

$$\langle x_N, t_N | x_1, t_1 \rangle$$

$$= \lim_{\Delta t \rightarrow 0} \left(\frac{m}{2\pi i \hbar \Delta t} \right)^{(N-1)/2} \int dx_2 \int dx_3 \dots \int dx_{N-2} e^{\frac{i}{\hbar} S}$$

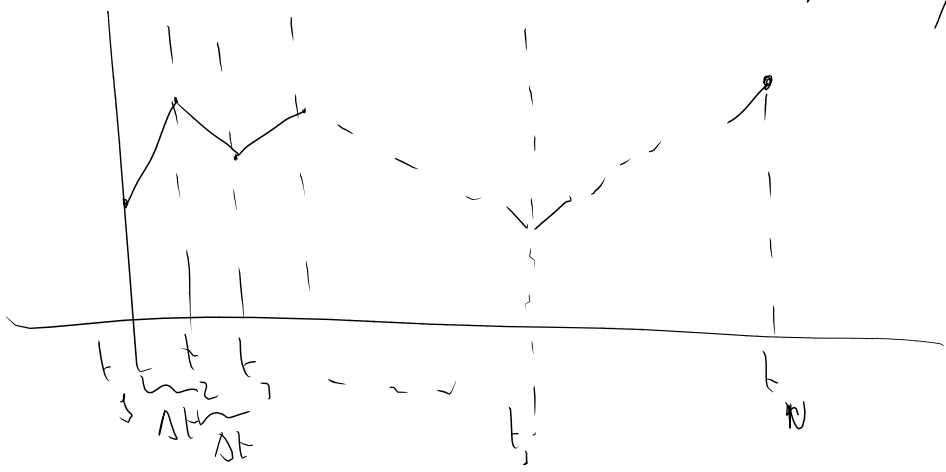
$$= \int \mathcal{D}[x(t)] e^{\frac{i}{\hbar} \int_{t_1}^{t_2} L_d(x(t), \dot{x}(t)) dt}$$

$$x(t_1) = x_1$$

$$x(t_N) = x_N$$

$$S = \sum \Delta t \cdot S(t_i, t_{i-1})$$

$$\Rightarrow S^{\text{free}}(t_i, t_{i-1}) = \frac{m}{2} \frac{(x_i - x_{i-1})^2}{\Delta t^2}$$



$$x_i = x(t_i)$$

$$\int dx_i \exp \left\{ \frac{i}{\hbar} \Delta t \left[S(t_{i+1}, t_i) + S(t_i, t_{i-1}) \right] \right\}$$

$$= \int dx_i \exp \left\{ \frac{i}{\hbar} \Delta t \frac{1}{2} m \left[\frac{(x_{i+1} - x_i)^2}{\Delta t^2} + \frac{(x_i - x_{i-1})^2}{\Delta t^2} \right] \right\}$$

$$= \int dx_i \exp \left\{ \frac{i m}{2 \hbar} \frac{1}{\Delta t} \left(2x_i^2 - 2x_i(x_{i+1} + x_{i-1}) + x_{i+1}^2 + x_{i-1}^2 - \frac{1}{4}(x_{i+1} + x_{i-1})^2 + \frac{1}{4}(x_{i+1} - x_{i-1})^2 \right) \right\}$$

$$= \int_{-\infty}^{\infty} dx_i \exp \left\{ \frac{im}{2\hbar\Delta t} \left[2 \left(x_i - \frac{1}{2}(x_{i+2} + x_{i-2}) \right)^2 + x_{i+2}^2 + x_{i-2}^2 - \frac{1}{2}(x_{i+2} + x_{i-2})^2 \right] \right\}$$

$$y_i = x_i - \frac{1}{2}(x_{i+2} + x_{i-2})$$

$$= \int_{-\infty}^{\infty} dy_i \exp \left\{ \frac{im}{2\hbar\Delta t} \left[2y_i^2 + \frac{1}{2}(x_{i+2} - x_{i-2})^2 \right] \right\}$$

$$\alpha = -\frac{im}{\hbar\Delta t}$$

$$= \sqrt{\frac{\pi}{\alpha}} \exp \left\{ \frac{im}{2 \cdot 2\hbar\Delta t} (x_{i+2} - x_{i-2})^2 \right\}$$

$$= \sqrt{\frac{i\pi\hbar\Delta t}{m}} \exp \left\{ \frac{i}{\hbar\Delta t} \Delta t \left(\frac{1}{2} m \frac{(x_{i+2} - x_{i-2})^2}{(\Delta t)^2} \right) \right\}$$

$$\int_{-\infty}^{\infty} dx_i \int_{-\infty}^{\infty} dx_{i+2} \exp \left\{ \frac{i}{\hbar} \left(S(i+2, i+3) + S(i+2, i) + S(i, i-1) \right) \right\}$$

