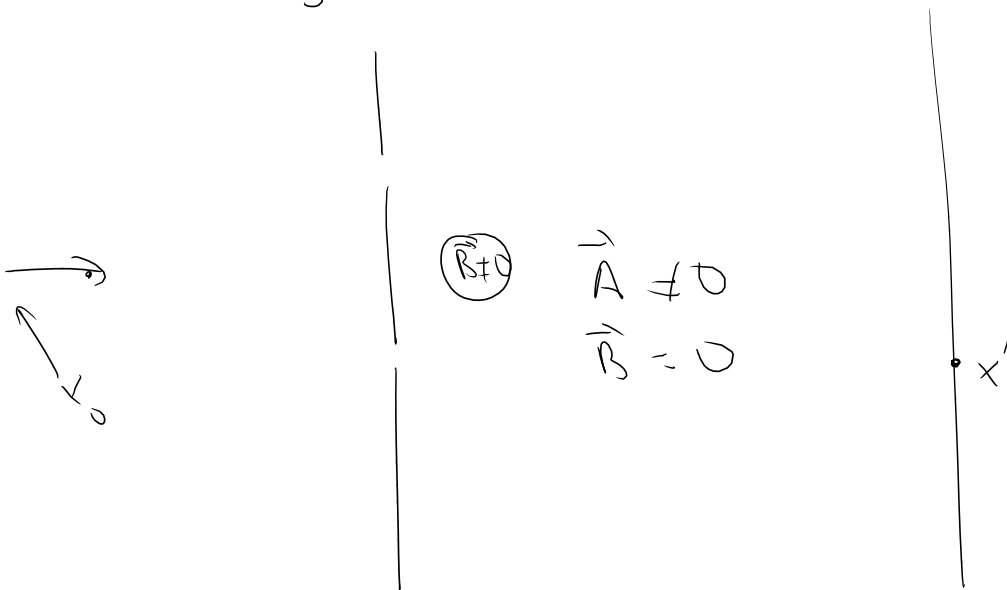


Aharonov-Bohm Effect in Path-Integrals

$$G(x, x'; t) \equiv \langle x' | e^{-\frac{i}{\hbar} H t} | x \rangle$$

$$= \int_{\mathcal{P}} x e^{\frac{i}{\hbar} S[x(t)]}$$

$$S[x] = \int_0^t dt' \mathcal{L}(\dot{x}, x; t')$$



$$\langle x' | e^{-\frac{i}{\hbar} H t} | x_0 \rangle$$

$$\mathcal{L} = \mathcal{L}^0 + q \vec{v} \cdot \vec{A}$$

$$\int_{\mathcal{P}} x e^{\frac{i}{\hbar} S} = \int_{\mathcal{P}} x e^{\frac{i}{\hbar} S} + \int_{\mathcal{P}} x e^{\frac{i}{\hbar} S}$$

$x(t)$ goes above $x(t)$ goes below

$$S[x(t)] - S[x'(t)] = \int_0^t dt q(\vec{v} \cdot \vec{A} - \vec{v}' \cdot \vec{A})$$

x, x' goes above
 B

$$\vec{v} dt = \frac{d\vec{\ell}}{dt} dt = d\vec{\ell}$$

$$\int dt q \vec{v} \cdot \vec{A} = q \int_{x_0}^{x_1} \vec{A} \cdot d\vec{\ell}$$

$$\int_{\text{path 1}}^{x_1} \vec{A} \cdot d\vec{\ell} - \int_{\text{path 2}}^{x_1} \vec{A} \cdot d\vec{\ell} = \oint \vec{A} \cdot d\vec{\ell} = \int (\vec{\nabla} \times \vec{A}) \cdot d\vec{S}$$

$= \begin{cases} 0 & \text{if both paths go above or below} \\ \phi_B & \text{if one goes above and the other goes below} \end{cases}$

$$\int_{\text{loop}} x e^{\frac{i}{\hbar} S} = \int_{\text{loop}} x e^{\frac{i}{\hbar} S} + \int_{\text{loop}} x e^{\frac{i}{\hbar} S}$$

\searrow
 $= e^{\frac{q_i}{\hbar} \int_{x_0}^{x_1} \vec{A} \cdot d\vec{\ell}_{\text{above}}}$

\searrow
 $= e^{\frac{q_i}{\hbar} \int_{x_0}^{x_1} \vec{A} \cdot d\vec{\ell}_{\text{below}}}$

