

$$\mathcal{E} = -\frac{1}{c} \frac{d\Phi_B}{dt}$$

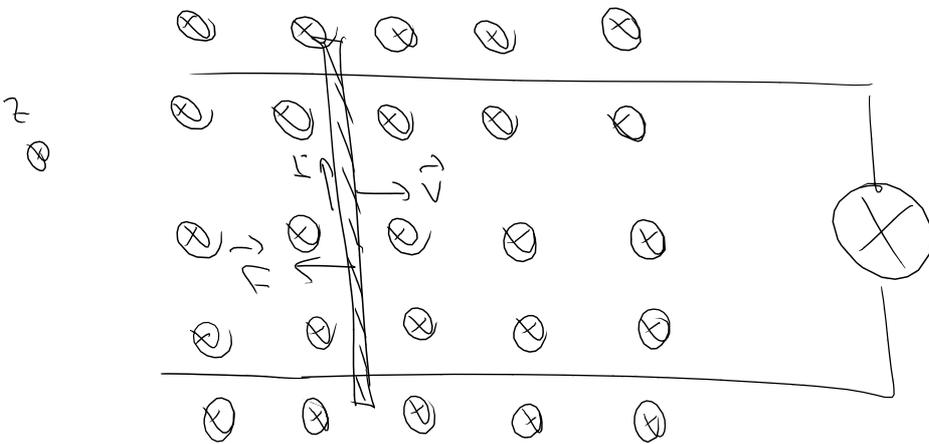
$$\Phi_B = \int_S \vec{B} \cdot d\vec{A}$$

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = \int_S (\vec{\nabla} \times \vec{E}) \cdot d\vec{A}$$

$$\int_S (\vec{\nabla} \times \vec{E}) \cdot d\vec{A} = -\frac{1}{c} \frac{d}{dt} \int_S \vec{B} \cdot d\vec{A} = -\frac{1}{c} \int_S \frac{\partial \vec{B}}{\partial t} \cdot d\vec{A}$$

$$\boxed{\vec{\nabla} \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t}}$$

Lenz Rule: induced current is in the direction which will oppose the change that creates it.

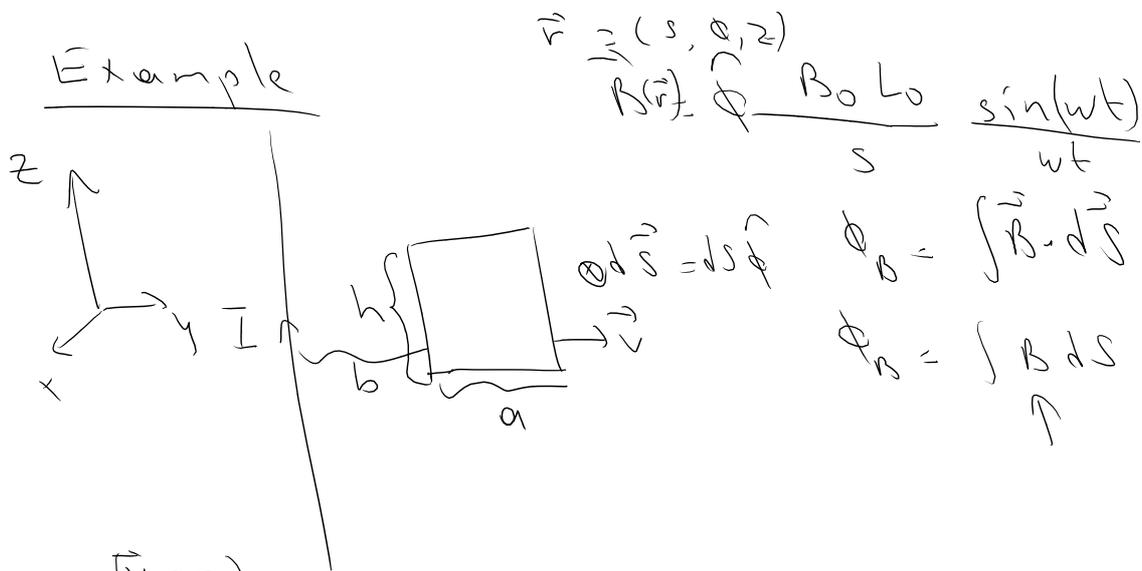


$$\vec{F} = q \vec{v} \times \vec{B}$$

$$d\vec{l} = I d\vec{l} \times \vec{B}$$

$$\Phi_B = \int \vec{B} \cdot d\vec{S}$$

Example



$(\vec{v} = 0)$

i) at  $t=0$ , what is the direction of the induced current?  
 counter clock wise

