hydraulic conductivity values of the overall barrier system and steady-state leakage rates

Soil type	Thickness of Vadose Zone	\bar{k}_{vz} ^(a)	\bar{k}_{vzcl} ^(b)	q_{hc} ^(c)	q_{mc} ^(d)
	(m)	(m/s)	(m/s)	(m/a)	(m/a)
Si	1	2.41x10 ⁻⁷	2.65x10 ⁻⁹	0.0992	0.0990
Si	5	3.22x10 ⁻⁸	7.41x10 ⁻⁹	0.246	0.246
Si	10	1.27x10 ⁻⁸	7.64x10 ⁻⁹	0.248	0.248
SiT	1	5.46x10 ⁻⁸	2.59x10 ⁻⁹	0.0969	0.0968
SiT	5	1.04x10 ⁻⁸	5.18x10 ⁻⁹	0.172	0.172
SiT	10	7.13x10 ⁻⁹	5.29x10 ⁻⁹	0.172	0.172
USi	1	1.00x10 ⁻⁸	2.29x10 ⁻⁹	0.0856	0.0855
USi	5	1.00x10 ⁻⁸	5.09x10 ⁻⁹	0.169	0.169
USi	10	1.00x10 ⁻⁸	6.81x10 ⁻⁹	0.215	0.216

^(a) Harmonic mean of vadose zone hydraulic conductivity

^(b) Harmonic mean of vadose zone and compacted clay liner hydraulic conductivity

^(c) Steady-state leakage rate as a result of hand calculations

^(d) Model calculated steady-state leakage rate

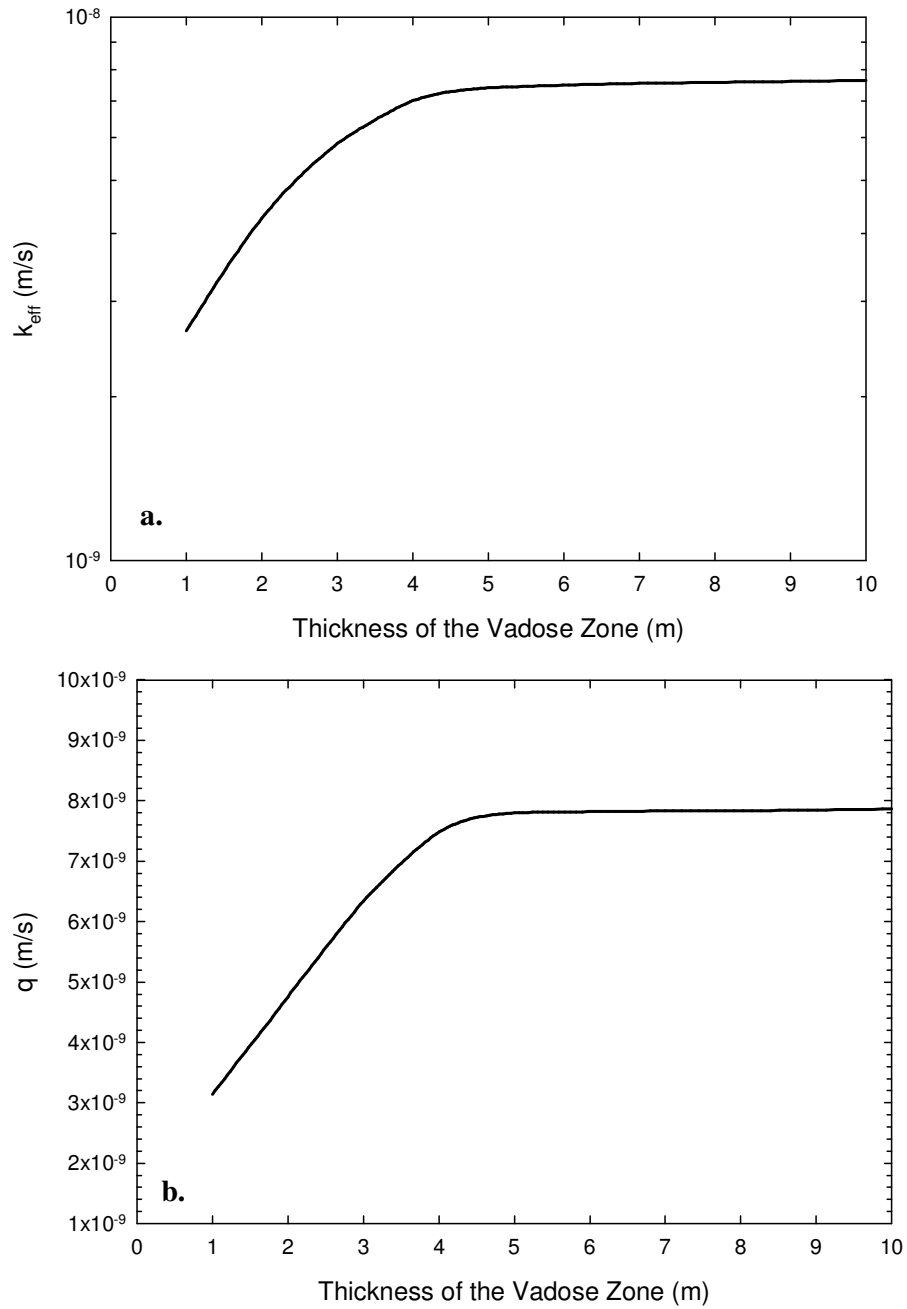


Figure 4. 7 Change in (a) the effective hydraulic conductivity of the overall barrier system and (b) the steady-state leakage rates with varying silty (Si) vadose zone thickness

When the barrier system is simulated using uniform saturated hydraulic conductivities, the steady-state leakage rates (denoted by $q_{K_{uni}}$) are the same as the leakage rates simulated using soil hydraulic conductivity functions of silt and silt tailings (denoted by $q_{K_{uni}}$), for vadose zone thicknesses less than 5 m. Vadose zones composed of silty soils and thicker than 5 m resulted in steady-state leakage rates that are 1.5 to 2.5 times greater than the ones obtained by using soil hydraulic conductivity functions. As previously stated, the hydraulic conductivity and therefore the steady state leakage rates occurring in uniform silts are not affected by pressure for vadose zones shallower than 10 m (Figure 4.8). Although the normalized leakage rates demonstrate a significant difference between saturated and unsaturated conditions, there is only one order of magnitude difference between saturated hydraulic conductivity values and the harmonic mean conductivity values for silty soils. Therefore, fine textured vadose zones can be modeled using uniform saturated hydraulic conductivity values.

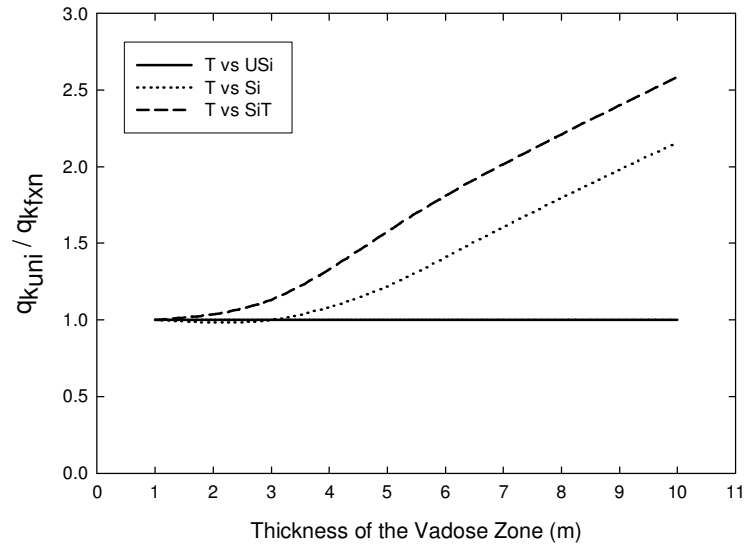


Figure 4. 8 Normalized steady-state leakage rates with varying fine textured vadose zone thickness (T stands for vadose zone thickness, USi stands for uniform silt, Si stands for silt, and SiT stands for silt tailings)

4.1.2.1. Effect of Compacted Clay Liner Hydraulic Conductivity

The effect of compacted clay liner hydraulic conductivity on the overall performance of the barrier system is also evaluated using a saturated compacted clay liner hydraulic conductivity of 1×10^{-10} m/s. For both coarse textured and fine textured vadose zones, one order of magnitude decrease in the compacted clay liner hydraulic conductivity (i.e. 1×10^{-10} m/s is used instead of 1×10^{-9} m/s) resulted in almost the same order (one order) of magnitude decrease in the effective hydraulic conductivity of the overall barrier system and steady-state leakage rates into the aquifer (Table 4.3). An order of magnitude increase in the vadose zone thickness, on the other hand, resulted in half order of magnitude increase in the steady-state leakage rate, and the effective hydraulic conductivity (Table 4.1 and Table 4.2). Therefore, the effect of compacted clay liner hydraulic conductivity is dominant over the vadose zone thickness and it should be considered as the controlling factor for leakage into the aquifer.

Table 4.3 The effect of compacted clay liner hydraulic conductivity on the effective hydraulic conductivity and steady-state leakage rates into the aquifer

	Coarse textured VZ				Fine textured VZ			
T_{vz} (m)	5	10	5	10	5	10	5	10
k_{ccl} (m/s)	1×10^{-9}	1×10^{-9}	1×10^{-10}	1×10^{-10}	1×10^{-9}	1×10^{-9}	1×10^{-10}	1×10^{-10}
q (m/yr)	0.214	0.223	0.028	0.034	0.246	0.248	0.029	0.031
k_{vzcl} (m/s)	6.45×10^{-9}	6.87×10^{-9}	8.51×10^{-10}	1.04×10^{-9}	7.41×10^{-9}	7.64×10^{-9}	8.70×10^{-10}	9.61×10^{-10}

4.2. Effect of Waste Thickness and Seepage Velocity on Steady-State Leakage Rates from Landfill Barrier Systems

The first set of simulations (groundwater seepage velocity sensitivity) showed that seepage velocity considerably affects the contaminant concentrations in the aquifer, due to dilution. As the seepage velocity in the aquifer increases, the contaminant concentrations decrease (Table 4.4). For the designs having geosynthetics in the bottom liners (C2L2), the relation between the decrease in the contaminant concentrations and increase in the seepage velocity is linear. For the designs with natural bottom liners or having compacted clay liners (C1L1, C3L5), the relation is not linear. This is due to the fact that lower concentrations are affected by dilution more than higher concentrations (Table 4.5). In Table 4.5, seepage velocities are normalized by the previously used seepage velocity of 1.2 m/d; and, concentrations are normalized with the concentration values calculated for 20 m waste thickness and 1.2 m/d seepage velocity. The representative seepage velocity values are selected as 0.05, 0.1, 0.5, and 1 m/d for the simulations.

Table 4. 4 Groundwater seepage velocity sensitivity analyses

C1L1 ^a	C_{max}	T_{max}	C2L2 ^b	C_{max}	T_{max}	C3L5 ^c	C_{max}	T_{max}
	mg/L	yr		mg/L	yr		mg/L	yr
$v_s = 0.05$ m/d	735	21	$v_s = 0.05$ m/d	11.6	1067	$v_s = 0.05$ m/d	725	23
$v_s = 0.1$ m/d	398	18	$v_s = 0.1$ m/d	5.8	1067	$v_s = 0.1$ m/d	392	19
$v_s = 0.5$ m/d	85.3	14	$v_s = 0.5$ m/d	1.16	1067	$v_s = 0.5$ m/d	84	16
$v_s = 1$ m/d	43	14	$v_s = 1$ m/d	0.58	992	$v_s = 1$ m/d	42	16

^a natural attenuation landfill

^b extensive engineering landfill

^c intermediate engineering landfill

Table 4. 5 Normalized concentrations occurred as a result of various seepage velocities

Normalized v_s	Normalized C	Normalized C	Normalized C
	C1L1 ^a	C2L2 ^b	C3L5 ^c
0.042	20.531	24.167	20.714
0.083	11.117	12.083	11.200
0.417	2.383	2.417	2.400
0.833	1.201	1.208	1.200

^a natural attenuation landfill

^b extensive engineering landfill

^c intermediate engineering landfill

Waste thickness sensitivity analyses, on the other hand, showed that the effect of waste thickness is not as evident as seepage velocity (Table 4.6). The waste thickness values are normalized by 20 m, and concentrations are normalized by the concentration values from a 20-m-thick waste. While contaminant concentration from a 30-m-thick waste is only 1.06 times higher than contaminant concentration from a 20-m-thick waste; contaminant concentration from a 15-m-thick waste is 1.45 times higher than contaminant concentration from a 5-m-thick waste (Table 4.7). This may be expected because 30 m is considered as a threshold depth (Yen and Scanlan, 1975) after which the biodegradation is very slow (El-Fadel and Khoury, 2000). Therefore, the waste thickness values to be used in the simulations were determined as 5 m and 20 m to represent shallow and deep landfills.

Table 4. 6 Normalized concentrations occurred as a result of various waste thicknesses

Normalized T_w	Normalized C	Normalized C	Normalized C
	C1L1 ^a	C2L2 ^b	C3L5 ^c
0.25	0.88	0.65	0.88
0.50	0.95	0.85	0.96
0.75	0.98	0.94	0.99
1.00	1.00	1.00	1.00
1.50	1.02	1.08	1.02

^a natural attenuation landfill ^b extensive engineering landfill

^c intermediate engineering landfill

Table 4. 7 Waste thickness sensitivity analyses

C1L1 ^a	C_{max}	T_{max}	C2L2 ^b	C_{max}	T_{max}	C3L5 ^c	C_{max}	T_{max}
	mg/L	yr		mg/L	yr		mg/L	yr
$T_w = 5$ m	31.4	14	$T_w = 5$ m	0.31	737	$T_w = 5$ m	30.8	15
$T_w = 10$ m	34.1	14	$T_w = 10$ m	0.41	860	$T_w = 10$ m	33.5	15
$T_w = 15$ m	35.1	14	$T_w = 15$ m	0.45	934	$T_w = 15$ m	34.5	15
$T_w = 20$ m	35.8	14	$T_w = 20$ m	0.48	1009	$T_w = 20$ m	35	16
$T_w = 30$ m	36.4	14	$T_w = 30$ m	0.52	1009	$T_w = 30$ m	35.7	16

^a natural attenuation landfill ^b extensive engineering landfill

^c intermediate engineering landfill

Third set of sensitivity analyses were performed to observe the respective effects of waste thickness and seepage velocity. As stated above, the seepage velocity is dominant over waste thickness. However, their combined effect is stronger. Table 4.8 shows that, keeping the seepage velocity constant, 4 folds increase in waste thickness increases contaminant concentrations 1.1 folds; however, keeping the waste thickness constant, 5 folds decrease in seepage velocity results in a 4.3 times increase in contaminant concentrations. Their combined effect results in a 5.3 times increase in contaminant concentration in the aquifer. These results show that actually the effects of waste thickness and seepage velocity are almost summed, which is expected as there is no correlation between these parameters.

Table 4. 8 Respective effects of waste thickness and seepage velocity on contaminant concentrations

Waste Thickness (m)	Seepage Velocity (m/d)	Concentration (C1L1^a) (mg/L)
5	0.5	74.7
5	0.1	318.3
20	0.5	85.3
20	0.1	398

^a natural attenuation landfill

As a result of sensitivity analyses, 0.05, 0.1, 0.5 and 1 m/d values are selected to be used as seepage velocities and 5 and 20 m values are selected to be used as waste thicknesses in landfill design simulations.

4.3. Performance-Based Evaluation of Landfill Design Alternatives

Performance of the design alternatives is evaluated under 4 headings: cover system performance, compliance to first performance criterion (hydraulic head on top of barrier liner), leachate collection and leakage rates, and compliance to second performance criterion (contaminant concentrations at the groundwater table) with respect to arid, moderate, and humid climates. The results presented in this section were evaluated to emphasize the importance of a performance-based design assessment and coalesced to construct the design component selection matrix which is used as the knowledge-base of the preliminary design phase in LFDSS.

4.3.1. Cover System Performance

A total of 9 HELP simulations for 3 different final covers (i.e. evapotranspiration final cover –C1, extensive engineering final cover –C2, and intermediate design final cover –C3) and 3 different climatic conditions (i.e. arid, moderate, and

humid) were performed to calculate the amount of infiltration into waste layers. The results of the simulations are presented in Table 4.9.

Table 4. 9 Infiltration rates by HELP model

Final cover	Arid	Moderate	Humid
	(P < 500 mm/y)	(500 ≤ P < 1000 mm/y)	(P ≥ 1000 mm/y)
	<i>Infiltration (q₀)</i>	<i>Infiltration (q₀)</i>	<i>Infiltration (q₀)</i>
	<i>(m/y)</i>	<i>(m/y)</i>	<i>(m/y)</i>
C1	0.046	0.249	0.585
C2	0.00141	0.00423	0.00889
C3	0.045	0.245	0.577

Table 4.9 indicates that the evapotranspiration final cover which is composed of only natural topsoil (C1) produced the highest infiltration. Extensive engineering final cover composed of natural topsoil, cover drainage layer, geomembrane, and clay liner (C2) restricted infiltration to a great extent. The intermediate design final cover from which the geomembrane was excluded (C3) was not sufficient in restricting infiltration. The data presented in Table 4.9 was used as “infiltration” input data in POLLUTE model.

4.3.2. Compliance with the First Performance Criterion (Stability)

The maximum allowable hydraulic head on top of barrier liner have been determined to be less than 1 m for stability reasons. For the design alternatives lacking drainage or leachate collection system in the final cover or bottom liner, the hydraulic head on top of the barrier liner can exceed the maximum allowable hydraulic head (1 m). POLLUTE was used to calculate the hydraulic head development on the barrier liner; and therefore, to evaluate the compliance of the design alternatives to the first performance criterion.

Under arid climates ($P < 500$ mm/y), as the infiltration was too low, no hydraulic head problems were observed, even for the designs coupled with final covers lacking drainage layer and/or geomembrane. Regardless of climatic conditions, when the vadose zone in which the landfill was placed had a hydraulic conductivity in the order of 10^{-7} m/s, the hydraulic head development was not significant. However, for lower conductivity vadose zones (10^{-8} m/s), under moderate climates ($500 \text{ mm/y} \leq P < 1000 \text{ mm/y}$) the bottom liner design composed of compacted clay liner placed on vadose zone ($L6^L$; $k = 6,63 \times 10^{-9} \text{ m/s}^{1, 2}$), and under humid climates ($P \geq 1000 \text{ mm/y}$) both $L6^L$ and natural attenuation bottom liner composed of only the vadose zone below waste ($L1^L$; $k = 1 \times 10^{-8} \text{ m/s}$) resulted in hydraulic head development exceeding 1 m, because their effective hydraulic conductivities were lower than the infiltration rate coming to the bottom liner ($q_0 = 1,4 \times 10^{-9} \text{ m/s}$ for moderate climates; $q_0 = 1,6 \times 10^{-8} \text{ m/s}$ for humid climates) (Table 4.10). Therefore, $L1^L$ and $L6^L$ bottom liner designs are not appropriate for moderate and humid climates unless they are coupled with an extensive engineering final cover (C2). So, the aforementioned design alternatives ($C1L1^L$, $C1L6^L$, $C3L1^L$, $C3L6^L$) were excluded from the simulation list.

¹ Superscript L indicates that the design alternative is suitable for low permeability aquitards ($k = 1 \times 10^{-8} \text{ m/s}$).

² The effective hydraulic conductivity values stated here and in the rest of the thesis are the harmonic means of liner and vadose zone hydraulic conductivities.

Table 4. 10 Hydraulic head values that are supposed to develop

Design	Arid (P < 500 mm/y)		Moderate (500 < P ≤ 1000 mm/y)		Humid (P > 1000 mm/y)	
	Hydraulic Head (m)		Hydraulic Head (m)		Hydraulic Head (m)	
	$k^{(a)}=10^{-7}$ m/s	$k=10^{-8}$ m/s	$k=10^{-7}$ m/s	$k=10^{-8}$ m/s	$k=10^{-7}$ m/s	$k=10^{-8}$ m/s
	$\phi = 0.35$	$\phi = 0.45$	$\phi = 0.35$	$\phi = 0.45$	$\phi = 0.35$	$\phi = 0.45$
C1L1		-		-		8.56
C1L6	-	-	-	2.03	2.39	19.09
C2L1		-		-		-
C2L6	-	-	-	-	-	-
C3L1		-		-		8.30
C3L6	-	-	-	1.83	2.21	18.68

^(a) The given hydraulic conductivity (k) and porosity (ϕ) values belong to vadose zone.

4.3.3. Leachate Collection (q_c) and Leakage Rates (q_l)

Leachate collection (q_c) and leakage rates (q_l) were calculated using POLLUTE. When the infiltration coming to the bottom liner is greater than the effective hydraulic conductivity (k_{eff}) of the bottom liner, the leachate collection system is effective and allows a leakage rate equal to the effective hydraulic conductivity of the bottom liner. Bottom liner designs having leachate collection systems, and the infiltration rates they receive are presented in Table 4.11. According to Table 4.11, leachate collection systems coupled with geomembranes are effective in leachate collection. Under arid climates ($P < 500$ mm/y), as the infiltration rate coming to the bottom liner (1.4×10^{-9} m/s) was lower than the effective hydraulic conductivity of bottom liner composed of leachate collection system over aquitard (L3; $k = 1 \times 10^{-8}$ m/s) and intermediate design bottom liner composed of leachate collection system and compacted clay liner (L5^L; $k = 6.6 \times 10^{-9}$ m/s), hydraulic head did not develop and leachate collection system was not functional. A leachate collection system is not necessary under these conditions, and the leakage is controlled primarily by final cover. Under moderate climates ($500 \text{ mm/y} \leq P < 1000$ mm/y), leachate collection system was effective when it was coupled with a

compacted clay liner (L5). Leachate collection system is required under humid ($P \geq 1000$ mm/y) climates as the infiltration rates are greater than any of the bottom liner effective hydraulic conductivities.

Table 4. 11 Effective hydraulic conductivity values of the bottom liners and the infiltration rates coming to the bottom liners

Design Alternative	k_{eff} (m/s)	Arid	Moderate	Humid
		($P < 500$ mm/y)	($500 \leq P < 1000$ mm/y)	($P \geq 1000$ mm/y)
		$q_0^{(a)}$ (m/s)	q_0 (m/s)	q_0 (m/s)
L2	$< 10^{-12}$	C1; 1.4×10^{-9}	C1; 7.9×10^{-9}	C1; 1.6×10^{-8}
		C2; 4.5×10^{-11}	C2; 1.3×10^{-10}	C2; 2.8×10^{-10}
		C3; 1.4×10^{-9}	C3; 7.8×10^{-9}	C3; 1.8×10^{-8}
L3	1×10^{-8}	C1; 1.4×10^{-9}	C1; 7.9×10^{-9}	C1; 1.6×10^{-8}
		C2; 4.5×10^{-11}	C2; 1.3×10^{-10}	C2; 2.8×10^{-10}
		C3; 1.4×10^{-9}	C3; 7.8×10^{-9}	C3; 1.8×10^{-8}
L4	$< 10^{-12}$	C1; 1.4×10^{-9}	C1; 7.9×10^{-9}	C1; 1.6×10^{-8}
		C2; 4.5×10^{-11}	C2; 1.3×10^{-10}	C2; 2.8×10^{-10}
		C3; 1.4×10^{-9}	C3; 7.8×10^{-9}	C3; 1.8×10^{-8}
L5	6.63×10^{-9}	C1; 1.4×10^{-9}	C1; 7.9×10^{-9}	C1; 1.6×10^{-8}
		C2; 4.5×10^{-11}	C2; 1.3×10^{-10}	C2; 2.8×10^{-10}
		C3; 1.4×10^{-9}	C3; 7.8×10^{-9}	C3; 1.8×10^{-8}

^(a) C1, C2, C3 indicates the final cover design producing the infiltration

As previously stated, the bottom liner designs allow leakage equal to their effective hydraulic conductivities. Effective hydraulic conductivity is the harmonic mean of the compacted clay liner hydraulic conductivity and the vadose zone hydraulic conductivity. For geomembranes, as they are not natural materials, an effective hydraulic conductivity value cannot be calculated; however, can be estimated (Table 4.11). The leakage rates from the bottom liner to the aquifer are presented in Table 4.12. As can be seen from the table, the hydraulic properties of the vadose zone played an important role in leachate collection and leakage. As the high conductivity vadose zones did not help in leachate collection, they resulted in higher leakage to the aquifers. Therefore, design of landfills on low

conductivity vadose zones should be considered for an efficient leachate collection and lower leakage rates to the aquifers.

Table 4. 12 Leakage rates by POLLUTE

Design Alternative	Arid ($P < 500$ mm/y)		Moderate ($500 \leq P < 1000$ mm/y)		Humid ($P \geq 1000$ mm/y)	
	q_c (m/y)	q_l (m/y)	q_c (m/y)	q_l (m/y)	q_c (m/y)	q_l (m/y)
	<i>C1 –infiltration</i>		0.046		0.249	
C1L1	-	0.046	-	0.249	-	-
C1L2	-	0.046	0.234	0.015	0.570	0.015
C1L3	-	0.046	-	0.249	0.260	0.325
C1L4	-	0.046	0.150	0.099 (k_h)	0.486	0.099 (k_h)
			0.239	0.010 (k_i)	0.575	0.010 (k_i)
C1L5	-	0.046	-	0.249 (k_h)	0.094	0.491 (k_h)
			0.034	0.215 (k_i)	0.370	0.215 (k_i)
C1L6	-	0.046		-		-
<i>C2 –infiltration</i>		0.0014		0.00423		0.0089
C2L1	-	0.0014	-	0.00423	-	0.0089
C2L2	-	0.0014	-	0.00423	-	0.0089
C2L3	-	0.0014	-	0.00423	-	0.0089
C2L4	-	0.0014	-	0.00423	-	0.0089
C2L5	-	0.0014	-	0.00423	-	0.0089
C2L6	-	0.0014	-	0.00423	-	0.0089
<i>C3 –infiltration</i>		0.045		0.245		0.577
C3L1	-	0.045	-	0.245	-	-
C3L2	0.030	0.015	0.230	0.015	0.562	0.015
C3L3	-	0.045	-	0.245	0.252	0.325
C3L4	-	0.045	0.146	0.099 (k_h)	0.478	0.099 (k_h)
	0.035	0.010	0.235	0.010 (k_i)	0.567	0.010 (k_i)
C3L5	-	0.045	-	0.245 (k_h)	0.086	0.491 (k_h)
			0.030	0.215 (k_i)	0.362	0.215 (k_i)
C3L6	-	0.045	-	-	-	-

^a Indicates high conductivity vadose zone ^b Indicates low conductivity vadose zone

4.3.4. Compliance with the Second Performance Criterion (Contaminant Concentration)

The maximum contaminant (Cl⁻) concentration that can be allowed at the receptor point had been determined to be 25 mg/L due to Turkish Drinking Water Standards (TSE, 1997). However, this standard was updated in 2005, and the maximum allowable chloride concentration was accepted to be 250 mg/L (TSE, 2005). In order to obtain conservative results, 25 mg/L was considered as the performance criterion for the preliminary evaluation of the design alternatives and for the design component selection matrix.

To evaluate the contamination that each of the 18 design alternatives would cause at the top of the aquifer, 1300 POLLUTE simulations were performed under 3 climatic conditions, with 2 different waste thicknesses, 4 different seepage velocity values, and 3 different landfill areas. In the main body of the thesis, only the results of major design alternatives (C1L1, C2L2, and C3L5) with medium and fast seepage velocities (0.5 m/d and 1 m/d) are presented in Tables; however, the discussions are based on the overall results of 1300 simulations. The complete results of simulations are given in Appendix-E.

Regardless of the climate, the natural attenuation landfill (C1L1) caused the highest contaminant concentration at the receptor, much above the accepted limit of 25 mg/L; such that, for a landfill of 50 ha, having 20-m-waste thickness, and with a slow seepage velocity of 0.1 m/d, the contaminant concentrations at the groundwater table were 227.8 mg/L, 557.9 mg/L, and 571.1 mg/L, for arid, moderate, and humid climates, respectively. As extensive engineering landfill (C2L2) removed most of the contaminant mass by leachate collection, this design resulted in the lowest contaminant concentrations at the receptor; such that, for a landfill of 50 ha, having 20-m-waste thickness, and with a slow seepage velocity of 0.5 m/d, the contaminant concentrations at the groundwater table were 2.16

mg/L, 5.6 mg/L, and 12.3 mg/L, for arid, moderate, and humid climates, respectively. Lower hydraulic conductivity vadose zones increased the efficiency of the leachate collection system by decreasing the effective hydraulic conductivity of the landfill bottom liner, and therefore, increased the performance of the landfill design alternative.

4.3.4.1. Performance Evaluation under Arid Climates ($P < 500$ mm/y)

As stated in Section 4.3.3, because the infiltration rate was less than the effective hydraulic conductivities of natural attenuation bottom liner (L1) and bottom liners having leachate collection systems coupled with compacted clay liners (L5), the leachate collection systems were not functional. Therefore, the leakage was controlled by the final cover.

When the seepage velocity was in the range of medium to fast (0.5 – 1 m/d), and the landfill area was less than 15 ha, all design alternatives complied with the contamination performance criterion. When the landfill size was medium (15 – 50 ha) and waste thickness could be designed as 5 m, all design alternatives placed on low conductivity vadose zones complied with the contamination criterion. Except under very slow seepage velocities (≤ 0.05 m/d), all landfill bottom liner designs coupled with extensive engineering final cover having geomembrane (C2) satisfied less than 25 mg/L chloride concentration at the receptor. When the seepage velocity in the aquifer was in the range of very slow to slow (0.05 – 0.1 m/d), only the design alternatives having geomembranes in their bottom liners (L2, L4) satisfied the performance criterion. For large landfills ($A > 50$ ha) with 20-m-waste thickness, seepage velocity also lost its effect of dilution and design alternatives lacking geomembranes either in their final covers or bottom liners did not comply with the performance criterion. For situations where the waste

thickness could be decreased to 5 m, designs lacking geomembranes also complied with the contamination criterion.

Extensive engineering bottom liners composed of leachate collection systems, geomembranes, and compacted clay liners (L2) satisfied the performance criterion under most of the design conditions. When L2 does not satisfy the performance criterion, the design alternative can be used on lower conductivity aquitards; or, double liner designs can be considered for very large ($A > 100$ ha) landfills.

The simulation results for arid climates are given in Table 4.13.

Table 4. 13 Performance of design alternatives under arid climates ($P < 500$ mm/y)

	T_{\max}	C_{\max}		T_{\max}	C_{\max}		T_{\max}	C_{\max}
C1L1	(y)	(mg/L)	C2L2	(y)	(mg/L)	C3L5	(y)	(mg/L)
C-S-m ^(a)	115	9.5	C-S-m ^(a)	1339	0.27	C-S-m ^(a)	123	9.2
C-S-f	115	4.8	C-S-f	1339	0.14	C-S-f	123	4.6
C-D-m	127	13.7	C-D-m	1834	0.43	C-D-m	138	13.3
C-D-f	127	6.8	C-D-f	1834	0.22	C-D-f	138	6.7
S-S-m	115	23.8	S-S-m	1339	0.69	S-S-m	123	23.0
S-S-f	115	11.9	S-S-f	1339	0.34	S-S-f	123	11.5
S-D-m	131	34.3	S-D-m	1834	1.08	S-D-m	138	33.3
S-D-f	127	17.1	S-D-f	1834	0.54	S-D-f	138	16.7
M-S-m	119	47.4	M-S-m	1339	1.37	M-S-m	126	45.6
M-S-f	118	23.8	M-S-f	1339	0.69	M-S-f	123	23.0
M-D-m	134	68.4	M-D-m	1834	2.16	M-D-m	143	66.6
M-D-f	131	34.3	M-D-f	1834	1.08	M-D-f	138	33.3

^(a) Landfill area → C: 2ha, S: 15ha, M: 50ha; waste thickness → S: 5m, D: 20m; seepage velocity → m: 0.5 m/d, f: 1 m/d

4.3.4.2. *Performance Evaluation under Moderate Climates ($500 \leq P < 1000$ mm/y)*

Under moderate conditions, as the infiltration rate (7.9×10^{-9} m/s) was lower than the hydraulic conductivities of natural attenuation bottom liner composed of only aquitard below waste (L1; $k = 1 \times 10^{-8}$ m/s) and bottom liners composed of leachate collection system placed on aquitards (L3; $k = 1 \times 10^{-8}$ m/s), the leachate collection system was not functional. Although the hydraulic conductivity of bottom liners composed of leachate collection system coupled with compacted clay liners (L5; $k = 6.6 \times 10^{-9}$ m/s) was lower than the infiltration rate, the leachate collection was not sufficient ($q_c = 0.03$ m/y), and the bottom liner design did not satisfy the performance criterion.

When the bottom liner designs lacking geomembranes (L1, L3, L5, L6) were coupled with final covers having geomembranes (C2), the composed design alternatives satisfied less than 25 mg/L chloride concentration at the receptor point, except for very slow seepage velocities (0.05 m/d). In the range of very slow to slow seepage velocities (0.05 – 0.1 m/d), only the design alternatives having geomembranes either in their bottom liners (L2, L4) or final cover (C2) satisfied the performance criterion. For faster seepage velocities (> 0.1 m/d), communal to medium size landfills ($< 1 - 50$ ha) with bottom liners having compacted clay (L5, L6) complied with the performance criterion. However, for large landfills ($A > 50$ ha), seepage velocity lost its effect of dilution and design alternatives having compacted clay liners did not comply with the performance criterion.

Extensive engineering bottom liners composed of leachate collection systems, geomembranes, and compacted clay liners (L2) satisfied the performance criterion under most of the design conditions. When L2 does not satisfy the performance

criterion, the design alternative can be designed on lower conductivity aquitards; or, double liner designs can be considered for very large ($A > 100$ ha) landfills.

The simulation results of the design alternatives under moderate climates are given in Table 4.14.

Table 4. 14 Performance of design alternatives under moderate climates ($500 \leq P < 1000$ mm/y)

	T_{\max}	C_{\max}		T_{\max}	C_{\max}		T_{\max}	C_{\max}
C1L1	(y)	(mg/L)	C2L2	(y)	(mg/L)	C3L5	(y)	(mg/L)
C-S-m ^(a)	21	66.9	C-S-m ^(a)	818	0.69	C-S-m ^(a)	25	54.7
C-S-f	21	33.6	C-S-f	818	0.35	C-S-f	25	27.5
C-D-m	22	82.3	C-D-m	1067	1.12	C-D-m	27	69.6
C-D-f	22	41.2	C-D-f	1067	0.56	C-D-f	26	34.9
S-S-m	21	162.5	S-S-m	818	1.73	S-S-m	26	134.1
S-S-f	21	83.5	S-S-f	818	0.86	S-S-f	25	68.3
S-D-m	22	203.0	S-D-m	1067	2.79	S-D-m	28	172.4
S-D-f	22	102.6	S-D-f	1067	1.40	S-D-f	27	86.9
M-S-m	22	302.5	M-S-m	818	3.46	M-S-m	27	252.5
M-S-f	21	162.7	M-S-f	818	1.73	M-S-f	26	134.1
M-D-m	25	392.4	M-D-m	1067	5.58	M-D-m	29	335.5
M-D-f	22	203.0	M-D-f	1067	2.79	M-D-f	28	172.4

^(a) Landfill area → C: 2ha, S: 15ha, M: 50ha; waste thickness → S: 5m, D: 20m; seepage velocity → m: 0.5 m/d, f: 1 m/d

4.3.4.3. Performance Evaluation under Humid Climates ($P \geq 1000$ mm/y)

Under humid climates, as the infiltration rate (1.6×10^{-8} m/s) was close to hydraulic conductivity of natural attenuation bottom liner composed of only aquitard below waste (L1; $k = 1 \times 10^{-8}$ m/s), the hydraulic properties of the vadose zone were insufficient to satisfy the performance criterion. Leachate collection systems were required under such conditions. However, even hydraulic

conductivity of bottom liners composed of leachate collection system coupled with compacted clay liner (L5; $k = 6.6 \times 10^{-9}$ m/s) was lower than the infiltration rate, the leachate collection efficiency ($q_c = 0.03$ m/y) was not sufficient.

Under humid climates, design alternatives lacking geomembranes did not comply with the performance criterion. Only for communal landfill sizes ($A \leq 2$ ha), intermediate engineering landfill designs composed of leachate collection system, and compacted clay liner placed on low conductivity aquitards (C1L5, C3L5) satisfied the contaminant criterion at the receptor. For small landfills ($A < 15$ ha), geomembranes were not required in the bottom liners when the design alternative had an extensive engineering final cover having geomembrane (C2). As the landfill size increased ($A > 15$ ha), design alternatives composed of extensive engineering final cover having geomembranes and bottom liners lacking geomembranes (C2L1, C2L3, C2L5) complied with the performance criterion only with seepage velocities faster than 0.5 m/d. Design alternatives having geomembranes in their bottom liners (C1L2, C1L4, C3L2, C3L4) complied with the contamination criterion. Waste thickness was not a controlling factor under humid climates.

As previously stated, extensive engineering bottom liners composed of leachate collection systems, geomembranes, and compacted clay liners (L2) satisfied the performance criterion under most of the design conditions. When L2 does not satisfy the performance criterion, the design alternative can be used on lower conductivity aquitards; or, double liner designs can be considered for very large ($A > 100$ ha) landfills.

Performance of the design alternatives under humid climates are presented in Table 4.15.

Table 4. 15 Performance of design alternatives under humid climates ($P \geq 1000$ mm/y)

	T_{\max}	C_{\max}		T_{\max}	C_{\max}		T_{\max}	C_{\max}
C1L1	(y)	(mg/L)	C2L2	(y)	(mg/L)	C3L5	(y)	(mg/L)
C-S-m ^(a)	9	164.3	C-S-m ^(a)	467	1.57	C-S-m ^(a)	25	40.3
C-S-f	9	85.4	C-S-f	467	0.79	C-S-f	24	20.3
C-D-m	9	195.6	C-D-m	602	2.45	C-D-m	26	61.9
C-D-f	9	99.4	C-D-f	602	1.22	C-D-f	26	31.0
S-S-m	10	359.0	S-S-m	467	3.92	S-S-m	25	97.7
S-S-f	9	200.8	S-S-f	467	1.96	S-S-f	25	50.2
S-D-m	11	460.0	S-D-m	602	6.12	S-D-m	26	152.4
S-D-f	10	241.9	S-D-f	602	3.06	S-D-f	26	77.2
M-S-m	10	571.1	M-S-m	484	7.84	M-S-m	26	179.8
M-S-f	10	359.0	M-S-f	467	3.92	M-S-f	25	97.7
M-D-m	12	795.4	M-D-m	602	12.23	M-D-m	28	291.1
M-D-f	11	459.6	M-D-f	602	6.12	M-D-f	26	152.4

^(a) Landfill area → C: 2ha, S: 15ha, M: 50ha; waste thickness→ S: 5m, D: 20m; seepage velocity → m: 0.5 m/d, f: 1 m/d

4.4. The Design Component Selection Matrix

Following the methodology described in Section 3.1.2, design component selection matrices were constructed by coalescing the results of over 1300 simulations of 18 landfill design alternatives using system simulation models (i.e. HELP and POLLUTE) considering the design variables (i.e. climate –total annual precipitation amount, waste load –landfill area, waste thickness, seepage velocity, and site hydrogeology –hydraulic conductivity, porosity and thickness of vadose zone). The alternative design combinations presented in the matrix were selected based on simulated landfill performance evaluations. The design component selection matrices (Table 4.16, 4.17, and 4.18) are used as knowledge-base in LFDSS in the preliminary design phase, as guidance for the selection of most appropriate design components for a given site and waste conditions.

Table 4. 16 Design component selection matrix for arid climates ^{a, d, e}

	Area ^b (ha)	T _w (5 m)				T _w (20 m)				
		AA	AB	AC	AD	AE	AF	AG	AH	
		v _{s-vs} ^c	v _{s-s}	v _{s-m}	v _{s-f}	v _{s-vs}	v _{s-s}	v _{s-m}	v _{s-f}	
1	C A ≤ 2	C1L2	C1L2	C1L1	C1L1	C1L4 ^L	C1L2	C1L1	C1L1	1
2		C1L4 ^L	C1L4 ^L	C1L2	C1L2	C2LX	C1L4 ^L	C1L2	C1L2	2
3		C2LX	C2LX	C1L3	C1L3	C3L2	C2LX	C1L3	C1L3	3
4		C3L2	C3L2	C1L4	C1L4	C3L4 ^L	C3L2	C1L4	C1L4	4
5		C3L4 ^L	C3L4 ^L	C1L5	C1L5		C3L4 ^L	C1L5	C1L5	5
6				C1L6	C1L6			C1L6	C1L6	6
7				C2LX	C2LX			C2LX	C2LX	7
8				C3L1	C3L1			C3L1	C3L1	8
9				C3L3	C3L3			C3L3	C3L3	9
10				C3L2	C3L2			C3L2	C3L2	10
11				C3L4	C3L4			C3L4	C3L4	11
12				C3L5	C3L5			C3L5	C3L5	12
13				C3L6	C3L6			C3L6	C3L6	13
14	S (2-15]	C1L4 ^L	C1L2	C1L1	C1L1	C2LX	C1L4 ^L	C1L2	C1L1	14
15		C2LX	C1L4 ^L	C1L2	C1L2	C3L2	C2LX	C1L4 ^L	C1L2	15
16		C3L2	C2LX	C1L3	C1L3		C3L2	C2LX	C1L3	16
17		C3L4 ^L	C3L2	C1L4 ^L	C1L4		C3L4 ^L	C3L2	C1L4	17
18			C3L4 ^L	C1L5 ^L	C1L5			C3L4 ^L	C1L5	18
19				C1L6 ^L	C1L6				C1L6	19
20				C2LX	C2LX				C2LX	20
21				C3L1	C3L1				C3L1	21
22				C3L3	C3L3				C3L3	22
23				C3L2	C3L2				C3L2	23
24				C3L4 ^L	C3L4				C3L4	24
25				C3L5 ^L	C3L5				C3L5	25
26				C3L6 ^L	C3L6				C3L6	26
27	M (15-50]	C2LX	C1L4 ^L	C1L2	C1L1	C2LX	C2LX	C1L2	C1L2	27
28		C3L2	C2LX	C1L4 ^L	C1L2		C3L2	C1L4 ^L	C1L4 ^L	28
29			C3L2	C2LX	C1L3			C2LX	C2LX	29
30			C3L4 ^L	C3L2	C1L4 ^L			C3L2	C3L2	30
31				C3L4 ^L	C1L5 ^L			C3L4 ^L	C3L4 ^L	31
32					C1L6 ^L					32
33					C2LX					33
34					C3L1					34
35					C3L3					35
36					C3L2					36
37					C3L4 ^L					37
38					C3L5 ^L					38
39					C3L6 ^L					39
40	L A > 50	C3L2	C2LX	C1L4 ^L	C1L2		C2LX	C1L4 ^L	C1L2	40
41			C3L2	C2LX	C1L4 ^L			C2LX	C1L4 ^L	41
42				C3L2	C2LX			C3L2	C2LX	42
43				C3L4 ^L	C3L2			C3L4 ^L	C3L2	43
44					C3L4 ^L				C3L4 ^L	44
R/ C		AA	AB	AC	AD	AE	AF	AG	AH	R/ C

^a L1, L3 are designed for low conductivity aquitards (unsaturated hydraulic conductivity, $K_{ave} = 10^{-7} - 10^{-8}$ m/s); L2 is designed for higher conductivity vadose zones ($K_{ave} = 10^{-7}$ m/s) and L4, L5, L6 are designed for higher conductivity ($K_{ave} = 10^{-7}$ m/s) or lower conductivity vadose zones ($K_{ave} = 10^{-8}$ m/s). ^b Landfill area → C: 0- 2ha (communal), S: 2 - 15ha (small), M: 15- 50ha (medium); L: 50 – 100ha (large). ^c Seepage velocity values: $v_{s-vs} = 0.05$ m/d (very slow), $v_{s-s} = 0.1$ m/d (slow), $v_{s-m} = 0.5$ m/d (medium), $v_{s-f} = 1$ m/d (fast). ^d Subscript L indicates the design alternative is designed for lower conductivity aquitards with hydraulic conductivity of 1×10^{-8} m/s. ^e LX indicates that all the bottom liner design alternatives (L1, L2, L3, L4, L5, L6) are appropriate.