$= e^{\frac{q_i}{\hbar} \int_{\text{above}} \vec{A} \cdot d\vec{\ell}}$

$\left[M_1 + e^{\frac{q_i}{\hbar} \phi_B} M_2 \right]$

$$G(x, x'; t) = \int \mathcal{D}x e^{\frac{i}{\hbar} S[x]}$$

$$\int \mathcal{D}x = \lim_{N \rightarrow \infty} \prod_{i=1}^{N-1} dx_i$$

$$\int_{\mathcal{R}} dx_i = \int_{\mathcal{R}} d(x_i + \delta_i)$$

$$x_i = y_i + \delta_i$$

$$\int_{\mathcal{R}} dx_i = \int_{\mathcal{R}} dy_i$$

$$\mathcal{D}x = \mathcal{D}y$$

$$\int \mathcal{D}x e^{\frac{i}{\hbar} S[x]} = \int \mathcal{D}(y + \delta y) e^{\frac{i}{\hbar} S[y + \delta y]}$$

$$= \int \mathcal{D}y e^{\frac{i}{\hbar} S[y + \delta y]}$$

$$= \int \mathcal{D}x e^{\frac{i}{\hbar} S[x + \delta x]}$$

$$\int \mathcal{D}x \left(e^{\frac{i}{\hbar} S[x]} - e^{\frac{i}{\hbar} S[x + \delta x]} \right) = 0$$

if δx are small and arbitrary

$$\int \mathcal{D}x e^{\frac{i}{\hbar} S[x]} \delta S = 0 = \langle \delta S \rangle$$

$$G(x, x', t) = \langle x' | e^{-\frac{i}{\hbar} H t} | x \rangle$$

change of notation

$$e^{-\frac{i}{\hbar} H t} = e^{-\frac{i}{\hbar} H \epsilon} e^{-\frac{i}{\hbar} H \epsilon} e^{-\frac{i}{\hbar} H \epsilon} \dots e^{-\frac{i}{\hbar} H \epsilon}$$

$$e^{-\frac{i}{\hbar} H t} | x \rangle = e^{-\frac{i}{\hbar} H \epsilon} e^{-\frac{i}{\hbar} H \epsilon} e^{-\frac{i}{\hbar} H \epsilon} \dots e^{-\frac{i}{\hbar} H \epsilon} | x \rangle$$

\uparrow $t=0$

$$= T e^{-\frac{i}{\hbar} \int_0^t dt' H(t')} | x \rangle$$

act at the time t'

$H(t')$ acts on my state at time t'

$$G(x, x', t) = \langle x' | T e^{-\frac{i}{\hbar} \int_0^t dt' H(t')} | x \rangle$$

$x(t') \equiv \hat{x}$ but acts on my state when it evolves until the time t'

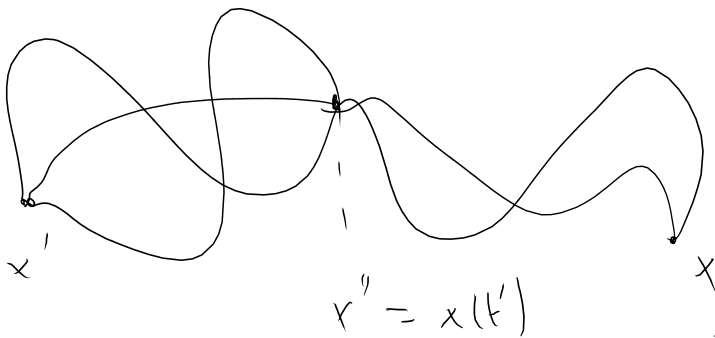
$$\langle x' | e^{-\frac{i}{\hbar} H(t-t')} x e^{-\frac{i}{\hbar} H t'} | x \rangle = \langle x' | T \left\{ x(t') e^{-\frac{i}{\hbar} \int H dt} \right\} | x \rangle$$

$$\langle x' | e^{-\frac{i}{\hbar} H(t-t')} \hat{x} e^{-\frac{i}{\hbar} H t'} | x \rangle$$

$$= \langle x' | e^{-\frac{i}{\hbar} H(t-t')} \int dx'' | x'' \rangle \langle x'' | e^{-\frac{i}{\hbar} H t'} | x \rangle$$

$$= \int dx'' \langle x' | e^{-\frac{i}{\hbar} H(t-t')} | x'' \rangle \langle x'' | e^{-\frac{i}{\hbar} H t'} | x \rangle$$

$$= \int dx'' \int_{x(t)=x'}^{x(t')=x''} \mathcal{D}x e^{-\frac{i}{\hbar} \int_{t'}^t \mathcal{L} dt} \int_{x(t=0)=x}^{x(t')=x''} \mathcal{D}x e^{-\frac{i}{\hbar} \int_0^{t'} \mathcal{L} dt}$$