ii)  $\vec{v} = v_0 \hat{y}$   $v_0 > 0$  constant  
 direction of the induced current ( $\omega \rightarrow 0$ )

$\vec{B} = \hat{\phi} \frac{B_0 L_0}{s}$   
 clock wise  $\hat{s}$  direction

iii)  $\mathcal{E}(t) = ?$

$\mathcal{E} = - \frac{1}{c} \frac{d\phi_B}{dt}$

$\int \vec{B} \cdot d\vec{S} = \int \frac{B_0 L_0}{s} \frac{\sin \omega t}{\omega t} dz ds$   
 $= B_0 L_0 \frac{\sin \omega t}{\omega t} \int_0^h dz \int_b^{b+a} \frac{ds}{s}$

$\phi_B = B_0 L_0 \frac{\sin \omega t}{\omega t} h \ln\left(\frac{b+a}{b}\right)$

$\mathcal{E} = - \frac{1}{c} \frac{d\phi_B}{dt}$

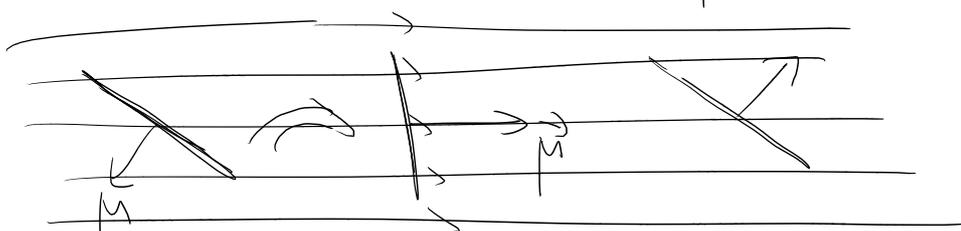
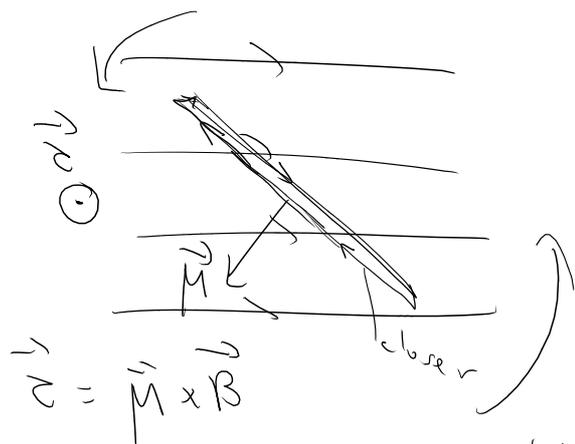
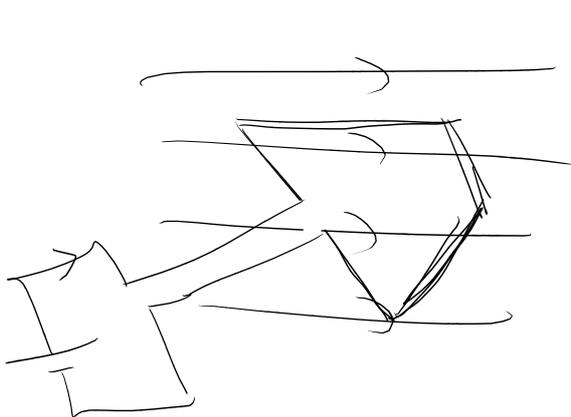
$$\begin{aligned}
 \mathcal{E} &= - \frac{B_0 L_0 h}{c} \ln\left(\frac{b+a}{b}\right) \frac{d}{dt} \frac{\sin \omega t}{\omega t} \\
 &= - \frac{B_0 L_0 h}{c} \frac{\sin \omega t}{\omega t} \frac{d}{dt} \ln\left(1 + \frac{a}{b}\right) \\
 &= - \frac{B_0 L_0 h}{c} \ln\left(\frac{b+a}{b}\right) \frac{d}{dt} \frac{\sin \omega t}{\omega t} \\
 &\quad - \frac{B_0 L_0 h}{c} \frac{\sin \omega t}{\omega t} \left[ \frac{d}{db} \ln\left(1 + \frac{a}{b}\right) \right] \frac{db}{dt}
 \end{aligned}$$