Table 4. 17 Design component selection matrix for moderate climates ^{a, d, e}

	Area ^b (ha)	T _w (5 m)				T _w (20 m)				
		MA	MB	MC	MD	ME	MF	MG	MH	
		v _{s-vs} ^c	v _{s-s}	v _{s-m}	v _{s-f}	v _{s-vs}	v _{s-s}	v _{s-m}	v _{s-f}	
1	C A ≤ 2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	1
2		C1L4 ^L	C1L4 ^L	C1L4	C1L4	C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4	2
3		C2LX	C2LX	C1L5	C1L5	C2LX	C2LX	C1L5	C1L5	3
4		C3L2	C3L2	C1L6	C1L6	C3L2	C3L2	C1L6	C1L6	4
5		C3L4 ^L	C3L4 ^L	C2LX	C2LX	C3L4 ^L	C3L4 ^L	C2LX	C2LX	5
6				C3L2	C3L2			C3L2	C3L2	6
7				C3L4	C3L4			C3L4 ^L	C3L4	7
8	S (2-15]	C1L2	C1L2	C1L2	C1L2	C1L4 ^L	C1L2	C1L2	C1L2	8
9		C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4	C3L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	9
10		C2LX	C2LX	C1L5 ^L	C1L5		C2LX	C2LX	C1L5	10
11		C3L2	C3L2	C1L6 ^L	C1L6		C3L2	C3L2	C1L6	11
12		C3L4 ^L	C3L4 ^L	C2LX	C2LX		C3L4 ^L	C3L4 ^L	C2LX	12
13				C3L2	C3L2				C3L2	13
14				C3L4 ^L	C3L4				C3L4 ^L	14
15	M (15-50]	C1L2	C1L2	C1L2	C1L2	C1L4 ^L	C1L4 ^L	C1L2	C1L2	15
16		C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	C3L4 ^L	C3L4 ^L	C1L4 ^L	C1L4 ^L	16
17		C3L2	C2LX	C2LX	C1L5 ^L			C2LX	C2LX	17
18		C3L4 ^L	C3L2	C3L2	C1L6 ^L			C3L2	C3L2	18
19			C3L4 ^L	C3L4 ^L	C2LX			C3L4 ^L	C3L4 ^L	19
20					C3L2					20
21					C3L4 ^L					21
22	L A > 50	C1L4 ^L	C1L2	C1L2	C1L2		C1L4 ^L	C1L2	C1L2	22
23		C3L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L		C3L4 ^L	C1L4 ^L	C1L4 ^L	23
24			C3L2	C2LX	C2LX			C2LX	C2LX	24
25			C3L4 ^L	C3L2	C3L2			C3L2	C3L2	25
26				C3L4 ^L	C3L4 ^L			C3L4 ^L	C3L4 ^L	26
R/ C			MA	MB	MC	MD	ME	MF	MG	MH

^a L1, L3 are designed for low conductivity aquitards (unsaturated hydraulic conductivity, $K_{ave} = 10^{-7} - 10^{-8}$ m/s); L2 is designed for higher conductivity vadose zones ($K_{ave} = 10^{-7}$ m/s) and L4, L5, L6 are designed for higher conductivity ($K_{ave} = 10^{-7}$ m/s) or lower conductivity vadose zones ($K_{ave} = 10^{-8}$ m/s). ^b Landfill area → C: 0- 2ha (communal), S: 2 - 15ha (small) , M: 15- 50ha (medium); L: 50 – 100ha (large). ^c Seepage velocity values: $v_{s-vs} = 0.05$ m/d (very slow), $v_{s-s} = 0.1$ m/d (slow), $v_{s-m} = 0.5$ m/d (medium), $v_{s-f} = 1$ m/d (fast). ^d Subscript L indicates the design alternative is designed for lower conductivity aquitards with hydraulic conductivity of 1×10^{-8} m/s. ^e LX indicates that all the bottom liner design alternatives (L1, L2, L3, L4, L5, L6) are appropriate.

Table 4. 18 Design component selection matrix for humid climates ^{a, d, e}

	Area ^b (ha)	T _w (5 m)				T _w (20 m)				
		HA	HB	HC	HD	HE	HF	HG	HH	
		v _{s-vs} ^c	v _{s-s}	v _{s-m}	v _{s-f}	v _{s-vs}	v _{s-s}	v _{s-m}	v _{s-f}	
1	C A ≤ 2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	1
2		C1L4 ^L	C1L4 ^L	C1L4	C1L4	C1L4 ^L	C1L4 ^L	C1L4	C1L4	2
3		C2LX	C2LX	C2LX	C1L5 ^L	C2LX	C2LX	C2LX	C2LX	3
4		C3L2	C3L2	C3L2	C2LX	C3L2	C3L2	C3L2	C3L2	4
5		C3L4 ^L	C3L4 ^L	C3L4	C3L2	C3L4 ^L	C3L4 ^L	C3L4	C3L4	5
6					C3L4					6
7					C3L5 ^L					7
8	S (2-15]	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	C1L2	8
9		C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4	C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	9
10		C3L2	C2LX	C2LX	C2LX	C3L2	C3L2	C2LX	C2LX	10
11		C3L4 ^L	C3L2	C3L2	C3L2	C3L4 ^L	C3L4 ^L	C3L2	C3L2	11
12			C3L4 ^L	C3L4 ^L	C3L4			C3L4 ^L	C3L4 ^L	12
13	M (15-50]	C1L2	C1L2	C1L2	C1L2	C1L4 ^L	C1L2	C1L2	C1L2	13
14		C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	C3L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	14
15		C3L2	C3L2	C2LX	C2LX		C3L2	C2LX	C2LX	15
16		C3L4 ^L	C3L4 ^L	C3L2	C3L2		C3L4 ^L	C3L2	C3L2	16
17				C3L4 ^L	C3L4 ^L			C3L4 ^L	C3L4 ^L	17
18	L A > 50	C1L2	C1L2	C1L2	C1L2	C1L4 ^L	C1L4 ^L	C1L2	C1L2	18
19		C1L4 ^L	C1L4 ^L	C1L4 ^L	C1L4 ^L	C3L4 ^L	C3L4 ^L	C1L4 ^L	C1L4 ^L	19
20		C3L4 ^L	C3L4 ^L	C2LX	C2LX			C2LX	C2LX	20
21				C3L2	C3L2			C3L2	C3L2	21
22				C3L4 ^L	C3L4 ^L			C3L4 ^L	C3L4 ^L	22
R/ C		HA	HB	HC	HD	HE	HF	HG	HH	R/ C

^a L1, L3 are designed for low conductivity aquitards (unsaturated hydraulic conductivity, $K_{ave} = 10^{-7} - 10^{-8}$ m/s); L2 is designed for higher conductivity vadose zones ($K_{ave} = 10^{-7}$ m/s) and L4, L5, L6 are designed for higher conductivity ($K_{ave} = 10^{-7}$ m/s) or lower conductivity vadose zones ($K_{ave} = 10^{-8}$ m/s). ^b Landfill area → C: 0- 2ha (communal), S: 2 - 15ha (small), M: 15- 50ha (medium); L: 50 – 100ha (large). ^c Seepage velocity values: $v_{s-vs} = 0.05$ m/d (very slow), $v_{s-s} = 0.1$ m/d (slow), $v_{s-m} = 0.5$ m/d (medium), $v_{s-f} = 1$ m/d (fast). ^d Subscript L indicates the design alternative is designed for lower conductivity aquitards with hydraulic conductivity of 1×10^{-8} m/s. ^e LX indicates that all the bottom liner design alternatives (L1, L2, L3, L4, L5, L6) are appropriate.

4.5. Landfill Design Case Studies using LFDSS

To demonstrate the use and capabilities of the developed decision support system, a real (Siirt) and a generic (hypothetical) landfill case were designed using LFDSS software.

4.5.1. Siirt Municipal Solid Waste Landfill Design

Siirt Municipal Solid Waste Landfill project was adjudicated by Directorate of Regional Development Administration of Southeastern Anatolia Project to DOLSAR Engineering Company. All the information used for the case study presented herein is gathered from the project reports prepared by DOLSAR Engineering Company.

4.5.1.1. General Site Information

Siirt is located between 37°55' northern latitude and 41°57' eastern longitude. It is surrounded by the provinces of Şırnak, Van, Batman, Bitlis and Mardin (Figure 4.9). The population of Siirt according to 2000 census is 98281.

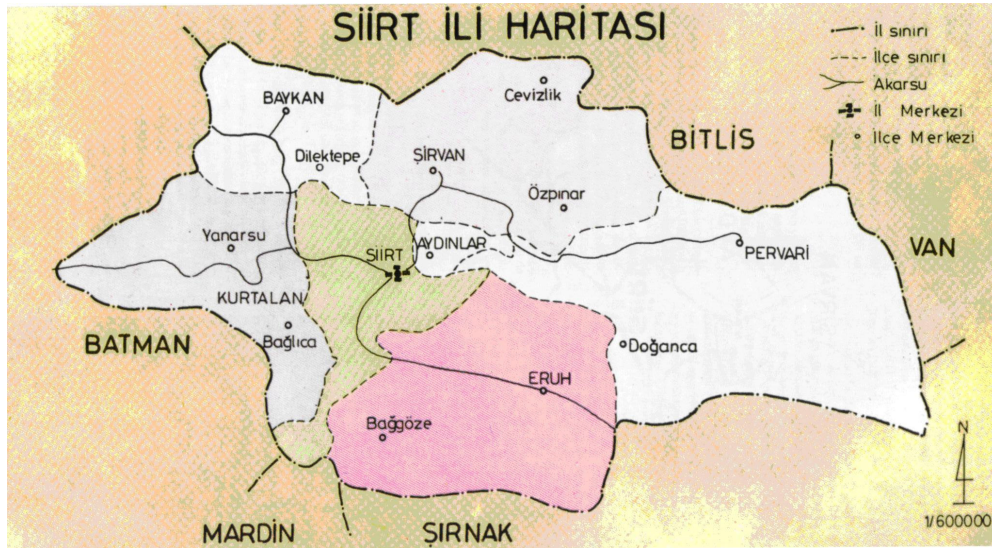


Figure 4. 9 City map for Siirt

Terrestrial climate conditions prevail for the city. Severe winter conditions with snow and arid summer conditions are observed. High evaporation occurs during

summer periods. Climatic data of the city are simulated using Visual HELP 2.2.03 and average precipitation data for 20 years are obtained as 395 mm/y.

Investigated site is located in the 1st degree seismic zone, and the average seismic coefficient is given as 0.4. Elevation of Siirt at the city center is 930 m, and it is surrounded by high mountains. Hydrogeologic data are collected using bore holes drilled by the State Hydraulic Works (DSI). According to the bore logs, the investigation site is composed of impermeable chalk-limestones, having a few fractures. The groundwater table is located far below the ground surface. Information obtained from the bore hole logs are presented in Table 4.19. Location of the bore holes are shown by red circles in topographic map of the site presented in Figure 4.10.

Table 4. 19 Bore hole data for the investigation site

WELL NO.	Thickness of Formation (m)	Type of Formation
1	0.5	Vegetative soil
	11.0	Gravel-silty clay
	8.5	Clayey limestone
2	0.5	Vegetative soil
	11.3	Gravel-silty clay
	8.2	Clayey limestone
3	0.5	Vegetative soil
	11.7	Gravel-silty clay
	7.8	Clayey limestone
4	0.5	Vegetative soil
	5.5	Gravel-silty clay
	14.0	Clayey limestone
5	0.5	Vegetative soil
	6.0	Gravel-silty clay
	13.5	Clayey limestone

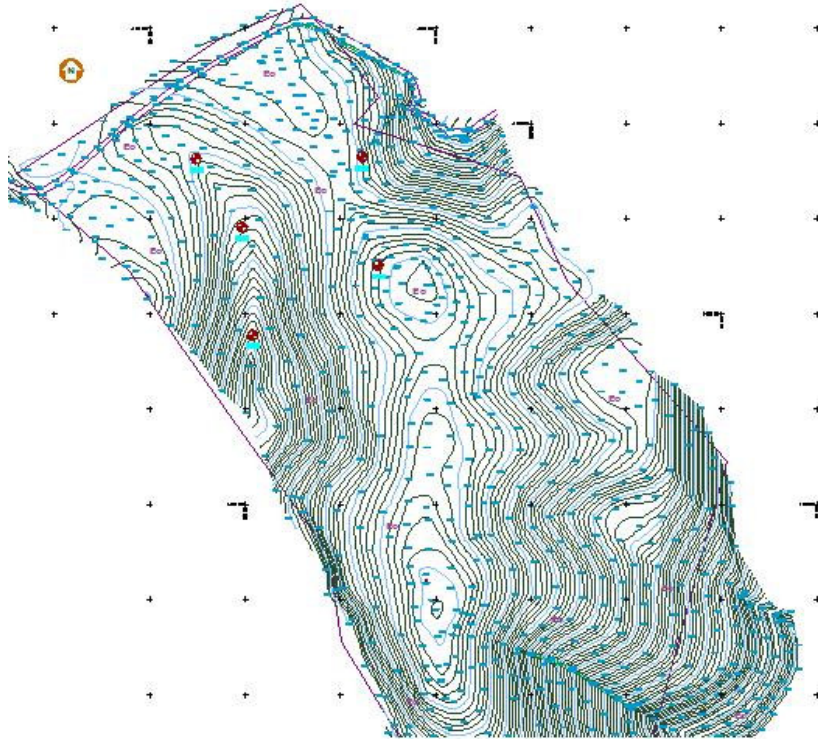


Figure 4. 10 Topographic map of Siirt landfill site and location of the bore wells in the investigation area

The city produces 86720 kg/day of waste, corresponding to a waste production rate of 0.77 kg/cap/day (according to the projected year 2005 population of 113403). The location of the proposed solid waste disposal facility is given in Figure 4.11. The proposed site is located at the east of the city, 4 km away from the city centre. The nearest residential area is 1.5 km away from the site.

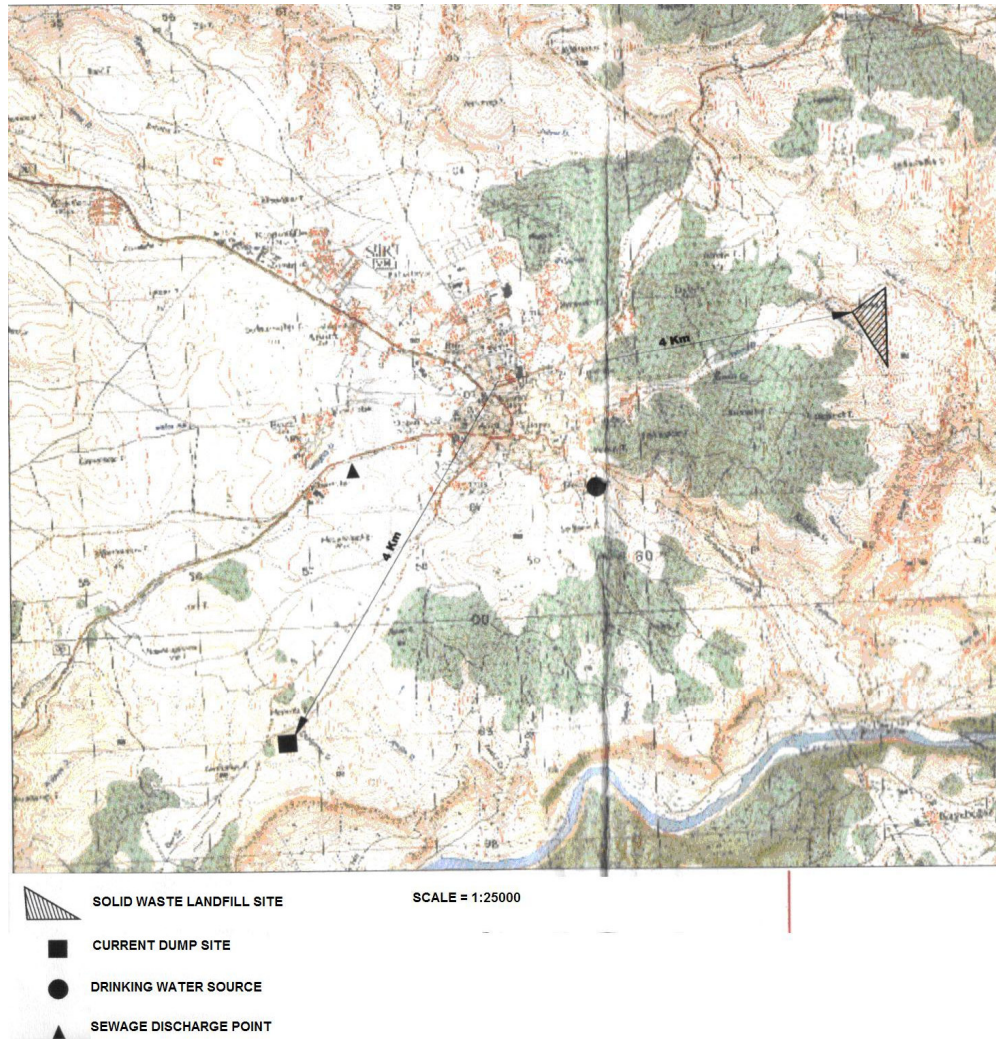


Figure 4. 11 Infrastructure Plan for City of Siirt

The proposed municipal solid waste landfill is planned to be constructed in two stages. The first stage is planned to serve between 2009 and 2020, and the second stage between 2021 and 2035. The waste production rates for first and second stages are projected to be 0.83 kg/cap/day and 0.95 kg/cap/day, respectively. The projected population for years 2009, 2020, and 2035 are 127372, 175311, and 271015, respectively. The volumes of the first and second stage landfills are given as 685014 m³, and 1453735 m³, respectively (accepting a density of well compacted waste at landfill); leading to a total landfill volume of 2138749 m³.

According to the solid waste composition analysis 23% of the waste is recyclable, 58.5% is organic, and 19% is other type of wastes.

For the case presented here, the first stage involving years 2009-2020 was modeled using LFDSS.

4.5.1.2. Volume Calculations in LFDSS

The volume calculation module (VCM) in LFDSS can be a useful tool for the situations where waste amount and volume data are not available to the user by the feasibility reports. For the case studied here, the waste production and landfill volume calculations were available; however, the module was still used in order to check the accuracy of the results. The input data used for the VCM are given in Table 4.20. The module calculated a waste volume of 661500 m³, which is in 10% range of the volume (685014 m³) given in the feasibility report.

Table 4. 20 Input parameters for volume calculation module

Design population	127372 (2009)
Operational lifetime of landfill (y)	12 (2009 – 2020)
Waste production rate (kg/cap/day)	0.83
Waste density (kg/m ³)	700 ^a

^a Accepted for the waste well compacted in the landfill.

4.5.1.3. *Base Grade Design of the Landfill at the Proposed Site*

Base grade design of the landfill at the selected site is a complex process involving the consideration of many factors such as site topography, available in situ clay thickness, groundwater flow direction and depth to water table, etc. Using the site specific hydrogeologic and geotechnical data as input, Virtual Landfill Model (VLF) embedded in LFDSS is capable of demonstrating the distribution of the available in situ clay layers and their thicknesses, groundwater depth and flow direction, and topographic features of site. VLF is capable of calculating base and surface area of landfill, excavation and fill volumes, surface volume after the final cover is placed, and available clay volume beneath the landfill after excavation, by superimposing the original and desired final topographic surfaces. Therefore, VLF was used in this case study to effectively locate and accomplish the base grade design of the first stage of Siirt Municipal Solid Waste Landfill.

VLF requires base, clay and groundwater DEMs (digital elevation model) to perform calculations. Therefore, first, elevation data of the site, obtained from the digital maps presented in the feasibility reports were converted to ASCII DEM files to obtain Base-DEM. As the digital maps were drawn using AutoCAD software, they were re-evaluated using ArcGIS software, and elevation data were created accepting a grid size of 5.3 m. As a second step, in situ clay thicknesses obtained from bore holes of geotechnical investigation were examined to create in situ Clay layer-DEM. As no groundwater was reported, Groundwater-DEM was not created. DEM files are presented in Appendix-F.

Once the Base-DEM and Clay-DEM were imported to the VLF model, the topographic features of the site and clay layers were visible (Figure 4.12). The distribution of in situ clay layers was indicated with pink color, where darker pink shades indicate clay layer thickness around 10 m, and lighter shades indicate clay

layer thickness around 5 m. Observing the clayey zones, the most suitable location to design the landfill base grade was decided to be approximately within the area shown by the yellow circle in Figure 4.12.

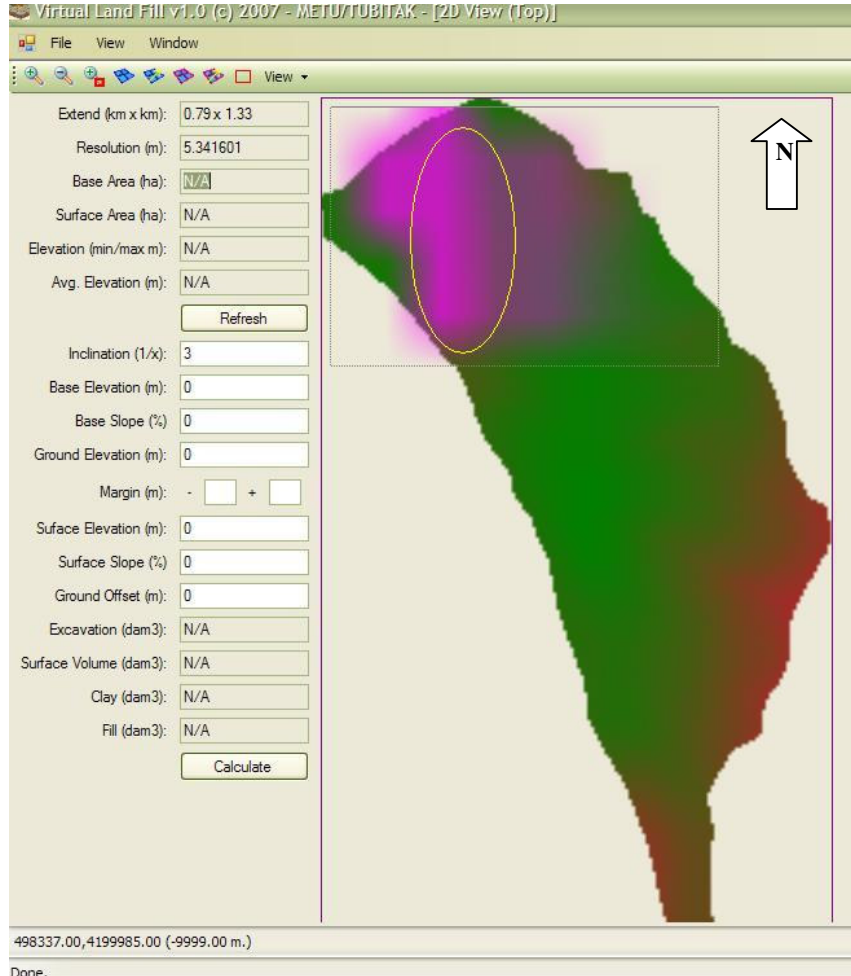


Figure 4. 12 Presentation of topography and clay layers for Siirt landfill in VLF.

Before drawing the landfill base on the natural topography, performing some simple hand calculations were required. For the case examined here, an average waste thickness of 20 m was accepted for the landfill volume of 685014 m³. Therefore, the base area of the landfill was calculated as:

$$A = \frac{V}{t_w} \frac{685014m^3}{20m} = 34250.7m^2 \cong 3.4ha \quad (4.1)$$

The base length and width of the landfill was selected as 340 m, and 100 m, respectively. The length of the landfill was located from north to south for the best use of the available in situ clay layer thickness. The landfill was drawn on the existing natural topography, and original ground elevations of the corners of landfill were obtained from VLF. Once the base length was determined, the excavation depth, side slopes, and ground elevation could be calculated based on the longer side of the landfill. To preserve some of the clay available on site for the base of the landfill, excavation depth was limited to 5 m. Taking 1v:3h side slopes, and 1% base slope, the base elevation was calculated as 954.4 m, and ground elevation was calculated as 960 m. An above-ground waste thickness of 15 m was considered to reach a total waste thickness of 20 m. Therefore the surface elevation was calculated as 975 m. The maximum slope of the final cover was selected as 5%. The base slope and cover slope directions were indicated with red and yellow arrows, respectively (Figure 4.13). Entering the calculated inclination, base slope, base and ground elevation, surface elevation, surface slope, and ground offset value (i.e. an approximate thickness of final cover), the VLF model calculated the excavation (408860 m³), fill (7570 m³), and surface volumes (255510 m³), as well as the available clay volume (115610 m³) beneath the landfill area (Figure 4.13). The total volume of landfill can then be calculated as 656800 m³, which is acceptable as it lies within the 10% range of the volume calculated (685014 m³) in the feasibility report (Eq. 4.2):

$$\begin{aligned} V_{total} &= V_{excavation} - V_{fill} + V_{surface} = 408.86dam^3 - 7.57dam^3 + 255.51dam^3 \\ V_{total} &= 656.80dam^3 = 656800m^3 \end{aligned} \quad (4.2)$$

After the excavation, VLF calculated that 115.61 dam³ (115610 m³) clay was still available at the base of the landfill.

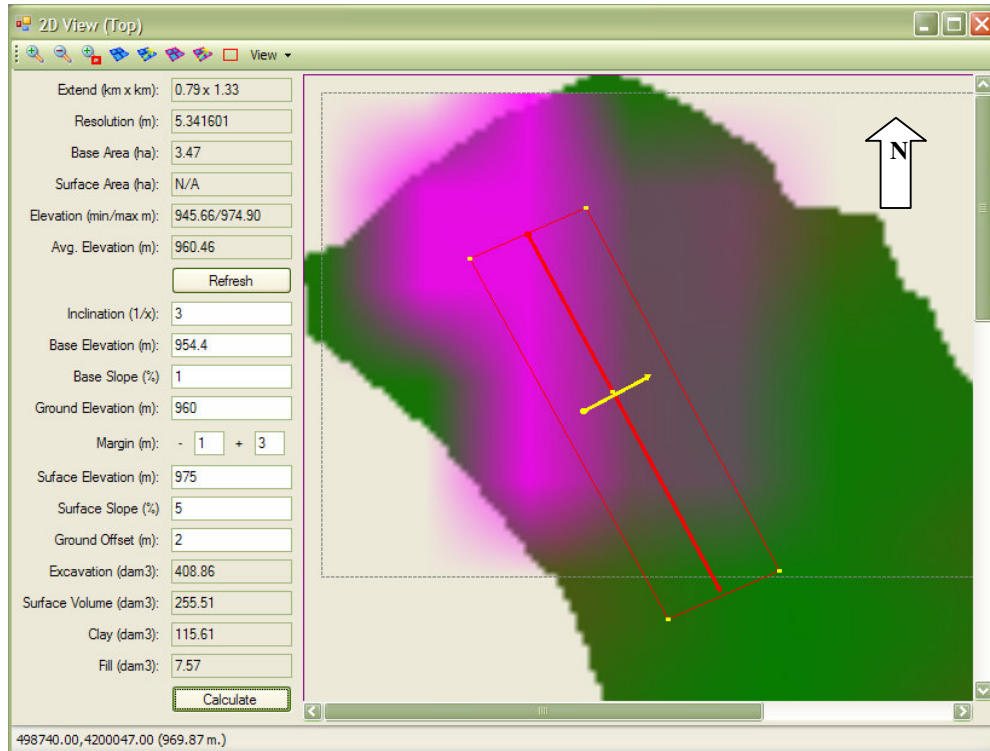


Figure 4. 13 Input data for VLF model and volume calculations

Once the “calculate” button was hit, VLF demonstrated the excavated and filled areas (Figure 4.14), the surface cover (Figure 4.15), and the available clay layers (Figure 4.16) in the 2D window. The landfill with or without final cover was presented by 3D window (Figure 4.17). As can be seen from Figure 4.17, the base grade design of the landfill is also visually found suitable considering the original site topography.

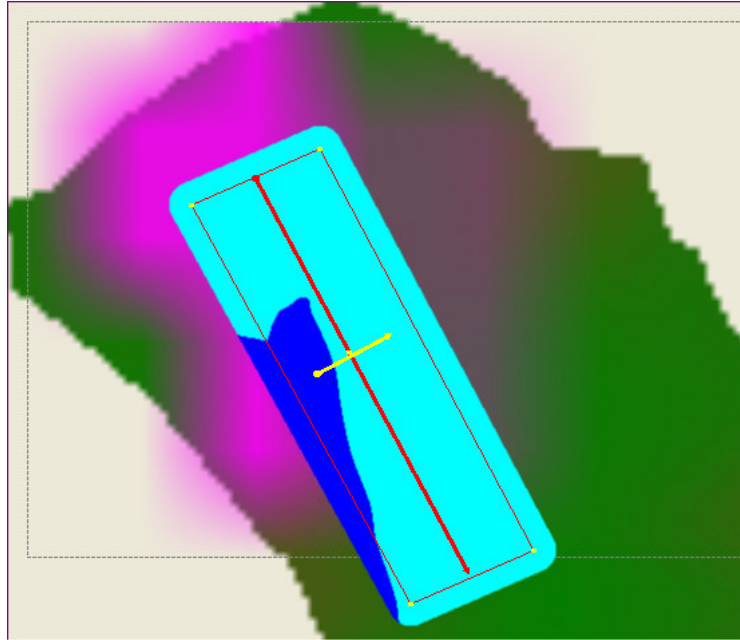


Figure 4. 14 Landfill excavation and fill areas by VLF –excavation areas are shown with light blue, and fill areas are shown with dark blue.

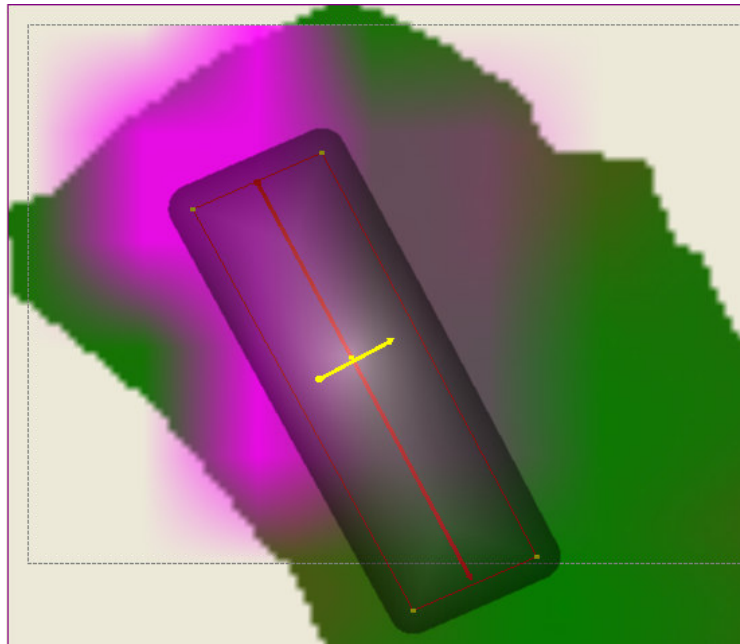


Figure 4. 15 Surface fill by VLF –lighter shades indicate higher elevations on the final cover.



Figure 4. 16 Demonstration of availability of clay layers at the base of the landfill by VLF –green color (within the landfill borders) indicates the presence of the clay layer, whereas red color indicates the absence of clay layer after excavation.

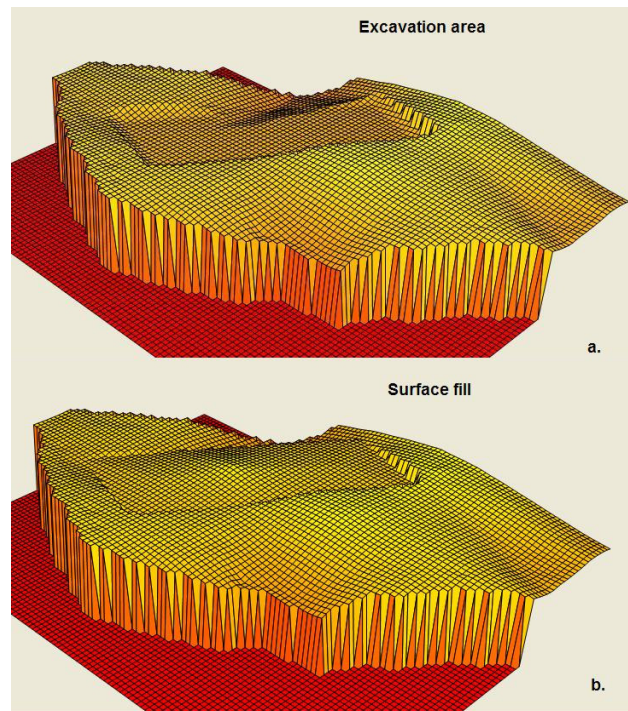


Figure 4. 17 3D demonstration of landfill (a) without and (b) with final cover by VLF

4.5.1.4. *Preliminary Design*

After the landfill base contour design was accomplished in the natural topography and volume calculations were performed by VLF, preliminary design phase in LFDSS can be implemented. The aim of the preliminary design phase is to propose alternatives for landfill design components and their design details considering general design variables (i.e. climate –total annual precipitation amount, waste load –landfill area, waste thickness, and site hydrogeology – groundwater seepage velocity, hydraulic conductivity, porosity and thickness of vadose zone). The waste thickness was taken as 20 m, size (the base area of the landfill) was calculated as 3.4 ha, and annual precipitation was given by Visual HELP 2.2.0.3 weather simulator for Siirt as 395 mm/y. As the site hydrogeology reveals the absence of significant groundwater resources, there would not be any groundwater contamination concern at the site. As the site lies in the arid climate range, has a small landfill base area, and groundwater contamination is of no concern, the flexibility and choices of the landfill design increases. This fact was also reflected in the results of the preliminary design module. Entering the design parameters, the preliminary design module proposed that all 18 landfill design alternatives (i.e. C1L1, C1L2, C1L3, C1L4, C1L5, C1L6, C2L1, C2L2, C2L3, C2L4, C2L5, C2L6, C3L1, C3L2, C3L4, C3L5, and C3L6) are appropriate for the given conditions; however, also states that most of these can lead to over designs for arid climates. As the results in Section 4.3.3 and Section 4.3.4.1 demonstrate, leachate collection systems in the bottom liners are not effective under arid climates. Therefore, LFDSS proposes that final cover designs with some level of intensive engineering coupled with simple bottom liner designs (i.e. C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) is satisfactory under given site conditions. The components of the final covers and bottom liners of design alternatives are listed in Table 4.21.

Table 4. 21 Components of final covers and bottom liners of design alternatives proposed by preliminary design module in LFDSS

Final Cover	Design Components
C1	Natural soil
C2	Natural soil +CDS ^a + geomembrane + clay liner
C3	Natural soil + CDS + clay liner
Bottom Liner	Design Components
L1	Only aquitard below waste
L6	CCL ^b + aquitard/unsaturated zone

^a cover drainage system ^b compacted clay liner

As there is no groundwater, the contamination performance criterion for the designs is not applicable. Therefore, compliance of the proposed alternatives with the stability performance criterion (i.e. the leachate head over bottom liner should be less than 1 m, and factor of safety values) should be taken into account in the site specific final design phase.

4.5.1.5. Infiltration Rate Calculations and Final Cover Performance Evaluation

To calculate the infiltration rate that the waste in landfill receives, HELP model in LFDSS was used. All of the proposed final covers (evapotranspiration final cover –C1, extensive engineering final cover -C2, and intermediate design final cover -C3) were simulated using HELP model. Before the simulation, HELP requires site specific weather data to be loaded. Therefore, files for evapotranspiration, precipitation, temperature, and solar radiation were obtained from the weather simulator of Visual HELP 2.2.0.3 in the format of ASC files, and imported to the HELP model in LFDSS. After the weather conditions were specified, soil and design data for C1, C2 and C3 were entered in the Soil&Design tab under the HELP model in LFDSS. Evapotranspiration final cover –C1 is composed of only natural topsoil above waste. Extensive engineering final cover –C2 is composed

of topsoil, cover drainage system, geomembrane, and clay liner. Intermediate design final cover –C3 is composed of topsoil, cover drainage system, clay liner. The design specifications of the layers were listed in Table 4.22.

Table 4. 22 Layer specifications used in cover designs in HELP model (soil values are obtained from HELP database)

Design Parameters	Topsoil	CDS^a	Clay Liner	Geomembrane
Thickness (m)	0.6	0.3	0.6	0.001
Soil texture	Fine sandy loam	Coarse sand	Silty clay	LDPE ^b
Total porosity	0.473	0.417	0.479	-
Field capacity	0.222	0.045	0.371	-
Wilting point	0.104	0.018	0.251	-
K _{sat} ^c (cm/s)	0.00052	0.01	0.00001	4x10 ⁻¹³
Drainage length (m)	-	30	-	-
Drain slope (%)	-	2	-	-
GM ^b pinhole density (#/ha)	-	-	-	2
GM installation defects (#/ha)	-	-	-	4
GM placement quality	-	-	-	Poor

^a cover drainage system ^b low density polyethylene

^c saturated hydraulic conductivity ^d geomembrane

The module was run from the Run tab under HELP model in LFDSS for 12 years (operational lifetime of first stage for years 2009 – 2020) for each of the cover design options. The infiltration rates were calculated by HELP model as 0.1580 m/y for evapotranspiration cover (C1), 0.0105 m/y for extensive engineering final

cover (C2), and as 0.1510 m/y for intermediate design final cover -C3. Lower infiltration rate from extensive engineering final cover (C2) option occurred due to the presence of geomembrane (LDPE –low density polyethylene). The infiltration rates were automatically transferred to POLLUTE model by LFDSS, and the simulations were continued with stability performance criterion calculations.

4.5.1.6. Landfill Stability Evaluation and Soil Contaminant Concentrations

As there is no groundwater beneath the landfill, POLLUTE model was run to calculate leachate head over landfill bottom liner in order to evaluate whether the proposed design alternative complies with the stability criterion (i.e. leachate head over bottom liner should be less than 1 m) for site specific conditions. Simulations were performed for the proposed design alternatives (i.e. C1L1, C1L6, C2L1, C2L6, C3L1, and C3L6). The design specifications of the designs are given in Table 4.23. Therefore, the necessity of including a leachate collection system in the bottom liner under the given site conditions would be investigated.

Table 4. 23 Final cover and bottom liner specifications of the investigated design alternatives

Design Alternative	Final Cover	Bottom Liner
C1L1	0.6 m of natural topsoil	Natural aquitard below waste
C1L6	0.6 m of natural topsoil	0.6 m CCL + natural aquitard
C2L1	0.6 m of natural topsoil + 0.3 m CDS ^a + geomembrane + 0.6 m CCL ^b	Natural aquitard below waste
C2L6	0.6 m of natural topsoil + 0.3 m CDS ^a + geomembrane + 0.6 m CCL ^b	0.6 m CCL + natural aquitard
C3L1	0.6 m of natural topsoil + 0.3 m CDS ^a + 0.6 m CCL ^b	Natural aquitard below waste
C3L6	0.6 m of natural topsoil + 0.3 m CDS ^a + 0.6 m CCL ^b	0.6 m CCL + natural aquitard

^a cover drainage system^b compacted clay liner

The site is composed of low permeability clayey-silty formations; therefore, a hydraulic conductivity value of 1×10^{-8} m/s with a porosity of 0.38 was accepted as vadose zone (aquitard) parameters. The input parameters used for POLLUTE simulations are summarized in Table 4.24.

Table 4. 24 Input parameters used for POLLUTE simulations

Section	Parameter	Value
Source	Infiltration (m/y) ^a	0.1580 for C1 final cover
		0.0105 for C2 final cover
		0.1510 for C3 final cover
Outflow	Leachate head (m) ^b	
Clay Liner	Thickness (m)	0.6
	Hydraulic conductivity (m/s)	1x10 ⁻⁹
	Porosity	0.40
Vadose	Thickness (m)	10
Zone/Aquitard	Hydraulic conductivity (m/s)	1x10 ⁻⁸ m/s
	Porosity	0.38

^a automatically calculated and transferred as a result of HELP runs

^b calculated by POLLUTE model, and reported at the end of the simulation to check whether the design satisfies stability criterion (i.e. leachate head should be below 1 m.)

All of the simulations demonstrated that leachate head did not develop over bottom liner –or within waste. As the leachate is not removed, most of the contaminant mass (86 – 95%) passed to the ground below the landfill.

4.5.1.7. Structural Stability Calculations

Although most of the geotechnical parameters were not given in the feasibility report by DOLSAR Engineering Company, illustrative stability analyses were performed using literature values (Sharma and Lewis, 1994) for the types of the soils, final cover, and bottom liner systems examined in the above sections. The stability analyses were performed using the *stability module* in LFDSS. It should be noted that, excavation slope and refuse fill stability analyses were carried out for a *single trial failure surface*. Analyses of a representative number of failure surfaces should be performed in order to decide on the stability of the excavation and the refuse. Types of analyses carried out for each of the simulated design

alternatives are given in Table 4.25. Parameters used in the structural stability analyses are presented in Table 2.26.