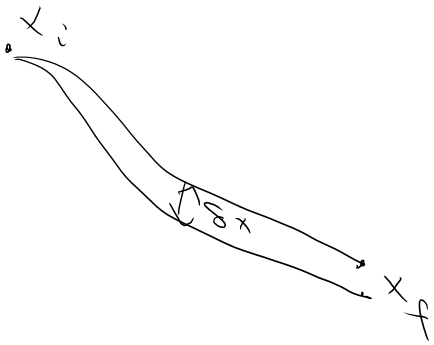
$$= \int_{x(t=0)=x}^{x(t')=x'} \mathcal{D}x x(t') e^{-\frac{i}{\hbar} S[x]}$$

$$= \langle x' | e^{-\frac{i}{\hbar} H(t-t')} x(t') e^{-\frac{i}{\hbar} H t'} | x \rangle$$

$$G(x, x'; t)$$

$$\frac{\partial G}{\partial x} = \int \mathcal{L} x \frac{\partial}{\partial x} \left(e^{-\frac{1}{\hbar} S} \right)$$

$$\frac{\partial G}{\partial x} = \int \mathcal{L} x \frac{1}{\hbar} \left(\frac{\partial S}{\partial x} \right) e^{-\frac{1}{\hbar} S}$$



$$\delta S = \int dt \delta \mathcal{L}$$

$$= \int dt \left(\frac{\partial \mathcal{L}}{\partial x} \delta x + \frac{\partial \mathcal{L}}{\partial \dot{x}} \delta \dot{x} \right)$$

$$= \int dt \left(\frac{\partial \mathcal{L}}{\partial \dot{x}} \delta \dot{x} \right) dt$$

$$+ \int dt \left(\frac{\partial \mathcal{L}}{\partial x} - \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{x}} \right) \delta x$$

$$\delta S = \left. \frac{\partial \mathcal{L}}{\partial \dot{x}} \delta x \right|_{t=t_i}^{t=t_f} = p_f \delta x_f - p_i \delta x_i$$

$\delta x(t=0) = \delta x(t_f) = 0$

$$\frac{\partial S}{\partial x} = p$$

$$\frac{\partial G}{\partial x} = \int \mathcal{L} x \left(\frac{i}{\hbar} \frac{\partial S}{\partial x} \right) e^{\frac{i}{\hbar} S}$$

$$= \int \mathcal{L} x \left(\frac{i}{\hbar} p \right) e^{\frac{i}{\hbar} S}$$

$$\frac{\partial^2 G}{\partial x^2} = \int \mathcal{L} x \left(\frac{i}{\hbar} p \right)^2 e^{\frac{i}{\hbar} S}$$