if  $\mathcal{E} > 0 \Rightarrow I_{ind} < 0$  clockwise

if  $\mathcal{E} < 0 \Rightarrow I_{ind} > 0$  counter clockwise

$$\mathcal{E} = - \frac{1}{c} \frac{d\phi_B}{dt}$$

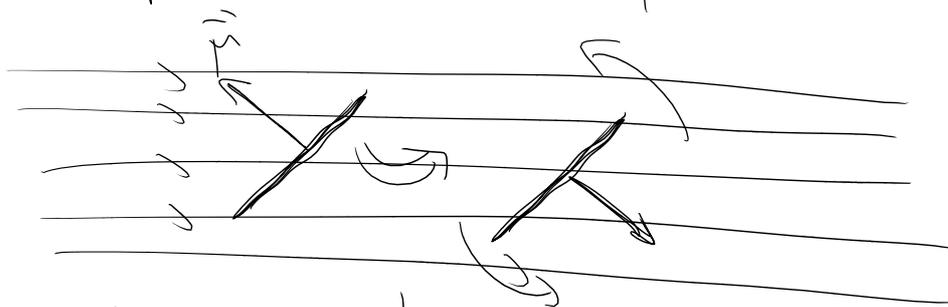
## Electric Generators & Electric Motors



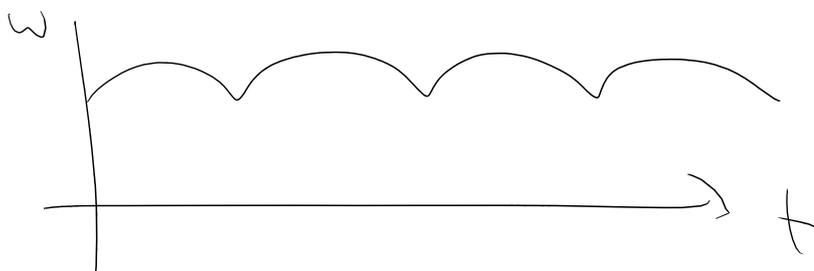
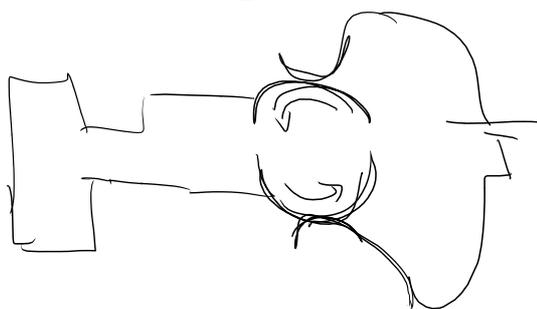
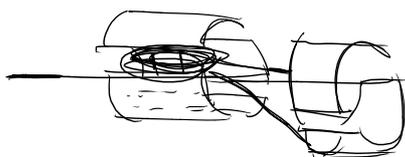
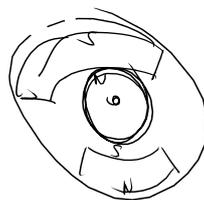
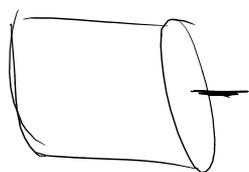
$$U = -\mu \cdot B$$