Table 4. 25 Stability analyses for the investigated design alternatives

Design Alternative	Final Cover	Bottom Liner
C1L1	Cover system stability for cohesionless soils with seepage	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface
C1L6	Cover system stability for cohesionless soils with seepage	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface
C2L1	Cover system stability –with geomembrane Stability under seismic forces	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface
C2L6	Cover system stability –with geomembrane Stability under seismic forces	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface
C3L1	Cover system stability for cohesive soils	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface
C3L6	Cover system stability for cohesive soils	Excavation slope stability –circular slip surface Refuse-fill stability – circular slip surface

Table 4. 26 Parameters used in stability module for factor of safety calculations

Parameter	Final Cover		Bottom Liner			
	Cohesionless	Cohesive	With GM ^b	Seismic forces	Excavation slope ^g	Refuse fill ^g
Cohesion (kN/m ²)	-	-	0	0	61 ^e	19
Friction angle (°)	-	-	30	30	5.5 ^e	20
Effective friction angle (°)	30	15	-	-	-	-
Slope angle (°)	2.87 (5%) ^f	2.87 ^f	-	-	-	-
γ^a _{bouyant-soil} (kN/m ³)	9.1	9.1	-	-	-	-
γ _{total-soil} (kN/m ³)	18.9	18.9	-	-	-	-
γ _{cover-soil} (kN/m ³)	-	-	18.5	18.5	-	-
Thickness of cover soil (m)	-	-	1.5 ^f	1.5 ^f	-	-
Slope length along GM (m)	-	-	202 ^f	202 ^f	-	-
Slope angle beneath GM (°)	-	-	2.87 ^f	2.87 ^f	-	-
ϕ^c _{cover soil-GM} (°)	-	-	22	22	-	-
Average seismic coefficient	-	-	-	0.40 ^e	-	-
Effective cohesion (kN/m ²)	-	4.8	-	-	-	-
H ^d (m)	-	15 ^f	-	-	-	-
Clay liner thickness (m)	-	0.6 ^f	-	-	-	-
γ _{water} (kN/m ³)	9.8	9.8	-	-	-	-

^a unit weight ^b geomembrane ^c internal angle of friction ^d height of slope ^e provided by
DOLSAR Engineering Company ^f design condition ^g single trial failure surface

Stability analyses for the designs without geomembrane liners in the final cover (C1L1, C1L6, C3L1, and C3L6) produced stable factor of safety values, which were greater than 1.5 (Sharma and Lewis, 1994; Koerner and Daniel, 1997). Although the designs having geomembrane liners in the final cover (C2L1, and C2L6) produced a stable factor of safety value with respect to cover stability concerns involving geomembranes, factor of safety value for seismic analysis (FS = 0.94) was less than the acceptable value of 1.00 (Koerner and Daniel, 1997). Therefore, further analysis (e.g. permanent deformation analysis, Koerner and Daniel, 1997) is required for these design alternatives. Designs having clay liners in the final cover (C3L1, and C3L6) happened to be more stable than the other final cover designs due to high factor of safety values (Table 4.27).

Table 4. 27 Factor of safety values calculated by the stability module in LFDSS

Design Alternative	Factor of Safety Values		
	<i>Cover system</i>	<i>Excavation slope^b</i>	<i>Refuse fill^b</i>
C1L1	5.54	1.94	3.49
C1L6	5.54	1.94	3.49
C2L1	9.17 (with GM ^a) 0.94 (seismic forces)	1.94	3.49
C2L6	9.17 (with GM) 0.94 (seismic forces)	1.94	3.49
C3L1	66.87	1.94	3.49
C3L6	66.87	1.94	3.49

^a geomembrane ^b single trial surface

4.5.1.8. Cost Calculations of Major Design Components

Major landfill components include native soil, topsoil, clay liners, drainage system components, and geosynthetics (i.e. geomembranes). Additional components taken into consideration for Siirt Municipal Solid Waste Landfill

were geotextile filters. Major, additional, and total costs of design alternatives were calculated using cost estimation module in LFDSS. Majority of the costs is related with soil excavation, which is independent of the design alternative. VLF model of LFDSS calculated the excavation and fill volumes as 408860 m³ and 7570 m³, respectively for the landfill examined in this case. For intermediate soil covers, one to four soil-to-waste ratio is commonly used. Considering 1v:3h slopes at the sides of the landfill, the length of the landfill approximately extends to 375 m, and the width of the landfill approximately extends to 130 m at the surface (Figure 4.18).

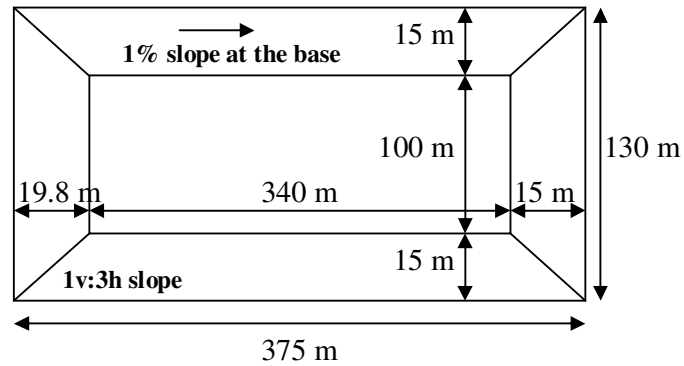


Figure 4. 18 Schematic view of the surface area of the landfill

0.6 m thick native topsoil was applied in the final cover that covers an area of approximately 5 ha (375 m x 130 m). Considering the total landfill volume of 685100 m³, soil requirement for intermediate and final covers were calculated as:

$$\text{Daily and intermediate covers} \quad V_{\text{int}} = \frac{685100m^3}{4} = 171275m^3 \quad (4.3)$$

$$\text{Final cover} \quad V_{\text{final}} = 0.6m \times 50000m^2 = 30000m^3 \quad (4.4)$$

Virtual Landfill (VLF) model demonstrated that almost half of the landfill base stayed on top of clayey zones (Figure 4.16). 0.6-m-thick clay layers would be

used for bottom liners and final covers. Amounts of clay required for bottom liner and final cover were approximately calculated as:

$$\text{Bottom clay; } V_{\text{clay}} = 0.6m \times 34000m^2 = 20400m^3 \quad (4.5)$$

$$\text{Final cover clay; } V_{\text{clay}} = 0.6m \times 50000m^2 = 30000m^3 \quad (4.6)$$

As almost half of the clay was visible at the base of the landfill, available clay volume at the base of the landfill was estimated to be 9000 m³. Therefore, the required excavation amount of clay was 11400 m³ (20400 m³ – 9000 m³) for bottom liners, and 30000 m³ for final covers; corresponding to a total of 41400 m³ (11400 m³ + 30000 m³).

Volumes of soil to be used during landfill construction, and excess amount of soil that is needed to be disposed of are given in Table 4.29.

Table 4. 28 Volumes of soil used in landfill construction

Area		Excavation	Fill	D&I ^a Covers	Final Cover	Total ^b	Excessive Soil Volume
(ha)		(m ³)	(m ³)	(m ³)	(m ³)	(m ³)	(m ³)
<i>Base</i>	<i>Cover</i>						
3.4	5.0	408860	7570	171275	30000	208845	200015

^a daily and intermediate ^b total of fill, daily and intermediate covers, and final cover

Cost analyses that were considered for design alternatives are presented in Table 4.29. Geotextiles for reinforcement were also considered as an additional cost for the designs including geomembranes.

Table 4. 29 Landfill components of the design alternatives considered for cost analyses

Design Alternative	Cost Analyses
C1L1	Native soil, topsoil
C1L6	Native soil, topsoil, clay
C2L1	Native soil, topsoil, clay, drainage, geomembrane, geotextile
C2L6	Native soil, topsoil, clay, drainage, geomembrane, geotextile
C3L1	Native soil, topsoil, clay, drainage
C3L6	Native soil, topsoil, clay, drainage

Soil amounts that were supposed to be used for the construction of various design alternatives are given in Table 4.30, and Table 4.31. Besides the aforementioned design alternatives (C1L1, C1L6, C2L1, C2L6, C3L1, and C3L6), design alternative having evapotranspiration final cover –natural topsoil over waste, with intermediate design bottom liner –leachate collection system coupled with compacted clay liner (C1L5), intermediate design final cover –natural topsoil, cover drainage system, and clay liner, with intermediate design bottom liner (C3L5), and intermediate design final cover with extensive engineering bottom liner –leachate collection system, geomembrane, and compacted clay liner (C3L2) were also included in the cost analyses in order to allow for a comparison.

Table 4. 30 Amounts of soil to be used in landfill construction

Soil Components	C1L1	C1L6	C2L1	C2L6	C3L1	C3L6
Native soil						
<i>Excavation (m³)</i>	408860	408860	408860	408860	408860	408860
<i>Loading (add 15%) (m³)</i>	230017	230017	230017	230017	230017	230017
<i>Spread native soil (m³)</i>	178845 ^a	178845 ^a	178845 ^a	178845 ^a	178845 ^a	178845 ^a
Topsoil						
<i>Spread topsoil (m³)</i>	30000 ^b	30000 ^b	30000 ^b	30000 ^b	30000 ^b	30000 ^b
<i>Compact topsoil (m³)</i>	30000	30000	30000	30000	30000	30000
Drainage						
<i>Stone (m³)</i>			15000 ^d	15000 ^d	15000 ^d	15000 ^d
<i>Spread stone (m³)</i>			15000	15000	15000	15000
Clay (Onsite/Offsite)						
<i>Clay excavation (m³)</i>		11400	30000	41400	30000	41400
<i>Spread clay (m³)</i>		11400	30000 ^e	50400 ^g	30000 ^e	50400 ^g
<i>Compact clay (m³)</i>		20400 ^c		20400		20400
Drainage tile						
<i>Pipe (m)</i>						
Synthetic membrane						
<i>60 mil HDPE (m²)</i>						
<i>40 mil PVC (m²)</i>			50000 ^f	50000 ^f		
<i>Installation (m²)</i>			50000	50000		
Geotextile filter						
<i>10 oz geotextile (m²)</i>			50000 ^f	50000 ^f		
<i>Installation (m²)</i>			50000	50000		

^a total of daily and intermediate covers and fill (171275m³ + 7570m³)

^b soil thickness x surface area (0.6m x 50000m²)

^c clay thickness x base area (0.6m x 34000m²)

^d stone layer thickness x surface area (0.3m x 50000m²)

^e clay thickness x surface area (0.6m x 50000m²)

^f surface area

^g total of surface clay and bottom liner clay (20400m³ + 30000m³)

Table 4. 31 Amounts of soil to be used in landfill construction for additional designs

Soil Components	C1L5	C3L5	C3L2
Native soil			
<i>Excavation (m³)</i>	408860	408860	408860
<i>Loading (add 15%) (m³)</i>	230017	230017	230017
<i>Spread native soil (m³)</i>	178845 ^a	178845 ^a	178845 ^a
Topsoil			
<i>Spread topsoil (m³)</i>	30000 ^b	30000 ^b	30000 ^b
<i>Compact topsoil (m³)</i>	30000	30000	30000
Drainage			
<i>Stone (m³)</i>	10200 ^c	25200 ^f	25200 ^f
<i>Spread stone (m³)</i>	10200	25200	25200
Clay (Onsite/Offsite)			
<i>Clay excavation (m³)</i>	11400	41400	41400
<i>Spread clay (m³)</i>	11400	50400 ^g	50400 ^g
<i>Compact clay (m³)</i>	20400 ^d	20400	20400
Drainage tile			
<i>Pipe (m)</i>	600 ^e	600 ^e	600 ^e
Synthetic membrane			
<i>60 mil HDPE (m²)</i>			34000 ^h
<i>40 mil PVC (m²)</i>			
<i>Installation (m²)</i>			34000
Geotextile filter			
<i>10 oz geotextile (m²)</i>			34000 ^h
<i>Installation (m²)</i>			34000

^a total of daily and intermediate covers and fill (171275m³ + 7570m³)

^b soil thickness x surface area (0.6m x 50000m²)

^c stone layer thickness x base area (0.3m x 34000m²)

^d clay thickness x base area (0.6m x 34000m²)

^e pipe installation interval is 50m; therefore, 6 pipes (340m/50m) of 100-m-long.

^f surface drainage + leachate collection system (15000m³ + 10200m³)

^g total of surface clay and bottom liner clay (20400m³ + 30000m³)

^h surface area

For Siirt, the unit costs of the major landfill components were not included in the feasibility report of DOLSAR; therefore, units costs presented in the cost estimation module were taken into consideration. The design alternatives including evapotranspiration final covers (C1) resulted in the least cost (less than 1.65 million USD), and the costs of the designs increased as the final cover specifications increased. The highest cost corresponded to the design alternative having cover drainage system, geomembrane liner, and clay liner in the final cover, and compacted clay liner in the bottom liner (C2L6). The cost of this alternative reached almost 2.2 million USD (Table 4.32).

When the additional designs (C1L5, C3L5, and C3L2) were investigated, the most compatible design with respect to financial aspects was determined to be the design with evapotranspiration final cover, and having leachate collection system and compacted clay liner in the bottom liner (C1L5). The cost of this design was around 1.6 million USD. The costs of other more sophisticated designs, having cover drainage, clay liners, leachate collection system, compacted clay liner (C3L5), and geomembrane (for C3L2), reached almost 2.3 million USD (Table 4.32). As there is no groundwater and no contamination concern beneath the landfill, increasing the specifications of the landfill design would not be necessary. Therefore, design alternatives having evapotranspiration covers (C1L1, C1L6, and C1L5) are feasible for the site under investigation. However, the results of stability calculations should be consulted for the final decision.

Table 4. 32 Major, additional and total costs of design alternatives

Design Alternative	Major Costs (USD)	Additional Costs^a (USD)	Total Cost (USD)
C1L1	1365913	-	1365913
C1L6	1513969	-	1513969
C2L1	1942563	43500	1986063
C2L6	2106819	43500	2150319
C3L1	1802563	-	1802563
C3L6	1966819	-	1966819
C1L5	1639681	-	1639681
C3L5	2092531	-	2092531
C3L2	2235331	29580	2264911

^a includes cost of geotextiles

4.5.1.9. Presentation of the Assessments and Decision Making

After all the modules in LFDSS were run for each of the design alternative under investigation (C1L1, C1L6, C2L1, C2L6, C3L1, and C3L6), the results produced by each model and module (i.e. Preliminary design module, POLLUTE model, stability module, and cost estimation module) were saved by the LFDSS in the performance report (Appendix-G). The saved file was imported to MS Excel results template provided with the software to compare the performances of the simulated design alternatives and ease the decision making process. The overall results of the simulations are presented in Table 4.33. Leachate head values were not included in results table (Table 4.33), as simulations are not performed for the designs that do not comply with the stability criterion (i.e. leachate head should be less than 1 m).

Table 4. 33 Overall results of the landfill design simulations by LFDSS

Design	Performance		Stability		Cost (USD)		
	Cl_{max}^a (mg/L)	T_{max}^b (yr)	FS values		Main Cost	Additional Cost	Total Cost
C1L1	478.5	31	Excavation slope	1.94	1365913	-	1365913
			Refuse-fill	3.49			
			Cover system	5.54			
			Geomembrane	-			
			Seismic	-			
C1L6	477.8	32	Excavation slope	1.94	1513969	-	1513969
			Refuse-fill	3.49			
			Cover system	5.54			
			Geomembrane	-			
			Seismic	-			
C2L1	430.1	594	Excavation slope	1.94	1942563	43500	1986063
			Refuse-fill	3.49			
			Cover system	9.17			
			Geomembrane	-			
			Seismic	0.93			
C2L6	428.9	642	Excavation slope	1.94	2106819	43500	2150319
			Refuse-fill	3.49			
			Cover system	9.17			
			Geomembrane	-			
			Seismic	0.93			
C3L1	473.1	32	Excavation slope	1.94	1802563	-	1802563
			Refuse-fill	3.49			
			Cover system	66.87			
			Geomembrane	-			
			Seismic	-			
C3L6	472.1	34	Excavation slope	1.94	1966819	-	1966819
			Refuse-fill	3.49			
			Cover system	66.87			
			Geomembrane	-			
			Seismic	-			

^a maximum soil chloride concentration

^b time that maximum concentration was observed

Absence of groundwater eliminated the necessity to evaluate contamination performance of the design alternatives. Stability analyses demonstrated that all of the investigated design alternatives produced stable factor of safety values with respect to slope stability. However, designs having geomembranes in the final cover (C2L1, and C2L6) failed to satisfy the safe factor of safety value (i.e. 1.00) for seismic stability. Moreover, the costs of the designs including geomembranes are much higher than the other investigated designs, and there was no contamination concern for the site. Therefore, design alternatives having geomembranes (C2L1, and C2L6) were excluded from the list of design alternatives.

Considering the flexibility of site requirements, design alternatives having evapotranspiration covers and either a natural aquitard or compacted clay liner below waste (C1L1, or C1L6) would be adequate for Siirt case. Design alternatives having intermediate design final covers composed of natural topsoil, cover drainage system, and clay liner –C3 (i.e. C3L1, and C3L6) may also be considered if higher stability for the cover is required. The decision of alternatives with evapotranspiration final cover –C1 (C1L1, C1L5, and C1L6) and intermediate design final cover –C3 (C3L1, and C3L6) was also found appropriate due to their low cost requirements.

4.5.2. Designing a Municipal Solid Waste Landfill for a Hypothetical Site

A hypothetical municipal solid waste landfill was designed in order to demonstrate the possible design applications that may be achieved using LFDSS. Maps belonging to the previous case study (Section 4.5.1) were used, as topographic and bore hole data were available. A hypothetical groundwater layer was created in order to demonstrate design situations involving groundwater. Site information of Siirt on geography and demography were used, as these data were

already available. A humid climate was selected for the hypothetical case from HELP database. All other relevant design data were arranged hypothetically. The site was referred to as X-city.

4.5.2.1. *General Site Information*

X-city resides at a northern latitude of $36^{\circ}12'$, and eastern longitude of $40^{\circ}55'$. The highest point above sea level is 1000 m, and the lowest point stays at 800 m. X-city has a humid subtropical climate, where the summers are hot and humid, and winters are chilly. Average annual precipitation reaches 1222 mm, winter and spring being the wettest seasons. According to 2000 census, the population of the city is 98281.

The city produces 170105 kg/d of waste, corresponding to a waste production rate of 1.04 kg/cap/d (according to the year 2005 projected population of 113403). 28-30% of the waste is recycled in the city.

Hydrogeologic data were adapted using bore hole data of Siirt Municipal Solid Waste Landfill. According to the adapted bore logs, the investigation site is composed of permeable chalk-limestones, demonstrating aquifer properties. The site under investigation is far from the fault lines; therefore, it is considered to be safe with respect to seismicity. The aquifer is located between 6 – 12 m below ground, and the potentiometric surface is 1 m above the top of the aquifer. The groundwater flows from south-east to north-west. Groundwater flow velocity is estimated to be in the range of 0.1 – 0.8 m/d. Information obtained from the bore holes are presented in Table 4.34. Location of the bore wells are shown by red circles in Figure 4.19.

Table 4. 34 Bore well data for the investigation site

WELL NO.	Thickness of Formation (m)	Type of Formation
1	0.5	Vegetative soil
	11.0	Gravel-silty clay
	8.5	Chalk-limestone
2	0.5	Vegetative soil
	11.3	Gravel-silty clay
	8.2	Chalk-limestone
3	0.5	Vegetative soil
	11.7	Gravel-silty clay
	7.8	Chalk-limestone
4	0.5	Vegetative soil
	5.5	Gravel-silty clay
	14.0	Chalk-limestone
5	0.5	Vegetative soil
	6.0	Gravel-silty clay
	13.5	Chalk-limestone

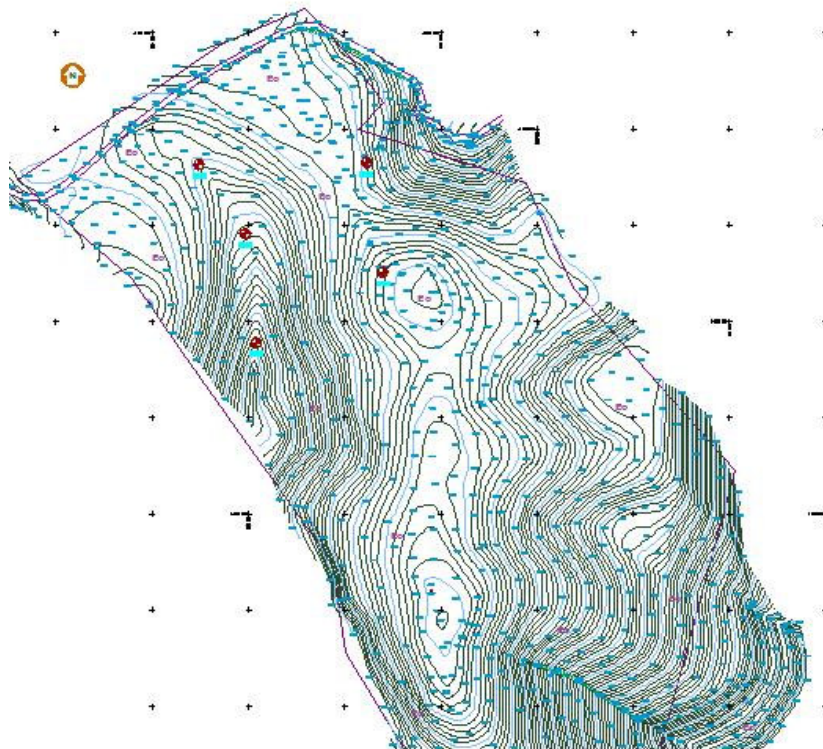


Figure 4. 19 Location of the bore wells in the investigation area

A municipal solid waste landfill to meet the solid waste disposal requirements of the city for 20 years is planned to be constructed in two stages in the investigated area. First stage will operate during 2010 – 2019, and the second stage during 2020 – 2029. Estimated waste production rate for both stages is 1.04 kg/cap/day. The projected populations for years 2010, 2020, and 2025 are 127371, 175311, and 271015, respectively. In this case study, the first stage of the landfill (2010 – 2019) was modeled and designed.

4.5.2.2. Volume Calculations in LFDSS

To calculate the volume requirement for the first stage of the X-city landfill, design population was accepted as the population for year 2010 (127371). Operational lifetime of landfill for the first stage was 10 years (2010 – 2019). The density of waste was taken as 600 kg/m³, which stands in the range accepted for waste well compacted in landfill (İller Bankası, 2000). The input data used for volume calculations are presented in Table 4.35.

Table 4. 35 Input parameters for volume calculation module

Design population	127371 (2010)
Operational lifetime of landfill (y)	10 (2010 – 2029)
Waste production rate (kg/cap/day)	1.04
Waste density (kg/m ³)	600 ^a

^a Accepted for the waste well compacted in the landfill.

The module calculated a waste volume of 805834 m³. As 28-30% of the wastes in the city are recycled, the required landfill volume reduced to 564084 m³ (Eq. 4.7).

$$V_{LF} = 805834 - 805834 \times 0.3 = 564083.8m^3 \quad (4.7)$$

Including the daily and intermediate covers, which covers one-fourth of the overall landfill volume, the total landfill volume requirement was calculated as 705105 m³ (Eq. 4.8).

$$V_{TOTAL} = 564083.8 + \frac{564083.8}{4} = 705104.8m^3 \quad (4.8)$$

4.5.2.3. *Base Grade Design of the Landfill at the Proposed Site*

To locate the landfill fulfilling the volume requirements to the given site, topographic conditions, available clay layer thickness, groundwater flow direction, and depth to groundwater were taken into consideration. Virtual Landfill Model was run from the LFDSS to locate the landfill and to perform volume calculations. Base-DEM (digital elevation model), Clay-DEM, and Groundwater-DEM were created and imported to VLF model, as described in Section 4.5.1.3. There are two Groundwater-DEM files, one is used for assigning groundwater direction, and the other is used for assigning depth of potentiometric surface. DEM files are presented in Appendix-F.

Once all the DEM files were imported to VLF model, the topographic features of the site, clay layer, and groundwater flow direction and depth were visible (Figure 4.20). Clay layers were indicated with orange color, and darker zones indicated a clay layer thickness around 11 m, whereas lighter zones indicated clay layer thickness around 5 m. Purple arrows indicated groundwater direction. Darker purple color indicated a groundwater depth of maximum 12 m, whereas lighter purple colors indicated a groundwater depth of minimum 3 m. Observing the clayey zones and zones with deeper aquifer, the most suitable location for landfill was found to be the one shown with yellow circle (Figure 4.20).

Considering an average waste thickness of 20 m, the landfill base area was calculated as 3.5 ha (Eq. 4.9).

$$A = \frac{V}{t_w} = \frac{705105m^3}{20m} = 35255.2m^2 \cong 3.5ha \quad (4.9)$$

The base length and width of the landfill was selected as 350 m, and 100 m, respectively. Two orientations were considered to demonstrate the best available use of in situ clay layer, and importance of presence of groundwater. In the first orientation, the longer side of the landfill was placed in the direction of groundwater flow (Figure 4.21.a), and in the second orientation, the longer side of the landfill was placed perpendicular to the groundwater flow direction (Figure 4.21.b).

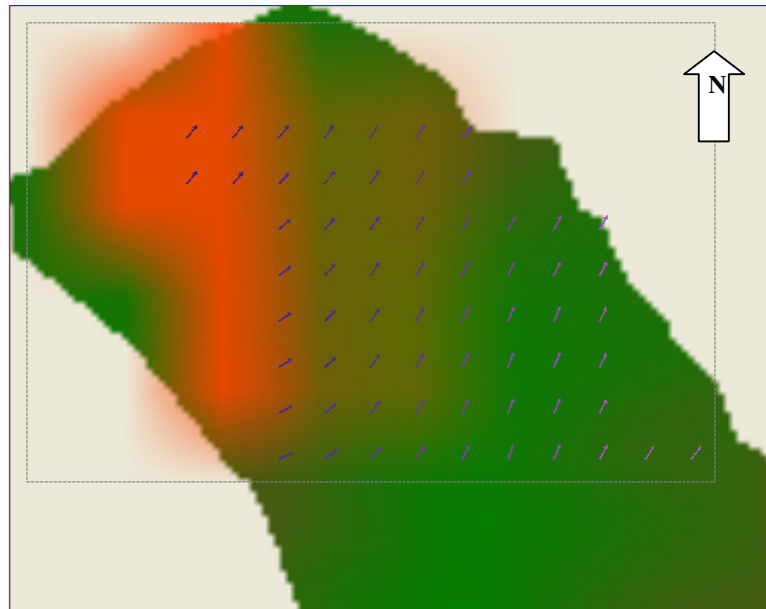
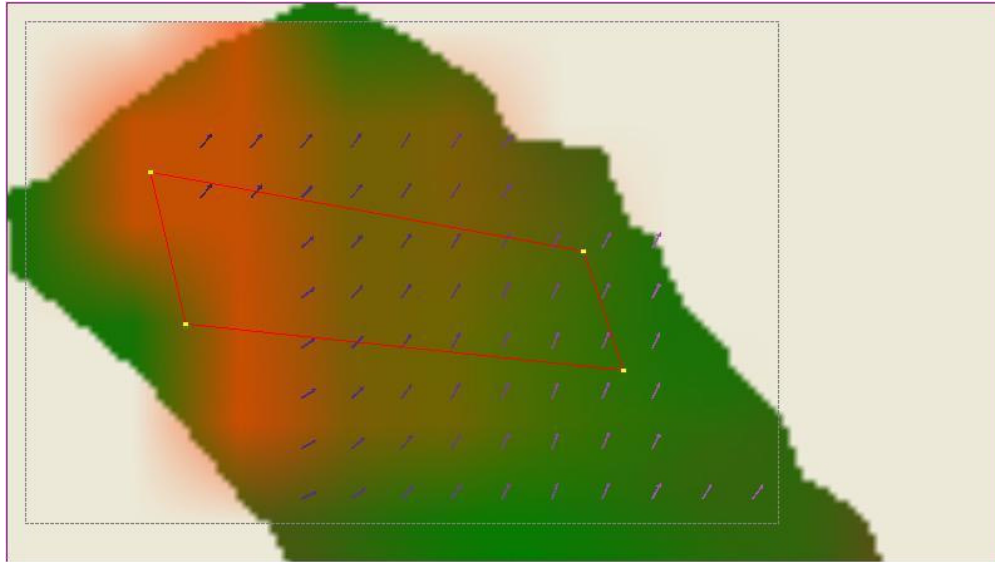
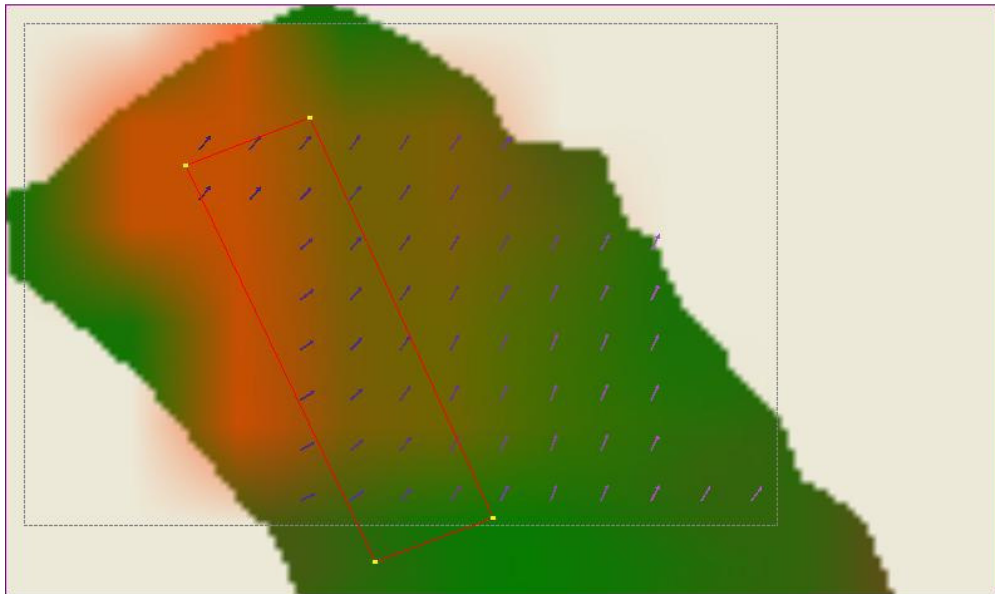


Figure 4. 20 Presentation of topography, clay layers, and groundwater depth and flow direction in VLF. Clay layers, indicated with orange color (such that darker zones indicated a clay layer thickness around 11 m, and lighter zones indicated clay layer thickness around 5 m). Purple arrows indicated groundwater direction and depth (such that, darker purple color indicated a groundwater depth of maximum 12 m, and lighter purple colors indicated a groundwater depth of minimum 3 m).



a.



b.

Figure 4. 21 Orientation of the landfill to the given site (a) longer side in the direction of groundwater flow (b) longer side perpendicular to the groundwater flow

4.5.2.3.1. Longer Side of the Landfill Perpendicular to Groundwater Flow Direction

Longer side of the landfill was located perpendicular to groundwater direction in VLF. The excavation depth was taken as 5 m, in order to preserve some of the clay layer available on site, and also to prevent reaching the groundwater which is 6 to 10 m below the ground surface within the borders of the selected landfill site. Side slopes were taken as 1v:3h, and base slope as 1%. The base elevation was then calculated as 952.5 m, and ground elevation as 957.5 m. An above-ground waste thickness of 15 m and a below-ground waste thickness of 5 m were considered to reach a total waste thickness of 20 m. Therefore the surface elevation was calculated as 972.5 m. The final cover was assigned a slope of 8%, and a small surface area of 0.01 ha was formed at the top of the landfill. The base slope direction was indicated with a red arrow. Entering the calculated inclination, base slope, base and ground elevation, surface elevation, surface slope, and ground offset value (i.e. an approximate thickness of final cover), the VLF model calculated the excavation (520950 m³), fill (4470 m³), and surface volumes (247120 m³), as well as the available clay volume (81820 m³) beneath the landfill area (Figure 4.22). The total volume of landfill can then be calculated as 763600 m³, which is acceptable as it lies within the 10% range of the volume calculated (705105 m³) by the volume calculation module (Eq. 4.10):

$$\begin{aligned} V_{total} &= V_{excavation} - V_{fill} + V_{surface} = 520.95dam^3 - 4.47dam^3 + 247.12dam^3 \\ V_{total} &= 763.6dam^3 = 763600m^3 \end{aligned} \quad (4.10)$$

After the excavation, VLF calculated that 81.82 dam³ (81820 m³) clay was still available at the base of the landfill.

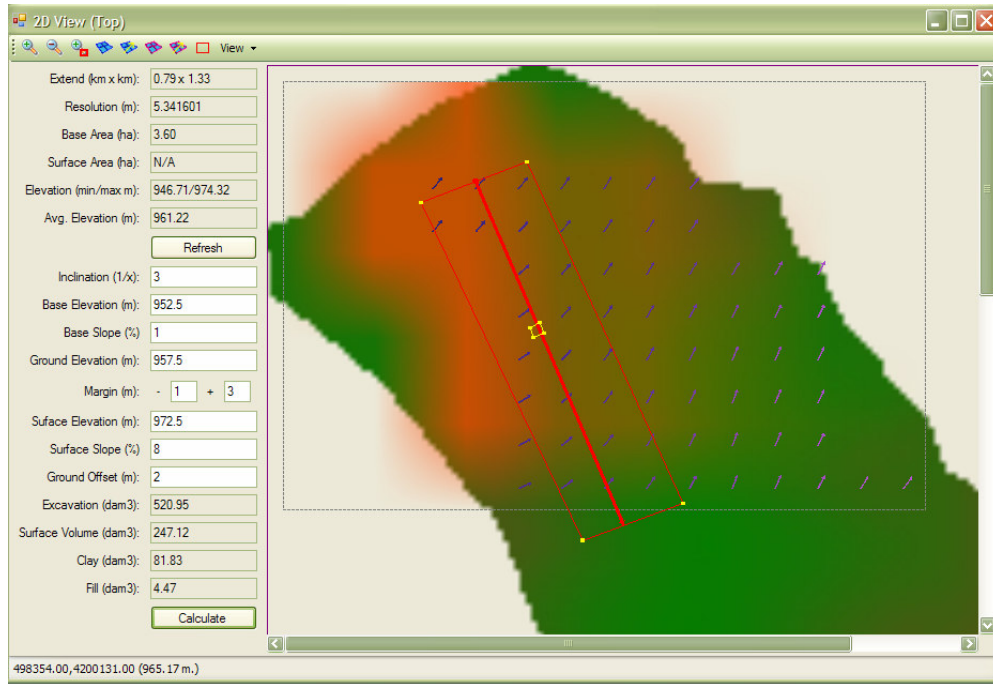


Figure 4. 22 Input data for VLF model and volume calculations for the case in which the landfill length is perpendicular to groundwater flow

Figure 4.22 demonstrates that depth to groundwater below the landfill varies between 6 to 10 m. Therefore, an excavation depth of 5 m represents a safe design with respect to the stability of the landfill.

Once the “calculate” button was hit, VLF demonstrated the excavated and filled areas (Figure 4.23), the surface fill (Figure 4.24), and the available clay layers (Figure 4.25) in the 2D window. A 3D visualization of the landfill with or without final cover was presented by 3D window (Figure 4.26). As can be seen from Figure 4.26, the orientation of the landfill was also found suitable considering the site topography.

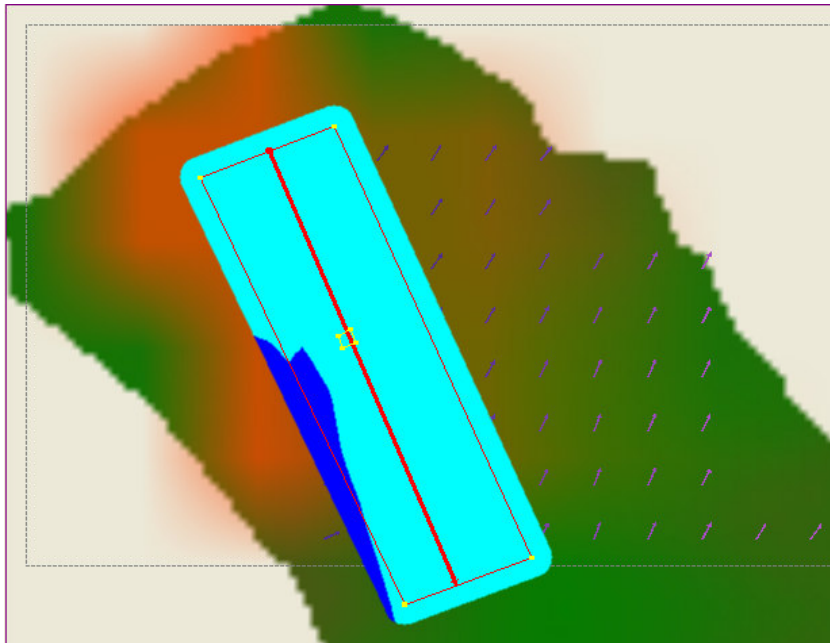


Figure 4. 23 Landfill excavation (light blue) and fill (dark blue) areas by VLF –landfill length perpendicular to groundwater

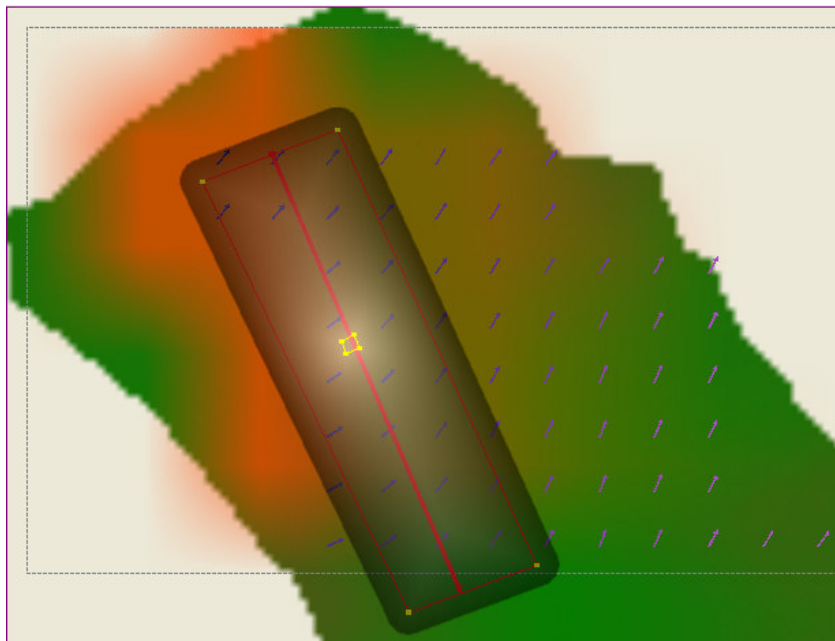


Figure 4. 24 Surface fill by VLF (lighter shades indicate higher elevations on the final cover) – landfill length perpendicular to groundwater



Figure 4. 25 Demonstration of availability of clay layers at the base of the landfill by VLF –green color (within the landfill borders) indicates the presence of the clay layer, whereas red color indicates the absence of clay layer after excavation –landfill length perpendicular to groundwater

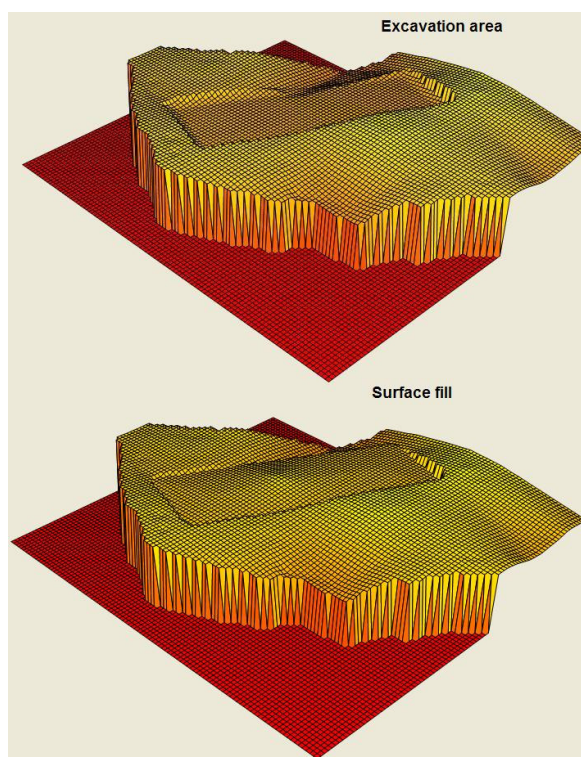


Figure 4. 26 3D demonstration of landfill with and without final cover by VLF –landfill length perpendicular to groundwater

4.5.2.3.2. Longer Side of the Landfill in the Direction of Groundwater Flow

Longer side of the landfill was located in the direction of groundwater flow in VLF. As can be seen from Figure 4.27, depth to groundwater at the eastern side of the landfill is around 4 m. Therefore, the excavation depth at the eastern side was limited to 3 m. Base slope direction was given to east to west side of the landfill; therefore, the excavation depth at the western side was 11.5 m. The original elevation was 969 m at that point, and with 1% slope along 350 m starting from an elevation of 961 m (the original elevation of the eastern end minus excavation depth; $964\text{m} - 3\text{m} = 961\text{m}$) results in a base elevation of 957.5 m, which was still above the piezometric surface present at an elevation of 957 m.

Considering an average excavation depth of 5 m, the ground elevation was calculated as 964 m. Side slopes were considered to be 1v:3h. 15-m-above-ground waste thickness was considered to reach a total waste thickness of 20 m. Therefore the surface elevation was calculated as 979 m. The final cover was assigned a slope of 3%. The base slope direction was indicated with a red arrow. Entering the calculated inclination, base slope, base and ground elevation, surface elevation, surface slope, and ground offset value (i.e. an approximate thickness of final cover), the VLF model calculated the excavation (408380 m^3), fill (6560 m^3), and surface volumes (277320 m^3), as well as the available clay volume (94810 m^3) beneath the landfill area (Figure 4.27). The total volume of landfill can then be calculated as 679140 m^3 , which is acceptable as it lies within the 10% range of the volume calculated (705105 m^3) by the volume calculation module (Eq. 4.11):

$$\begin{aligned} V_{total} &= V_{excavation} - V_{fill} + V_{surface} = 408.38\text{dam}^3 - 6.56\text{dam}^3 + 277.32\text{dam}^3 \\ V_{total} &= 697.14\text{dam}^3 = 679140\text{m}^3 \end{aligned} \quad (4.11)$$

After the excavation, VLF calculated that 94.18 dam³ (94180 m³) clay was still available at the base of the landfill.