$$= \int_{-\infty}^{\infty} dx_{i+2} \left(\frac{i\pi\hbar\Delta t}{m} \right)^{1/2} \exp \left\{ \frac{i}{\hbar} \Delta t \frac{1}{2} m \left(\frac{x_{i+2} - x_{i+3}}{\Delta t} \right)^2 \right\} \leftarrow$$

$$+ \frac{i}{\hbar} \Delta t \frac{1}{2} m \frac{(x_{i+2} - x_{i-2})^2}{\Delta t^2} \right\}$$

$$= \int_{-\infty}^{\infty} dx_{i+2} \left(\frac{i\pi\hbar\Delta t}{m} \right)^{1/2} \exp \left\{ \frac{i}{\hbar} \Delta t \frac{1}{2} m \left[\frac{1}{(\Delta t)^2} \frac{1}{n} \left[n(x_{i+2} - x_{i+3})^2 + (x_{i+2} - x_{i-2})^2 \right] \right] \right\}$$

$$= \int_{-\infty}^{\infty} dx_{i+1} \left(\frac{i \sigma \hbar \Delta t}{m} \right)^{1/2} \exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \frac{1}{n} \right.$$

$$\left. \left[(n+1) x_{i+1}^2 - 2 x_{i+1} (n x_{i+2} + x_{i-1}) + n x_{i+2}^2 + x_{i-1}^2 \right. \right. \\ \left. \left. + (n+1) \left(\frac{n x_{i+2} + x_{i-1}}{n+1} \right)^2 - (n+1) \left(\frac{n x_{i+2} + x_{i-1}}{n+1} \right)^2 \right] \right\}$$

$$= \int_{-\infty}^{\infty} dx_{i+1} \left(\frac{i \sigma \hbar \Delta t}{m} \right)^{1/2} \exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \frac{1}{n} \right.$$

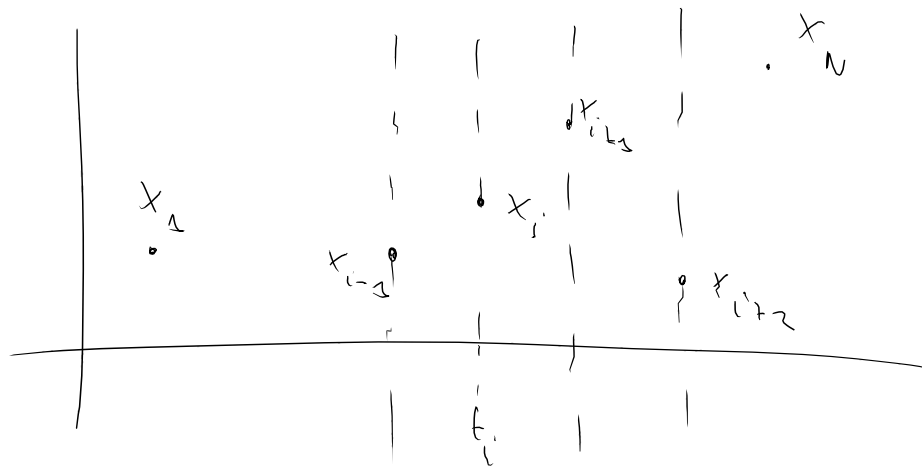
$$\left. \left[(n+1) \left(x_{i+1} - \frac{(n x_{i+2} + x_{i-1})}{n+1} \right)^2 + n x_{i+2}^2 + x_{i-1}^2 \right. \right. \\ \left. \left. - \frac{n^2 x_{i+2}^2 + x_{i-1}^2 + 2n x_{i+2} x_{i-1}}{n+1} \right] \right\}$$

$$= \left(\frac{i \sigma \hbar \Delta t}{m} \right)^{1/2} \left[\frac{\sigma}{-\frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \left(\frac{n+1}{n} \right)} \right]^{1/2} \\ \exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \frac{1}{n} \left[x_{i+2}^2 \left(n - \frac{n^2}{n+1} \right) + x_{i-1}^2 \left(1 - \frac{1}{n+1} \right) \right. \right.$$

$$\left. - \frac{2n x_{i+2} x_{i-1}}{n+1} \right] \right\}$$

$$= \left(\frac{i \sigma \hbar \Delta t}{m} \right)^{1/2} \left(\frac{i \sigma \hbar 2n}{m (n+1) \Delta t} \right)^{1/2}$$

$$\exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \frac{1}{n+1} \left(x_{i+2} - x_{i-1} \right)^2 \right\}$$



evaluate all $N-2$ integrals

$$\langle x_N, t_N | x_1, t_1 \rangle = \exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{1}{\Delta t} \frac{1}{(N-1)} (x_N - x_1)^2 \right\}$$