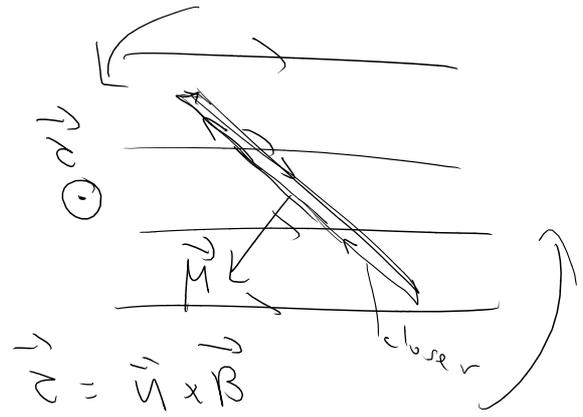
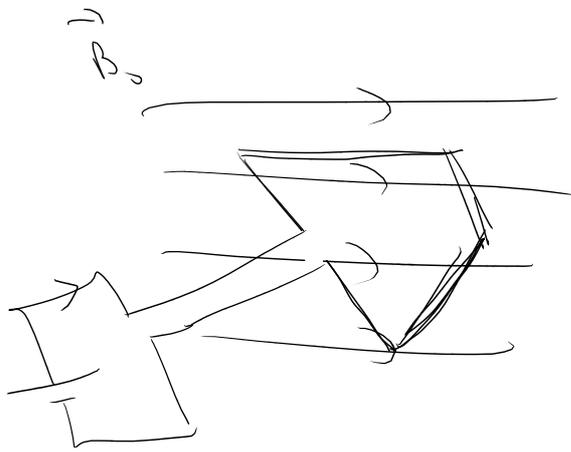
$$M = I a N$$

flip the direction of the current



electric motor.





$$\Phi_B = \int \vec{B} \cdot d\vec{S} = B_0 \int dS \cos \theta = B_0 A \cos \theta$$

$$\mathcal{E} = - \frac{1}{c} \frac{d\Phi_B}{dt} = + \frac{1}{c} B_0 A (\sin \theta) \frac{d\theta}{dt}$$

$$\mathcal{E} = \frac{B_0 A}{c} (\sin \theta) \omega(t)$$

if  $\theta = \omega t$   $\omega = \text{const}$

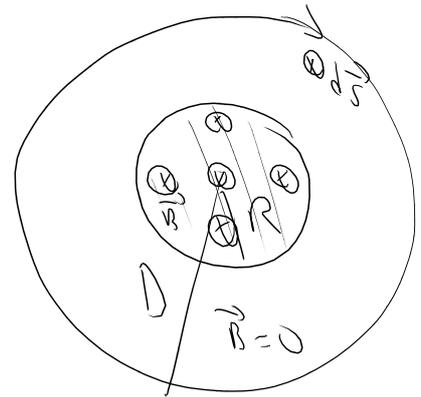
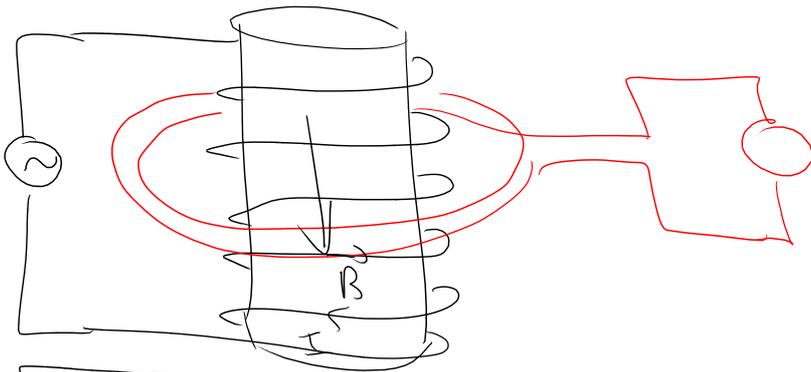
$$\mathcal{E} = \frac{B_0 A}{c} \omega \sin \omega t$$

$$[\mathcal{E}] = \left[ \int \vec{E} \cdot d\vec{l} \right] = [\vec{E}] [l]$$

$$[\vec{E}] [l] = [B_0] \frac{[A]}{c} [\omega]$$

$$[l] = \frac{[A]}{[c]} [\omega] = \frac{[A]}{[l][\omega]} [\omega] = [l]$$

# Example



$$\vec{B} = B_0 \sin(\omega t)$$

$$B_0 > 0 \text{ if } I > 0$$

$$\Phi_B = (2) B_0 \sin(\omega t) \pi R^2$$

$$\mathcal{E} = - \frac{1}{c} \left( \frac{d\Phi_B}{dt} \right) = - \frac{2 B_0 \pi R^2 \omega \cos(\omega t)}{c} = \mathcal{E}$$