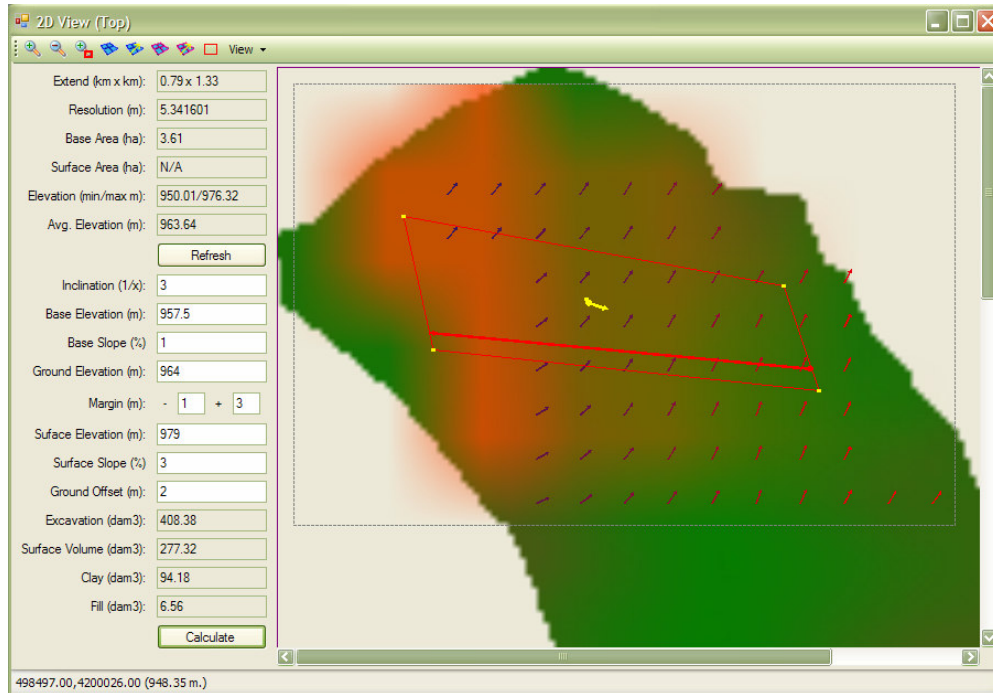


Figure 4. 27 Input data for VLF model and volume calculations for the case in which the landfill length is in the direction of groundwater flow

Once the “calculate” button was hit, VLF demonstrated the excavated and filled areas (Figure 4.28), the surface fill (Figure 4.29), and the available clay layers (Figure 4.30) in the 2D window. 3D visualization of the landfill with or without final cover was presented by 3D window (Figure 4.31). As can be seen from Figure 4.31, the orientation of the landfill was also found suitable considering the site topography.

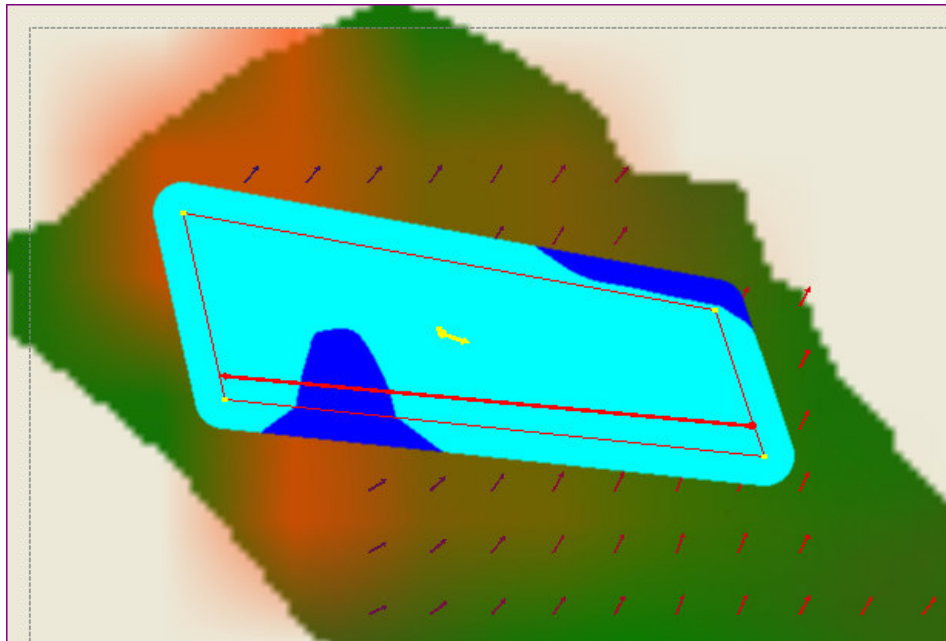


Figure 4. 28 Landfill excavation (light blue) and fill (dark blue) areas by VLF –landfill length in the direction of groundwater flow

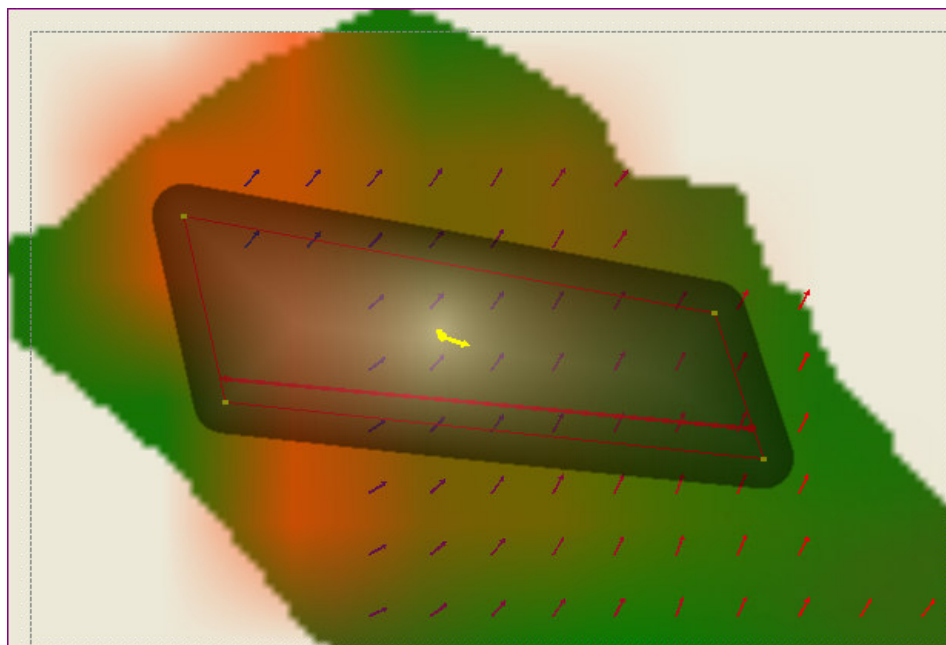


Figure 4. 29 Surface fill by VLF (lighter shades indicate higher elevations on the final cover) – landfill length in the direction of groundwater flow



Figure 4. 30 Demonstration of availability of clay layers at the base of the landfill by VLF –green color (within the landfill borders) indicates the presence of the clay layer, whereas red color indicates the absence of clay layer after excavation –landfill length in the direction of groundwater flow

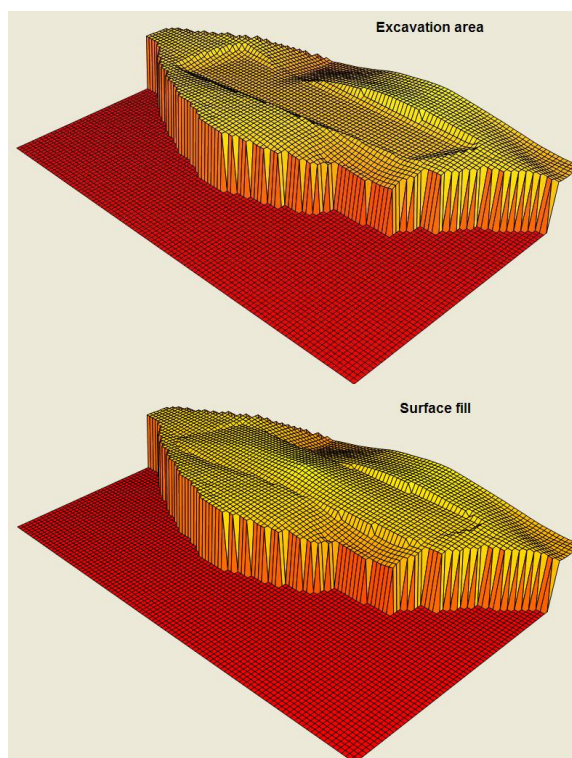


Figure 4. 31 3D demonstration of landfill with and without final cover by VLF –landfill length in the direction of groundwater flow

Both of the base grade designs were applicable for the design of the landfill for X-city. However, the second case might cause instabilities where piezometric surface rises above 1 m in wet seasons. Moreover, orienting the longer side of the landfill in the direction of groundwater flow potentially increases the mass load to the aquifer. The longer side of the landfill is 350 m, whereas the shorter side is 100 m. The peak concentrations calculated for each of the configurations demonstrated that orienting the longer side of the landfill parallel to the groundwater flow direction resulted in almost 3.5 folds increase in peak concentrations (e.g. the simulated peak chloride concentration for design with extensive engineering final cover coupled with a natural attenuation bottom liner – C2L1- increased from 27.3 mg/L to 94.7 mg/L). The excavation volume in the latter case (i.e. longer side parallel to groundwater flow direction, 408380 m³) is calculated to be smaller than the first orientation (i.e. longer side perpendicular to groundwater flow direction, 520950 m³) due to limited excavation depth. However, to satisfy the required landfill volume, the fill volume requirement increases from 4470 m³ to 6560 m³ and surface volume requirement increases from 247120m³ to 277320 m³ when the longer side of the landfill is oriented parallel to groundwater flow direction. Therefore, the orientation considering the length of the landfill in the direction of groundwater flow would not be considered as a design option.

4.5.2.4. *Preliminary Design*

Once the landfill was located on the given area and the dimensions were obtained using VLF, preliminary design alternatives were proposed by the Preliminary Design module in LFDSS, considering general site parameters. The thickness and area of the landfill were known from the VLF model, and annual precipitation was given as 1222 mm. It was reported that the groundwater velocity was in the range of 0.1 – 0.8 m/d. To observe the effect of the velocity range, lower end (0.1 m/d) and upper end (0.8 m/d) velocities were used for evaluation. The preliminary

design module proposed design alternatives C1L2, C1L4^L, C3L2, and C3L4^L for the cases where groundwater flow velocity was around 0.1 m/d. Superscript L indicates that the design alternative performs well only when placed above low-permeability aquitards. Increasing the flow velocity increased the number of design alternatives, and C2LX (i.e. C2L1, C2L2, C2L3, C2L4, C2L5, and C2L6) were also added to the proposed designs where groundwater flow velocity was around 0.8 m/d. Specifications of the design alternatives were given in Table 4.37.

Table 4. 36 Components of final covers and bottom liners of design alternatives proposed by preliminary design module in LFDSS for X-city

Design	Final Cover	Bottom Liner
C1L2	Natural topsoil	LCS ^b + geomembrane + CCL ^c + aquitard/vadose zone
C1L4 ^L	Natural topsoil	LCS ^b + geomembrane + aquitard
C3L2	Natural topsoil + CDS ^a + Clay liner	LCS ^b + geomembrane + CCL ^c + aquitard/vadose zone
C3L4 ^L	Natural topsoil + CDS ^a + Clay liner	LCS ^b + geomembrane + aquitard
C2L1	Natural topsoil + CDS ^a + geomembrane + Clay liner	Natural aquitard below waste
C2L2	Natural topsoil + CDS ^a + geomembrane + Clay liner	LCS ^b + geomembrane + CCL ^c + aquitard/vadose zone
C2L3	Natural topsoil + CDS ^a + geomembrane + Clay liner	LCS ^b + aquitard
C2L4	Natural topsoil + CDS ^a + geomembrane + Clay liner	LCS ^b + geomembrane + aquitard/vadose zone
C2L5	Natural topsoil + CDS ^a + geomembrane + Clay liner	LCS ^b + CCL ^c + aquitard/vadose zone
C2L6	Natural topsoil + CDS ^a + geomembrane + Clay liner	CCL ^c + aquitard/vadose zone

^a cover drainage system ^b leachate collection system ^c compacted clay liner

Unlike Siirt Municipal Solid Waste Landfill case study, the groundwater was susceptible to pollution due to leakage from the landfill. Therefore, each of 10 proposed design alternatives were simulated using HELP and POLLUTE models in LFDSS.

4.5.2.5. Infiltration Rate Calculations and Final Cover Performance Evaluation

HELP model in LFDSS was used to calculate infiltration rate passing through the final cover and reaching the waste in landfill. All of the proposed final covers (evapotranspiration final cover –C1, extensive engineering final cover -C2, and intermediate design final cover -C3) were simulated using HELP model. Site specific weather data were imported to HELP model tabs for evapotranspiration, precipitation, temperature, and solar radiation. Soil and design data for each of the final cover designs were identified in the Soil&Design tab. As described in Section 4.5.1.5, evapotranspiration final cover –C1 is composed of only natural topsoil above waste. Extensive engineering final cover –C2 is composed of topsoil, cover drainage system, geomembrane, and clay liner. Intermediate design final cover –C3 is composed of topsoil, cover drainage system, clay liner. The design specifications of the layers are the same as listed in Table 4.22 of Section 4.5.1.5.

The model was run from the Run tab for 10 years (operational lifetime of first stage for years 2010 – 2019) for all of the final cover design options. The infiltration rates were calculated as 0.519 m/y for evapotranspiration cover (C1), 0.034 m/y for extensive engineering final cover (C2), and as 0.495 m/y for intermediate design final cover -C3. Lower infiltration rate from extensive engineering final cover (C2) option occurred due to the presence of geomembrane layer (LDPE –low density polyethylene). The infiltration rates were automatically

transferred to POLLUTE model by LFDSS, and the simulations were continued with groundwater contamination calculations.

4.5.2.6. Groundwater Contamination and Landfill Design Performance Evaluation

POLLUTE model was run in order to calculate leachate head over landfill bottom liner for the designs without leachate collection systems, and to calculate groundwater contaminant concentrations at the top of the aquifer. Each of 10 design alternatives (C1L2, C1L4^L, C3L2, C3L4^L, C2L1, C2L2, C2L3, C2L4, C2L5, and C2L6) were simulated using POLLUTE model. The design specifications of the landfill alternatives were given in Table 4.37.

Table 4. 37 Final cover and bottom liner specifications of the investigated design alternatives for X-City

Design Alternative	Final Cover	Bottom Liner
C1L2	0.6 m of natural topsoil	0.3 m LCS ^b + 2 mm geomembrane + 0.6 m CCL ^c + vadose zone/aquitard
C1L4 ^L	0.6 m of natural topsoil	0.3 m LCS + 2 mm geomembrane + aquitard
C3L2	0.6 m of natural topsoil + 0.3 m CDS ^a + 0.6 m clay liner	0.3 m LCS + 2 mm geomembrane + 0.6 m CCL + vadose zone/aquitard
C3L4 ^L	0.6 m of natural topsoil + 0.3 m CDS ^a + 0.6 m clay liner	0.3 m LCS + 2 mm geomembrane + aquitard
C2L1	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	Natural aquitard below waste
C2L2	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	0.3 m LCS + 2 mm geomembrane + 0.6 m CCL + vadose zone/aquitard
C2L3	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	0.3 m LCS + aquitard
C2L4	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	0.3 m LCS + 2 mm geomembrane + vadose zone/aquitard
C2L5	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	0.3 m LCS + 2 mm + 0.6 m CCL + vadose zone/aquitard
C2L6	0.6 m of natural topsoil + 0.3 m CDS ^a + 1 mm geomembrane + 0.6 m clay liner	0.6 m CCL + vadose zone/aquitard

^a cover drainage system

^b leachate collection system

^c compacted clay liner

For the simulations, initial peak contaminant (chloride) concentration in the leachate was accepted as 1000 mg/L, which is typical for municipal solid waste leachate (İller Bankası, 2000). Waste density was accepted as 600 kg/m^3 , as previously reported. Effective mixing thickness in the aquifer was accepted as 3 m. As the potentiometric surface is 1 m above the aquifer top, groundwater level relative to the top of the aquifer was taken as 1 m. Lower (0.1 m/d) and upper (0.8 m/d) end groundwater velocity values were used for outflow velocity. As longer side of the landfill was placed perpendicular to the groundwater flow, the waste length was accepted as 100 m, which was the length of the landfill base in the direction of groundwater flow. Aquitard thickness –remaining after excavation– was 5 m. The aquitard was composed of low-permeability silty clay. The hydraulic conductivity of the drainage material used for leachate collection system was taken as 0.001 m/s. The input parameters used in POLLUTE simulations are given in Table 4.39.

Table 4. 38 Input parameters used for POLLUTE simulations

Section	Parameter	Value
Source	Concentration (mg/L)	1000
	Waste length (m)	100
	Waste thickness (m)	20
	Infiltration (m/y) ^a	0.519 for C1 final cover 0.034 for C2 final cover 0.495 for C3 final cover
	Waste density (kg/m ³)	600
Hydraulic Heads	Groundwater level relative to top of aquifer (m)	1
Leakage	LCS ^b Conductivity (m/s)	0.001
Outflow	Outflow velocity (m/y)	36.5 m/y (0.1 m/d) 292 m/y (0.8 m/d)
	Leachate head (m) ^c	
Clay Liner	Thickness (m)	0.6
	Hydraulic conductivity (m/s)	1x10 ⁻⁹
	Porosity	0.40
Vadose	Thickness (m)	5
Zone/Aquitard	Hydraulic conductivity (m/s)	1x10 ⁻⁸ m/s
	Porosity	0.38
Aquifer	Thickness (m)	3
	Porosity	0.30

^a automatically calculated and transferred as a result of HELP runs

^b leachate collection system

^c calculated by POLLUTE model for the designs without leachate collection systems, and reported at the end of the simulation to check whether the design satisfies stability criterion (i.e. leachate head should be below 1 m.)

The design alternatives without leachate collection systems (C2L1, and C2L6) satisfied the stability criterion. Both of the designs resulted in zero hydraulic head

over bottom liner. Therefore, stability with respect to leachate head criterion was satisfied for each of the design alternatives.

Although the design component selection matrix was constructed conservatively allowing for a maximum of 25 mg/L chloride concentration at the groundwater (TSE, 1997), the maximum allowable concentration reported for chloride in groundwater is 250 mg/L (TSE, 2005). Therefore, it is reasonable to evaluate the performance of the design alternatives with respect to 250-mg/L standard. Each of 10 design alternatives satisfied less than 250 mg/L chloride concentration at the groundwater table, for both of the groundwater velocity values. With respect to 25 mg/L standard, design alternatives lacking geomembranes in the bottom liner failed to satisfy the contamination criterion for lower end velocity value of 0.1 m/d. The results are presented in Table 4.39.

Table 4. 39 POLLUTE simulation results for leachate head and soil contamination

Design Alternative	Groundwater Contamination			
	C_{max}^a (mg/L)		T_{max}^b (y)	
	$v_s = 0.1$ m/d	$v_s = 0.8$ m/d	$v_s = 0.1$ m/d	$v_s = 0.8$ m/d
C1L2	0.41	0.05	177	177
C1L4 ^L	1.17	0.15	130	130
C3L2	0.43	0.05	177	177
C3L4 ^L	1.21	0.15	130	130
C2L1	27.30	3.41	85	85
C2L2	2.35	0.29	340	312
C2L3	27.32	3.42	85	85
C2L4	5.23	0.65	235	235
C2L5	27.11	3.39	92	92
C2L6	27.11	3.39	92	92

^a maximum groundwater concentration of chloride

^b time that the maximum concentration is observed

Although all of the simulations satisfied the contamination criterion, the design alternatives having geomembrane liners both in the cover and in the liner (i.e. C2L2, and C2L4) would not be investigated further, due to possible high cost. Also, designs with extensive engineering final cover (C2) having only leachate collection system or compacted clay liner above aquitard in the bottom liner (i.e. C2L3, and C2L6) was not taken into consideration as they produced almost the same contaminant concentrations with natural attenuation bottom liner (C2L1) and intermediate design bottom liner (C2L5) (Table 4.39). These design alternatives might be considered if the compatible designs did not produce stable factor of safety values. Therefore, the number of design alternatives to be investigated reduced to six (C1L2, C1L4^L, C3L2, C3L4^L, C2L1, and C2L5).

As the designs satisfied the contamination criterion for both of the groundwater velocity values, contaminant concentrations produced as a result of lower end velocity value (0.1 m/d) was accepted for conservative results.

4.5.2.7. *Structural Stability Calculations*

Illustrative stability analyses were performed using literature values for the types of the soils, final cover, and bottom liner systems examined in the above sections. The stability analyses were performed using the *stability module* in LFDSS. Types of analyses carried out for each of the simulated design alternatives are given in Table 4.40. It should be noted that, excavation slope and refuse fill stability analyses were carried out for *a single trial failure surface*. Analyses of a representative number of failure surfaces should be performed in order to decide on the stability of the excavation and the refuse. Seismic analysis was not carried out as the area was not reported to be in the earthquake zone. Parameters used in stability analyses are presented in Table 4.41.

Table 4. 40 Stability analyses for the investigated design alternatives for X-City

Design Alternative	Final Cover	Bottom Liner
C1L2	Cover system stability for cohesionless soils with seepage	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface Geomembrane stability
C1L4 ^L	Cover system stability for cohesionless soils with seepage	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface Geomembrane stability
C3L2	Cover system stability for cohesive soils	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface Geomembrane stability
C3L4 ^L	Cover system stability for cohesive soils	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface Geomembrane stability
C2L1	Cover system stability –with geomembrane	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface
C2L5	Cover system stability –with geomembrane	Excavation slope stability – circular slip surface Refuse-fill stability –circular slip surface

Table 4. 41 Parameters used in stability module for factor of safety calculations for X-City^f

Parameter	Final Cover		Bottom Liner			
	<i>Cohesionless</i>	<i>Cohesiv e</i>	<i>With GM^b</i>	<i>Excavation slope^g</i>	<i>Refuse fill^g</i>	<i>GM stability</i>
Cohesion (kN/m ²)	-	-	0	15	19	-
Friction angle (°)	-	-	30	1.3	20	15
Effective friction angle (°)	30	15	-	-	-	-
Slope angle (°)	4.57 (8%) ^e	4.57 ^e	-	-	-	-
$\gamma_{\text{total-soil}}$ (kN/m ³)	18.9	18.9	-	-	-	-
$\gamma_{\text{cover-soil}}$ (kN/m ³)	-	-	18.5	-	-	18.7
Thickness of cover soil (m)	-	-	1.5 ^e	-	-	-
Slope length along GM (m)	-	-	194 ^e	-	-	-
Slope angle beneath GM (°)	-	-	24.57 ^e	-	-	-
$\phi^c_{\text{cover soil-GM}}$ (°)	-	-	22	-	-	-
Effective cohesion (kN/m ²)	-	4.8	-	-	-	-
H ^d (m)	-	15 ^e	-	-	-	5, 7.5
Clay liner thickness (m)	-	0.6 ^e	-	-	-	-
γ_{water} (kN/m ³)	9.8	9.8	-	-	-	-
Height of LCS (m)	-	-	-	-	-	0.3
γ_{granular} (kN/m ³)	-	-	-	-	-	14.2
Slope angle (°)	-	-	-	-	-	18.4 (1v:3h) ^e
$\phi^c_{\text{geotextile-GM}}$ (°)	-	-	-	-	-	20
Anchor height (m)	-	-	-	-	-	1, 1.5

^a unit weight ^b geomembrane ^c internal angle of friction ^d height of slope ^e design condition

^f literature values for geotechnical data were gathered from Sharma and Lewis, 1994. ^g single trial surface

Stability analyses for all six design alternatives produced stable factor of safety values which were calculated to be greater than 1.5 (Sharma and Lewis, 1994; Koerner and Daniel, 1997). Especially, cover systems with compacted clay liners (cohesive soils) resulted in high stability (Table 4.42). The bottom liners having geomembranes were found stable when the anchor height was greater than or equal to 1 m. Therefore, each of six design alternatives may be considered safe for construction.

Table 4. 42 Factor of safety values calculated by the stability module in LFDSS for X-city designs

Design	Factor of Safety Values (FS)					
	Cover system	Excavation slope ^a	Refuse fill ^a	Geomembrane stability		
				Slope height (m)	Anchor height (m)	FS
C1L2	3.48	3.20	3.49	5	1	2.42
				7.5	1	1.61
				5	1.5	5.44
				7.5	1.5	3.63
C1L4 ^L	3.48	3.20	3.49	5	1	2.42
				7.5	1	1.61
				5	1.5	5.44
				7.5	1.5	3.63
C3L2	44.69	3.20	3.49	5	1	2.42
				7.5	1	1.61
				5	1.5	5.44
				7.5	1.5	3.63
C3L4 ^L	44.69	3.20	3.49	5	1	2.42
				7.5	1	1.61
				5	1.5	5.44
				7.5	1.5	3.63
C2L1	9.17	3.20	3.49	-	-	-
C2L5	9.17	3.20	3.49	-	-	-

^a single trial surface

4.5.2.8. Cost Calculations of Major Design Components

Major landfill components include native soil, topsoil, clay liners, drainage system components, and geosynthetics (i.e. geomembranes). Additional component taken into consideration here was geotextile filters. Major, additional, and total costs of design alternatives were calculated using cost estimation module in LFDSS. Majority of the costs was related with soil excavation, which was independent of the design alternative. VLF model of LFDSS calculated the excavation and fill volumes as 520950 m³ and 4470 m³ respectively for the landfill examined for X-City. For intermediate soil covers one to four soil to waste ratio is commonly accepted. Considering 1v:3h slopes at the sides of the landfill, the length of the landfill approximately extends to 388 m, and the width of the landfill approximately extends to 130 m at the surface (Figure 4.32).

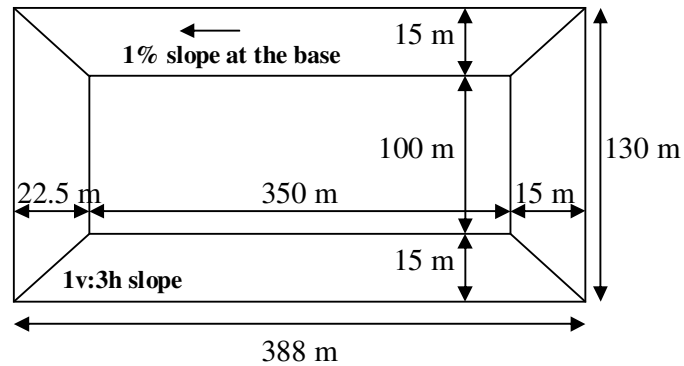


Figure 4. 32 Schematic view of the surface area of the landfill for X-City

A native topsoil of 0.6 m thick was applied in the final cover, which covers an area of approximately 5 ha (388 m x 130 m). Considering the total landfill volume of 705105 m³, soil requirement for intermediate and final covers were calculated as:

Daily and intermediate covers $V_{int} = \frac{705105m^3}{4} = 176276m^3$ (4.12)

Final cover $V_{final} = 0.6m \times 50000m^2 = 30000m^3$ (4.13)

Volumes of soil to be used during landfill construction, and excess amount of soil that is needed to be disposed are given in Table 4.43.

Table 4. 43 Volumes of soil used in landfill construction for X-City landfill

Area		Excavation	Fill	D&I ^a Covers	Final Cover	Total ^b	Excessive Soil Volume
(ha)		(m ³)	(m ³)	(m ³)	(m ³)	(m ³)	(m ³)
<i>Base</i>	<i>Cover</i>						
3.5	5.0	520950	4470	176276	30000	210746	310204

^a daily and intermediate ^b total of fill, daily and intermediate covers, and final cover

Analyses that were considered for design alternatives are presented in Table 4.44. Geotextiles for reinforcement were also considered as an additional cost for the designs including geomembranes.

Table 4. 44 Landfill components of the design alternatives considered for cost analyses

Design Alternative	Cost Analyses
C1L2	Native soil, topsoil, drainage, drainage tile, clay, geomembrane, geotextile
C1L4 ^L	Native soil, topsoil, drainage, drainage tile, geomembrane, geotextile
C3L2	Native soil, topsoil, drainage, drainage tile, clay, geomembrane, geotextile
C3L4 ^L	Native soil, topsoil, drainage, drainage tile, geomembrane, geotextile
C2L1	Native soil, topsoil, drainage, clay, geomembrane, geotextile
C2L5	Native soil, topsoil, drainage, clay, geomembrane, geotextile

Virtual Landfill (VLF) model demonstrated that almost half of the landfill base stayed on top of clayey zones. A 0.6-m-thick clay layer would be used for bottom liners and final covers. Amounts of clay required for bottom liner and final cover were approximately calculated as:

$$\text{Bottom clay; } V_{clay} = 0.6m \times 35000m^2 = 21000m^3 \quad (4.14)$$

$$\text{Final cover clay; } 0.6m \times 50000m^2 = 30000m^3 \quad (4.15)$$

As almost half of the clay was visible at the base of the landfill, available clay volume was estimated to be 10000 m³. Therefore, the required excavation amount of clay was 11000 m³ (21000 m³ – 10000 m³) for bottom liners, and 30000 m³ for final covers; corresponding to a total of 41000 m³ (11000 m³ + 30000 m³).

Soil amounts that were supposed to be used for the construction of various design alternatives are given in Table 4.45.

Table 4. 45 Amounts of soil to be used in landfill construction for X-City landfill

Soil Components	C1L2	C1L4^L	C3L2	C3L4^L	C2L1	C2L5
Native soil						
<i>Excavation (m³)</i>	520950	520950	520950	520950	520950	520950
<i>Loading (add 15%) (m³)</i>	356735	356735	356735	356735	356735	356735
<i>Spread native soil (m³)</i>	180746 ^a	180746 ^a	180746 ^a	180746 ^a	180746 ^a	180746 ^a
Topsoil						
<i>Spread topsoil (m³)</i>	30000 ^b	30000 ^b	30000 ^b	30000 ^b	30000 ^b	30000 ^b
<i>Compact topsoil (m³)</i>	30000	30000	30000	30000	30000	30000
Drainage						
<i>Stone (m³)</i>	10500 ^c	10500 ^c	25500 ^g	25500 ^g	15000 ^c	25500 ^g
<i>Spread stone (m³)</i>	10500	10500	25500	25500	15000	25500
Clay (Onsite/Offsite)						
<i>Clay excavation (m³)</i>	11000		41000		30000	41000
<i>Spread clay (m³)</i>	11000		41000		30000	41000
<i>Compact clay (m³)</i>	21000 ^d		21000 ^d			21000 ^d
Drainage tile						
<i>Pipe (m)</i>	700 ^e	700 ^e	700 ^e	700 ^e		700 ^e
Synthetic membrane						
<i>60 mil HDPE (m²)</i>	35000 ^f	35000 ^f	35000 ^f	35000 ^f		
<i>40 mil PVC (m²)</i>					50000 ^h	50000 ^h
<i>Installation (m²)</i>	35000	35000	35000	35000	50000	50000
Geotextile filter						
<i>10 oz geotextile (m²)</i>	35000 ^f	35000 ^f	35000 ^f	35000 ^f	50000 ^h	50000 ^h
<i>Installation (m²)</i>	35000	35000	35000	35000	50000	50000

^a total of daily and intermediate covers and fill (176276m³ + 4470m³)

^b soil thickness x surface area (0.6m x 50000m²)

^c stone layer thickness x base area (0.3m x 35000m²)

^d clay thickness x base area (0.6m x 35000m²)

^e pipe installation interval is 50m; therefore, 7 pipes (350m/50m) of 100-m-long.

^f base area

^g stone layer thickness x base area + stone layer thickness x surface area (0.3m x 35000m² + 0.3m x 50000m²)

^h surface area

The design alternatives resulted in costs around 2.0 – 2.5 million USD (Table 4.46). The design alternatives including evapotranspiration final covers (C1) resulted in the least cost (1.9 – 2.1 million USD), and the costs of the designs increased as the final cover specifications increased. This occurred due to larger surface area of the final cover and higher requirement of the surface materials (geomembranes, clay liners, etc.) associated with larger surface area. The highest cost corresponded to the design alternative with extensive engineering final cover having cover drainage system, geomembrane, and clay liner, and intermediate design bottom liner having leachate collection system and compacted clay liner (C2L5). Cost of this alternative exceeded 2.5 million USD. As groundwater in the area is susceptible to contamination, and the site receives considerable amount of precipitation, sophisticated bottom liners having geomembranes should be considered, instead of more sophisticated final covers. This kind of decision will not only increase the performance of the design, but also reduce the costs associated with construction.

Table 4. 46 Major, additional and total costs of design alternatives for X-City

Design Alternative	Major Costs (USD)	Additional Costs^a (USD)	Total Cost (USD)
C1L2	2071164	30450	2101614
C1L4 ^L	1925224	30450	1955674
C3L2	2507814	30450	2538264
C3L4 ^L	2097874	30450	2128324
C2L1	2224324	43500	2267824
C2L5	2501694	43500	2545194

^a includes cost of geotextiles

4.5.2.9. *Presentation of the Assessments and Decision Making*

After all the modules in LFDSS were run for each of the design alternative under investigation (C1L2, C1L4^L, C3L2, C3L4^L, C2L1, and C2L5), the results produced by each model and module (i.e. Preliminary design module, POLLUTE model, stability module, and cost estimation module) were saved by the LFDSS in the performance report (Appendix-G). The saved file was imported to MS Excel results template provided with the software to compare the performances of the simulated design alternatives and ease the decision making process. The overall results of the simulations of design alternatives are presented in Table 4.47. Leachate head values were not included in results table (Table 4.47), as simulations are not performed for the designs that do not comply with the stability criterion (i.e. leachate head should be less than 1 m).

Table 4. 47 Overall results of the landfill design simulations by LFDSS for X-City

Design	Performance		Stability		Cost (USD)		
	Cl_{max}^a (mg/L)	T_{max}^b (yr)	FS values		Main Cost	Additional Cost	Total Cost
C1L2	0.41	177	Excavation slope	3.20	2071164	30450	2101614
			Refuse-fill	3.49			
			Cover system	3.48			
			Geomembrane	5/1/2.42 ^c			
				7.5/1/1.61			
				5/1.5/5.44			
	7.5/1.5/3.63						
		Seismic	-				
C1L4 ^L	1.17	130	Excavation slope	3.20	1925224	30450	1955674
			Refuse-fill	3.49			
			Cover system	3.48			
			Geomembrane	5/1/2.42 ^c			
				7.5/1/1.61			
				5/1.5/5.44			
	7.5/1.5/3.63						
		Seismic	-				
C3L2	0.43	177	Excavation slope	3.20	2507814	30450	2538264
			Refuse-fill	3.49			
			Cover system	45.68			
			Geomembrane	5/1/2.42 ^c			
				7.5/1/1.61			
				5/1.5/5.44			
	7.5/1.5/3.63						
		Seismic	-				

^a maximum soil chloride concentration ^b time that maximum concentration was observed

^c slope height (m) /anchor height (m) /factor of safety

Table 4. 47 Overall results of the landfill design simulations by LFDSS for X-City (*cont'd*)

Design	Performance		Stability		Cost (USD)		
	Cl_{max}^a (mg/L)	T_{max}^b (yr)	FS values		Main Cost	Additional Cost	Total Cost
C3L4 ^L	1.21	130	Excavation slope	3.20	2097874	30450	2128324
			Refuse-fill	3.49			
			Cover system	45.68			
			Geomembrane	5/1/2.42 ^c			
				7.5/1/1.61			
				5/1.5/5.44			
	7.5/1.5/3.63						
		Seismic	-				
C2L1	27.30	85	Excavation slope	3.20	2224324	43500	2267824
			Refuse-fill	3.49			
			Cover system	9.17			
			Geomembrane	-			
			Seismic	-			
C2L5	27.11	92	Excavation slope	3.20	2501694	43500	2545194
			Refuse-fill	3.49			
			Cover system	9.17			
			Geomembrane	-			
			Seismic	-			

^a maximum soil chloride concentration ^b time that maximum concentration was observed

^c slope height (m) / anchor height (m) / factor of safety

Although each of 6 design alternatives resulted in groundwater chloride concentrations less than 250 mg/L, the design alternatives having extensive engineering final covers (C2) and either natural attenuation bottom liners (L1) or intermediate design bottom liners having leachate collection systems and compacted clay liners (L5) produced higher chloride concentrations (27.30 mg/L and 27.11 mg/L, respectively) at the groundwater table. Considering the high costs associated with the aforementioned designs, these design alternatives (C2L1, and C2L5) would not be selected for X-City.

Remaining four design alternatives (C1L2, C1L4^L, C3L2, and C3L4^L) produced negligible amounts of chloride concentration at the groundwater table (0.41 mg/L, 1.17 mg/L, 0.43 mg/L, and 1.21 mg/L, respectively for C1L2, C1L4^L, C3L2, and C3L4^L). The result was mainly associated with geomembrane liners installed in the bottom liner. Extensive engineering bottom liners (L2) include leachate collection systems, geomembrane liners, and compacted clay liners; whereas, C4 bottom liners include leachate collection systems and geomembrane liners placed over low-permeability aquitards. The designs also produced stable factor of safety values. However, design alternatives having final covers composed of cohesive soils (i.e. covers including clay liners; such as C3) were found to be more stable with respect to factor of safety values. If the final cover stability is guaranteed for design alternatives having evapotranspiration final covers (C1), these design alternatives (C1L2, and C1L4^L) may be preferred due to relatively low construction costs (1.95 – 2.10 million USD). Otherwise, alternatives with intermediate design final covers having cover drainage system and clay liners (C3) should be considered, although the costs of these design alternatives (C3L2, and C3L4^L) are higher (2.13 – 2.54 million USD).

CHAPTER 5

CONCLUSIONS

Conclusions of the study are presented under three main headings: evaluation of the effects of design variables on the performance of landfill designs, evaluation of the results of the performance-based landfill design simulation, and evaluation of the strengths and weaknesses of the developed DSS (LFDSS) based on case study results.

5.1. Effects of Design Variables on the Performance of Landfills

The contaminant concentrations in the aquifer decreased as the seepage velocity increased, due to dilution. The effect of dilution is stronger for lower contaminant concentrations; therefore, the decrease is observed to be predominant for extensive engineering designs (C2L2) and a weaker dilution effect was observed for designs with less-engineered components (C1L1, and C3L5). The effect of waste thickness is not as evident as seepage velocity. The contaminant concentrations increased with increasing waste thickness, reaching an asymptotic threshold depth of (30 m). This phenomenon is related to faster waste stabilization as the older waste at the bottom treats the leachate of fresh waste at the top due to increased biological activity in the older waste. The sensitivity analyses for the combined effect of seepage velocity and waste thickness demonstrated that the

effects of both parameters are additive, which was expected as these variables are independent of each other.

Hydraulic properties of the vadose zone appeared to have a much more complex effect on the performance of the landfill. Failure to consider the presence of an unsaturated zone beneath a CCL and the assumption of zero suction at the base of the CCL can result in substantial underestimation of the leakage through the clay liner. This consideration should be given to the effect of the vadose zone on the leakage through the CCL.

Unsaturated soil hydraulic conductivity is a function of water content and, hence, it increases with increasing water content towards the water table. Because the thickness of soil with low moisture content, and hence low hydraulic conductivity, increases with increasing vadose zone thickness, the harmonic mean hydraulic conductivity values of the vadose zone decrease with increasing thickness of the vadose zone. When the barrier system is simulated using unsaturated soil hydraulic conductivity functions, the resulting harmonic mean hydraulic conductivity values of the coarse textured vadose zones are 3 – 4 orders of magnitude less than the uniform saturated hydraulic conductivity values. For fine textured vadose zones, however, the difference is only one order of magnitude. Therefore, the representative values to be used in the design of landfills were selected as 10^{-7} m/s for sandy vadose zones and $10^{-7} - 10^{-8}$ m/s for silty aquitards.

For both coarse and fine textured vadose zones, the effective hydraulic conductivity of the overall barrier system increases with increasing thickness of the vadose zone. The increased effective hydraulic conductivity values result in a gradual increase in the steady state leakage rates into the aquifer. Steady-state leakage rates in the fine and coarse textured vadose zones reach an asymptotic value at about 5 m and 10 m thickness, respectively, for the cases examined herein. The coarse textured vadose zones thicker than 10 m and fine textured

vadose zones thicker than 5 m start to act as a part of the barrier system. A 5 to 10-m-thick vadose zone can be not only an effective advective barrier, but also be an effective diffusive barrier. For inorganic contaminants, as the thicknesses of CCL and vadose increase, the diffusive mass flux and thus concentrations of contaminants diffusing through the barrier tend to decrease due to the decrease in concentration gradients.

Modeling the barrier systems using uniform saturated hydraulic conductivity values resulted in 2.0 – 3.5 times greater steady-state leakage rates than using unsaturated hydraulic conductivity functions, for coarse textured vadose zones. For fine textured vadose zones, the same steady-state leakage rates were obtained by modeling both with uniform saturated hydraulic conductivities and unsaturated hydraulic conductivity functions for vadose zones, shallower than 5 m. When the vadose zone thickness was increased beyond 5 m, nearly 1.5 to 2.5 times greater steady-state leakage rates were produced by using uniform saturated hydraulic conductivity values. Therefore, it was concluded that, realistic modeling of the barrier systems composed of coarse textured vadose zones requires the consideration of the unsaturated soil hydraulic conductivities. On the other hand, uniform saturated hydraulic conductivity values can still be used for modeling the barrier systems composed of fine textured vadose zones to achieve conservative results.

One order of magnitude decrease in the hydraulic conductivity of the CCL resulted in the same order of magnitude decrease in the steady-state leakage rate; whereas, the same order of magnitude increase in the vadose zone thickness only resulted in half order of magnitude increase in the steady-state leakage rate. While the vadose zone thickness affects the effective hydraulic conductivity of the overall barrier system, and in turn the steady-state leakage rates, the CCL hydraulic conductivity was the primary factor controlling the steady-state leakage rates through the barrier system.

As the climate gets wetter, the specifications of the landfill design should be more stringent. As the waste thickness and landfill size (base length in the direction of groundwater flow) increased, contaminant concentration reaching the aquifer increased. However, as landfill size and precipitation increased, the effect of waste thickness on contaminant concentrations diminished. Seepage velocity dilutes the contaminants in the leachate; therefore, lower contaminant concentrations were observed at the receptor when the seepage velocity was higher. The hydraulic properties of the vadose zone (i.e. hydraulic conductivity, porosity, and vadose zone thickness) affected the effective hydraulic conductivity of the bottom liner; and therefore, the rate of leakage into the aquifer. The leakage rate decreased with decreasing vadose zone hydraulic conductivity.

Therefore, climate, landfill area, waste thickness, seepage velocity, and site hydrogeology were selected to be considered as design variables that would be used for the design component selection matrix. The design component selection matrix accommodates the results of 1300 simulations performed considering the aforementioned design variables. It is used as a knowledge-base in the preliminary phase of the landfill decision support system. The design component selection matrix offers guidance in design selection and is beneficial in selecting preliminary landfill design alternatives when general site parameters are known.

5.2. Evaluation of Performance-based Landfill Design Simulations

Evapotranspiration final covers composed of only natural topsoil over waste (C1) produced the highest infiltration rate; whereas, extensive engineering final covers including natural topsoil, drainage layer, geomembrane, and clay liner (C2) restricted the infiltration rate to a great extent. Clay liners without geomembranes were not sufficient in limiting the infiltration to the waste. If the leakage below landfill is controlled by final cover design, then geomembranes in final covers or capillary barrier final covers should be considered.

Hydraulic head developed on top of landfill barrier for the designs lacking leachate collection systems (L1, L6). For arid climates, as the infiltration rate was lower than the hydraulic conductivity of the compacted clay liner in the aforementioned designs, hydraulic head development above the liner was not observed. Under moderate climates, significant hydraulic head (> 1 m) was developed when the vadose zone hydraulic conductivity was less than 10^{-7} m/s. Under humid climates, both natural attenuation bottom liner composed only of aquitard below waste (L1) and bottom liner composed of compacted clay liner without leachate collection system (L6) resulted in a hydraulic head greater than 1 m. Therefore, it is concluded that leachate collection systems are required for designs under moderate and humid climates regardless of the type of final cover design, in order to satisfy the stability of the landfill design (i.e. less than 1-m-leachate head over bottom liner).