$$\frac{\partial S}{\partial t} = -H$$

$$dL = p dq - H dt$$

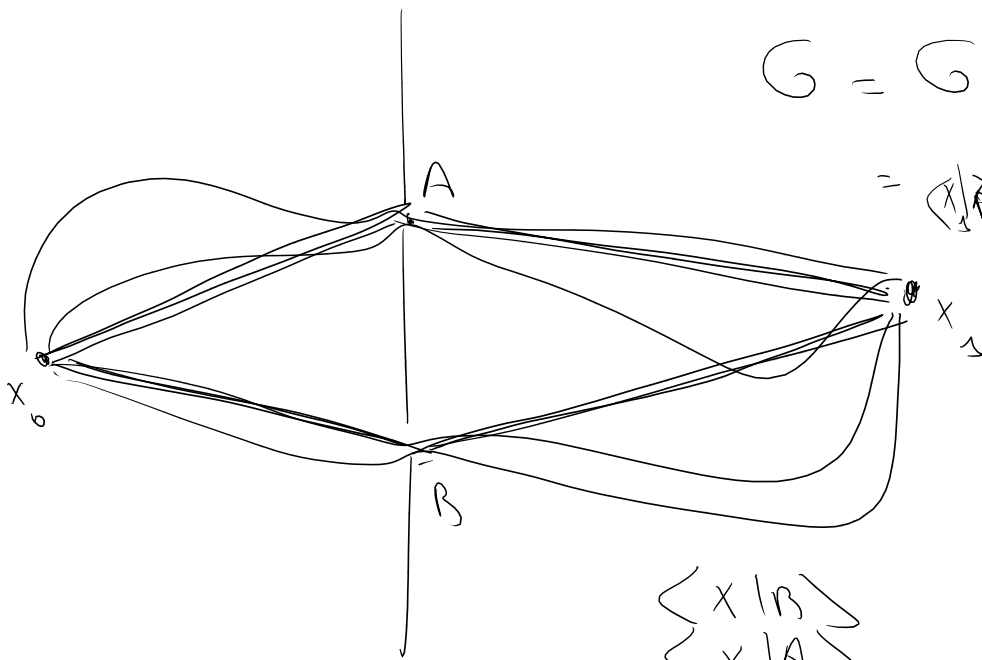
$$\frac{\partial G}{\partial t} = \int \mathcal{L} x \left(\frac{i}{\hbar} \frac{\partial S}{\partial t} \right) e^{\frac{i}{\hbar} S}$$

$$= \int \mathcal{L} x \left(\frac{i}{\hbar} H \right) e^{\frac{i}{\hbar} S}$$

$$= \int \mathcal{L} x \left(\frac{i}{\hbar} \right) \left(\frac{p^2}{2m} + V(x) \right) e^{\frac{i}{\hbar} S}$$

$$= \frac{i}{\hbar} \left[\left(\frac{\partial}{\partial x} \right)^2 \frac{1}{2m} + V(x) \right] G$$

$$\psi(x, t) = \int dx' G(x, x', t) \psi(x'; t=0)$$



$$G = G_{\text{lower}} + G_{\text{higher}}$$

$$= \langle x_1 | B \rangle \langle B | x_0 \rangle + \langle x_1 | A \rangle \langle A | x_0 \rangle$$

$$\begin{cases} \langle x | B \rangle \\ \langle x | A \rangle \end{cases}$$

$$S_{\text{cl}}^{\text{free}} = \int dt \frac{1}{2} m \dot{x}^2 = \frac{1}{2} m v^2 t$$

$$= \frac{1}{2} m \frac{(\overbrace{x - x_0}^{\Delta x})^2}{t} \uparrow$$

$$= \frac{1}{2} m \Delta x v$$

$$\frac{i}{\hbar} \Delta L$$

$\sim \epsilon$

SHO

$\propto \sqrt{A}^{1/2}$

$$G(x_i, x_f; t) = \sqrt{\frac{m\omega}{2\pi i k \sin \omega(t_f - t_i)}} \exp\left\{ \frac{i}{\hbar} \frac{1}{2} m\omega \frac{(x_i^2 + x_f^2) \cos \omega(t_f - t_i) - 2x_i x_f}{\sin \omega(t_f - t_i)} \right\}$$

$$= \langle x_f | e^{-\frac{i}{\hbar} H t} | x_i \rangle \quad t \equiv t_f - t_i$$

$$\frac{i}{\hbar} t \equiv \beta \Rightarrow t = -i\beta\hbar$$

$$\sin(\omega t) = \frac{e^{i\omega t} - e^{-i\omega t}}{2i} = \frac{e^{\beta\hbar\omega} - e^{-\beta\hbar\omega}}{2i} = -i \sinh(\beta\hbar\omega)$$

$$\cos(\omega t) = \frac{e^{i\omega t} + e^{-i\omega t}}{2} = \cosh(\beta\hbar\omega)$$

$$G(x_i, x_f; t) = \sqrt{\frac{m\omega}{2\pi i k \sin \omega(t_f - t_i)}} \exp\left\{ \frac{i}{\hbar} \frac{1}{2} m\omega \frac{(x_i^2 + x_f^2) \cos \omega(t_f - t_i) - 2x_i x_f}{\sin \omega(t_f - t_i)} \right\}$$

$$= \sqrt{\frac{m\omega}{2\pi k \sinh(\hbar\omega\beta)}} \exp\left\{ -\frac{m\omega}{2\hbar} \frac{(x_i^2 + x_f^2) \cosh(\hbar\omega\beta) - 2x_i x_f}{\sinh(\hbar\omega\beta)} \right\}$$