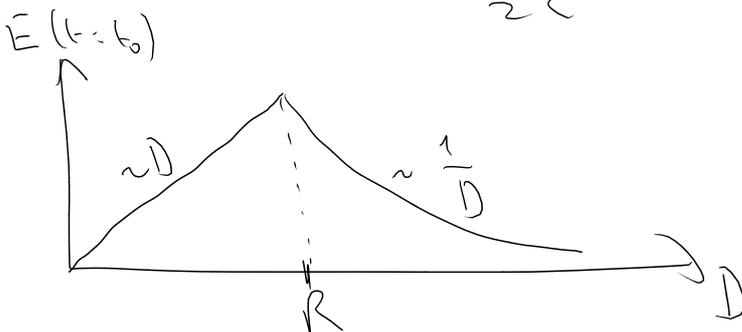
$$2 \pi D \mathcal{E} = - \frac{B_0 \pi R^2 \omega \cos(\omega t)}{c}$$

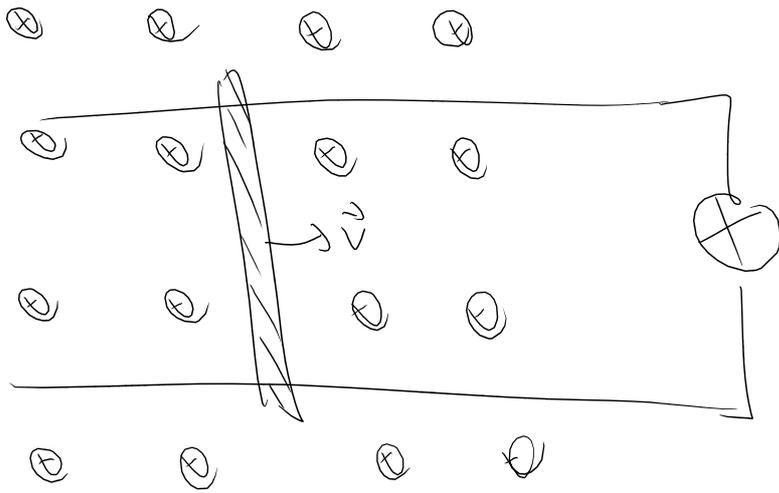
$$\mathcal{E} = - \frac{B_0 R^2 \omega \cos(\omega t)}{2c D}$$

$\mathcal{E}$  inside the solenoid ( $D < R$ )