Under arid climates, as the infiltration rate was much lower than any of the bottom liner hydraulic conductivities composed of natural material (L1, L3, L5, and L6); leachate collection system was not functional. In this case, leakage rate is controlled by the final cover. Under moderate climates, the leachate collection systems were effective only when coupled with a compacted clay liner. Under humid climates, the infiltration rate was higher than any of the bottom liner design hydraulic conductivities. Efficiency of leachate collection systems coupled with compacted clay liners was not sufficient, and inclusion of geomembranes were required.

Under arid climates, when groundwater seepage velocities were in the range of medium to fast (0.5 – 1 m/d), all the design alternatives complied with the performance criterion for communal to small sized landfills ($A < 15$ ha). For medium sized landfills having shallow waste thickness (5 m), all design alternatives implemented on low conductivity vadose zones complied with performance criterion. Except for very slow seepage velocities (0.05 m/d) which

required geomembrane inclusion in the bottom liner, design alternatives composed of extensive engineering final cover (C2) performed satisfactorily. For large landfills ($A > 50$ ha) having a waste thickness of 20 m, the seepage velocity was insufficient in diluting the contaminant load in the aquifer; and, inclusion of geomembranes in the bottom liner designs became necessary. For shallower waste thicknesses (5 m), geomembranes were optional for performance.

Under moderate climates, as the efficiency of leachate collection system coupled with compacted clay liner (L5) was not sufficient, this design alternative did not comply with the performance criterion. Similar to the results under arid climates, except for very slow seepage velocities (0.05 m/d) which required geomembrane inclusion in the bottom liner, design alternatives composed of extensive engineering final cover (C2) performed satisfactorily. For faster velocities ($v > 0.1$ m/d), designs having compacted clay liners in their bottom liners complied with the performance criterion. For large landfills ($A > 50$ ha), the seepage velocity was insufficient in diluting the contaminant load in the aquifer; and, inclusion of geomembranes in the bottom liner designs became obligatory.

Under humid climates, as the infiltration rate was higher than the effective hydraulic conductivity of natural attenuation bottom liners composed of only aquitard below waste (L1) and of bottom liners composed of leachate collection systems placed on low conductivity aquitards (L3), the hydraulic properties of these designs were insufficient to comply with the performance criterion. Moreover, designs having leachate collection systems coupled with compacted clay liners did not satisfy the contaminant concentration requirement at the receptor, either. Only for communal size landfills ($A < 2$ ha) placed on low conductivity vadose zones, bottom liner designs composed of leachate collection systems coupled with compacted clay liners performed satisfactorily. For small size landfills (2 – 15 ha) having extensive engineering covers (C2), and for medium size landfills (15 – 50 ha) under medium to fast seepage velocities ($v >$

0.5 m/d), geomembranes could be excluded from the bottom liner. For larger landfills, geomembranes were required in the bottom liners. Bottom liner designs having geomembranes complied with the performance criterion for all circumstances. The waste thickness was not effective in controlling the contaminant concentrations under humid climates.

Operational concerns like leachate circulation and design of cells in the landfill may change design performance; therefore, under such circumstances, the designer should change default design conditions. For example, a site under arid climatic conditions may be simulated considering moderate or humid climate effect if leachate recirculation is applied.

5.3. Evaluation of the Developed DSS (LFDSS)

Volume Calculation Module (VCM) provides a good estimate of required landfill volume, when detailed data on waste production and amounts are not available to the user. Landfill design model (Virtual Landfill –VLF) is a unique model developed specifically for LFDSS. The user is guided on the best available area to locate the landfill with respect to groundwater and clay layer thickness concerns. As many configurations as required can be drawn on the given map, and different orientations of the landfill may be examined. The drawbacks of VLF include the requirement of map digitalization and interpretation of topographic, clay layer, and groundwater layer data into ASCII files to create digital elevation models, and the requirement of a priori hand-calculated base and ground elevations based on side and base slopes, and original ground elevations. Preliminary design module offers a rule-based expert system composed of the results of 1300 landfill design simulations. The module achieves preliminary evaluation of required design specifications based on general site data; in other words, proposes preliminary design alternatives appropriate for the given site conditions. Coupled with landfill bottom liner design and subsurface transport model (POLLUTE), landfill cover

design model (HELP) becomes a part of a complete landfill design and subsurface transport model running under LFDSS. Although the model requires extensive amount of climatic data (i.e. evapotranspiration, daily precipitation, daily temperature, and daily solar radiation), it is yet the best available hydrologic model. Stability and major cost estimation modules offer fast preliminary stability analyses and total landfill construction cost, respectively; although, collecting geotechnical data and calculating soil and material amounts may be a tedious work.

Besides the model- and module-specific benefits, LFDSS has some major strengths. LFDSS provides a systematic and practical approach to determine the best performing landfill design(s), which pose acceptable environmental risks and low investment costs, for given site and waste conditions. The developed DSS allows for a complete landfill design, which starts from landfill volume calculation, and proceeds with landfill base contour design, final cover and bottom liner design, and subsurface transport modeling. A similar complete landfill design model has not been reported in the literature. It offers fast preliminary design and guidance on the selection of preliminary design alternatives (i.e. design components and their design details). LFDSS provides evaluations of landfill design alternatives allowing for comparison between each simulated landfill design alternative, and helps in making decisions based on performance, stability and cost analyses.

Among all the advantages that the LFDSS proposes, being a prototype decision support system, LFDSS has some drawbacks. LFDSS is designed for Windows operating system, and the operation under Macintosh operation system is not tested. The system requires some hand calculations to be performed for some of the modules (i.e. VLF, and cost estimation module), and extensive amount of data for HELP, and stability module. As POLLUTE model does not provide open-codes, LFDSS requires POLLUTE model to be a registered software in the

computer under which LFDSS runs. Possible improvements on the listed drawbacks are proposed in the Recommendations for Future Studies (Chapter 6).

CHAPTER 6

RECOMMENDATIONS FOR FUTURE STUDIES

The developed decision support system serves as a prototype DSS for an integral landfill design, starting from waste and landfill volume calculations, and proceeding with landfill base contour design, final cover design, bottom liner design, and subsurface transport modeling. This prototype system is open to development and future research.

HELP and POLLUTE software integrated under LFDSS may be replaced with a complete landfill design and simulation model, performing the processes of both models. A hydrologic model, which is to include a database under which Turkish climatic data are stored, can be developed instead of HELP. A weather simulator can be added to the new model in order to simulate the climatic data for given number of years. Therefore, extensive amount of climatic data requirement may be eliminated. Also, capillary barrier modeling for final cover systems can be achieved if unsaturated modeling components are also added to the hydrologic model. A bottom liner design and subsurface transport model can also be developed and integrated to the hydrologic model. Therefore, a complete landfill design model may be developed and used instead of HELP-POLLUTE integration. This integral model can not only serve as new landfill design software, but also can eliminate the need of a licensed POLLUTE software in the computer under which the DSS runs.

The landfill design model (Virtual Landfill -VLF) can be improved to be more user friendly by minimizing hand calculations, and to present the cross-sectional profiles of the landfill, and clay and groundwater layers beneath the landfill to the user. Stability module can also be improved if it is given the capability of drawing slip surface vs. factor of safety graphs and presenting the graphical solution to the user. Hydrogeologic, cost, and geotechnical parameter databases can be added to the DSS to be used when the user needs to use literature values in case of unavailability of site-specific data. A complete new module on hydraulic calculations for the design of leachate collection and surface drainage systems can be developed and integrated to the system, in order to optimize leachate collection and surface drainage efficiency.

Besides the improvements in models and modules, the prototype DSS can be improved by adding decision modules on waste management and pre-landfilling strategies, and site selection process. The user can be guided to decide on best waste management applications with respect to waste minimization strategies like reuse, and recycling, and evaluations on disposal alternatives such as combustion, composting, etc. Site selection processes can be guided by multiple-criteria decision analysis.

It can be concluded that, this thesis study not only proposed a new approach on landfill design and modeling, but also has given rise to future research and development on an integral solid waste management and landfill design. Each of the possible studies summarized in the above paragraphs can a subject of new research projects and thesis studies.

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APPENDIX-A

SCHEMATIC DRAWINGS OF LANDFILL DESIGN ALTERNATIVES

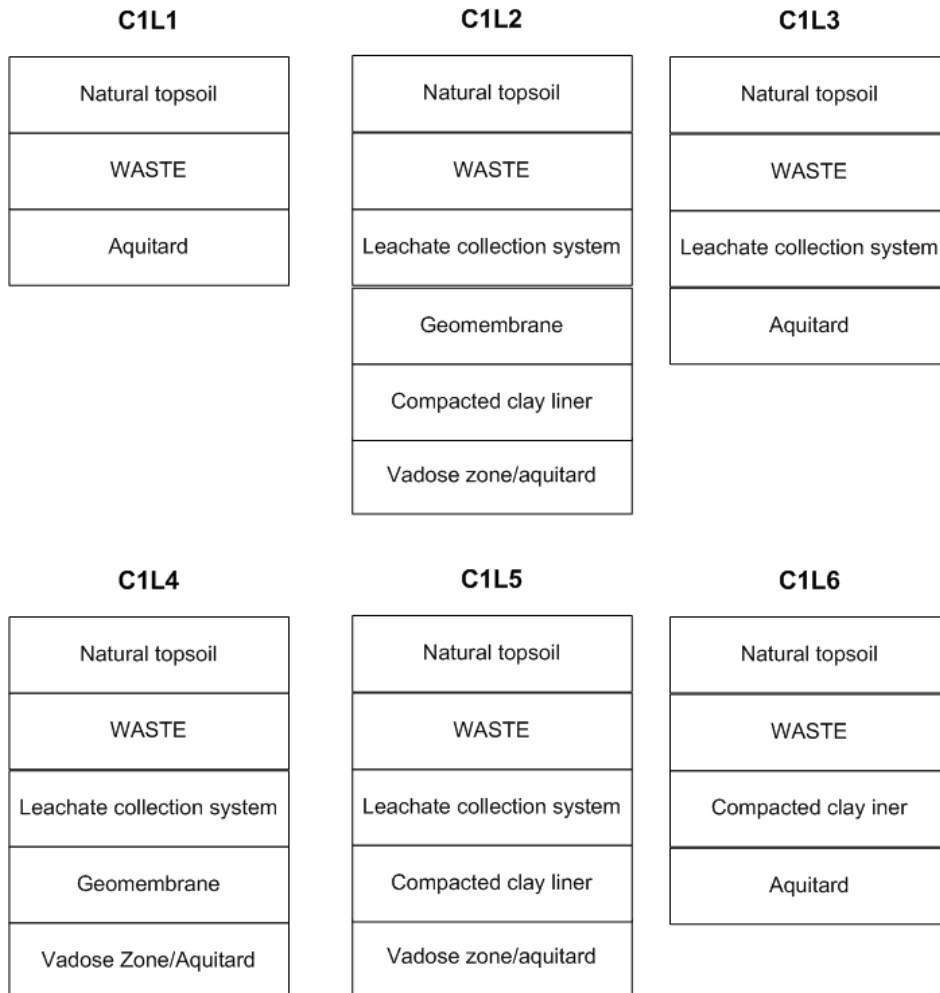


Figure A. 1 Design alternatives having evapotranspiration final cover –C1

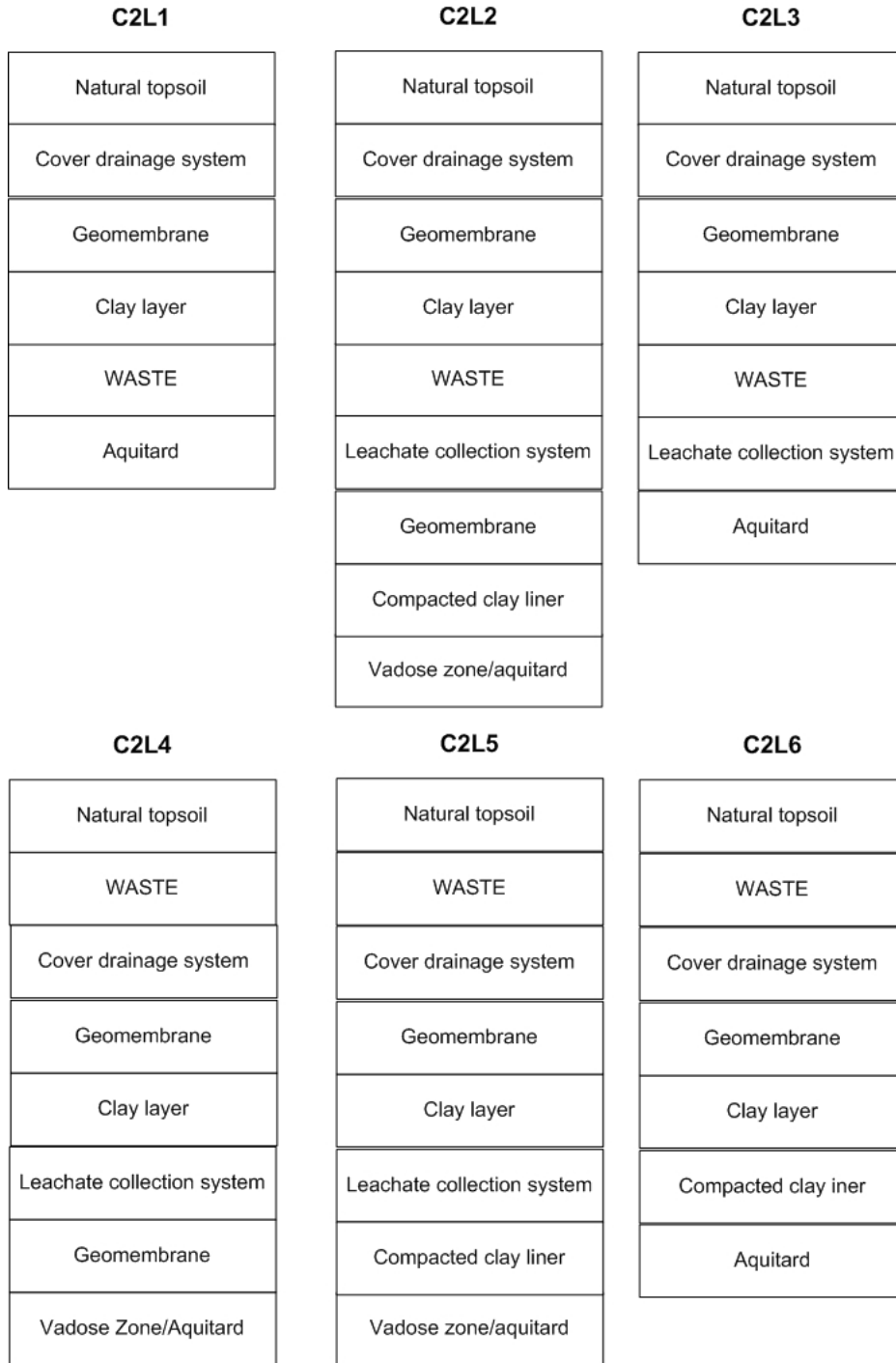


Figure A. 2 Design alternatives having extensive engineering design final cover –C2

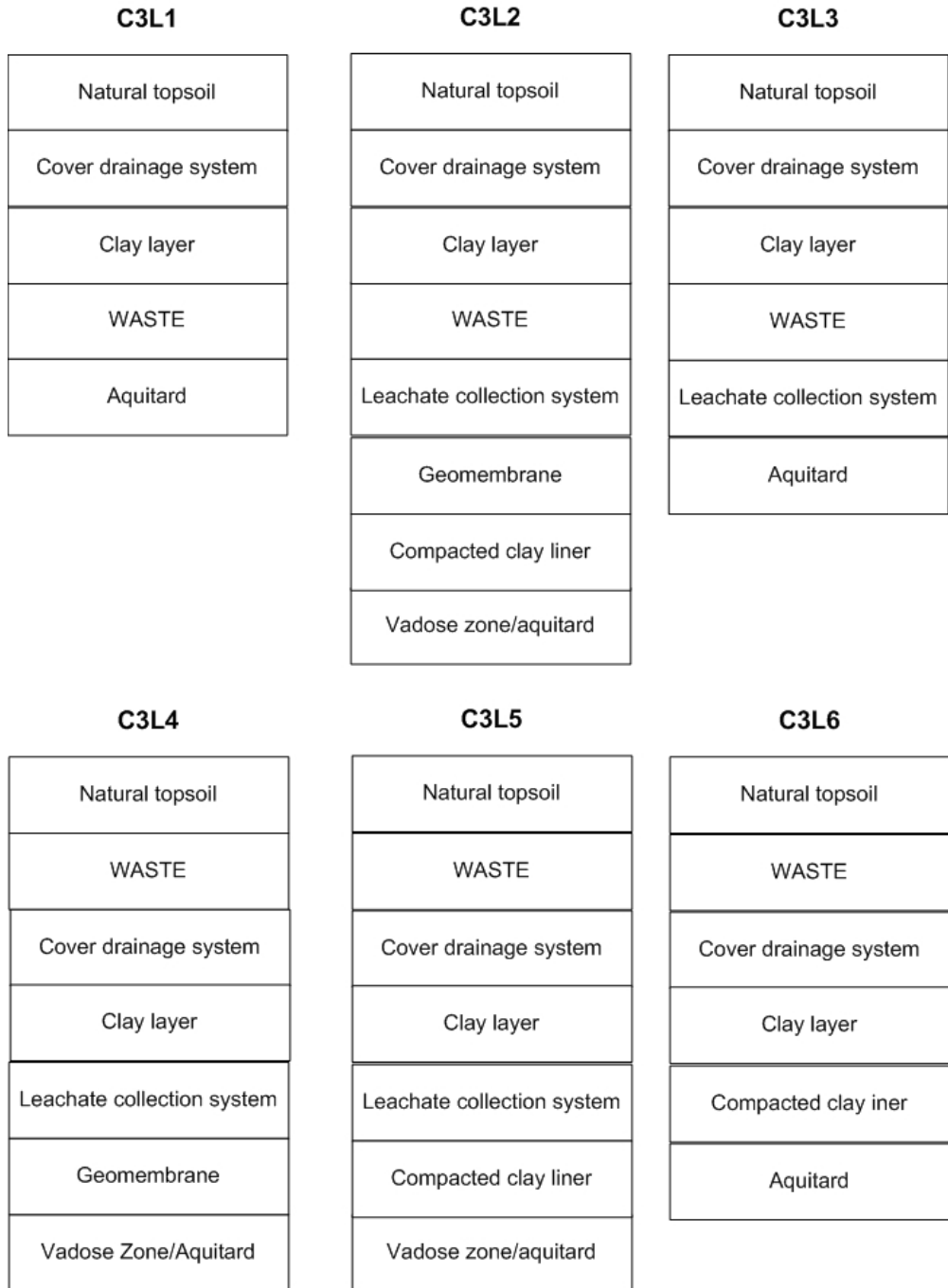


Figure A. 3 Design alternatives having intermediate design final cover –C3

APPENDIX-B

TECHNICAL DOCUMENTATION FOR LANDFILL DECISION SUPPORT SYSTEM (LFDSS)

Landfill Decision Support System (LFDSS) is a decision support system application developed in order to aid the user in solid waste landfill design. LFDSS was developed in C# programming language based on “Windows Forms” visual user interface library. The programme operates on Windows 2000 or higher; however, it is anticipated that the programme may perform under different operating environment (such as Linux, MacOS, etc.) with small changes, except for HELP and POLLUTE. LFDSS accommodates six modules: Preliminary Design, HELP, POLLUTE, Stability, Cost, and Volume Calculation. This section presents technical and design data of each module.

B.1. Preliminary Design

“Preliminary Design” is a tool that proposes how the layers in a particular landfill design should be, based on user defined parameter values for design variables (i.e. thickness, velocity, size, and climate) (Figure B.1). The proposed landfill designs are selected from the previously identified design alternatives.

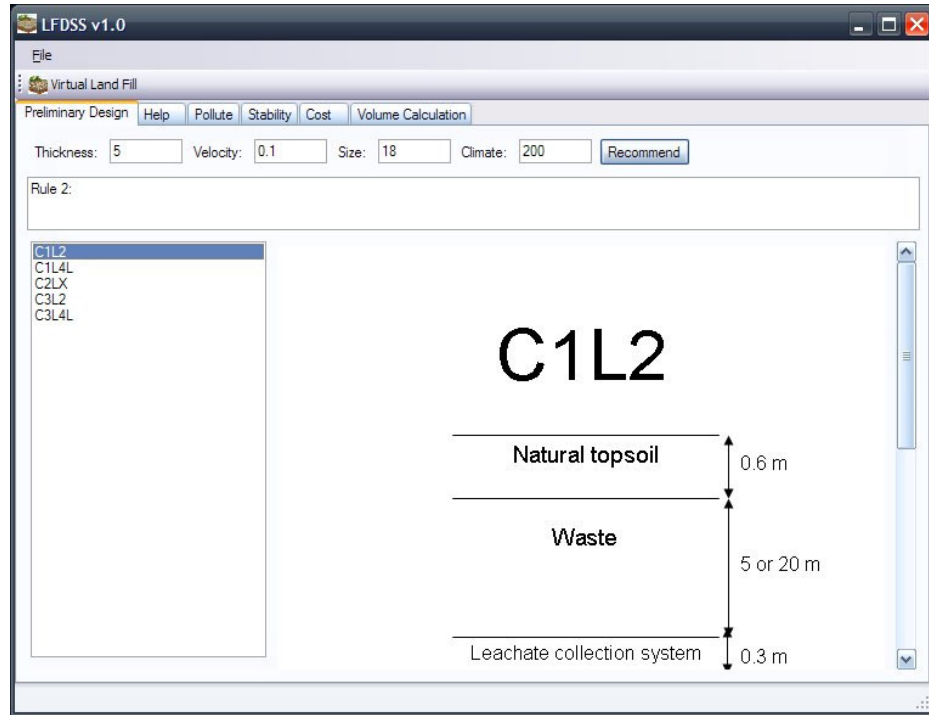


Figure B. 1 Preliminary Design module in LFDSS

Preliminary Design tool is composed of a *backend* that defines the design alternatives proposed under particular conditions, and a *frontend* that presents the design alternatives visually to the user. Backend is basically a rule-interpreter. Each rule is a mathematical expression which identifies the restrictions on parameter values (i.e. being smaller than/smaller than or equal to/greater than/greater or equal to/equal to a certain value). More than one restriction can be defined for the any parameter. These rules, restrictions for different parameters, are defined to be separated by commas (,) (e.g. climate=500,thickness=5,velocity=0.1,size>2,size<15), and read from a file called “rules.txt” to allow for easy upgrade. Backend loads the rules contained by the file in the given order, forms the respective mathematical expression, and checks whether the consistency of the user defined parameters with the rule for each rule. Any consistent rule is performed by frontend. There are two actions defined: displaying a message or displaying a landfill design alternative. Actions are

defined as separated by semicolons (;) at the end of the rule statement. If a message is to be displayed, the definition is in the shape of a message text contained within double quotation marks (“ ”) (e.g. “USE DOUBLE LINER SYSTEMS”). If a landfill design alternative is to be displayed, the definition is made by stating the corresponding cells in a comma separated value (CSV) spreadsheet file. For example, a definition in the form of *mod.csv:A2-A5* states that the corresponding cells are formed by the values contained *between 2nd and 5th rows of column A of file mod.csv*. This definition format allows easier rule – landfill design matching, especially when there are more than one rule for a special group of cells. Spreadsheet files in CSV format can easily be created and arranged using spreadsheet software (e.g. MS Excel or Openoffice) or a text editor. An example for a rule file is give in Figure B.2.

```
climate=500,thickness=5,velocity=0.1,size>2,size<15; "USE  
DOUBLE LINER SYSTEMS"  
climate=200,thickness=5,velocity=0.1,size>15; mod.csv:A2-A5
```

Figure B. 2 A rule file defined in preliminary design module in LFDSS

Frontend performs the action and displays it to the user when a matching rule is found. If the action is displaying a message, this message is displayed at the top of the Preliminary Design page together with the rule number. If the action is displaying a schematic view of the landfill design, the list of design alternatives is displayed on the left hand-side of the page. When any of the listed designs is selected by the user, a schematic view belonging to that particular design is displayed on the page. These schemes are loaded from image files contained in *images* folder under LFDSS operating folder (Figure B.1). Image files should be in PNG format and have the same name as the design alternative. Instead of embedding the images into the software, they are read from a folder specified by the user; therefore, addition of new designs is allowed when new landfill design

alternatives are defined. Image files in PNG format can easily be created and arranged using imaging software (e.g. Paint).

B.2. HELP

Hydrologic Evaluation of Landfill Performance (HELP) is a software developed for hydrologic evaluation of landfill performance. HELP operates under MSDOS operating system; therefore, fast and easy definition of input data is not possible under up-to-date operating systems. HELP software under LFDSS compensates this drawback and automatically calculates the infiltration rate input data required for landfill design calculations. HELP is composed of six sub-modules: “Soil&Design”, “Evapotranspiration”, “Precipitation”, “Temperature”, and “Solar Radiation”. Each module is defined as separate pages under a tab view, and allows entering required input or uploading HELP input files (Figure B.3).

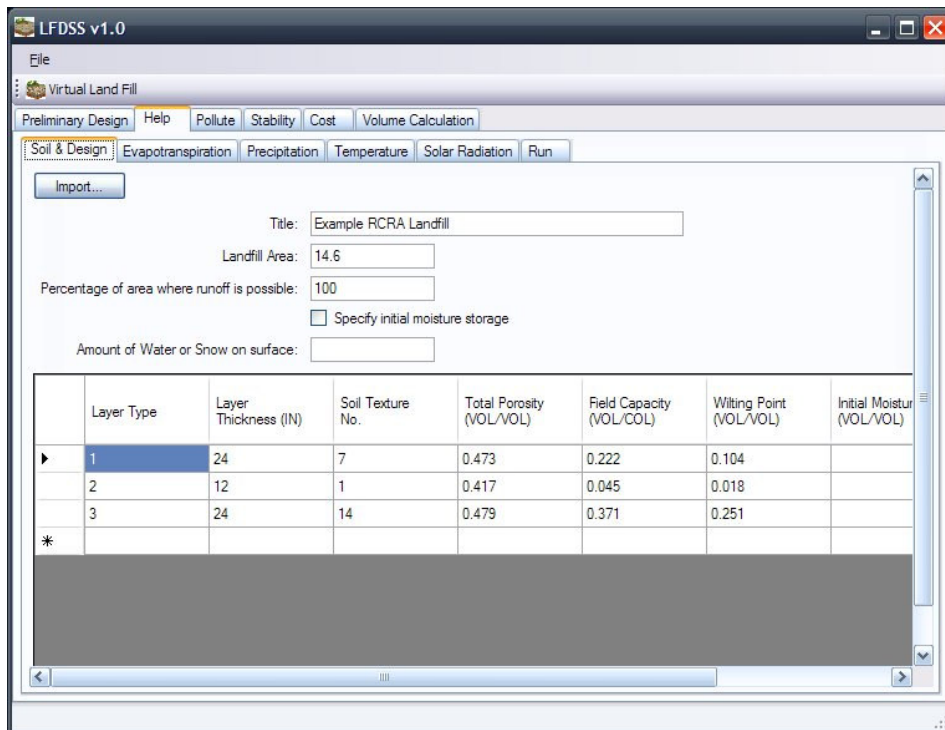


Figure B. 3 HELP module under LFDSS

HELP input data are stored under text files with different formats. To upload these data and to create similar files before running the model, the file formats were examined, the way that HELP stores the data within each file format was determined, and parsers to read those data and savers to record the data were developed. LFDSS stores user-defined or uploaded data in a single file in XML format. This allows processing of data by other software, and easy transfer of data. Data can be saved on the current file via “Save” option, or on another file via “Save as” option, under *File* menu. Data stored in a particular file can be re-loaded using “Load” option. Once the input data are entered, and the user selects “Run” option under Run sub-module, the data are transferred to the format that can be processed by HELP, and then, depending on the user-defined parameters (e.g. number of years to simulate), HELP is run as a separate process and “infiltration rate” data is separated from the processed output. The value of “infiltration rate” is displayed to the user in the related box (Figure B.4). Moreover, it is transferred to POLLUTE module.

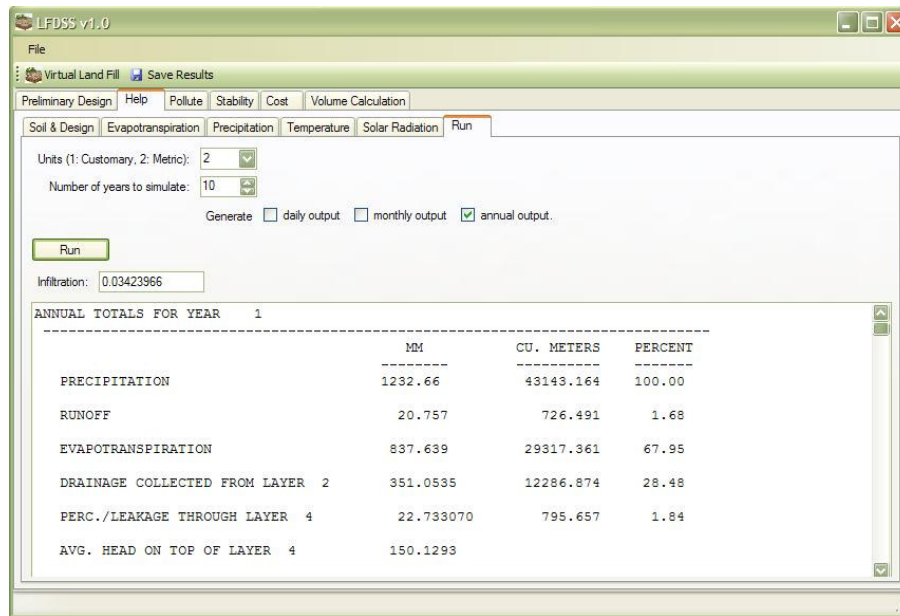


Figure B. 4 Run sub-module under HELP in LFDSS

B.3. POLLUTE

POLLUTE is a software developed for contaminant migration analyses and the code operates under Microsoft Windows operating system. To perform analyses using this software, first a model is required to be set and input data related to that model are required to be entered in multiple dialog boxes. This is a time consuming process for the user. POLLUTE module under LFDSS is capable of running POLLUTE software automatically based on infiltration rate data obtained from HELP model and other user-defined input, calculating maximum contaminant concentration at the groundwater table and saving the result to a text file, and displaying the POLLUTE result report of contaminant concentrations at specified times. In maximum concentrations analysis, the text file that is created as a result of the analysis is displayed to the user automatically. POLLUTE module consists of three sub-modules. The first sub-module (parameters) allows the user to select landfill bottom liner components and to enter input parameters belonging to the selected components (Figure B.5). Infiltration rate data, which is one of the parameters, is obtained via HELP module using HELP software, and transferred to POLLUTE automatically.

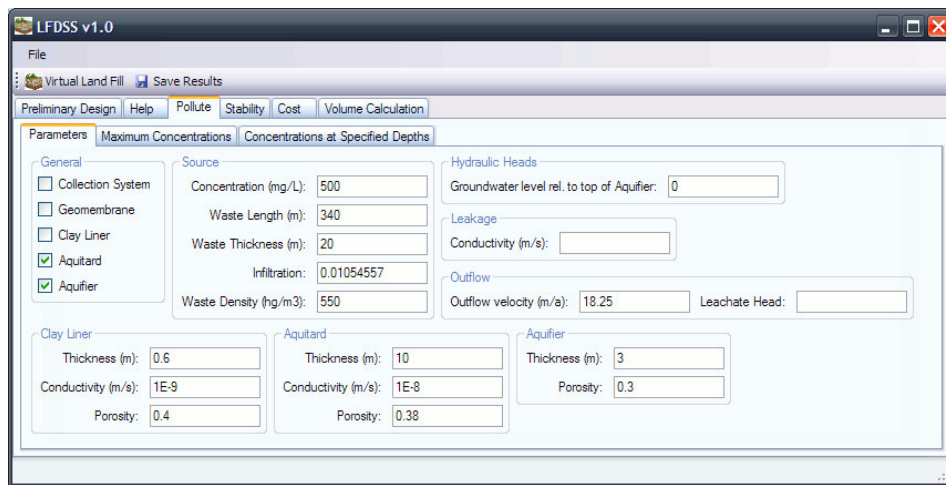


Figure B. 5 POLLUTE module in LFDSS –Parameters sub-module

Using the second sub-module (maximum concentrations), parameters belonging to maximum concentration analyses is entered and the maximum concentrations file is obtained (Figure B.6.a). The third sub-module (concentration at specified times) allows the user to enter input parameters to obtain concentrations at specified times. (Figure B.6.b)

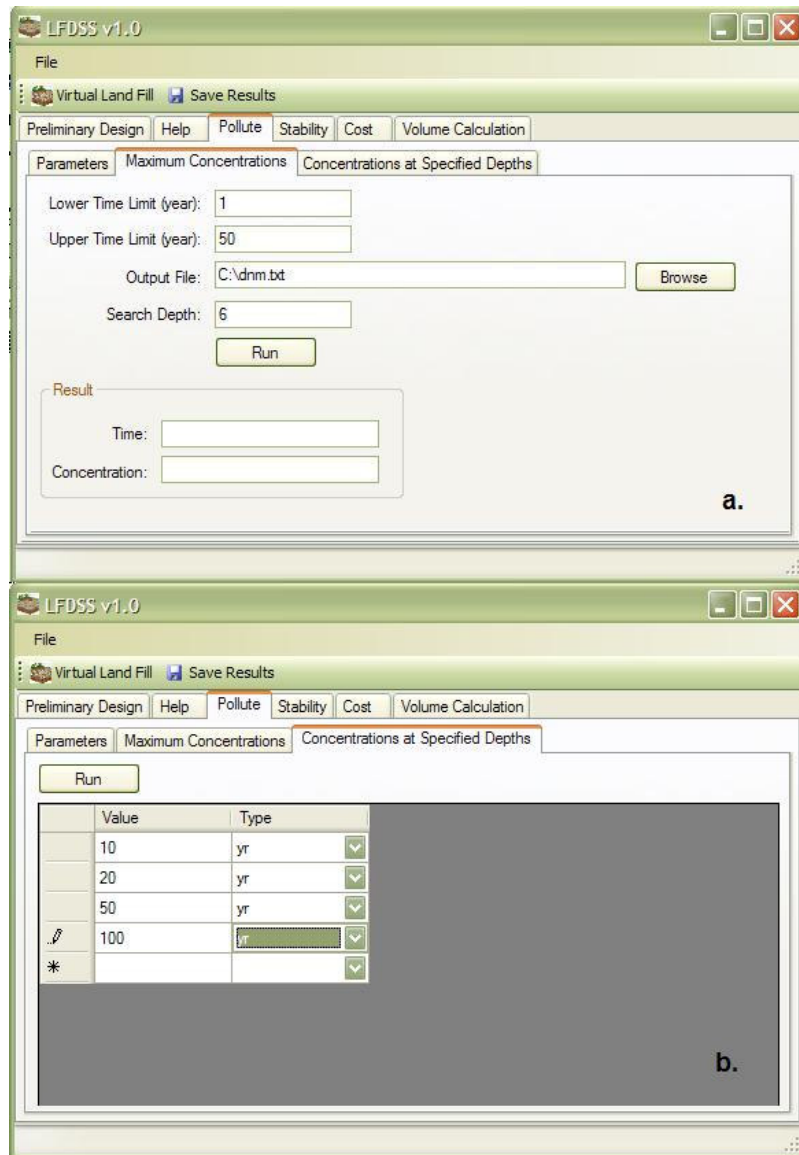


Figure B. 6 POLLUTE module in LFDSS. a. Maximum concentrations sub-module. b. concentrations at specified times sub-module

Normally, POLLUTE programme does not allow commands outside the programme, and it does not have external support for parameter entry. To establish interaction between LFDSS and POLLUTE, a free software called *AutoIt* was used. This programme defines macros to any programme running under Microsoft Windows operating system, and allows sending external windows messages, and keyboard or mouse commands, as if it is being used by a real user. In other words, it allows automation. AutoIt has a script language similar to BASIC language, developed for this purpose. First, steps to be followed while creating models and entering input parameters were identified in POLLUTE programme, then windows elements required to receive commands were determined, and scripts that enter input parameters to the related window elements based on the type of analysis in the identified order were developed. These scripts are given in the Annex. AutoIt can create an EXE file that runs independently from a defined script file. When the user selects “Run” under any of the analysis sub-modules (i.e. maximum concentrations, or concentrations at specified times), LFDSS stores the related parameters in a text file, having a format that can be read by the script file, and as a separate process, first runs POLLUTE programme and then runs the EXE file of the related type of analysis created by AutoIt. When POLLUTE is closed by completing the analysis process, if the maximum analysis sub-module is selected, LFDSS displays the output file to the user as a text file. The basic advantage of using AutoIt programme to establish interaction between LFDSS and POLLUTE is the ability of supporting the new versions of POLLUTE by updating the script file only without requiring any changes in LFDSS programme.

B.3.1. Annex –Scripts for POLLUTE

B.3.1.1. *Maximum Concentrations Sub-Module*

```
; Wait for activation
Dim $params
Dim $iniFile = "LFSim_Pollute.ini"
Dim $title

Func GetParam($name)
    Dim $n = $params[0][0]
    Dim $i
    For $i = 1 to $n
        If $params[$i][0] == $name Then
            Return $params[$i][1]
        EndIf
    Next
    Return ""
EndFunc

Func CheckBox($name)
    ControlCommand($title, "", $name, "Check")
EndFunc

Func TextBox($name, $val)
    ControlSetText($title, "", $name, GetParam($val))
EndFunc

$params = IniReadSection($iniFile, "Parameters")
if @error == 1 Then
    MsgBox(0, "Error", "Unable to open " & $iniFile & ". Please check your
installation.")
    Exit
EndIf

FileDelete("leachate_head.txt")

WinWaitActive("POLLUTE")
Send("{Enter}")
Sleep(200);
; Open project
Send("!f");
Send("p");
Send("o");
WinWaitActive("Open Project");
Send("{Enter}");
; Open model
```

```

Send("!f");
Send("m");
Send("o");
Send("{Enter}");
; Open parameters dialog
Send("!d");
Send("m");
$title = "Vertical Migration"
WinWaitActive($title);
; Set general parameters
If GetParam("CollectionSystem") == "True" Then
    CheckBox("TGroupBox1")
Else
    CheckBox("TGroupBox2")
EndIf
If GetParam("Geomembrane") == "True" Then
    CheckBox("TGroupBox11")
Else
    CheckBox("TGroupBox12")
EndIf
If GetParam("ClayLiner") == "True" Then
    CheckBox("TGroupBox9")
Else
    CheckBox("TGroupBox10")
EndIf
If GetParam("Aquitard") == "True" Then
    CheckBox("TGroupBox7")
Else
    CheckBox("TGroupBox8")
EndIf
If GetParam("Aquifer") == "True" Then
    CheckBox("TGroupBox5")
Else
    CheckBox("TGroupBox6")
EndIf
; Set source parameters
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TFloatEdit6", "SourceConcentration")
TextBox("TFloatEdit5", "SourceWasteLength")
TextBox("TFloatEdit4", "SourceWasteThickness")
TextBox("TFloatEdit3", "Infiltration")
TextBox("TFloatEdit2", "SourceWasteDensity")
; Set hydraulic heads parameters
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TFloatEdit1", "HydHeadsGroundWater")
; Set geomembrane parameters
If GetParam("Geomembrane") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    ControlCommand($title, "", "TPageControl1", "TabRight")

```

```

        TextBox("TFloatEdit6", "LeakageConductivity")
    EndIf
; Set clay liner parameters
If GetParam("ClayLiner") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit1", "ClayLinerThickness")
    TextBox("TFloatEdit3", "ClayLinerConductivity")
    TextBox("TFloatEdit6", "ClayLinerPorosity")
EndIf
If GetParam("Aquitard") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit6", "AquitardThickness")
    TextBox("TFloatEdit4", "AquitardConductivity")
    TextBox("TFloatEdit1", "AquitardPorosity")
EndIf
If GetParam("Aquifer") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit2", "AquiferThickness")
    TextBox("TFloatEdit1", "AquiferPorosity")
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit1", "OutflowVelocity")
    If (GetParam("CollectionSystem") <> "True") Then
        $head = ControlGetText($title, "", "TEdit1")
        FileWriteLine("leachate_head.txt", $head)
    Endif
EndIf

Send("{Enter}");

Send("!d");
Send("r");
$title = "Run Parameters"
WinWaitActive($title);
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TFloatEdit4", "LowerTime")
TextBox("TFloatEdit3", "UpperTime")
TextBox("TFloatEdit1", "SearchDepth")
Send("{Enter}")

Send("!e")
Send("r")
Sleep(5000)
WinWaitNotActive("Run Model")
Send("!o")
Send("e")
Send("d")
WinWaitActive("Export Output")
ControlCommand("Export Output", "", "TGroupBox17", "Check")
Send("!n")

```

```

Send("!n")
Send("!n")
Send("!n")
Send("!n")
Send("!n")
ControlSetText("Export Output", "", "C:\TEMP\SMEXPORT.TXT",
GetParam("OutputFile"))
Sleep(1000)
Send("{Enter}")
Sleep(1000)
WinWaitNotActive("SMExport 4.10")
WinClose("POLLUTE");

```

B.3.1.2. Concentrations at Specified Times Sub-Module

```

; Wait for activation
Dim $params
Dim $iniFile = "LFSim_PolluteSD.ini"
Dim $title

Func GetParam($name)
    Dim $n = $params[0][0]
    Dim $i
    For $i = 1 to $n
        If $params[$i][0] == $name Then
            Return $params[$i][1]
        EndIf
    Next
    Return ""
EndFunc

Func CheckBox($name)
    ControlCommand($title, "", $name, "Check")
EndFunc

Func TextBox($name, $val)
    ControlSetText($title, "", $name, GetParam($val))
EndFunc

$params = IniReadSection($iniFile, "Parameters")
if @error == 1 Then
    MsgBox(0, "Error", "Unable to open " & $iniFile & ". Please check your
installation.")
    Exit
EndIf

FileDelete("leachate_head.txt")

```

```

WinWaitActive("POLLUTE")
Send("{Enter}")
Sleep(200);
; Open project
Send("!f");
Send("p");
Send("o");
WinWaitActive("Open Project");
Send("{Enter}");
; Open model
Send("!f");
Send("m");
Send("o");
Send("{Enter}");
; Open parameters dialog
Send("!d");
Send("m");
$title = "Vertical Migration"
WinWaitActive($title);
; Set general parameters
If GetParam("CollectionSystem") == "True" Then
    CheckBox("TGroupButton1")
Else
    CheckBox("TGroupButton2")
EndIf
If GetParam("Geomembrane") == "True" Then
    CheckBox("TGroupButton11")
Else
    CheckBox("TGroupButton12")
EndIf
If GetParam("ClayLiner") == "True" Then
    CheckBox("TGroupButton9")
Else
    CheckBox("TGroupButton10")
EndIf
If GetParam("Aquitard") == "True" Then
    CheckBox("TGroupButton7")
Else
    CheckBox("TGroupButton8")
EndIf
If GetParam("Aquifer") == "True" Then
    CheckBox("TGroupButton5")
Else
    CheckBox("TGroupButton6")
EndIf
; Set source parameters
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TFloatEdit6", "SourceConcentration")
TextBox("TFloatEdit5", "SourceWasteLength")

```

```

TextBox("TFloatEdit4", "SourceWasteThickness")
TextBox("TFloatEdit3", "Infiltration")
TextBox("TFloatEdit2", "SourceWasteDensity")
; Set hydraulic heads parameters
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TFloatEdit1", "HydHeadsGroundWater")
; Set geomembrane parameters
If GetParam("Geomembrane") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit6", "LeakageConductivity")
EndIf
; Set clay liner parameters
If GetParam("ClayLiner") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit1", "ClayLinerThickness")
    TextBox("TFloatEdit3", "ClayLinerConductivity")
    TextBox("TFloatEdit6", "ClayLinerPorosity")
EndIf
If GetParam("Aquitard") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit6", "AquitardThickness")
    TextBox("TFloatEdit4", "AquitardConductivity")
    TextBox("TFloatEdit1", "AquitardPorosity")
EndIf
If GetParam("Aquifer") == "True" Then
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit2", "AquiferThickness")
    TextBox("TFloatEdit1", "AquiferPorosity")
    ControlCommand($title, "", "TPageControl1", "TabRight")
    TextBox("TFloatEdit1", "OutflowVelocity")
    If (GetParam("CollectionSystem") <> "True") Then
        $head = ControlGetText($title, "", "TEdit1")
        FileWriteLine("leachate_head.txt", $head)
    EndIf
EndIf

Send("{Enter}");

AutoItSetOption("MouseCoordMode", 2)

Send("!d");
Send("r");
$title = "Run Parameters"
WinWaitActive($title)
; $size = WinGetPos($title)
ControlClick($title, "", "TGroupButton2")
ControlCommand($title, "", "TPageControl1", "TabRight")
TextBox("TIntegerEdit1", "NumberOfTimes")

```

```

$pos = ControlGetPos($title, "", "TComboBox1")
$num = Int(GetParam("NumberOfTimes"))
For $i = 1 to $num
    TextBox("TFloatEdit1", StringFormat("Value%d", $i))
    TextBox("TComboBox1", StringFormat("Type%d", $i))
    MouseClick("left", $pos[0] + 46, $pos[1] - 22)
    Sleep(100)
Next
ControlClick($title, "Yes", "TGroupButton2")

Send("{Enter}")

Send("!e")
Send("r")
Sleep(5000)
WinWaitNotActive("Run Model")
Send("!o")
Send("l")

```

B.4. Stability

Stability module is a tool developed to perform stability analyses of landfills. It is composed of five sub-modules: “Excavation-slope”, “Refuse-fill”, “Cover System”, “Geomembrane Stability”, and “Seismic Forces”. These sub-modules are developed as separate pages in a tab-view. Each sub-module contains a tabular data entry area based on the pre-defined formulae (Figure B.7). Data input via copy-paste from external sources (e.g. MS Excel) is allowed, and a system was developed to separate pasted data into parts and entering the separated data into related boxes. After data input, the user selects the “Calculate” option to easily calculate two factor of safety values for “Excavation-slope” and “Refuse-fill”, four FS values for “Cover System”, and one FS value for “Geomembrane Stability”, and “Seismic Forces”.