$$Z = \int dx \langle x | e^{-\beta H} | x \rangle \quad \int_{-\infty}^{\infty} dx e^{-ax^2} = \sqrt{\frac{\pi}{a}}$$

$$= \int dx \sqrt{\frac{hw}{2\pi k \sinh(kw\beta)}} \exp \left\{ -\frac{mw}{2k} x^2 \frac{(\cosh kw\beta - 1)}{\sinh(kw\beta)} \right\}$$

$$= \sqrt{\frac{mw}{2\pi k \sinh(kw\beta)}} \sqrt{\frac{\cancel{2\pi k \sinh(kw\beta)}}{mw(\cosh kw\beta - 1)}}$$

$$Z = \sqrt{\frac{1}{2}} \frac{1}{\sqrt{\cosh(kw\beta) - 1}}$$

$$\cosh(\Theta) = \frac{e^{\Theta} + e^{-\Theta}}{2} = \frac{(e^{\Theta/2} + e^{-\Theta/2})^2}{2} + 1$$

$$\cosh(\Theta) = 2 \left(\sinh \frac{\Theta}{2} \right)^2 + 1$$

$$Z = \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2 \sinh^2 \left(\frac{k w \beta}{2} \right)}} = \frac{1}{2} \frac{1}{\sinh \left(\frac{k w \beta}{2} \right)}$$

$$Z = \frac{1}{e^{\frac{hw\beta}{2}} - e^{-\frac{hw\beta}{2}}} = \frac{e^{-\frac{hw\beta}{2}}}{1 - e^{-hw\beta}}$$

$$= e^{-\frac{hw\beta}{2}} \sum_{n=0}^{\infty} e^{-n hw\beta}$$

$$= \sum_{n=0}^{\infty} e^{-\frac{hw(n+1/2)}{\beta}}$$

$$\langle x_f | e^{-\beta H} | x_i \rangle = \sum e^{-\beta E_n} \varphi_n(x_f) \varphi_n(x_i)$$

$$\xrightarrow{\beta \rightarrow \infty} e^{-\beta E_0} \varphi_0(x_f) \varphi_0(x_i)$$

$$\sinh(kw\beta) \xrightarrow{\beta \rightarrow \infty} \frac{e^{kw\beta}}{2}$$

$$\cosh(kw\beta) \xrightarrow{\beta \rightarrow \infty} \frac{e^{kw\beta}}{2}$$

$$G = \sqrt{\frac{mw}{2\pi k \sinh(kw\beta)}} \exp \left\{ -\frac{mw}{2k} \frac{(x_i^2 + x_f^2) \cosh(kw\beta) - 2x_i x_f}{\sinh(kw\beta)} \right\}$$

$$\xrightarrow{\beta \rightarrow \infty} \sqrt{\frac{mw}{2\pi k e^{kw\beta}}} \exp \left\{ -\frac{mw}{2k} (x_i^2 + x_f^2) \right\}$$

$$= \sqrt{\frac{mw}{2\pi k}} \exp \left\{ -\frac{mw}{2k} x_i^2 \right\} \exp \left\{ -\frac{mw}{2k} x_f^2 \right\} e^{-\frac{k w \beta}{2}}$$

$$E_0 = \frac{k w}{2}; \quad \varphi_0(x) \propto e^{-\frac{mw}{2k} x^2}$$

$$G = \langle x_f | e^{-H(\beta-\beta')} e^{-\beta' H} | x_i \rangle$$

$$\lim_{\beta' \rightarrow \infty} e^{-\beta' H} | x_i \rangle = e^{-\beta' E_0} | G \rangle \varphi_0(x_i)$$

$$\lim_{\beta \rightarrow \infty} \langle x \rangle e^{-\beta H} \propto \langle 1 \rangle$$

$$\lim_{\beta \rightarrow \infty} \langle x \rangle e^{-\beta H} \propto \langle 1 \rangle$$

$$K \int dx e^{-\beta H(x)}$$

$$\frac{1}{\mathcal{Z}} \int dt (L^0 + L'(x))$$

$$\Rightarrow \int dx e^{-\beta H(x)} \frac{1}{\mathcal{Z}} \int dt (L^0 + L'(x))$$

$$K = e^{-\beta \int dt (L^0 + L'(x))}$$

$$E_G = \lim_{\beta \rightarrow \infty} \frac{1}{K} \frac{\partial}{\partial \beta} K$$

J=0