$$2 \pi R \mathcal{E} = - B_0 \pi (D^2) \frac{\omega}{c} \cos(\omega t)$$

$$\mathcal{E} = \frac{B_0 \omega}{2c} D \cos(\omega t)$$



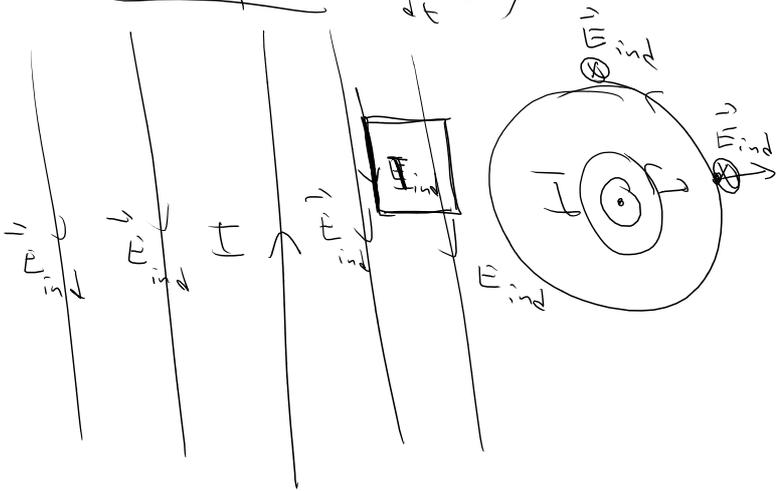


$$\vec{E}' = -\vec{v} \times \vec{B}$$

$$= \vec{B} \times \vec{v}$$

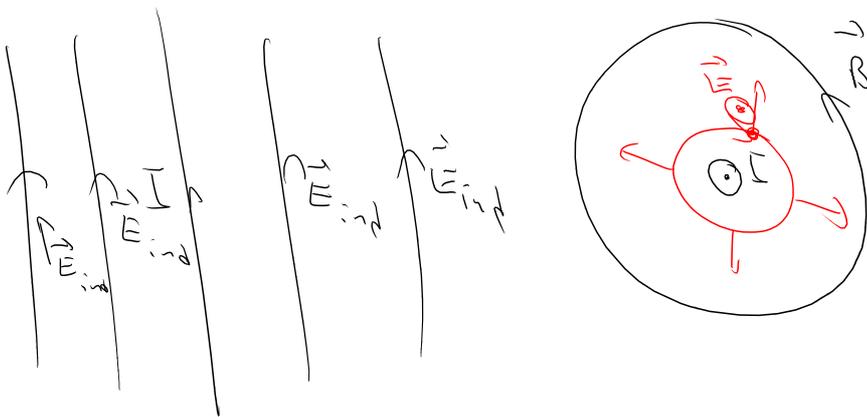
$\vec{v}$ : velocity of  $\vec{B}$  field lines

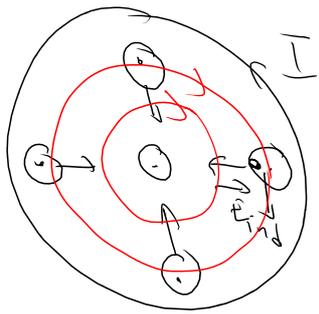
Example ( $\frac{dB}{dt} > 0$ )



Example ( $\frac{dB}{dt} < 0$ )

$$\vec{E}_{ind} = \vec{B} \times \vec{v}$$





$$\vec{E}_{ind} = \vec{B} \times \frac{\vec{v}}{c}$$

$$\vec{B} = \frac{\vec{v} \times \vec{E}}{c}$$

for a moving point charge.

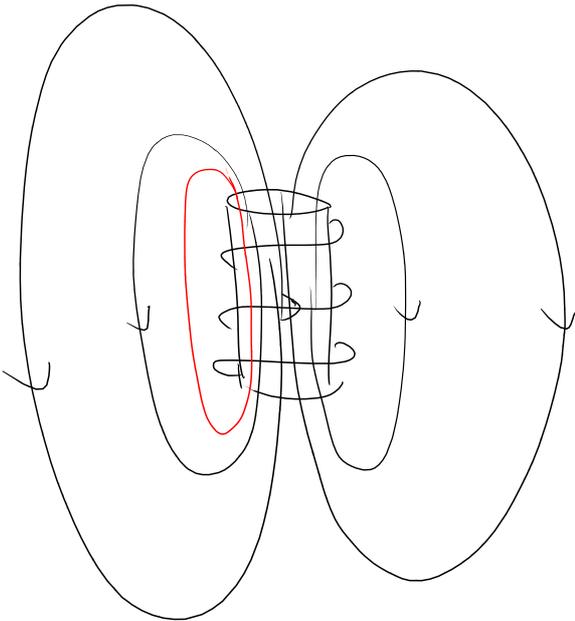
$$\vec{v} \times \vec{E}_{ind} = \vec{v} \times \left( \vec{B} \times \frac{\vec{v}}{c} \right)$$

$$= \vec{B} \left( \frac{v^2}{c} \right) - \vec{v} \left( \frac{\vec{B} \cdot \vec{v}}{c} \right)$$

assume  $\vec{B} \perp \vec{v} \Rightarrow \vec{B} \cdot \vec{v} = 0$

$$v = c$$

$$\vec{B} = \frac{\vec{v}}{c} \times \vec{E}_{ind}$$



$$\vec{\nabla} \times \vec{E} = - \frac{1}{c} \frac{\partial \vec{B}}{\partial t}$$