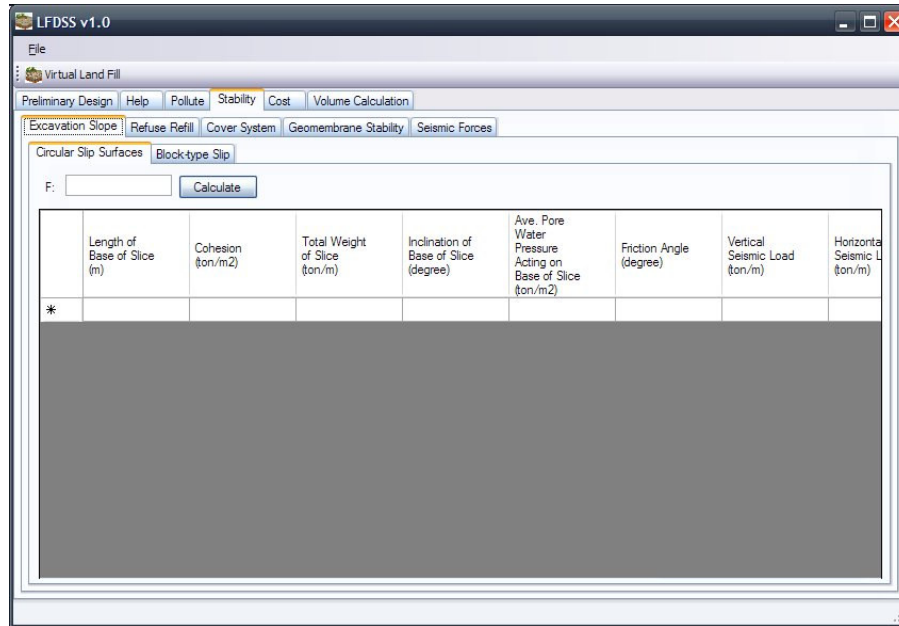


Figure B. 7 Stability module in LFDSS

B.5. Cost

Cost module is a tool for performing major, additional, and total financial landfill analyses for different landfill design components, collected under main headings of “Native Soil”, “Top Soil”, “Drainage”, Clay –Onsite and Offsite”, “Drainage Tile”, “Synthetic Membrane”, “Geotextiles”, and “Vegetative Soil”. A tabular data entry area was defined for each heading/component. These tables display the name of the component, brief description of the processes related to the component, units, and it is possible to enter unit costs and amounts of materials used (Figure B.8). Each table is displayed on the same page to allow the user view the general condition. When the user selects “Calculate”, each component in the tables are scanned and total for components are calculated. Based on the calculated cost, the total cost is summed and displayed in the “Total Main Component Cost” box. The procedure is repeated for additional components as well, and the total cost is written in “Total Additional Component Cost” box. Total landfill construction cost is the sum of main and additional component

costs. The input data can be transferred to other programmes using copy-paste feature.

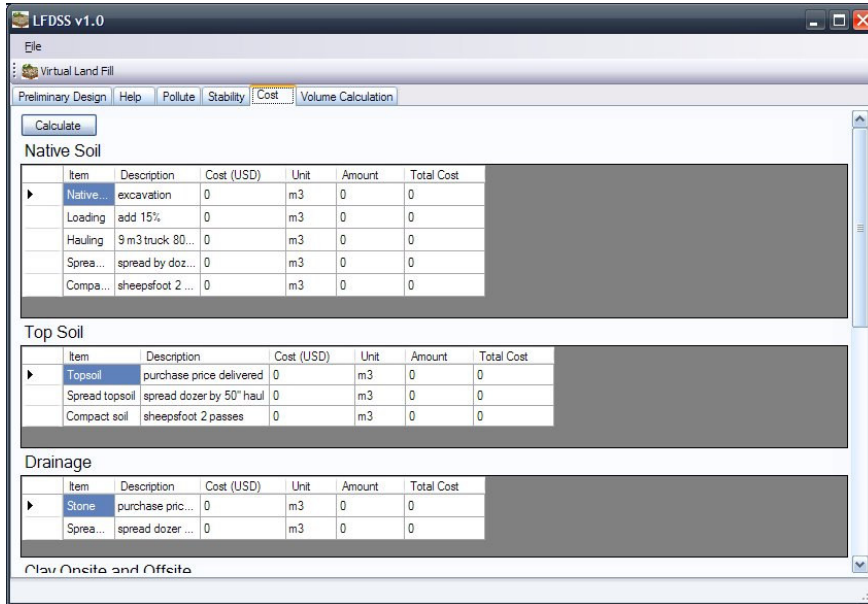


Figure B. 8 Cost calculation module in LFDSS

B.6. Volume Calculation

Volume module is a tool that calculates the required landfill volume based on design parameters such as population, operational lifetime of landfill, waste production rate, waste density, recycling ratio, and daily and intermediate cover ratio. The module contains the related boxes for parameter entry (Figure B.9). When the “Calculate” option is selected, the landfill volume is calculated based on the formulae defined in MS Excel, and the result is displayed to the user. For a reference of waste density, reference waste density values given by the Bank of States (İller Bankası) are presented to the user as guidance at the bottom of the page.

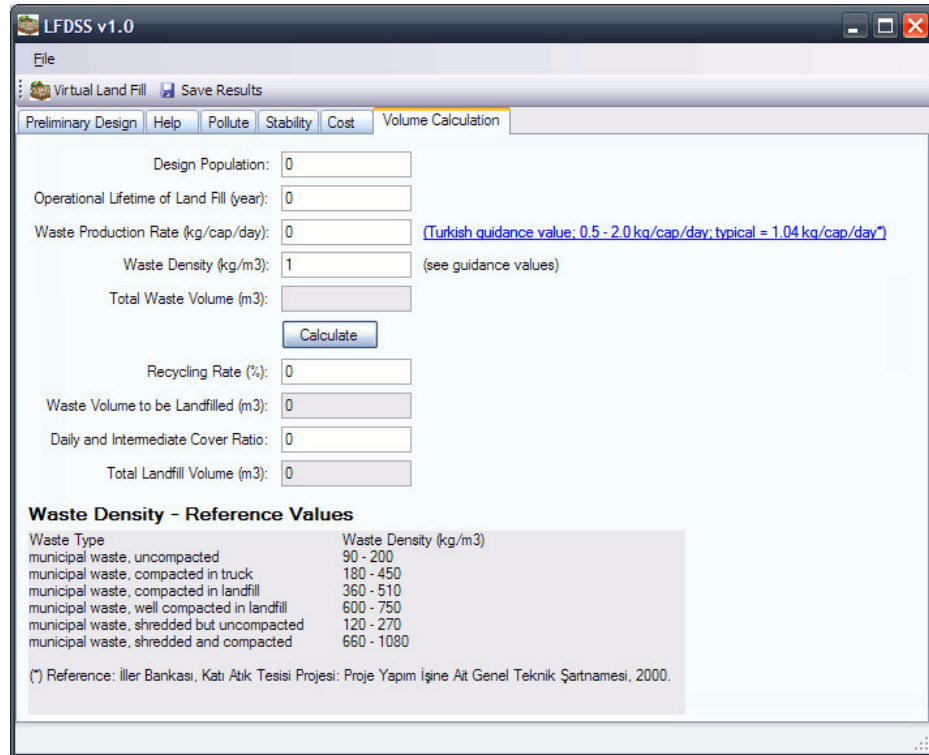


Figure B. 9 Cost module in LFDSS

APPENDIX-C

DESIGN COMPONENT SELECTION MATRIX RULES

1. climate<=500,thickness=5,velocity>0,velocity<=0.05,size<=2;
sample.csv:S1-S5
2. climate<=500,thickness=5,velocity>0.05,velocity<=0.1,size<=2;
sample.csv:T1-T5
3. climate<=500,thickness=5,velocity>0.1,velocity<=0.5,size<=2; "ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
4. climate<=500,thickness=5,velocity>0.5,velocity<=1.0,size<=2; "ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
5. climate<=500,thickness=20,velocity>0,velocity<=0.05,size<=2;
sample.csv:W1-W4
6. climate<=500,thickness=20,velocity>0.05,velocity<=0.1,size<=2;
sample.csv:X1-X5

7. climate<=500,thickness=20,velocity>0.1,velocity<=0.5,size<=2; "ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
8. climate<=500,thickness=20,velocity>0.5,velocity<=1.0,size<=2; "ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
9. climate<=500,thickness=5,velocity>0,velocity<=0.05,size>2,size<=15;
sample.csv:S14-S17
10. climate<=500,thickness=5,velocity>0.05,velocity<=0.1,size>2,size<=15;
sample.csv:T14-T18
11. climate<=500,thickness=5,velocity>0.1,velocity<=0.5,size>2,size<=15;
"ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
12. climate<=500,thickness=5,velocity>0.5,velocity<=1.0,size>2,size<=15;
"ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS! FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6) IS SATISFACTORY!"
13. climate<=500,thickness=20,velocity>0,velocity<=0.05,size>2,size<=15;
sample.csv:W14-W15

14. climate<=500,thickness=20,velocity>0.05,velocity<=0.1,size>2,size<=15;
sample.csv:X14-X17
15. climate<=500,thickness=20,velocity>0.1,velocity<=0.5,size>2,size<=15;
sample.csv:Y14-Y18
16. climate<=500,thickness=20,velocity>0.5,velocity<=1.0,size>2,size<=15;
"ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE
CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS!
FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF
INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6)
IS SATISFACTORY!"
17. climate<=500,thickness=5,velocity>0,velocity<=0.05,size>15,size<=50;
sample.csv:S27-S28
18. climate<=500,thickness=5,velocity>0.05,velocity<=0.1,size>15,size<=50;
sample.csv:T27-T30
19. climate<=500,thickness=5,velocity>0.1,velocity<=0.5,size>15,size<=50;
sample.csv:U27-U31
20. climate<=500,thickness=5,velocity>0.5,velocity<=1.0,size>15,size<=50;
"ALL DESIGN ALTERNATIVES ARE APPROPRIATE FOR THE SITE
CONDITIONS; BUT, SOME OF THEM CAN BE OVERDESIGNS!
FOR ARID CLIMATES, ONLY COVER WITH SOME LEVEL OF
INTENSIVE ENGINEERING (C1L1, C1L6, C2L1, C2L6, C3L1, C3L6)
IS SATISFACTORY!"
21. climate<=500,thickness=20,velocity>0,velocity<=0.05,size>15,size<=50;
sample.csv:W27-W28
22. climate<=500,thickness=20,velocity>0.05,velocity<=0.1,size>15,size<=50
; sample.csv:X27-X28
23. climate<=500,thickness=20,velocity>0.1,velocity<=0.5,size>15,size<=50;
sample.csv:Y27-Y31
24. climate<=500,thickness=20,velocity>0.5,velocity<=1.0,size>15,size<=50;
sample.csv:Z27-Z31

25. climate<=500,thickness=5,velocity>0,velocity<=0.05,size>50;
sample.csv:S40-S41
26. climate<=500,thickness=5,velocity>0.05,velocity<=0.1,size>50;
sample.csv:T40-T41
27. climate<=500,thickness=5,velocity>0.1,velocity<=0.5,size>50;
sample.csv:U40-U43
28. climate<=500,thickness=5,velocity>0.5,velocity<=1.0,size>50;
sample.csv:V40-V44
29. climate<=500,thickness=20,velocity>0,velocity<=0.05,size>50; "USE
DOUBLE LINER SYSTEMS; OR EXTENSIVE ENGINEERING
LANDFILL DESIGN ON CLAYEY SOILS"
30. climate<=500,thickness=20,velocity>0.05,velocity<=0.1,size>50;
sample.csv:X40-X41
31. climate<=500,thickness=20,velocity>0.1,velocity<=0.5,size>50;
sample.csv:Y40-Y43
32. climate<=500,thickness=20,velocity>0.5,velocity<=1.0,size>50;
sample.csv:Z40-Z44
33. climate>500,climate<=1000,thickness=5,velocity>0,velocity<=0.05,size<
=2; sample.csv:A1-A5
34. climate>500,climate<=1000,thickness=5,velocity>0.05,velocity<=0.1,size
<=2; sample.csv:B1-B5
35. climate>500,climate<=1000,thickness=5,velocity>0.1,velocity<=0.5,size<
=2; sample.csv:C1-C7
36. climate>500,climate<=1000,thickness=5,velocity>0.5,velocity<=1.0,size<
=2; sample.csv:D1-D7
37. climate>500,climate<=1000,thickness=20,velocity>0,velocity<=0.05,size
<=2; sample.csv:E1-E5
38. climate>500,climate<=1000,thickness=20,velocity>0.05,velocity<=0.1,siz
e<=2; sample.csv:F1-F5

39. climate>500,climate<=1000,thickness=20,velocity>0.1,velocity<=0.5,size<=2; sample.csv:G1-G7
40. climate>500,climate<=1000,thickness=20,velocity>0.5,velocity<=1.0,size<=2; sample.csv:H1-H7
41. climate>500,climate<=1000,thickness=5,velocity>0,velocity<=0.05,size>2,size<=15; sample.csv:A8-A12
42. climate>500,climate<=1000,thickness=5,velocity>0.05,velocity<=0.1,size>2,size<=15; sample.csv:B8-B12
43. climate>500,climate<=1000,thickness=5,velocity>0.1,velocity<=0.5,size>2,size<=15; sample.csv:C8-C14
44. climate>500,climate<=1000,thickness=5,velocity>0.5,velocity<=1.0,size>2,size<=15; sample.csv:D8-D14
45. climate>500,climate<=1000,thickness=20,velocity>0,velocity<=0.05,size>2,size<=15; sample.csv:E8-E9
46. climate>500,climate<=1000,thickness=20,velocity>0.05,velocity<=0.1,size>2,size<=15; sample.csv:F8-F12
47. climate>500,climate<=1000,thickness=20,velocity>0.1,velocity<=0.5,size>2,size<=15; sample.csv:G8-G12
48. climate>500,climate<=1000,thickness=20,velocity>0.5,velocity<=1.0,size>2,size<=15; sample.csv:H8-H14
49. climate>500,climate<=1000,thickness=5,velocity>0,velocity<=0.05,size>15,size<=50; sample.csv:A15-A18
50. climate>500,climate<=1000,thickness=5,velocity>0.05,velocity<=0.1,size>15,size<=50; sample.csv:B15-B19
51. climate>500,climate<=1000,thickness=5,velocity>0.1,velocity<=0.5,size>15,size<=50; sample.csv:C15-C19
52. climate>500,climate<=1000,thickness=5,velocity>0.5,velocity<=1.0,size>15,size<=50; sample.csv:D15-D21
53. climate>500,climate<=1000,thickness=20,velocity>0,velocity<=0.05,size>15,size<=50; sample.csv:E15-E16

54. climate>500,climate<=1000,thickness=20,velocity>0.05,velocity<=0.1,size>15,size<=50; sample.csv:F15-F16
55. climate>500,climate<=1000,thickness=20,velocity>0.1,velocity<=0.5,size>15,size<=50; sample.csv:G15-G19
56. climate>500,climate<=1000,thickness=20,velocity>0.5,velocity<=1.0,size>15,size<=50; sample.csv:H15-H19
57. climate>500,climate<=1000,thickness=5,velocity>0,velocity<=0.05,size>50; sample.csv:A22-A23
58. climate>500,climate<=1000,thickness=5,velocity>0.05,velocity<=0.1,size>50; sample.csv:B22-B25
59. climate>500,climate<=1000,thickness=5,velocity>0.1,velocity<=0.5,size>50; sample.csv:C22-C26
60. climate>500,climate<=1000,thickness=5,velocity>0.5,velocity<=1.0,size>50; sample.csv:D22-D26
61. climate>500,climate<=1000,thickness=20,velocity>0,velocity<=0.05,size>50; "USE DOUBLE LINER SYSTEMS; OR EXTENSIVE ENGINEERING LANDFILL DESIGN ON CLAYEY SOILS"
62. climate>500,climate<=1000,thickness=20,velocity>0.05,velocity<=0.1,size>50; sample.csv:F22-F23
63. climate>500,climate<=1000,thickness=20,velocity>0.1,velocity<=0.5,size>50; sample.csv:G22-G26
64. climate>500,climate<=1000,thickness=20,velocity>0.5,velocity<=1.0,size>50; sample.csv:H22-H26
65. climate>1000,thickness=5,velocity>0,velocity<=0.05,size<=2; sample.csv:J1-J5
66. climate>1000,thickness=5,velocity>0.05,velocity<=0.1,size<=2; sample.csv:K1-K5
67. climate>1000,thickness=5,velocity>0.1,velocity<=0.5,size<=2; sample.csv:L1-L5

68. climate>1000,thickness=5,velocity>0.5,velocity<=1.0,size<=2;
sample.csv:M1-M7
69. climate>1000,thickness=20,velocity>0,velocity<=0.05,size<=2;
sample.csv:N1-N5
70. climate>1000,thickness=20,velocity>0.05,velocity<=0.1,size<=2;
sample.csv:O1-O5
71. climate>1000,thickness=20,velocity>0.1,velocity<=0.5,size<=2;
sample.csv:P1-P5
72. climate>1000,thickness=20,velocity>0.5,velocity<=1.0,size<=2;
sample.csv:Q1-Q5
73. climate>1000,thickness=5,velocity>0,velocity<=0.05,size>2,size<=15;
sample.csv:J8-J11
74. climate>1000,thickness=5,velocity>0.05,velocity<=0.1,size>2,size<=15;
sample.csv:K8-K12
75. climate>1000,thickness=5,velocity>0.1,velocity<=0.5,size>2,size<=15;
sample.csv:L8-L12
76. climate>1000,thickness=5,velocity>0.5,velocity<=1.0,size>2,size<=15;
sample.csv:M8-M12
77. climate>1000,thickness=20,velocity>0,velocity<=0.05,size>2,size<=15;
sample.csv:N8-N11
78. climate>1000,thickness=20,velocity>0.05,velocity<=0.1,size>2,size<=15;
sample.csv:O8-O11
79. climate>1000,thickness=20,velocity>0.1,velocity<=0.5,size>2,size<=15;
sample.csv:P8-P12
80. climate>1000,thickness=20,velocity>0.5,velocity<=1.0,size>2,size<=15;
sample.csv:Q8-Q12
81. climate>1000,thickness=5,velocity>0,velocity<=0.05,size>15,size<=50;
sample.csv:J13-J16
82. climate>1000,thickness=5,velocity>0.05,velocity<=0.1,size>15,size<=50;
sample.csv:K13-K16

83. climate>1000,thickness=5,velocity>0.1,velocity<=0.5,size>15,size<=50;
sample.csv:L13-L17
84. climate>1000,thickness=5,velocity>0.5,velocity<=1.0,size>15,size<=50;
sample.csv:M13-M17
85. climate>1000,thickness=20,velocity>0,velocity<=0.05,size>15,size<=50;
sample.csv:N13-N14
86. climate>1000,thickness=20,velocity>0.05,velocity<=0.1,size>15,size<=50
; sample.csv:O13-O16
87. climate>1000,thickness=20,velocity>0.1,velocity<=0.5,size>15,size<=50;
sample.csv:P13-P17
88. climate>1000,thickness=20,velocity>0.5,velocity<=1.0,size>15,size<=50;
sample.csv:Q13-Q17
89. climate>1000,thickness=5,velocity>0,velocity<=0.05,size>50;
sample.csv:J18-J20
90. climate>1000,thickness=5,velocity>0.05,velocity<=0.1,size>50;
sample.csv:K18-K20
91. climate>1000,thickness=5,velocity>0.1,velocity<=0.5,size>50;
sample.csv:L18-L22
92. climate>1000,thickness=5,velocity>0.5,velocity<=1.0,size>50;
sample.csv:M18-M22
93. climate>1000,thickness=20,velocity>0,velocity<=0.05,size>50;
sample.csv:N18-N19
94. climate>1000,thickness=20,velocity>0.05,velocity<=0.1,size>50;
sample.csv:O18-O19
95. climate>1000,thickness=20,velocity>0.1,velocity<=0.5,size>50;
sample.csv:P18-P22
96. climate>1000,thickness=20,velocity>0.5,velocity<=1.0,size>50;
sample.csv:Q18-Q22

APPENDIX-D

TECHNICAL DOCUMENTATION FOR VIRTUAL LANDFILL (VLF)

VLF is developed for the purpose of virtual landfill base contour design on digital maps. It is written on .NET Framework using C#, based on “Windows Forms” visual user interface library. The programme operates on Windows 2000 or higher and developed using Microsoft Visual 2005. It is anticipated that the programme may perform under different operating environment (such as Linux, MacOS, etc.) via Mono project (Mono, 2007). The general view of the programme is given in Figure D.1.

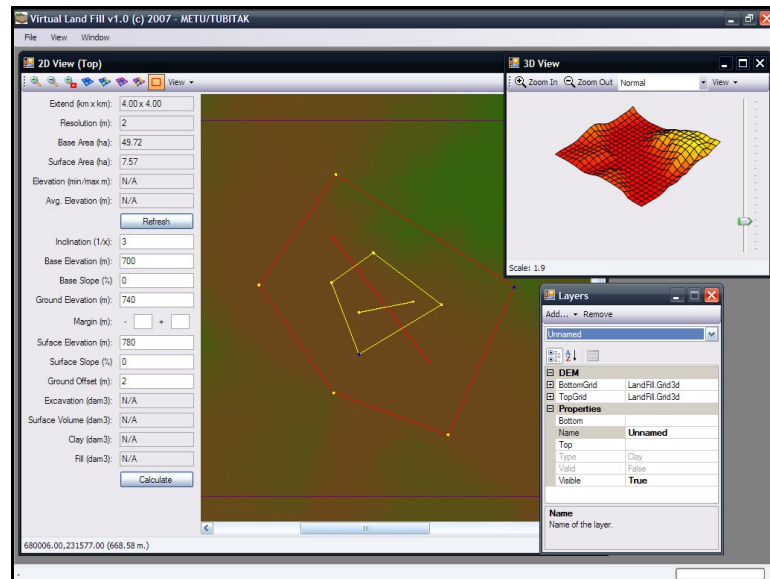


Figure D. 1 General view of VLF

VLF can perform the operations listed below:

- i. Unlimited number of 3 dimensional topographic, clay layer, and groundwater layer maps of the site for landfill construction can be uploaded to the model (the number of maps are actually limited by the capacity of the computer).
- ii. Topographic map and landfill can be viewed both in 2 and 3 dimensions; whereas, other layers (i.e. clay and groundwater) can be viewed in 2 dimensions.
- iii. On the 2 dimensional topographic map, landfill base and final cover can be drawn in any kind of geometric shape. Also, the slope directions of both landfill base and final cover can be identified.
- iv. Based on the shape, dimensions, and slopes of the landfill, excavation and fill processes on the site and the final view of the site after the landfill is placed can be viewed both in 2D and 3D.

D.1. VLF Technical Details

VLF is based on Single document interface (SDI)/Multiple view approach. This approach allows the user to view the working area in different shapes and properties while working on a single landfill. For this purpose, 2 and 3D views are included in the software.

Primarily, topographic information of the site is required to place the landfill on the site and to perform volume calculations. Site elevation information can be uploaded to VLF in USGS Digital Elevation Model format. For this purpose, a parser was written to process text-based ASCII DEM files. DEM files to be uploaded must be converted to metric projection to be used in the calculations. There are no limitations for resolution or size of the DEM data. Elevation data of particular points only on a regular grid of the site are present in DEM files. In grid

class, there are functions that calculate the elevation of any point in the site using elevation data of points nearby the point of interest, by interpolation. By this way, the resolution of the topographic data and calculations are independent of each other. Elevation data can be uploaded to the programme using “File/Import Base DEM” menu. The working area is shown in 2D and 3D after the upload process is completed.

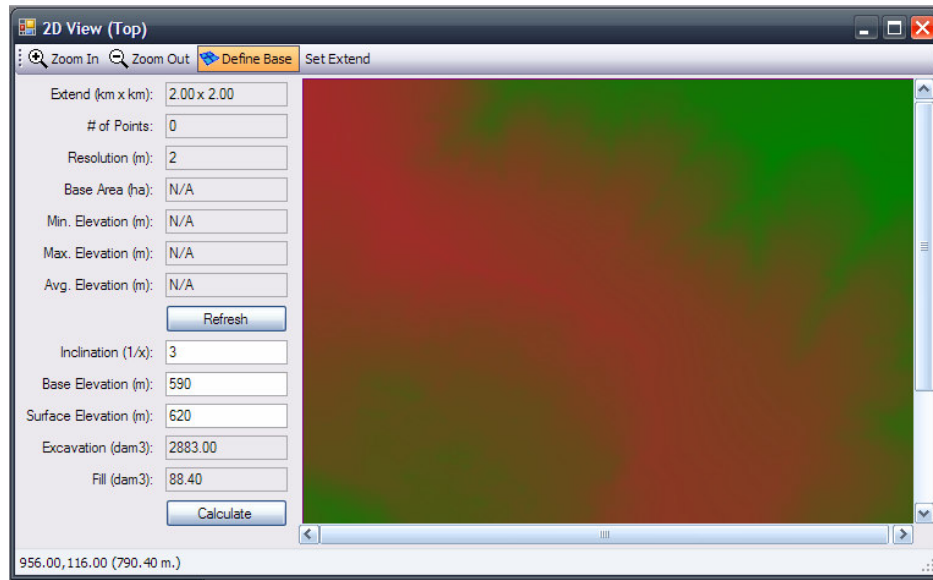


Figure D. 2 Displaying the elevation (topographic map) in VLF

To display the elevation map, instead of point-by-point drawing using DEM data each time, a bitmap view is formed by processing DEM data only once. The size of the bitmap is the same as DEM data, higher elevations are colored in green whereas lower elevations are colored in brown. This bitmap is printed on the screen to display the elevation map. This enables faster display. Site map can be zoomed in or zoomed out using “zoom in” and “zoom out” buttons in the toolbar (Figure D.3). Zoom in and zoom out functions are performed using “scale transform” function of “Graphics” class in .NET Framework.

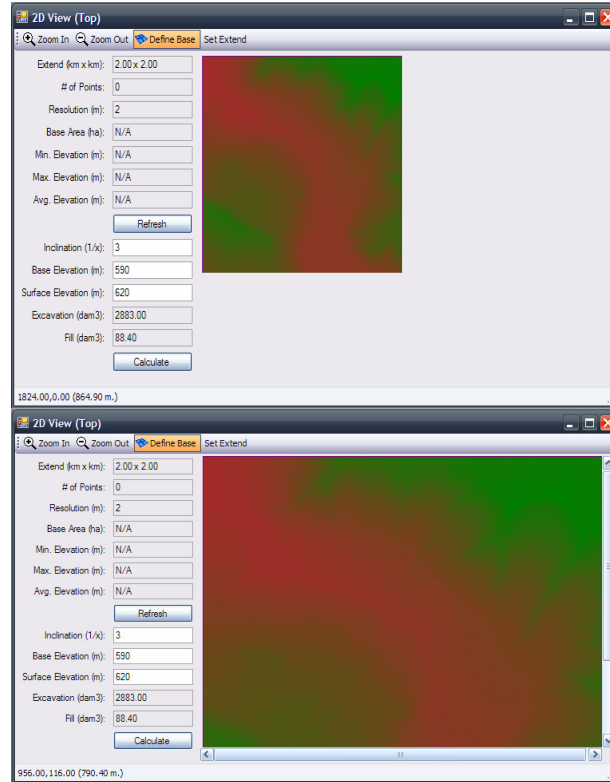


Figure D. 3 Zoom in and Zoom out functions

Landfill base area can be defined on the site using “Define Base” button. Base area can be defined as a polygon, which can either be concave or convex. While the “define base” button is clicked, the edges of the polygon are defined using left-button of the mouse on the desired points around the site. Right-click of the mouse takes the last selected point back (Figure D.4). To ease the point selection process, coordinates and elevation of the point that the cursor is on is shown instantaneously on the status bar.

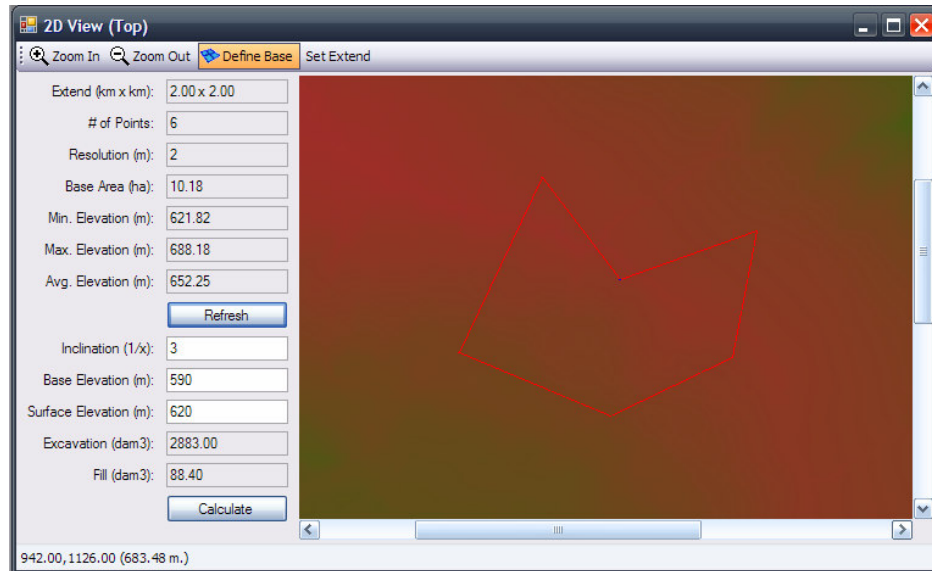


Figure D. 4 Defining landfill base area

Using “Refresh” button in the knowledge sheet, minimum, maximum, and average elevation of the base can be calculated. A class called “Polygon” was written to process polygonal data. Points forming the polygon are stored as float data type. VLF can perform various calculations on the inner area of the polygon; such as finding the minimum elevation of the base, calculating cut and fill volumes, etc. To perform these calculations, the points included by the polygon need to be determined. The simplest way to achieve this is to check whether or not a particular point is inside the polygon. However, this is an inefficient and time-consuming way. Instead, *scanline conversion* method is used. The polygon is scanned from top to bottom, the points intersecting a horizontal line are determined and the lines between these points are processed (Figure D.5). Therefore, unnecessary points are not processed. For this purpose, a generic scanline conversion algorithm that supports active edge list based convex polygons was written in Polygon class. This algorithm is used to calculate minimum, maximum, and average elevations of the base.

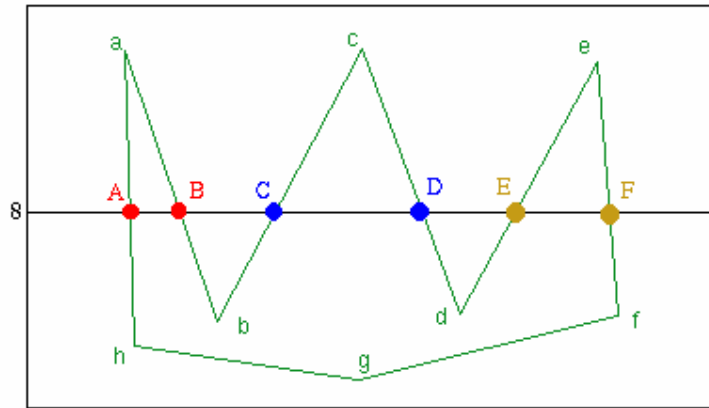


Figure D. 5 Scanline conversion method

Once the landfill base is defined, it is possible to perform volume calculations by entering the values into the bottom part of the knowledge sheet. These parameters are base elevation, surface elevation and inclination/slope. Slope is defined as the ratio of depth to length (Figure D.6).

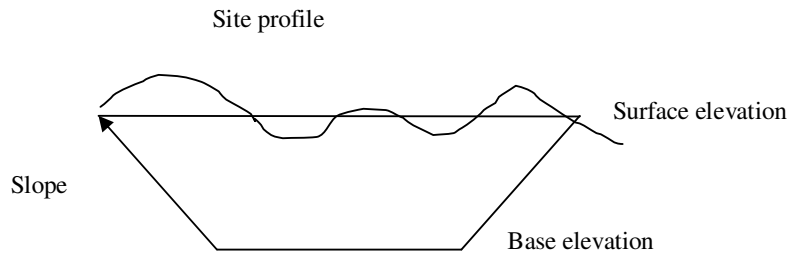


Figure D. 6 Site parameters

Minimum, maximum and average elevations can be used while determining the site parameters. After the values of the site parameters are entered, cut and fill volumes are calculated pressing “Calculate” button. Cut volume is displayed in the “excavation” part and fill volume is displayed in the “fill” part of the knowledge sheet in cubic decameters. Areas to be excavated are shown in light blue, whereas, areas to be filled are shown in dark blue. Calculations are

performed with 1 m sensitivity. These areas are determined using scanline conversion method by calculating the elevation difference between surface elevation and base elevation. Then, for all the sides of the base area, outward horizontal projection is taken and calculations are performed for these areas. For the edges, angular scanning is used to determine the intermediate points and the areas staying between the projections of the adjacent sides are calculated inside the polygons formed by these points (Figure D.7).

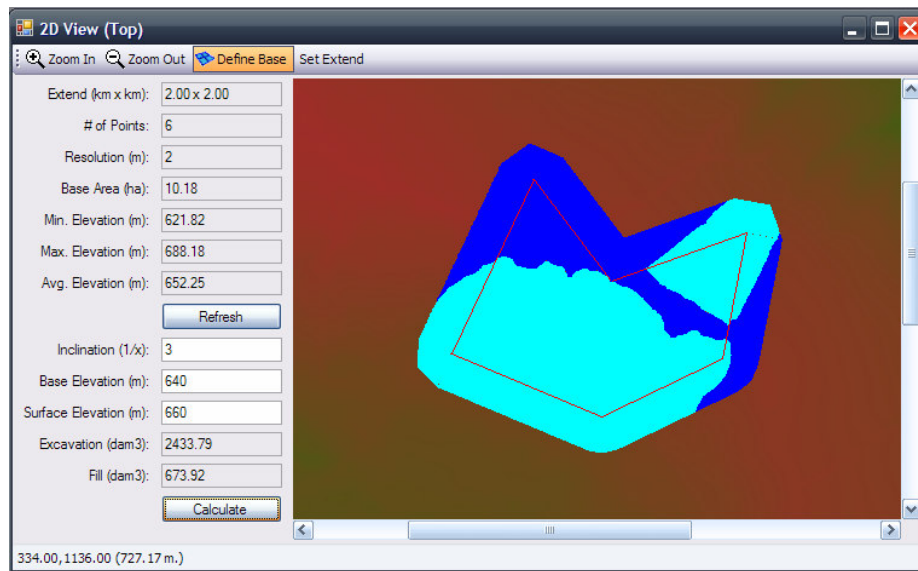


Figure D. 7 Cut and fill calculation results

As the polygon can be convex or concave, it is possible that the horizontal projections of different sides can coincide with each other and inner area of the polygon (Figure D.8). To eliminate miscalculations due to this phenomenon (multiple calculations of a single point), a matrix with 1 m sensitivity around the landfill site is created and calculation results are recorded in this matrix. Calculations are not repeated for the previously recorded elements. To accelerate the display on elevation map, a bitmap is created from the matrix and used in printing on the screen.

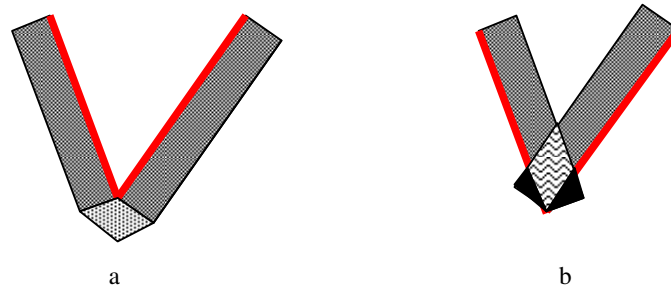


Figure D. 8 (a) Empty edges as a result of horizontal projection (lighter shades) (b) Areas that coincide (waving shades) and rest in the polygon (black shades) as a result of horizontal projection

3D view of any working area can be obtained in VLF. For this purpose, a class that supports surface-based display (Surface3Drenderer) is used. 3D display calculations are performed without using any 3D drawing library (i.e. OpenGL or Direct3D); therefore, the system is able to operate under any platform and with low requirements. For 3D display, particular points are sampled from a regular grid area and adjacent points are linked to each other by a plane. 2 dimensional projections are taken using virtual aspect and direction of the user while drawing the planes. Higher quality views can be obtained by changing the sampling intervals (Figure D.9).

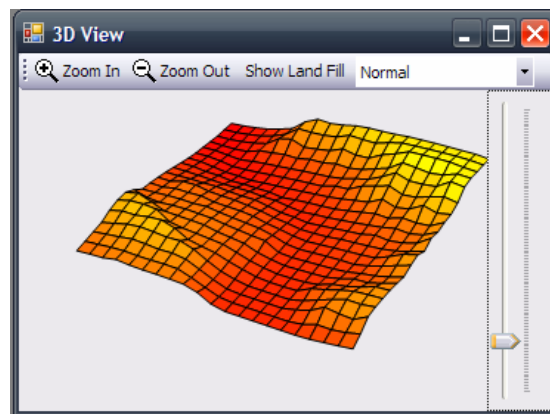


Figure D. 9 3D view

Using “zoom in” and “zoom out” buttons on the tool bar at the top of the 3D view window, it is possible to approach to the site. It is possible to rotate and view the site from different aspects by moving the mouse while the left button is clicked. Using the pull down menu on the right hand side of the toolbar, sampling and display quality (low to high) can be selected. The cursor on the right hand side of the window can be slid to exaggerate elevation differences up to 10 times (Figure D.10).

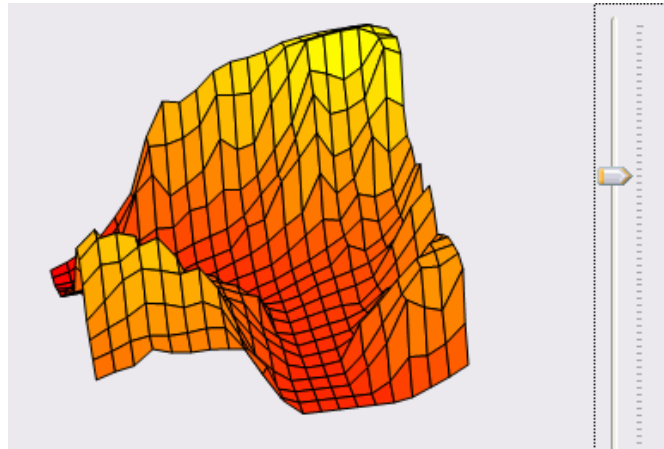


Figure D. 10 Exaggerated elevation difference

The calculated landfill is displayed in 3D on the site when “Show Landfill” button on the toolbar is clicked (Figure D.11). It is also possible to view only a part of the site (e.g. landfill) in 3D. The desired rectangular area is selected using “Set extend” button in the toolbar of 2D display window. While the button is selected, upper left and lower right corners of the rectangle are defined by left clicking the mouse. Right clicking the mouse selects the entire area.

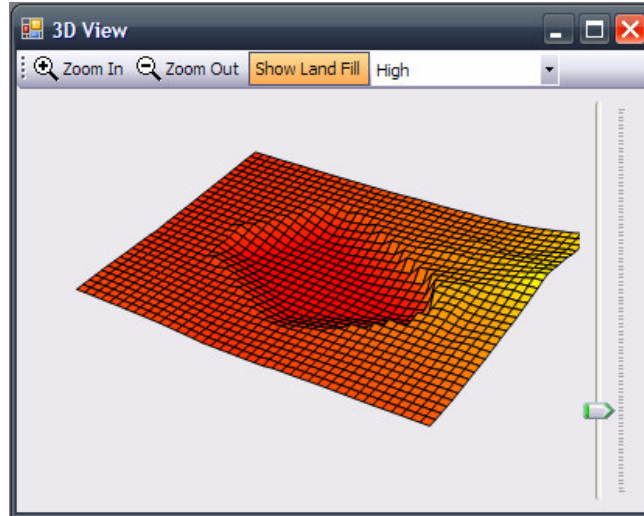


Figure D. 11 3D View of the landfill

D.2. VLF Sub-modules

VLF is basically composed of six interrelated sub-modules, called “Regional Data Map”, “Layers”, “Polygon”, “Landfill”, “2-Dimensional (2D) View”, and “3-Dimensional (3D) View”. Technical and design details of VLF application based on these sub-modules are presented in the following sections.

D.2.1. Regional Data Map (RDM)

Regional data map (RDM) was developed to upload any numeric data belonging to the site (e.g. elevation of the site) and to calculate the value of any point within the given area. RDM module allows the data to be uploaded in ASCII DEM (digital elevation model) file format. In this file format, an area having rectangular borders can be divided into regular grids at a specified interval (e.g. 4 m), and data of each point on the grid are stored in a matrix composed of values corresponding to each point. Information on the area and the matrix are stored as a text file. The first six rows of the matrix belong to number of columns (NCLOS), number of rows (NROWS), coordinate of the upper left corner of the area (XLLCORNER),

coordinate of the lower right corner of the area (YLLCORNER), resolution (CELLSIZE), and no data value to define points that do not have any data (NODATA_VALUE). Following the first six rows, there are NROWS-number of rows containing NOLCS-number of numbers showing the values of points at that row. An example ASCII DEM file part is given below:

```
NCOLS 2001
NROWS 2001
XLLCORNER 678999.000
YLLCORNER 233999.000
CELLSIZE 2.000
NODATA_VALUE -9999.000
597.96 597.97 598.03 598.14 598.18...
598.03 598.03 598.08 598.16 598.25...
598.13 598.18 598.21 598.26 598.31...
.
.
```

RDM module contains a parser to upload ASCII DEM files. The parser reads the information in text file, and converts the information to a data structure that can be processed and defined as an independent class. If the borders of the area are large and the resolution is high, size of ASCII DEM file can be big, and the upload process can take longer time. The upload progress is presented to the user via a progress bar, using event-base interaction features of C# language. Another important feature of RDM module is that the module can bilinearly interpolate the value of any point on the map from the data on the grid. In bilinear interpolation, the value of the point is calculated using the data of nearest four points. By this way, if required, higher resolution processes can be performed without being restricted to the resolution of the map. RDM module is used to upload elevation map and data that belongs to layers (Section D.2.2) and to access these data in VLF.

D.2.2. Layers

In landfill design, the distribution and thickness of the clay layers, and the groundwater level and flow direction directly affect the design. VLF model allows the user to define as many numbers of layers as he/she requires. These layers are managed by “Layers” module. A major class was defined in order to collect all layers under the same structure, and to perform the functions and to manage the information common to all layers (e.g. layer coordinates, type, name, visibility, etc.). All layers are derived from this major class. Each class contains one or more RDM. For example, clay layers consist of two RDMs that define top and bottom of clay layers. RDMs of clay layers can differ from the site elevation map in resolution and dimensions. Layers module uploads and accesses these data using RDM module.

In VLF software, the user interaction with layers is achieved by Layers window (Figure D.12). This window allows the user to add new layers, change layer properties, or delete existing layers. Layers window is composed of three sections: process buttons on top, layers list below the buttons, and property grid that demonstrates the layer properties at the bottom. Every process selected by the user is forwarded to Layers module and performed by the module. Layer classes were defined to include “category” and “description” characteristics of C# language; therefore, the connection between layers, and property grid and processes defined in property grid was easily established.

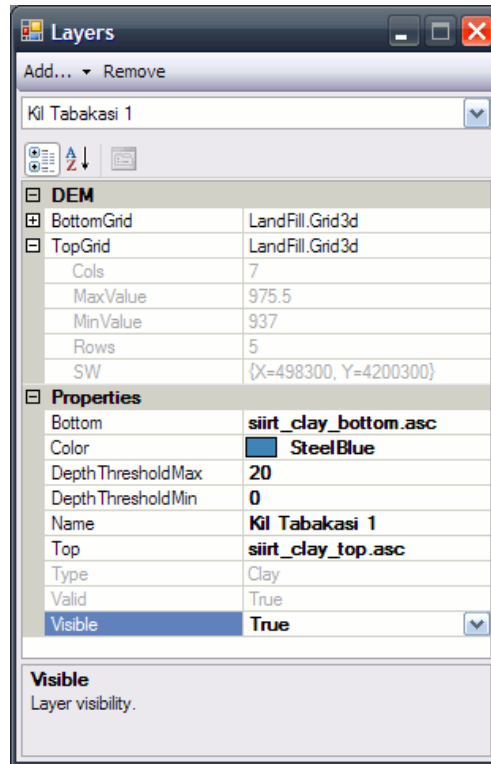


Figure D. 12 Layers window in VLF

Clay layer is defined by RDMs defining top and bottom borders of the layer (i.e. “TopGrid” and “BottomGrid”), layer color (i.e. “Color”), and lower and upper color threshold values (i.e. “DepthTresholdMin” and “DepthTresholdMax”). The values of the parameters can be defined visually by the user. Moreover, detailed information on RDMs of the layer are presented in the Layers window. Color threshold values define the visualization of the clay layer in 2D view. Deeper clay thickness is shown by darker shades; whereas, thinner layers are shown by lighter shades (Figure D.13). Threshold values allow increasing the accent on the layer to make it more visible on the topographic (elevation) map.

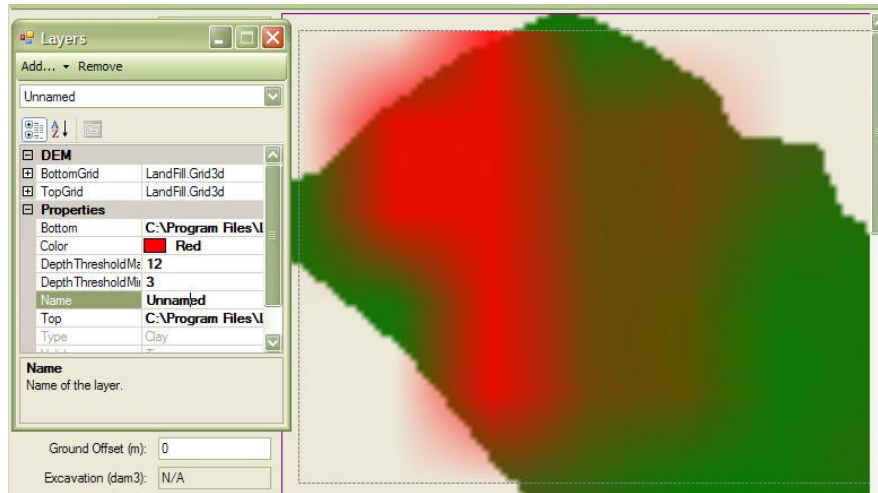


Figure D. 13 Demonstrating clay layers; darker red shade indicates clay layer thickness around 12 m, and lighter red indicates clay layer thickness around 3 m.

Groundwater layer is defined by RDMs defining depth and flow direction of the layer (i.e. “Depth” and “Direction”), layer colors (i.e. “ColorMin” and “ColorMax”), and lower and upper color threshold values (i.e. “DepthTresholdMin” and “DepthTresholdMax”). Similar to the clay layers, the values of the parameters can be defined visually by the user. The values should be in degrees in the direction-RDM, which defines the flow direction of groundwater. Groundwater layers are demonstrated by arrows showing the direction of flow in 2D view. Regarding the ground elevation, layers deeper than the upper threshold value are shown by arrows in “ColorMax” color, and layers above the lower threshold value are shown by arrows in “ColorMin” color. Layers between the upper and lower threshold values are colored linearly between these two colors (Figure D.14). For the sake of visibility of the arrows, they are drawn in equal intervals depending on the degree of the zoom.

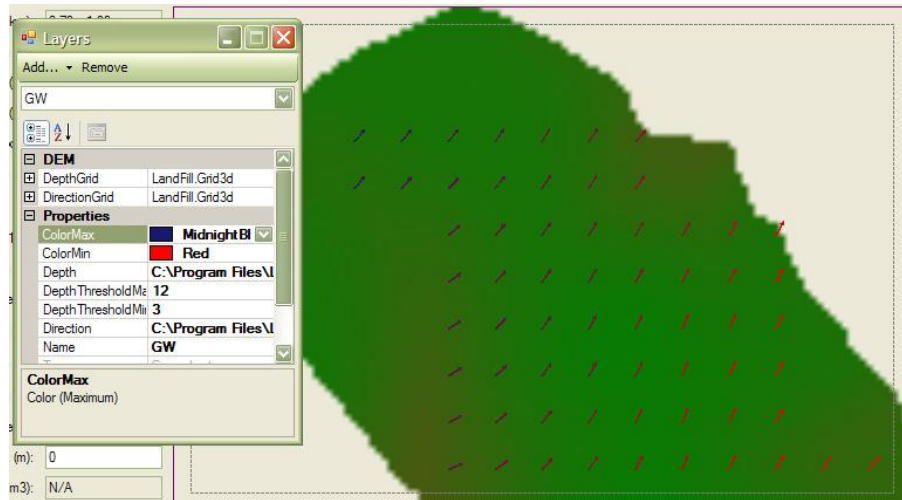


Figure D. 14 Demonstration of groundwater layers in VLF

D.2.3. Polygon

The landfill is designed by defining the base area, final cover limits, and design parameters (e.g. side slopes, base elevation, etc.) in VLF. Base and surface area are defined as polygons. “Polygon” module was developed to create polygons and to perform the following processes on the polygons:

- i. Adding points (corners) to polygon, changing the coordinates of an existing point, or deleting the point from polygon.
- ii. Holding any point on the polygon as selected (active).
- iii. Calculating the area and the center of the polygon.
- iv. Calculating the distance of a point to the polygon.
- v. Determining the polygon edge closest to a particular point.
- vi. Identifying whether a particular point is enclosed by the polygon.

Besides the above-listed functions, the “Polygon” module includes the additional functions that determine whether or not two lines intersect, find the intersection

point of two lines, and calculate the distance of a particular point to a line. All the calculations are based on related geometry formulae.

D.2.4. Landfill

“Landfill” module was developed to form a realistic model of landfill on the given site based on the site elevation map and other layers, defined landfill base and ground elevations, and other defined parameters. Landfill module both performs volume calculations and determines the way that the other layers are affected by the calculations. This module uses RDM module for elevation map, Layers module for layer information, and Polygon module to obtain landfill borders. All calculations are performed 1-m resolution. A landfill is composed of two main components; landfill base and landfill final cover. Besides the landfill base and final cover, the landfill is defined by the parameters listed below:

- i. Base elevation: base reference elevation of landfill
- ii. Base slope: landfill base slope and direction
- iii. Ground elevation: landfill ground/excavation elevation
- iv. Inclination: value of side slopes
- v. Margin: defines how high the ground elevation from the original topographic elevation can be
- vi. Surface elevation: reference elevation of the final cover
- vii. Surface slope: slope and slope direction of final cover
- viii. Ground offset: approximate thickness of final cover

Landfill module can create base and/or final cover models. As the shape of the final cover depends on the base of the landfill and limits of the excavation, it cannot be calculated independently. To create the landfill model, the largest possible ground borders are defined using base borders, and “Base elevation”, “Ground elevation” and “Inclination” parameters. The technical details of drawing

the landfill base were previously described in Section D.1. Base profile is calculated by considering the base slope and direction for the points inside the polygon, and inclination and distance to base polygon for the points outside the polygon. After base elevation for each point is calculated, layers are analyzed and the relation of the base with these layers (e.g. whether or not the base resides within the top and bottom layers of the clay) are determined. The statistics are updated based on these relations. When the final cover is designed, ground limits are created using ground offset parameter, and the final cover profile is created similar to the base profile. Interaction with layers is not required during final cover design.

As a result of calculations, changes that the landfill excavation and final cover create on the original topography are stored as separate RDMs. These RDMs are reflected to the user by 2D and 3D View modules (Sections D.2.5, and D.2.6).

D.2.5. Two-Dimensional (2D) View

“2D” module is a tool that allows the user to visually interact with the topographic map, design the landfill, and view the results of the design. 2D window in VLF is managed by this module. This window is composed of four parts: toolbar at the top, knowledge sheet on the left, bird’s-eye view demonstration on the right, and status bar at the bottom (Figure D.15). Bird’s-eye view demonstration is the main area that the model visually presents the user topographic map and layers, and the user can define base, reference points, and slopes of the landfill, and view the results of the design. For this area, a special class derived from UserControl of “Windows Forms” library. The features and capabilities (e.g. fast display, zoom in and out) of this class are described in Section D.1.

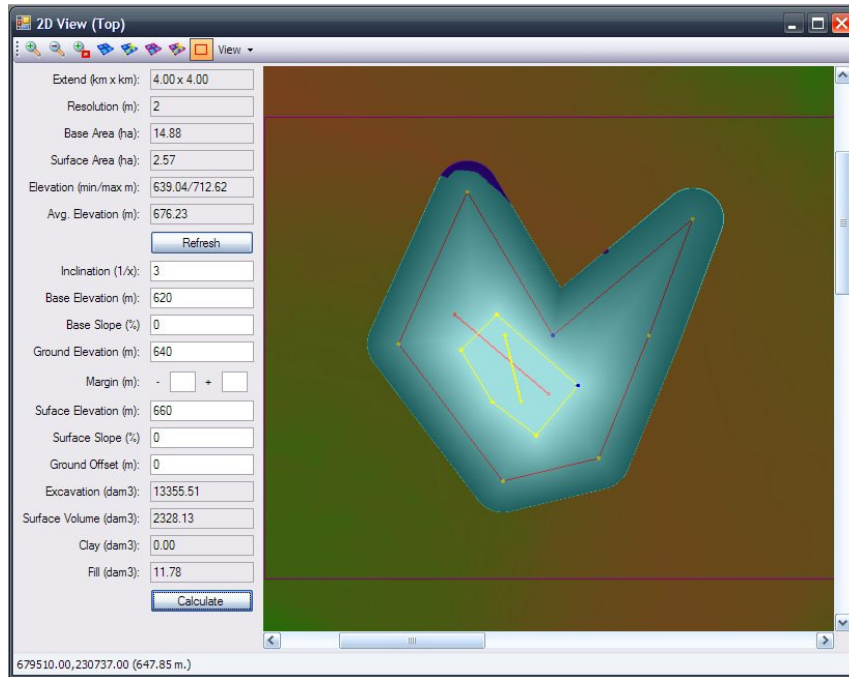


Figure D. 15 2D View window in VLF

Four buttons on the tool bar following “zoom in”, “zoom out”, “zoom special” buttons are used to define base and final cover of the landfill. These are “define base”, “define base slope”, “define surface”, and “define surface slope” buttons. “Define base” and “define surface” buttons allow the user to draw the polygon of landfill base or final cover using the mouse. When any of these buttons is selected, a second toolbar appears below the main toolbar (Figure D.16). This new toolbar includes point selection, point addition, and point deletion buttons. Point selection button allows activating any point of the polygon, and dragging the point to the desired location. Point addition button allows the addition of a new point, following the currently active point. Point deletion button deletes the selected corner of the polygon. These tools allow easy definition and alteration of the base and final cover polygons.

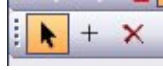


Figure D. 16 Second toolbar in VLF

When the “define base slope” and “Define surface slope” buttons are selected, the user can define the direction of the slope with an arrow. Beginning-point of the arrow is also considered as the reference point. The coordinates and elevation of the particular point is displayed in the status bar when the mouse is browsed on topographic map. This allows sensitive placement of landfill corners, if necessary.

The knowledge sheet on the left-hand side has two main functions. “Refresh” button allows the user to observe the area of the base and surface of the landfill in hectares (ha), and also access the statistics of the site (e.g. minimum, maximum, and average elevation of the area including the landfill base). These statistics are calculated by RDM and Polygon modules. The boxes below Refresh button are reserved for landfill design parameters. Once the “Calculate” button is hit, the input data are forwarded to the Landfill module and design calculations are performed. Model results are visually presented to the user in the bird’s-eye view area. Also, the excavation, fill and available clay layer volumes are presented to the user in cubic decameters. The user can select which features of the design (i.e. base area, surface area, landfill, surface fill (final cover), clay layer, groundwater layer) to view using the “View” button in toolbar.

D.2.6. Three-Dimensional (3D) View

“3D View” module is a tool to demonstrate the original topography and the landfill in three dimensions. All or a part of the site, and landfill with or without final cover can be viewed. 3D view window is managed by this module. This window consists of toolbar at the top, zooming level on the right, 3D view in the middle, and status bar at the bottom (Figure D.17). Creation of 3D image is described in Section D.1. The 3D image can be viewed from different angles by

holding the cursor on the image and moving the cursor to the left and right. The 3D View module accesses the related information for demonstration using RDM and Landfill modules.

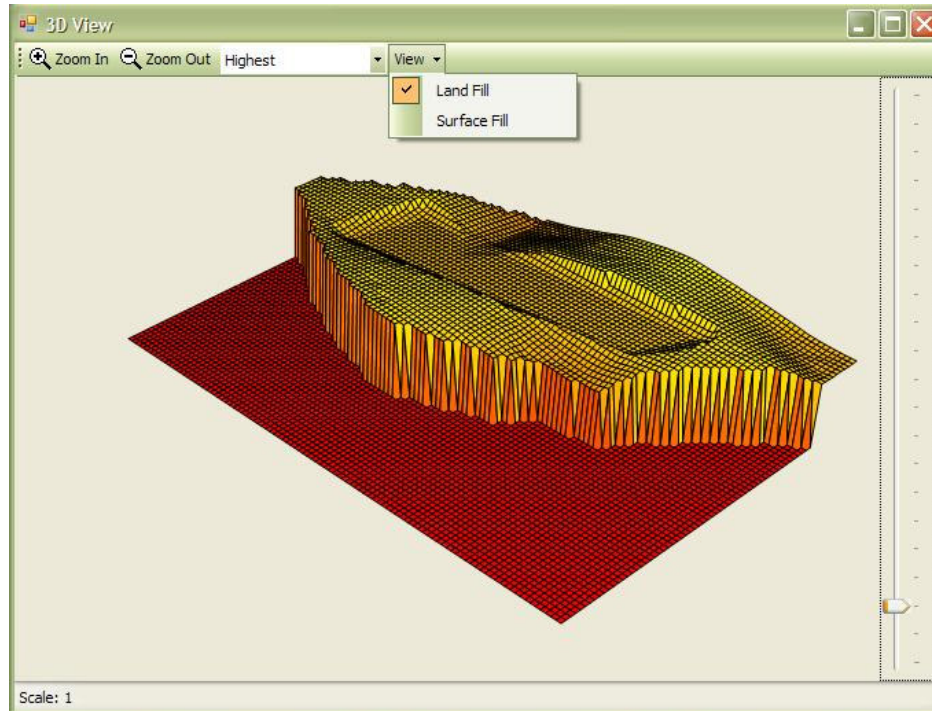


Figure D. 17 3D View window in VLF

APPENDIX-E

SIMULATION RESULTS OF LANDFILL DESIGN ALTERNATIVES

The encoding of the simulations is as follows:

Table E. 1 Coding of the simulations

Cover Design	Liner Design	Climate	Area (ha)	Waste Thickness	Seepage Velocity (m/d)
1: C1	1: L1	1: Arid	02: 2	05: 5-m thick	V1: 0.05
2: C2	2: L2	2: Moderate	15: 15	waste	V2: 0.1
3: C3	3: L3	3: Humid	50: 50	20: 20-m thick	V3: 0.5
	4: L4			waste	V4: 1
	5: L5				
	6: L6				

For example, the design code 1121505V2 means C1L1 (11) landfill design, under moderate climate (2), having an area of 15 ha (15), with a waste thickness of 5 m (05), and the groundwater seepage velocity is 0.1 m/d (V2).

Table E. 2 Simulation results for C1L1 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1110205V1	119	94.5	1120205V1	24	521.1	1130205V1	10	571.1
1110205V2	119	47.4	1120205V2	23	302.3	1130205V2	10	571.1
1110205V3	114.5	9.5	1120205V3	21	66.7	1130205V3	9	164.3
1110205V4	114.5	4.8	1120205V4	21	33.6	1130205V4	9	85.4
1110220V1	134	136.7	1120220V1	28	728.8	1130220V1	12	796.2
1110220V2	134	68.4	1120220V2	24	392.5	1130220V2	12	796.2
1110220V3	127	13.7	1120220V3	22	82.3	1130220V3	9	195.6
1110220V4	127	6.8	1120220V4	22	41.2	1130220V4	9	99.4
1111505V1	123	227.7	1121505V1	24	558.1	1131505V1	10	571.1
1111505V2	119	117.6	1121505V2	24	558.1	1131505V2	10	571.1
1111505V3	114.5	23.8	1121505V3	21	162.5	1131505V3	10	359.0
1111505V4	114.5	11.9	1121505V4	21	83.5	1131505V4	9	200.8
1111520V1	142	336.6	1121520V1	29	790.5	1131520V1	12	796.2
1111520V2	134	170.5	1121520V2	29	790.5	1131520V2	12	796.2
1111520V3	131	34.3	1121520V3	22	203.8	1131520V3	10.5	460.0
1111520V4	127	17.1	1121520V4	22	102.8	1131520V4	10	241.9
1115005V1	134	418.6	1125005V1	25	557.9	1135005V1	10	571.1
1115005V2	123	227.8	1125005V2	25	557.9	1135005V2	10	571.1
1115005V3	119	47.4	1125005V3	22	302.3	1135005V3	10	571.1
1115005V4	117.5	23.8	1125005V4	21	162.5	1135005V4	10	359.0
1115020V1	156	644.1	1125020V1	29	790.5	1135020V1	12	795.4
1115020V2	142	336.6	1125020V2	29	790.5	1135020V2	12	795.4
1115020V3	134	68.4	1125020V3	24	392.5	1135020V3	12	795.4
1115020V4	131	34.3	1125020V4	23	203.2	1135020V4	10.5	459.6

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 3 Simulation results for C1L2 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1210205V1	259	16.8	1220205V1	218	4.1	1230205V1	210	1.75
1210205V2	250	8.5	1220205V2	218	2.0	1230205V2	205	0.88
1210205V3	250	1.7	1220205V3	211	0.4	1230205V3	205	0.18
1210205V4	250	0.9	1220205V4	211	0.2	1230205V4	205	0.09
1210220V1	309	34.0	1220220V1	248	13.7	1230220V1	225.5	6.72
1210220V2	297	17.0	1220220V2	242	6.9	1230220V2	225.5	3.36
1210220V3	297	3.4	1220220V3	243	1.4	1230220V3	220	0.67
1210220V4	297	1.7	1220220V4	243	0.7	1230220V4	220	0.34
1211505V1	258	41.7	1221505V1	226	10.0	1231505V1	215	4.35
1211505V2	250	21.2	1221505V2	215	5.1	1231505V2	211	2.21
1211505V3	250	4.3	1221505V3	215	1.0	1231505V3	205	0.44
1211505V4	250	2.1	1221505V4	215	0.5	1231505V4	205	0.22
1211520V1	314	84.4	1221520V1	248	34.0	1231520V1	231	16.59
1211520V2	304.5	42.1	1221520V2	248	17.1	1231520V2	225.5	8.39
1211520V3	297	8.5	1221520V3	242	3.4	1231520V3	220	1.69
1211520V4	297	4.3	1221520V4	242	1.7	1231520V4	220	0.84
1215005V1	275.5	81.1	1225005V1	232	19.3	1235005V1	225.5	8.35
1215005V2	259	41.7	1225005V2	226	10.0	1235005V2	215	4.35
1215005V3	248	8.4	1225005V3	215	2.0	1235005V3	205	0.88
1215005V4	248	4.2	1225005V4	215	1.0	1235005V4	205	0.44
1215020V1	316	166.7	1225020V1	260.5	65.8	1235020V1	242	32.0
1215020V2	316	84.3	1225020V2	248	34.0	1235020V2	231	16.59
1215020V3	301	17.0	1225020V3	242	6.9	1235020V3	225.5	3.36
1215020V4	301	8.4	1225020V4	242	3.4	1235020V4	220	1.69

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 4 Simulation results for C1L3 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1310205V1	119	94.5	1320205V1	24	521.1	1330205V1	18	445.5
1310205V2	119	47.4	1320205V2	23	302.3	1330205V2	17	311.7
1310205V3	114.5	9.5	1320205V3	21	66.7	1330205V3	15.5	76.7
1310205V4	114.5	4.8	1320205V4	21	33.6	1330205V4	15	38.9
1310220V1	134	136.7	1320220V1	28	728.8	1330220V1	20	708.1
1310220V2	134	68.4	1320220V2	24	392.5	1330220V2	19	460.2
1310220V3	127	13.7	1320220V3	22	82.3	1330220V3	16	102.4
1310220V4	127	6.8	1320220V4	22	41.2	1330220V4	16	51.4
1311505V1	123	227.7	1321505V1	24	558.1	1331505V1	18	445.5
1311505V2	119	117.6	1321505V2	24	558.1	1331505V2	18	445.5
1311505V3	114.5	23.8	1321505V3	21	162.5	1331505V3	16	178.9
1311505V4	114.5	11.9	1321505V4	21	83.5	1331505V4	16	95.0
1311520V1	142	336.6	1321520V1	29	790.5	1331520V1	20	708.0
1311520V2	134	170.5	1321520V2	29	790.5	1331520V2	20	708.0
1311520V3	131	34.3	1321520V3	22	203.8	1331520V3	17	247.4
1311520V4	127	17.1	1321520V4	22	102.8	1331520V4	16.5	127.4
1315005V1	134	418.6	1325005V1	25	557.9	1335005V1	18	445.5
1315005V2	123	227.8	1325005V2	25	557.9	1335005V2	18	445.5
1315005V3	119	47.4	1325005V3	22	302.3	1335005V3	17	311.7
1315005V4	117.5	23.8	1325005V4	21	162.5	1335005V4	16	178.9
1315020V1	156	644.1	1325020V1	29	790.5	1335020V1	20	708.1
1315020V2	142	336.6	1325020V2	29	790.5	1335020V2	20	708.1
1315020V3	134	68.4	1325020V3	24	392.5	1335020V3	19	460.2
1315020V4	131	34.3	1325020V4	23	203.2	1335020V4	17	247.4

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 5 Simulation results for C1L4 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1410205V1	371	6.3	1420205V1	312.5	1.3	1430205V1	306	0.56
1410205V2	363	3.1	1420205V2	312.5	0.75	1430205V2	306	0.28
1410205V3	354	0.6	1420205V3	312.5	0.13	1430205V3	301	0.056
1410205V4	354	0.3	1420205V4	312.5	0.066	1430205V4	301	0.028
1410220V1	458.5	16.0	1420220V1	352	4.91	1430220V1	316	2.21
1410220V2	458.5	8.0	1420220V2	352	2.46	1430220V2	316	1.11
1410220V3	458.5	1.6	1420220V3	352	0.49	1430220V3	316	0.22
1410220V4	458.5	0.8	1420220V4	352	0.25	1430220V4	316	0.11
1411505V1	372	15.6	1421505V1	327	3.25	1431505V1	316	1.39
1411505V2	372	7.8	1421505V2	312.5	1.64	1431505V2	306	0.70
1411505V3	363	1.6	1421505V3	312.5	0.33	1431505V3	301	0.14
1411505V4	354	0.8	1421505V4	312.5	0.16	1431505V4	301	0.07
1411520V1	458.5	39.8	1421520V1	352	12.19	1431520V1	327	5.49
1411520V2	458.5	20.0	1421520V2	352	6.13	1431520V2	316	2.76
1411520V3	458.5	4.0	1421520V3	352	1.23	1431520V3	316	0.56
1411520V4	458.5	2.0	1421520V4	352	0.61	1431520V4	316	0.28
1415005V1	382	30.7	1425005V1	327	6.36	1435005V1	327	2.73
1415005V2	372	15.6	1425005V2	327	3.25	1435005V2	316	1.39
1415005V3	363	3.1	1425005V3	312.5	0.66	1435005V3	306	0.28
1415005V4	363	1.6	1425005V4	312.5	0.33	1435005V4	301	0.14
1415020V1	477	79.0	1425020V1	367	23.95	1435020V1	343	10.80
1415020V2	458.5	39.8	1425020V2	352	12.19	1435020V2	327	5.49
1415020V3	458.5	8.0	1425020V3	352	2.46	1435020V3	316	1.11
1415020V4	458.5	4.0	1425020V4	352	1.23	1435020V4	316	0.56

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 6 Simulation results for C1L4 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1410205V1	97	105.6	1420205V1	43	312.5	1430205V1	41	106.1
1410205V2	94	54.7	1420205V2	41	312.5	1430205V2	40	58.5
1410205V3	93	11.0	1420205V3	40	312.5	1430205V3	38	12.3
1410205V4	93	5.5	1420205V4	40	312.5	1430205V4	38	6.2
1410220V1	107	144.4	1420220V1	47	352	1430220V1	45	217.7
1410220V2	104	72.4	1420220V2	44.5	352	1430220V2	42	115.6
1410220V3	104	14.5	1420220V3	43.5	352	1430220V3	41	23.7
1410220V4	104	7.2	1420220V4	42	352	1430220V4	41	11.9
1411505V1	104	257.9	1421505V1	47	327	1431505V1	43	198.0
1411505V2	97	134.9	1421505V2	43.5	312.5	1431505V2	41	126.0
1411505V3	93	27.4	1421505V3	40	312.5	1431505V3	38.5	30.4
1411505V4	93	13.7	1421505V4	40	312.5	1431505V4	38	15.3
1411520V1	115	353.1	1421520V1	54	352	1431520V1	49	445.6
1411520V2	107	180.1	1421520V2	48	352	1431520V2	44.5	262.5
1411520V3	107	36.2	1421520V3	43.5	352	1431520V3	42	58.9
1411520V4	104	18.1	1421520V4	43.5	352	1431520V4	41	29.6
1415005V1	110	462.5	1425005V1	47	327	1435005V1	43.5	208.9
1415005V2	104	257.9	1425005V2	47	327	1435005V2	43.5	198.0
1415005V3	94	54.7	1425005V3	41	312.5	1435005V3	40	58.5
1415005V4	93	27.4	1425005V4	40	312.5	1435005V4	39	30.4
1415020V1	127	666.8	1425020V1	54	367	1435020V1	49	475.9
1415020V2	115	353.1	1425020V2	54	352	1435020V2	49	445.6
1415020V3	104	72.4	1425020V3	44.5	352	1435020V3	42	115.6
1415020V4	104	36.2	1425020V4	43.5	352	1435020V4	42	58.9

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 7 Simulation results for C1L5 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1510205V1	123	93.7	1520205V1	29	440.0	1530205V1	27	299.2
1510205V2	123	47.2	1520205V2	27	251.6	1530205V2	26	178.6
1510205V3	123	9.4	1520205V3	25	54.5	1530205V3	24	40.1
1510205V4	121	4.7	1520205V4	25	27.3	1530205V4	24	20.2
1510220V1	142	136.3	1520220V1	32	625.8	1530220V1	30	521.9
1510220V2	142	68.2	1520220V2	29	335.0	1530220V2	28	290.2
1510220V3	142	13.6	1520220V3	26	69.5	1530220V3	26	61.7
1510220V4	134	6.8	1520220V4	26	348	1530220V4	26	31.0
1511505V1	131	227	1521505V1	29	524.2	1531505V1	27	348.9
1511505V2	127	116.8	1521505V2	29	524.2	1531505V2	27	348.0
1511505V3	123	23.6	1521505V3	26	133.3	1531505V3	25	97.1
1511505V4	123	11.8	1521505V4	25	67.9	1531505V4	24	50.0
1511520V1	149	335.9	1521520V1	33	757.5	1531520V1	31	630.1
1511520V2	142	170.1	1521520V2	33	757.5	1531520V2	31	630.1
1511520V3	142	34.1	1521520V3	27	172.3	1531520V3	26	152.0
1511520V4	142	17	1521520V4	26	86.7	1531520V4	26	77.0
1515005V1	142	416.7	1525005V1	29	524.2	1535005V1	27	348.9
1515005V2	131	227	1525005V2	29	524.2	1535005V2	27	348.9
1515005V3	123	47.2	1525005V3	27	251.6	1535005V3	26	178.6
1515005V4	123	23.6	1525005V4	26	133.3	1535005V4	25	97.1
1515020V1	164	643.1	1525020V1	33	770.0	1535020V1	31	630.1
1515020V2	149	335.9	1525020V2	33	770.0	1535020V2	31	630.1
1515020V3	142	68.2	1525020V3	29	335.0	1535020V3	28	290.2
1515020V4	142	34.1	1525020V4	27	172.3	1535020V4	26	152.0

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 8 Simulation results for C1L5 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1510205V1	100	106.0	1520205V1	21	531.7	1530205V1	10	540.6
1510205V2	97	53.4	1520205V2	19	312.7	1530205V2	10	502.7
1510205V3	97	10.7	1520205V3	17	71.5	1530205V3	9	140.0
1510205V4	97	5.4	1520205V4	17	36.0	1530205V4	8.5	72.4
1510220V1	115	143.0	1520220V1	25	731.6	1530220V1	12	774.8
1510220V2	110.5	71.8	1520220V2	20.5	395.5	1530220V2	12	707.4
1510220V3	107	14.4	1520220V3	18	84.3	1530220V3	9	164.5
1510220V4	107	7.2	1520220V4	18	42.2	1530220V4	9	83.7
1511505V1	106	252.7	1521505V1	21	568.1	1531505V1	10.5	540.6
1511505V2	101.5	131.8	1521505V2	21	568.1	1531505V2	10.5	540.6
1511505V3	97	26.8	1521505V3	18	171.6	1531505V3	9	302.6
1511505V4	97	13.4	1521505V4	17	89.0	1531505V4	9	169.8
1511520V1	121	350.6	1521520V1	25	794.8	1531520V1	12	774.7
1511520V2	115	178.6	1521520V2	25	794.8	1531520V2	12	774.7
1511520V3	107	36.0	1521520V3	19.5	206.4	1531520V3	11	385.8
1511520V4	107	18.0	1521520V4	18	105.0	1531520V4	9	203.1
1515005V1	115	454.0	1525005V1	21	568.1	1535005V1	10.5	540.6
1515005V2	106	252.7	1525005V2	21	568.1	1535005V2	10.5	540.6
1515005V3	97	53.4	1525005V3	19	312.9	1535005V3	10	502.7
1515005V4	97	26.8	1525005V4	18	171.6	1535005V4	9	302.6
1515020V1	134	663.6	1525020V1	25	794.8	1535020V1	12	774.8
1515020V2	121	350.6	1525020V2	25	794.8	1535020V2	12	774.8
1515020V3	110.5	71.8	1525020V3	20.5	395.5	1535020V3	12	707.4
1515020V4	107	36.0	1525020V4	19.5	206.4	1535020V4	10.5	385.8

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 9 Simulation results for C1L6 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1610205V1	123	93.7	1620205V1	N/A ^d	N/A	1630205V1	N/A	N/A
1610205V2	123	47.2	1620205V2	N/A	N/A	1630205V2	N/A	N/A
1610205V3	123	9.4	1620205V3	N/A	N/A	1630205V3	N/A	N/A
1610205V4	121	4.7	1620205V4	N/A	N/A	1630205V4	N/A	N/A
1610220V1	142	136.3	1620220V1	N/A	N/A	1630220V1	N/A	N/A
1610220V2	142	68.2	1620220V2	N/A	N/A	1630220V2	N/A	N/A
1610220V3	142	13.6	1620220V3	N/A	N/A	1630220V3	N/A	N/A
1610220V4	134	6.8	1620220V4	N/A	N/A	1630220V4	N/A	N/A
1611505V1	131	227	1621505V1	N/A	N/A	1631505V1	N/A	N/A
1611505V2	127	116.8	1621505V2	N/A	N/A	1631505V2	N/A	N/A
1611505V3	123	23.6	1621505V3	N/A	N/A	1631505V3	N/A	N/A
1611505V4	123	11.8	1621505V4	N/A	N/A	1631505V4	N/A	N/A
1611520V1	149	335.9	1621520V1	N/A	N/A	1631520V1	N/A	N/A
1611520V2	142	170.1	1621520V2	N/A	N/A	1631520V2	N/A	N/A
1611520V3	142	34.1	1621520V3	N/A	N/A	1631520V3	N/A	N/A
1611520V4	142	17	1621520V4	N/A	N/A	1631520V4	N/A	N/A
1615005V1	142	416.7	1625005V1	N/A	N/A	1635005V1	N/A	N/A
1615005V2	131	227	1625005V2	N/A	N/A	1635005V2	N/A	N/A
1615005V3	123	47.2	1625005V3	N/A	N/A	1635005V3	N/A	N/A
1615005V4	123	23.6	1625005V4	N/A	N/A	1635005V4	N/A	N/A
1615020V1	164	643.1	1625020V1	N/A	N/A	1635020V1	N/A	N/A
1615020V2	149	335.9	1625020V2	N/A	N/A	1635020V2	N/A	N/A
1615020V3	142	68.2	1625020V3	N/A	N/A	1635020V3	N/A	N/A
1615020V4	142	34.1	1625020V4	N/A	N/A	1635020V4	N/A	N/A

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

^d design does not satisfy stability performance criterion

Table E. 10 Simulation results for C1L6 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
1610205V1	100	106.0	1620205V1	21	531.7	1630205V1	N/A ^d	N/A
1610205V2	97	53.4	1620205V2	19	312.7	1630205V2	N/A	N/A
1610205V3	97	10.7	1620205V3	17	71.5	1630205V3	N/A	N/A
1610205V4	97	5.4	1620205V4	17	36.0	1630205V4	N/A	N/A
1610220V1	115	143.0	1620220V1	25	731.6	1630220V1	N/A	N/A
1610220V2	110.5	71.8	1620220V2	20.5	395.5	1630220V2	N/A	N/A
1610220V3	107	14.4	1620220V3	18	84.3	1630220V3	N/A	N/A
1610220V4	107	7.2	1620220V4	18	42.2	1630220V4	N/A	N/A
1611505V1	106	252.7	1621505V1	21	568.1	1631505V1	N/A	N/A
1611505V2	101.5	131.8	1621505V2	21	568.1	1631505V2	N/A	N/A
1611505V3	97	26.8	1621505V3	18	171.6	1631505V3	N/A	N/A
1611505V4	97	13.4	1621505V4	17	89.0	1631505V4	N/A	N/A
1611520V1	121	350.6	1621520V1	25	794.8	1631520V1	N/A	N/A
1611520V2	115	178.6	1621520V2	25	794.8	1631520V2	N/A	N/A
1611520V3	107	36.0	1621520V3	19.5	206.4	1631520V3	N/A	N/A
1611520V4	107	18.0	1621520V4	18	105.0	1631520V4	N/A	N/A
1615005V1	115	454.0	1625005V1	21	568.1	1635005V1	N/A	N/A
1615005V2	106	252.7	1625005V2	21	568.1	1635005V2	N/A	N/A
1615005V3	97	53.4	1625005V3	19	312.9	1635005V3	N/A	N/A
1615005V4	97	26.8	1625005V4	18	171.6	1635005V4	N/A	N/A
1615020V1	134	663.6	1625020V1	25	794.8	1635020V1	N/A	N/A
1615020V2	121	350.6	1625020V2	25	794.8	1635020V2	N/A	N/A
1615020V3	110.5	71.8	1625020V3	20.5	395.5	1635020V3	N/A	N/A
1615020V4	107	36.0	1625020V4	19.5	206.4	1635020V4	N/A	N/A

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

^d design does not satisfy stability performance criterion

Table E. 11 Simulation results for C2L1 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2110205V1	1171	2.89	2120205V1	800	6.30	2130205V1	522	13.60
2110205V2	1171	1.45	2120205V2	800	3.15	2130205V2	522	6.80
2110205V3	1171	0.29	2120205V3	800	0.63	2130205V3	522	1.36
2110205V4	1171	0.15	2120205V4	800	0.32	2130205V4	522	0.68
2110220V1	1727	4.74	2120220V1	1171	10.74	2130220V1	645	22.81
2110220V2	1727	2.37	2120220V2	1171	5.37	2130220V2	645	11.41
2110220V3	1727	0.47	2120220V3	1088	1.08	2130220V3	645	2.28
2110220V4	1727	0.24	2120220V4	1088	0.54	2130220V4	645	1.14
2111505V1	1171	7.19	2121505V1	800	15.68	2131505V1	522	33.81
2111505V2	1171	3.61	2121505V2	800	7.87	2131505V2	522	16.94
2111505V3	1171	0.75	2121505V3	800	1.58	2131505V3	522	3.39
2111505V4	1171	0.36	2121505V4	800	0.79	2131505V4	522	1.69
2111520V1	1727	11.81	2121520V1	1171	26.81	2131520V1	645	56.91
2111520V2	1727	5.92	2121520V2	1171	13.42	2131520V2	645	28.51
2111520V3	1727	1.19	2121520V3	1171	2.69	2131520V3	645	5.71
2111520V4	1727	0.59	2121520V4	1088	1.34	2131520V4	645	2.85
2115005V1	1171	14.27	2125005V1	856	31.18	2135005V1	522	67.11
2115005V2	1171	7.19	2125005V2	800	15.68	2135005V2	522	33.81
2115005V3	1171	1.45	2125005V3	800	3.15	2135005V3	522	6.78
2115005V4	1171	0.72	2125005V4	800	1.58	2135005V4	522	3.39
2115020V1	1727	23.5	2125020V1	1171	53.48	2135020V1	701	113.56
2115020V2	1727	11.81	2125020V2	1171	26.81	2135020V2	645	56.91
2115020V3	1727	2.37	2125020V3	1171	5.37	2135020V3	645	11.41
2115020V4	1727	1.19	2125020V4	1171	2.69	2135020V4	645	5.71

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 12 Simulation results for C2L2 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2210205V1	1375	2.8	2220205V1	778	7.5	2230205V1	473	15.8
2210205V2	1375	1.4	2220205V2	737	3.7	2230205V2	473	7.9
2210205V3	1375	0.28	2220205V3	737	0.75	2230205V3	473	1.6
2210205V4	1375	0.14	2220205V4	737	0.37	2230205V4	473	0.8
2210220V1	1952	4.32	2220220V1	1067	11.6	2230220V1	587	24.5
2210220V2	1952	2.16	2220220V2	1067	5.8	2230220V2	587	12.3
2210220V3	1952	0.43	2220220V3	1067	1.2	2230220V3	587	2.5
2210220V4	1952	0.22	2220220V4	1067	0.6	2230220V4	587	1.2
2211505V1	1333	6.9	2221505V1	859	17.4	2231505V1	473	39.4
2211505V2	1333	3.5	2221505V2	818	8.7	2231505V2	473	19.8
2211505V3	1333	0.69	2221505V3	818	1.7	2231505V3	473	4.0
2211505V4	1333	0.35	2221505V4	818	0.9	2231505V4	473	2.0
2211520V1	1952	10.8	2221520V1	1142	28	2231520V1	587	61.2
2211520V2	1952	5.4	2221520V2	1067	14	2231520V2	587	30.7
2211520V3	1952	1.1	2221520V3	1067	2.8	2231520V3	587	6.1
2211520V4	1952	0.54	2221520V4	1067	1.4	2231520V4	587	3.1
2215005V1	1333	13.7	2225005V1	859	34.6	2235005V1	496	78.4
2215005V2	1333	6.9	2225005V2	859	17.4	2235005V2	473	39.4
2215005V3	1333	1.4	2225005V3	818	3.5	2235005V3	473	7.9
2215005V4	1333	0.69	2225005V4	818	1.7	2235005V4	473	4.0
2215020V1	1952	21.5	2225020V1	1142	55.9	2235020V1	628	122.2
2215020V2	1952	10.8	2225020V2	1142	28	2235020V2	587	61.2
2215020V3	1952	2.16	2225020V3	1067	5.6	2235020V3	587	12.3
2215020V4	1952	1.08	2225020V4	1067	2.8	2235020V4	587	6.1

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 13 Simulation results for C2L3 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2310205V1	1171	2.89	2320205V1	800	6.30	2330205V1	522	13.60
2310205V2	1171	1.45	2320205V2	800	3.15	2330205V2	522	6.80
2310205V3	1171	0.29	2320205V3	800	0.63	2330205V3	522	1.36
2310205V4	1171	0.15	2320205V4	800	0.32	2330205V4	522	0.68
2310220V1	1727	4.74	2320220V1	1171	10.74	2330220V1	645	22.81
2310220V2	1727	2.37	2320220V2	1171	5.37	2330220V2	645	11.41
2310220V3	1727	0.47	2320220V3	1088	1.08	2330220V3	645	2.28
2310220V4	1727	0.24	2320220V4	1088	0.54	2330220V4	645	1.14
2311505V1	1171	7.19	2321505V1	800	15.68	2331505V1	522	33.81
2311505V2	1171	3.61	2321505V2	800	7.87	2331505V2	522	16.94
2311505V3	1171	0.75	2321505V3	800	1.58	2331505V3	522	3.39
2311505V4	1171	0.36	2321505V4	800	0.79	2331505V4	522	1.69
2311520V1	1727	11.81	2321520V1	1171	26.81	2331520V1	645	56.91
2311520V2	1727	5.92	2321520V2	1171	13.42	2331520V2	645	28.51
2311520V3	1727	1.19	2321520V3	1171	2.69	2331520V3	645	5.71
2311520V4	1727	0.59	2321520V4	1088	1.34	2331520V4	645	2.85
2315005V1	1171	14.27	2325005V1	856	31.18	2335005V1	522	67.11
2315005V2	1171	7.19	2325005V2	800	15.68	2335005V2	522	33.81
2315005V3	1171	1.45	2325005V3	800	3.15	2335005V3	522	6.78
2315005V4	1171	0.72	2325005V4	800	1.58	2335005V4	522	3.39
2315020V1	1727	23.5	2325020V1	1171	53.48	2335020V1	701	113.56
2315020V2	1727	11.81	2325020V2	1171	26.81	2335020V2	645	56.91
2315020V3	1727	2.37	2325020V3	1171	5.37	2335020V3	645	11.41
2315020V4	1727	1.19	2325020V4	1171	2.69	2335020V4	645	5.71

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 14 Simulation results for C2L4 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2410205V1	1339	2.85	2420205V1	859	6.34	2430205V1	536	13.76
2410205V2	1264	1.43	2420205V2	859	3.17	2430205V2	536	6.89
2410205V3	1264	0.29	2420205V3	859	0.63	2430205V3	536	1.38
2410205V4	1264	0.14	2420205V4	859	0.32	2430205V4	536	0.69
2410220V1	1698	4.63	2420220V1	1203	10.72	2430220V1	679	22.91
2410220V2	1698	2.32	2420220V2	1203	5.36	2430220V2	679	11.46
2410220V3	1698	0.46	2420220V3	1203	1.07	2430220V3	679	2.29
2410220V4	1698	0.23	2420220V4	1203	0.54	2430220V4	679	1.15
2411505V1	1339	7.09	2421505V1	859	15.79	2431505V1	536	34.32
2411505V2	1339	3.56	2421505V2	859	7.92	2431505V2	536	17.20
2411505V3	1264	0.72	2421505V3	859	1.59	2431505V3	536	3.44
2411505V4	1264	0.36	2421505V4	859	0.79	2431505V4	536	1.72
2411520V1	1833	11.55	2421520V1	1203	26.76	2431520V1	679	57.19
2411520V2	1698	5.78	2421520V2	1203	13.40	2431520V2	679	28.64
2411520V3	1698	1.16	2421520V3	1203	2.68	2431520V3	679	5.73
2411520V4	1698	0.58	2421520V4	1203	1.34	2431520V4	679	2.87
2415005V1	1339	14.08	2425005V1	859	31.37	2435005V1	566	68.05
2415005V2	1339	7.09	2425005V2	859	15.79	2435005V2	536	34.32
2415005V3	1264	1.43	2425005V3	859	3.18	2435005V3	536	6.89
2415005V4	1264	0.72	2425005V4	859	1.59	2435005V4	536	3.44
2415020V1	1834	22.96	2425020V1	1203	53.36	2435020V1	734	114.00
2415020V2	1834	11.55	2425020V2	1203	26.76	2435020V2	679	57.19
2415020V3	1698	2.32	2425020V3	1203	5.36	2435020V3	679	11.46
2415020V4	1698	1.16	2425020V4	1203	2.68	2435020V4	679	5.73

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 15 Simulation results for C2L4 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2410205V1	1264	2.88	2420205V1	778	7.13	2430205V1	457	16.04
2410205V2	1273	1.44	2420205V2	778	3.57	2430205V2	457	8.02
2410205V3	1273	0.29	2420205V3	778	0.71	2430205V3	457	1.6
2410205V4	1273	0.14	2420205V4	778	0.36	2430205V4	457	0.80
2410220V1	1727	4.45	2420220V1	1067	11.33	2430220V1	567	24.68
2410220V2	1727	2.23	2420220V2	1067	5.66	2430220V2	567	12.35
2410220V3	1727	0.45	2420220V3	1067	1.13	2430220V3	567	2.47
2410220V4	1727	0.22	2420220V4	1067	0.57	2430220V4	567	1.23
2411505V1	1339	7.16	2421505V1	778	17.79	2431505V1	457	40.03
2411505V2	1264	3.60	2421505V2	778	8.91	2431505V2	457	20.05
2411505V3	1264	0.72	2421505V3	778	1.78	2431505V3	457	4.01
2411505V4	1203	0.36	2421505V4	778	0.89	2431505V4	457	2.01
2411520V1	1698	11.09	2421520V1	1067	28.29	2431520V1	580	61.65
2411520V2	1698	5.55	2421520V2	1067	14.16	2431520V2	567	30.85
2411520V3	1698	1.11	2421520V3	1067	2.83	2431520V3	567	6.17
2411520V4	1698	0.56	2421520V4	1067	1.42	2431520V4	567	3.09
2415005V1	1339	14.26	2425005V1	798	35.44	2435005V1	457	79.43
2415005V2	1339	7.16	2425005V2	778	17.79	2435005V2	457	40.03
2415005V3	1264	1.44	2425005V3	778	3.57	2435005V3	457	8.02
2415005V4	1264	0.72	2425005V4	778	1.78	2435005V4	457	4.01
2415020V1	1698	22.08	2425020V1	1067	56.48	2435020V1	595	123.00
2415020V2	1698	11.09	2425020V2	1067	28.29	2435020V2	580	61.65
2415020V3	1698	2.22	2425020V3	1067	5.66	2435020V3	566	12.34
2415020V4	1698	1.11	2425020V4	1067	2.83	2435020V4	566	6.17

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 16 Simulation results for C2L5 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2510205V1	1339	2.74	2520205V1	856	6.11	2530205V1	536	13.33
2510205V2	1273	1.37	2520205V2	917	3.05	2530205V2	536	6.67
2510205V3	1273	0.27	2520205V3	917	0.61	2530205V3	536	1.34
2510205V4	1273	0.14	2520205V4	849	0.31	2530205V4	536	0.67
2510220V1	1834	4.55	2520220V1	1151	10.60	2530220V1	734	22.58
2510220V2	1834	2.28	2520220V2	1151	5.28	2530220V2	679	11.31
2510220V3	1834	0.46	2520220V3	1151	1.06	2530220V3	679	2.26
2510220V4	1834	0.23	2520220V4	1151	0.53	2530220V4	679	1.13
2511505V1	1273	6.81	2521505V1	917	15.20	2531505V1	566	33.19
2511505V2	1273	3.42	2521505V2	917	7.62	2531505V2	536	16.65
2511505V3	1273	0.69	2521505V3	917	1.53	2531505V3	536	3.34
2511505V4	1273	0.34	2521505V4	917	0.76	2531505V4	536	1.67
2511520V1	1834	11.34	2521520V1	1273	26.34	2531520V1	734	56.44
2511520V2	1834	5.68	2521520V2	1151	13.20	2531520V2	734	28.22
2511520V3	1834	1.14	2521520V3	1151	2.64	2531520V3	679	5.66
2511520V4	1834	0.57	2521520V4	1151	1.32	2531520V4	679	2.83
2515005V1	1375	13.50	2525005V1	902	30.30	2535005V1	566	66.05
2515005V2	1273	6.81	2525005V2	917	15.22	2535005V2	566	33.09
2515005V3	1273	1.37	2525005V3	917	3.05	2535005V3	536	6.67
2515005V4	1273	0.69	2525005V4	917	1.53	2535005V4	536	3.34
2515020V1	1834	22.54	2525020V1	1273	52.57	2535020V1	734	112.70
2515020V2	1834	11.34	2525020V2	1273	26.34	2535020V2	734	56.44
2515020V3	1834	2.28	2525020V3	1151	52.28	2535020V3	679	11.31
2515020V4	1834	1.14	2525020V4	1151	2.64	2535020V4	679	5.66

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 17 Simulation results for C2L5 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2510205V1	1339	2.75	2520205V1	800	6.86	2530205V1	457	15.47
2510205V2	1339	1.38	2520205V2	781	3.42	2530205V2	457	7.74
2510205V3	1339	0.28	2520205V3	781	0.69	2530205V3	457	1.55
2510205V4	1339	0.14	2520205V4	781	0.34	2530205V4	457	0.77
2510220V1	1698	4.36	2520220V1	1009	11.13	2530220V1	580	24.36
2510220V2	1698	2.18	2520220V2	1009	5.57	2530220V2	580	12.81
2510220V3	1698	0.44	2520220V3	1009	1.11	2530220V3	580	2.44
2510220V4	1698	0.22	2520220V4	1083	0.56	2530220V4	580	1.22
2511505V1	1339	6.86	2521505V1	798	17.10	2531505V1	457	38.54
2511505V2	1339	3.44	2521505V2	798	8.57	2531505V2	457	19.33
2511505V3	1339	0.69	2521505V3	798	1.72	2531505V3	457	3.87
2511505V4	1339	0.34	2521505V4	798	0.86	2531505V4	457	1.94
2511520V1	1698	10.88	2521520V1	1009	27.78	2531520V1	580	6.83
2511520V2	1698	5.45	2521520V2	1009	13.91	2531520V2	580	30.45
2511520V3	1698	1.09	2521520V3	1009	2.79	2531520V3	580	6.09
2511520V4	1698	0.55	2521520V4	1009	1.39	2531520V4	580	3.05
2515005V1	1339	13.65	2525005V1	818	34.07	2535005V1	481	76.75
2515005V2	1339	6.86	2525005V2	798	17.10	2535005V2	457	38.54
2515005V3	1339	1.38	2525005V3	798	8.43	2535005V3	457	7.74
2515005V4	1339	0.69	2525005V4	798	1.72	2535005V4	457	3.87
2515020V1	1834	21.73	2525020V1	1009	55.35	2535020V1	625	121.19
2515020V2	1698	10.88	2525020V2	1009	27.78	2535020V2	580	6.83
2515020V3	1698	2.18	2525020V3	1009	5.57	2535020V3	580	12.18
2515020V4	1698	1.09	2525020V4	1009	2.79	2535020V4	580	6.09

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 18 Simulation results for C2L6 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2610205V1	1339	2.74	2620205V1	856	6.11	2630205V1	536	13.33
2610205V2	1273	1.37	2620205V2	917	3.05	2630205V2	536	6.67
2610205V3	1273	0.27	2620205V3	917	0.61	2630205V3	536	1.34
2610205V4	1273	0.14	2620205V4	849	0.31	2630205V4	536	0.67
2610220V1	1834	4.55	2620220V1	1151	10.60	2630220V1	734	22.58
2610220V2	1834	2.28	2620220V2	1151	5.28	2630220V2	679	11.31
2610220V3	1834	0.46	2620220V3	1151	1.06	2630220V3	679	2.26
2610220V4	1834	0.23	2620220V4	1151	0.53	2630220V4	679	1.13
2611505V1	1273	6.81	2621505V1	917	15.20	2631505V1	566	33.19
2611505V2	1273	3.42	2621505V2	917	7.62	2631505V2	536	16.65
2611505V3	1273	0.69	2621505V3	917	1.53	2631505V3	536	3.34
2611505V4	1273	0.34	2621505V4	917	0.76	2631505V4	536	1.67
2611520V1	1834	11.34	2621520V1	1273	26.34	2631520V1	734	56.44
2611520V2	1834	5.68	2621520V2	1151	13.20	2631520V2	734	28.22
2611520V3	1834	1.14	2621520V3	1151	2.64	2631520V3	679	5.66
2611520V4	1834	0.57	2621520V4	1151	1.32	2631520V4	679	2.83
2615005V1	1375	13.50	2625005V1	902	30.30	2635005V1	566	66.05
2615005V2	1273	6.81	2625005V2	917	15.22	2635005V2	566	33.09
2615005V3	1273	1.37	2625005V3	917	3.05	2635005V3	536	6.67
2615005V4	1273	0.69	2625005V4	917	1.53	2635005V4	536	3.34
2615020V1	1834	22.54	2625020V1	1273	52.57	2635020V1	734	112.70
2615020V2	1834	11.34	2625020V2	1273	26.34	2635020V2	734	56.44
2615020V3	1834	2.28	2625020V3	1151	52.28	2635020V3	679	11.31
2615020V4	1834	1.14	2625020V4	1151	2.64	2635020V4	679	5.66

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 19 Simulation results for C2L6 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
2610205V1	1339	2.75	2620205V1	800	6.86	2630205V1	457	15.47
2610205V2	1339	1.38	2620205V2	781	3.42	2630205V2	457	7.74
2610205V3	1339	0.28	2620205V3	781	0.69	2630205V3	457	1.55
2610205V4	1339	0.14	2620205V4	781	0.34	2630205V4	457	0.77
2610220V1	1698	4.36	2620220V1	1009	11.13	2630220V1	580	24.36
2610220V2	1698	2.18	2620220V2	1009	5.57	2630220V2	580	12.81
2610220V3	1698	0.44	2620220V3	1009	1.11	2630220V3	580	2.44
2610220V4	1698	0.22	2620220V4	1083	0.56	2630220V4	580	1.22
2611505V1	1339	6.86	2621505V1	798	17.10	2631505V1	457	38.54
2611505V2	1339	3.44	2621505V2	798	8.57	2631505V2	457	19.33
2611505V3	1339	0.69	2621505V3	798	1.72	2631505V3	457	3.87
2611505V4	1339	0.34	2621505V4	798	0.86	2631505V4	457	1.94
2611520V1	1698	10.88	2621520V1	1009	27.78	2631520V1	580	6.83
2611520V2	1698	5.45	2621520V2	1009	13.91	2631520V2	580	30.45
2611520V3	1698	1.09	2621520V3	1009	2.79	2631520V3	580	6.09
2611520V4	1698	0.55	2621520V4	1009	1.39	2631520V4	580	3.05
2615005V1	1339	13.65	2625005V1	818	34.07	2635005V1	481	76.75
2615005V2	1339	6.86	2625005V2	798	17.10	2635005V2	457	38.54
2615005V3	1339	1.38	2625005V3	798	8.43	2635005V3	457	7.74
2615005V4	1339	0.69	2625005V4	798	1.72	2635005V4	457	3.87
2615020V1	1834	21.73	2625020V1	1009	55.35	2635020V1	625	121.19
2615020V2	1698	10.88	2625020V2	1009	27.78	2635020V2	580	6.83
2615020V3	1698	2.18	2625020V3	1009	5.57	2635020V3	580	12.18
2615020V4	1698	1.09	2625020V4	1009	2.79	2635020V4	580	6.09

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 20 Simulation results for C3L1 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3110205V1	123	92.00	3120205V1	24.5	515.10	3130205V1	10	570.60
3110205V2	119	46.30	3120205V2	23	298.00	3130205V2	10	570.60
3110205V3	119	9.30	3120205V3	21	65.80	3130205V3	9	162.10
3110205V4	119	4.60	3120205V4	21	32.94	3130205V4	9	84.20
3110220V1	142	133.10	3120220V1	29	717.10	3130220V1	12	795.80
3110220V2	134	66.90	3120220V2	25	386.00	3130220V2	12	795.80
3110220V3	134	13.40	3120220V3	22	80.90	3130220V3	9.5	192.90
3110220V4	134	6.70	3120220V4	22	40.50	3130220V4	9	97.90
3111505V1	127	222.70	3121505V1	25	556.70	3131505V1	10	570.90
3111505V2	123	114.60	3121505V2	25	556.70	3131505V2	10	570.90
3111505V3	119	23.20	3121505V3	22	160.00	3131505V3	10	354.60
3111505V4	119	11.60	3121505V4	21	82.00	3131505V4	9	198.00
3111520V1	145	329.00	3121520V1	29	790.60	3131520V1	12	795.80
3111520V2	141	166.30	3121520V2	29	790.60	3131520V2	12	795.80
3111520V3	134	33.40	3121520V3	24	199.30	3131520V3	11	753.49
3111520V4	134	16.70	3121520V4	22	101.10	3131520V4	10	238.60
3115005V1	138	409.60	3125005V1	25	556.80	3135005V1	10	570.80
3115005V2	127	222.70	3125005V2	25	556.80	3135005V2	10	570.80
3115005V3	119	46.30	3125005V3	23	298.00	3135005V3	10	570.80
3115005V4	119	23.20	3125005V4	22	160.00	3135005V4	10	354.60
3115020V1	156	630.40	3125020V1	29	790.60	3135020V1	12	795.60
3115020V2	145	330.00	3125020V2	29	790.60	3135020V2	12	795.60
3115020V3	134	66.90	3125020V3	25	386.00	3135020V3	12	795.60
3115020V4	134	33.40	3125020V4	24	199.30	3135020V4	11	453.90

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 21 Simulation results for C3L2 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3210205V1	207	1.79	3220205V1	218	4.14	3230205V1	212	1.79
3210205V2	207	0.90	3220205V2	312	2.07	3230205V2	206	0.90
3210205V3	207	0.18	3220205V3	312	0.42	3230205V3	206	0.18
3210205V4	207	0.09	3220205V4	312	0.21	3230205V4	206	0.09
3210220V1	222	6.80	3220220V1	246	13.86	3230220V1	223	6.81
3210220V2	222	3.41	3220220V2	246	6.94	3230220V2	223	3.41
3210220V3	222	0.68	3220220V3	239.5	1.39	3230220V3	223	0.68
3210220V4	221	0.34	3220220V4	239.5	0.69	3230220V4	223	0.34
3211505V1	214	4.41	3221505V1	232	10.21	3231505V1	218.5	4.40
3211505V2	211	2.23	3221505V2	218	5.16	3231505V2	212	2.23
3211505V3	207	0.45	3221505V3	212	1.04	3231505V3	206	0.45
3211505V4	207	0.22	3221505V4	212	0.52	3231505V4	206	0.22
3211520V1	229	16.80	3221520V1	252	34.31	3231520V1	229	16.81
3211520V2	229	8.48	3221520V2	246	17.31	3231520V2	223	8.49
3211520V3	222	1.71	3221520V3	246	3.47	3231520V3	223	1.71
3211520V4	222	0.85	3221520V4	239.5	0.17	3231520V4	223	0.85
3215005V1	229	8.45	3225005V1	229	19.61	3235005V1	223	0.46
3215005V2	214	4.41	3225005V2	223	10.21	3235005V2	218.5	4.40
3215005V3	207	0.90	3225005V3	212	2.07	3235005V3	206	0.90
3215005V4	207	0.45	3225005V4	212	1.04	3235005V4	206	0.45
3215020V1	240.5	32.40	3225020V1	264	66.57	3235020V1	239.5	32.39
3215020V2	229	16.80	3225020V2	252	34.31	3235020V2	229	16.81
3215020V3	222	3.41	3225020V3	246	6.94	3235020V3	223	3.41
3215020V4	222	1.71	3225020V4	246	3.47	3235020V4	223	1.71

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 22 Simulation results for C3L3 design alternative

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3310205V1	123	92.00	3320205V1	24.5	515.10	3330205V1	18	447.40
3310205V2	119	46.30	3320205V2	23	298.00	3330205V2	17	313.40
3310205V3	119	9.30	3320205V3	21	65.80	3330205V3	16	77.00
3310205V4	119	4.60	3320205V4	21	32.94	3330205V4	15	39.00
3310220V1	142	133.10	3320220V1	29	717.10	3330220V1	20	710.30
3310220V2	134	66.90	3320220V2	25	386.00	3330220V2	19	461.00
3310220V3	134	13.40	3320220V3	22	80.90	3330220V3	16	102.50
3310220V4	134	6.70	3320220V4	22	40.50	3330220V4	16	51.50
3311505V1	127	222.70	3321505V1	25	556.70	3331505V1	18	448.00
3311505V2	123	114.60	3321505V2	25	556.70	3331505V2	18	448.00
3311505V3	119	23.20	3321505V3	22	160.00	3331505V3	16	180.00
3311505V4	119	11.60	3321505V4	21	82.00	3331505V4	15.5	95.20
3311520V1	145	329.00	3321520V1	29	790.60	3331520V1	20	710.20
3311520V2	141	166.30	3321520V2	29	790.60	3331520V2	20	710.20
3311520V3	134	33.40	3321520V3	24	199.30	3331520V3	17	247.90
3311520V4	134	16.70	3321520V4	22	101.10	3331520V4	17	127.40
3315005V1	138	409.60	3325005V1	25	556.80	3335005V1	18	448.00
3315005V2	127	222.70	3325005V2	25	556.80	3335005V2	18	448.00
3315005V3	119	46.30	3325005V3	23	298.00	3335005V3	17	313.90
3315005V4	119	23.20	3325005V4	22	160.00	3335005V4	16	180.00
3315020V1	156	630.40	3325020V1	29	790.60	3335020V1	20	710.30
3315020V2	145	330.00	3325020V2	29	790.60	3335020V2	20	710.30
3315020V3	134	66.90	3325020V3	25	386.00	3335020V3	19	461.00
3315020V4	134	33.40	3325020V4	24	199.30	3335020V4	17	247.90

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 23 Simulation results for C3L4 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3410205V1	372	6.38	3420205V1	316	1.33	3430205V1	306	0.57
3410205V2	363	3.20	3420205V2	316	0.67	3430205V2	306	0.29
3410205V3	363	0.64	3420205V3	316	0.13	3430205V3	301	0.06
3410205V4	363	0.32	3420205V4	316	0.07	3430205V4	301	0.03
3410220V1	458.5	16.17	3420220V1	354	4.98	3430220V1	316	2.24
3410220V2	458.5	8.09	3420220V2	354	2.49	3430220V2	316	1.12
3410220V3	458.5	1.62	3420220V3	354	0.50	3430220V3	316	0.23
3410220V4	458.5	0.81	3420220V4	354	0.24	3430220V4	316	0.11
3411505V1	372	15.87	3421505V1	316	3.30	3431505V1	316	1.41
3411505V2	372	7.98	3421505V2	316	1.66	3431505V2	306	0.71
3411505V3	363	1.60	3421505V3	316	0.33	3431505V3	301	0.14
3411505V4	363	0.80	3421505V4	316	0.17	3431505V4	301	0.07
3411520V1	458.5	40.23	3421520V1	354	12.36	3431520V1	327	5.57
3411520V2	458.5	20.20	3421520V2	354	6.22	3431520V2	316	2.80
3411520V3	458.5	4.05	3421520V3	354	1.25	3431520V3	316	0.56
3411520V4	458.5	2.02	3421520V4	354	0.62	3431520V4	316	0.28
3415005V1	391	31.22	3425005V1	335	6.47	3435005V1	327	2.76
3415005V2	372	15.87	3425005V2	316	3.30	3435005V2	316	1.41
3415005V3	363	3.20	3425005V3	316	0.67	3435005V3	306	0.29
3415005V4	363	1.60	3425005V4	316	0.33	3435005V4	301	0.14
3415020V1	477	79.88	3425020V1	372	24.29	3435020V1	343	10.90
3415020V2	458.5	40.23	3425020V2	354	12.36	3435020V2	327	5.57
3415020V3	458.5	8.09	3425020V3	354	2.49	3435020V3	316	1.12
3415020V4	458.5	4.05	3425020V4	354	1.25	3435020V4	316	0.56

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 24 Simulation results for C3L4 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3410205V1	98	106.00	3420205V1	43	176.20	3430205V1	41	107.10
3410205V2	95	53.30	3420205V2	41	94.90	3430205V2	39	59.20
3410205V3	95	10.70	3420205V3	40	19.60	3430205V3	38	12.40
3410205V4	95	5.30	3420205V4	40	9.80	3430205V4	38	6.20
3410220V1	109	141.10	3420220V1	47	276.40	3430220V1	45	219.00
3410220V2	106	70.80	3420220V2	45	143.70	3430220V2	42	116.20
3410220V3	106	14.20	3420220V3	43	29.10	3430220V3	41	23.80
3410220V4	106	7.10	3420220V4	43	14.60	3430220V4	41	11.90
3411505V1	103	252.30	3421505V1	46	347.30	3431505V1	43	200.10
3411505V2	98	131.50	3421505V2	43	211.30	3431505V2	41	127.30
3411505V3	95	26.70	3421505V3	40	48.70	3431505V3	38	30.60
3411505V4	95	13.40	3421505V4	40	24.50	3431505V4	38	15.50
3411520V1	117	345.50	3421520V1	54	601.10	3431520V1	48	448.00
3411520V2	112	176.00	3421520V2	48	337.60	3431520V2	46	263.90
3411520V3	106	305.40	3421520V3	43	72.60	3431520V3	42	59.20
3411520V4	106	17.70	3421520V4	43	36.40	3431520V4	41	29.70
3415005V1	112	453.40	3425005V1	46	368.20	3435005V1	43	211.00
3415005V2	103	252.30	3425005V2	46	347.30	3435005V2	43	200.10
3415005V3	95	53.30	3425005V3	41	94.90	3435005V3	39	59.20
3415005V4	95	26.70	3425005V4	40	48.70	3435005V4	39	30.60
3415020V1	132	654.30	3425020V1	55	648.00	3435020V1	50	478.80
3415020V2	117	345.50	3425020V2	54	601.10	3435020V2	48	448.00
3415020V3	106	70.80	3425020V3	45	143.70	3435020V3	42	116.20
3415020V4	106	35.40	3425020V4	43	72.60	3435020V4	42	59.20

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 25 Simulation results for C3L5 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3510205V1	127	91.5	3520205V1	28.5	444	3530205V1	27	301.2
3510205V2	126	46.0	3520205V2	26	253.5	3530205V2	26	179.8
3510205V3	123	9.2	3520205V3	25	55.0	3530205V3	24.5	40.3
3510205V4	123	4.6	3520205V4	25	27.6	3530205V4	24	20.3
3510220V1	143	133.1	3520220V1	32	627.4	3530220V1	30	523.9
3510220V2	143	66.6	3520220V2	29	335.6	3530220V2	28	291.1
3510220V3	142	13.4	3520220V3	26	70	3530220V3	26	61.9
3510220V4	142	6.7	3520220V4	26	35	3530220V4	26	31.0
3511505V1	131	223.1	3521505V1	29	527.9	3531505V1	27	351.5
3511505V2	127	115.0	3521505V2	29	527.9	3531505V2	27	351.1
3511505V3	123	23.2	3521505V3	26	134.6	3531505V3	25	97.7
3511505V4	123	11.6	3521505V4	25	69	3531505V4	24.5	50.2
3511520V1	149	329.2	3521520V1	33	759.6	3531520V1	31	623.7
3511520V2	142	166.5	3521520V2	33	759.6	3531520V2	31	623.7
3511520V3	142	33.4	3521520V3	28	172.5	3531520V3	26	152.4
3511520V4	142	16.7	3521520V4	27	87.1	3531520V4	26	77.2
3515005V1	142	411.4	3525005V1	29	527.9	3535005V1	27	351.5
3515005V2	131	223.1	3525005V2	29	527.9	3535005V2	27	351.5
3515005V3	23	46.3	3525005V3	26	253.5	3535005V3	26	179.8
3515005V4	123	23.2	3525005V4	25	134.4	3535005V4	25	97.7
3515020V1	164	631.6	3525020V1	33	771.6	3535020V1	31	632.7
3515020V2	149	329.2	3525020V2	33	771.6	3535020V2	31	632.7
3515020V3	142	66.9	3525020V3	29	336	3535020V3	28	291.1
3515020V4	142	33.4	3525020V4	28	172.5	3535020V4	26	152.4

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 26 Simulation results for C3L5 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3510205V1	103	104.4	3520205V1	19	530	3530205V1	10.5	543.5
3510205V2	101	52.6	3520205V2	17	313.5	3530205V2	10	505.3
3510205V3	98	10.6	3520205V3	15	73.1	3530205V3	9	140
3510205V4	98	5.3	3520205V4	15	36.9	3530205V4	8.5	72.7
3510220V1	113	140.5	3520220V1	23	725	3530220V1	12	708.5
3510220V2	113	70.4	3520220V2	20	405.8	3530220V2	12	708.5
3510220V3	108	14.1	3520220V3	16	85.5	3530220V3	9	164.8
3510220V4	108	7.0	3520220V4	16	42.9	3530220V4	9	83.9
3511505V1	108	34.9	3521505V1	21.5	567.9	3531505V1	10	543.1
3511505V2	103	129.9	3521505V2	21.5	567.9	3531505V2	10	543.1
3511505V3	98	26.4	3521505V3	18	169.6	3531505V3	9	304.2
3511505V4	98	13.2	3521505V4	17	88	3531505V4	9	170.6
3511520V1	121	344.1	3521520V1	25	794.7	3531520V1	12	776.4
3511520V2	113	175.2	3521520V2	25	794.7	3531520V2	12	776.4
3511520V3	108	35.2	3521520V3	19	203.8	3531520V3	10	387
3511520V4	108	17.6	3521520V4	18	103.5	3531520V4	9.5	203.6
3515005V1	117	448.8	3525005V1	21.5	567.9	3535005V1	10	543.1
3515005V2	108	349.4	3525005V2	21.5	567.9	3535005V2	10	543.1
3515005V3	101	52.6	3525005V3	19	309.6	3535005V3	10	505.2
3515005V4	98	26.4	3525005V4	18	169.6	3535005V4	9	304.2
3515020V1	134	651.7	3525020V1	25	794.7	3535020V1	12	776.5
3515020V2	121	344.1	3525020V2	25	794.7	3535020V2	12	776.5
3515020V3	113	70.4	3525020V3	21	390.6	3535020V3	12	709.2
3515020V4	108	35.2	3525020V4	19	203.8	3535020V4	10	387

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

Table E. 27 Simulation results for C3L6 design alternative over low hydraulic conductivity aquitards ($k = 1 \times 10^{-8}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3610205V1	127	91.5	3620205V1	N/A ^d	N/A	3630205V1	N/A ^d	N/A
3610205V2	126	46.0	3620205V2	N/A	N/A	3630205V2	N/A	N/A
3610205V3	123	9.2	3620205V3	N/A	N/A	3630205V3	N/A	N/A
3610205V4	123	4.6	3620205V4	N/A	N/A	3630205V4	N/A	N/A
3610220V1	143	133.1	3620220V1	N/A	N/A	3630220V1	N/A	N/A
3610220V2	143	66.6	3620220V2	N/A	N/A	3630220V2	N/A	N/A
3610220V3	142	13.4	3620220V3	N/A	N/A	3630220V3	N/A	N/A
3610220V4	142	6.7	3620220V4	N/A	N/A	3630220V4	N/A	N/A
3611505V1	131	223.1	3621505V1	N/A	N/A	3631505V1	N/A	N/A
3611505V2	127	115.0	3621505V2	N/A	N/A	3631505V2	N/A	N/A
3611505V3	123	23.2	3621505V3	N/A	N/A	3631505V3	N/A	N/A
3611505V4	123	11.6	3621505V4	N/A	N/A	3631505V4	N/A	N/A
3611520V1	149	329.2	3621520V1	N/A	N/A	3631520V1	N/A	N/A
3611520V2	142	166.5	3621520V2	N/A	N/A	3631520V2	N/A	N/A
3611520V3	142	33.4	3621520V3	N/A	N/A	3631520V3	N/A	N/A
3611520V4	142	16.7	3621520V4	N/A	N/A	3631520V4	N/A	N/A
3615005V1	142	411.4	3625005V1	N/A	N/A	3635005V1	N/A	N/A
3615005V2	131	223.1	3625005V2	N/A	N/A	3635005V2	N/A	N/A
3615005V3	23	46.3	3625005V3	N/A	N/A	3635005V3	N/A	N/A
3615005V4	123	23.2	3625005V4	N/A	N/A	3635005V4	N/A	N/A
3615020V1	164	631.6	3625020V1	N/A	N/A	3635020V1	N/A	N/A
3615020V2	149	329.2	3625020V2	N/A	N/A	3635020V2	N/A	N/A
3615020V3	142	66.9	3625020V3	N/A	N/A	3635020V3	N/A	N/A
3615020V4	142	33.4	3625020V4	N/A	N/A	3635020V4	N/A	N/A

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

^d design does not satisfy stability performance criterion

Table E. 28 Simulation results for C3L6 design alternative over high hydraulic conductivity aquitards ($k = 1 \times 10^{-7}$ m/s)

Design ^a	Arid		Moderate			Humid		
	T ^b (y)	C ^c (mg/L)	Design	T (y)	C (mg/L)	Design	T (y)	C (mg/L)
3610205V1	103	104.4	3620205V1	19	530	3630205V1	N/A ^d	N/A
3610205V2	101	52.6	3620205V2	17	313.5	3630205V2	N/A	N/A
3610205V3	98	10.6	3620205V3	15	73.1	3630205V3	N/A	N/A
3610205V4	98	5.3	3620205V4	15	36.9	3630205V4	N/A	N/A
3610220V1	113	140.5	3620220V1	23	725	3630220V1	N/A	N/A
3610220V2	113	70.4	3620220V2	20	405.8	3630220V2	N/A	N/A
3610220V3	108	14.1	3620220V3	16	85.5	3630220V3	N/A	N/A
3610220V4	108	7.0	3620220V4	16	42.9	3630220V4	N/A	N/A
3611505V1	108	34.9	3621505V1	21.5	567.9	3631505V1	N/A	N/A
3611505V2	103	129.9	3621505V2	21.5	567.9	3631505V2	N/A	N/A
3611505V3	98	26.4	3621505V3	18	169.6	3631505V3	N/A	N/A
3611505V4	98	13.2	3621505V4	17	88	3631505V4	N/A	N/A
3611520V1	121	344.1	3621520V1	25	794.7	3631520V1	N/A	N/A
3611520V2	113	175.2	3621520V2	25	794.7	3631520V2	N/A	N/A
3611520V3	108	35.2	3621520V3	19	203.8	3631520V3	N/A	N/A
3611520V4	108	17.6	3621520V4	18	103.5	3631520V4	N/A	N/A
3615005V1	117	448.8	3625005V1	21.5	567.9	3635005V1	N/A	N/A
3615005V2	108	349.4	3625005V2	21.5	567.9	3635005V2	N/A	N/A
3615005V3	101	52.6	3625005V3	19	309.6	3635005V3	N/A	N/A
3615005V4	98	26.4	3625005V4	18	169.6	3635005V4	N/A	N/A
3615020V1	134	651.7	3625020V1	25	794.7	3635020V1	N/A	N/A
3615020V2	121	344.1	3625020V2	25	794.7	3635020V2	N/A	N/A
3615020V3	113	70.4	3625020V3	21	390.6	3635020V3	N/A	N/A
3615020V4	108	35.2	3625020V4	19	203.8	3635020V4	N/A	N/A

^a simulation code

^b time that maximum concentration occurs

^c maximum concentration at the groundwater table

^d design does not satisfy stability performance criterion

APPENDIX-F

DIGITAL ELEVATION MODELS (DEM) FOR VIRTUAL LANDFILL MODEL

F.1. Base-DEM

ncols 149
nrows 250
xllcorner 498285.4254264
yllcorner 4198984.8884888
cellsize 5.3416012000043
NODATA_value -9999
-9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999
-9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 969.0527 968.5507 967.9955
967.4854 966.9977 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999
-9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 969.2311 968.9075 968.5374 968.1226 967.692 967.2805 966.874 966.4358
965.8516 965.2787 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999 -9999 -9999 -9999 --9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999

9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999
-9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -9999 -
9999 -9999 -9999 -9999

F.2. Clay-DEM: Top

NCOLS 7
NROWS 5
XLLCORNER 498300
YLLCORNER 4199900
CELLSIZE 100.00
NODATA_VALUE -9999.000
-9999.000 -9999.000 968.794 -9999.000 -9999.000 -9999.000 -9999.000
-9999.000 960.584 964.660 966.200 944.000 -9999.000 -9999.000
-9999.000 965.100 953.064 965.900 966.800 965.300 -9999.000
-9999.000 -9999.000 944.459 966.650 975.200 967.500 -9999.000
-9999.000 -9999.000 937.000 959.500 975.500 963.600 951.000

F.3. Clay-DEM: Bottom

NCOLS 7
NROWS 5
XLLCORNER 498300
YLLCORNER 4199900
CELLSIZE 100.00
NODATA_VALUE -9999.000
-9999.000 -9999.000 957.794 -9999.000 -9999.000 -9999.000 -9999.000
-9999.000 949.584 953.660 960.200 938.000 -9999.000 -9999.000
-9999.000 954.100 942.064 959.900 960.800 962.300 -9999.000
-9999.000 -9999.000 933.459 960.650 969.200 964.500 -9999.000

-9999.000 -9999.000 926.000 953.500 969.500 960.600 950.000

F.4. Groundwater-DEM: Depth

NCOLS 7

NROWS 5

XLLCORNER 498300

YLLCORNER 4199900

CELLSIZE 100.00

NODATA_VALUE -9999.000

-9999.000 -9999.000 10.794 -9999.000 -9999.000 -9999.000 -9999.000

-9999.000 11.584 9.660 8.200 6.000 -9999.000 -9999.000

-9999.000 11.100 9.064 8.900 6.800 3.300 -9999.000

-9999.000 -9999.000 9.459 8.650 5.200 3.500 -9999.000

-9999.000 -9999.000 9.000 7.500 5.500 3.600 3.000

F.5. Groundwater-DEM: Direction

NCOLS 7

NROWS 5

XLLCORNER 498300

YLLCORNER 4199900

CELLSIZE 100.00

NODATA_VALUE -9999.000

-9999.000 -9999.000 57.794 -9999.000 -9999.000 -9999.000 -9999.000

-9999.000 49.584 53.660 60.200 38.000 -9999.000 -9999.000

-9999.000 54.100 42.064 59.900 60.800 62.300 -9999.000

-9999.000 -9999.000 33.459 60.650 69.200 64.500 -9999.000

-9999.000 -9999.000 26.000 53.500 69.500 60.600 50.000

APPENDIX-G

PERFORMANCE REPORTS PRESENTED BY LFDSS

G.1. Siirt Municipal Solid Waste Landfill Case Study

C1L2,0.412059310093705,177.77202359375,3.19753280971486,,3.48939250033159,,3.47976810827197,,2.41804742076412:1.61203161384274:5.44060669671926:3.62707113114617,,1914468.51,30450,1944918.51

C1L4L,1.17249841380301,135.54014234375,3.19753280971486,,3.48939250033159,,3.47976810827197,,2.41804742076412:1.61203161384274:5.44060669671926:3.62707113114617,,1768528.51,30450,1798978.51

C3L2,0.43108218233377,180.77375,3.19753280971486,,3.48939250033159,,45.6805678449124,,2.41804742076412:1.61203161384274:5.44060669671926:3.62707113114617,,2507813.51,30450,2538263.51

C3L4L,1.21587401637304,135.54014234375,3.19753280971486,,3.48939250033159,,45.6805678449124,,2.41804742076412:1.61203161384274:5.44060669671926:3.62707113114617,,2097873.51,30450,2128323.51

C2L1,27.300851078987,91.7644375,3.19753280971486,,3.48939250033159,,,,9.16546829404725,,2224323.51,43500,2267823.51

C2L5,27.1129931286085,95.470440625,3.19753280971486,,3.48939250033159,,
,,9.16546829404725,,2501693.51,43500,2545193.51

G.2. X-City Municipal Solid Waste Landfill Case Study

C1L1,478.543042393043,30.627090625,1.93698511401535,,4.92608534100826,,
,5.52787104235528,,,,,1365913.27,0,1365913.27

C1L6,477.801922884831,32.04772515625,1.93698511401535,,4.9260853410082
6,,5.52787104235528,,,,,1513969.27,0,1513969.27

C2L1,430.051536018161,594.27625,1.93698511401535,,4.92608534100826,,,,,1
6.6330993279735,,1.70555641358764,1942563.27,43500,1986063.27

C2L6,428.853358456206,641.8519375,1.93698511401535,,4.92608534100826,,,,
,16.6330993279735,,1.70555641358764,2106819.27,43500,2150319.27

C3L1,473.111119403799,32.04772515625,1.93698511401535,,4.9260853410082
6,,,,,135.337487570689,,,,,1802563.27,0,1802563.27

C3L6,472.180902137091,34.2481130714453,1.93698511401535,,4.92608534100
826,,,,,135.337487570689,,,,,1966819.27,0,1966819.27

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FOREIGN LANGUAGES

Advanced English, Intermediate French, Beginning German

SELECTED PUBLICATIONS

Papers Published in International Peer-Reviewed Journals (Science Citation Index)

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7. Tarhan, B., ve Ünlü, K., (2004). Performance Based Sanitary Landfill Design: Geographic Information Systems Interfaced with System Simulation Models. CD-ROM: ISWA 2004 World Environment Congress and Exhibition, 17-21 October 2004, Rome, Italy.
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