$$\left\{ \left(\frac{2i\eta\hbar\Delta t}{m} \right)^{\frac{N-2}{2}} \left(\frac{1}{1+\Delta} \frac{2}{2+\Delta} \frac{3}{3+\Delta} \dots \frac{(N-1)}{N-1+\Delta} \right)^{1/2} \right\}$$

$$\lim_{\substack{N \rightarrow \infty \\ \Delta t \rightarrow 0 \\ N\Delta t = t_N - t_1}} \left(\frac{2i\eta\hbar\Delta t}{m} \right)^{\frac{N-1}{2}} \exp \left\{ \frac{i}{\hbar} \frac{1}{2} m \frac{(x_N - x_1)^2}{(t_N - t_1)} \right\} \sqrt{\frac{m}{2i\eta\hbar(t_N - t_1)}}$$

$$\langle x_N, t_N | x_1, t_1 \rangle = \sqrt{\frac{m}{2i\eta\hbar(t_N - t_1)}} \exp \left\{ \frac{i m}{2\hbar} \frac{(x_N - x_1)^2}{(t_N - t_1)} \right\}$$

$$\langle x_N, t_N | x_1, t_1 \rangle$$

$$= \lim_{\Delta t \rightarrow 0} \left(\frac{1}{2\pi i \hbar \Delta t} \right)^{(N-1)/2} \int_{t_1}^{t_2} \int_{x_1}^{x_2} \dots \int_{x_{N-2}}^{x_{N-1}} e^{\frac{i}{\hbar} S} \\ = \int \mathcal{D}[x(t)] e^{\frac{i}{\hbar} \int_{t_1}^{t_2} L_{cl}(x(t), \dot{x}(t)) dt}$$

$$S[x] = S[x_{cl} + \eta]$$

$$\begin{aligned} &= S[x_{cl}] + \overset{=0}{\frac{\delta S}{\delta \eta}} \bigg|_{x=x_{cl}} \eta + \frac{\delta^2 S}{\delta \eta^2} \bigg|_{x=x_{cl}} \frac{\eta^2}{2} + \dots \end{aligned}$$

$$\psi = \sqrt{\rho} e^{\frac{i}{\hbar} S}$$

$$S \approx S_{cl}$$

$$\vec{E} = -\nabla\phi \quad \phi \rightarrow \phi + \Lambda_0$$

$$H = \frac{p^2}{2m} + \phi \quad \tilde{H} = \frac{\vec{p}^2}{2m} + \phi + \Lambda_0$$

$\langle x \rangle$, $\langle p \rangle$, ... should be same for both systems.

$$H|\psi\rangle = E|\psi\rangle \quad \tilde{H}|\tilde{\psi}\rangle = \tilde{E}|\tilde{\psi}\rangle$$

$$|\tilde{\psi}\rangle = U|\psi\rangle, \quad U = ?$$

$$\langle \psi | \tilde{\psi} \rangle = 1 = \langle \psi | \psi \rangle$$

$$\langle x \rangle_{\psi} = \langle x \rangle_{\tilde{\psi}} \Rightarrow \boxed{x = U^\dagger x U}$$

$$\tilde{E} = E + \Lambda_0$$

$$\tilde{H} = H + \Lambda_0$$

$$|\tilde{\psi}\rangle_{t=0} = |\psi\rangle_{t=0}$$

$$|\tilde{\psi}(t)\rangle = e^{-\frac{i}{\hbar} \tilde{H} t} |\tilde{\psi}(t=0)\rangle$$

$$= e^{-\frac{i}{\hbar} H t} e^{-\frac{i}{\hbar} \Lambda_0 t} |\psi(t=0)\rangle$$

$$\boxed{|\tilde{\psi}(t)\rangle = e^{-\frac{i}{\hbar} \Lambda_0 t} |\psi(t)\rangle}$$

$$|\psi(t)\rangle = e^{-\frac{i}{\hbar} E t} |\psi(t=0)\rangle$$

$$|\tilde{\psi}(t)\rangle = e^{-\frac{i}{\hbar} (E + \Lambda_0) t} |\psi(t=0)\rangle$$

$$|\hat{\psi}(t)\rangle = e^{-\frac{i}{\hbar} (E + \Lambda_0) t} |\tilde{\psi}(t=0)\rangle$$

$$\hat{E} = E + \Lambda_0$$

$$\begin{aligned} \tilde{\psi}(\vec{r}, t) &= \int d\vec{r}' \langle \vec{r} | \tilde{\psi}(t) \rangle \tilde{\psi}(\vec{r}', 0) \\ &= \int d\vec{r}' \langle \vec{r} | \tilde{\psi}(t) \rangle \psi(\vec{r}', 0) \end{aligned}$$

$$\langle \vec{r} | \tilde{\psi}(t) \rangle = \int \mathcal{D}[x(t)] e^{\frac{i}{\hbar} \int dt \tilde{L}}$$

$$\tilde{L} = T - \tilde{\phi} = T - (\phi + \Lambda_0) = L - \Lambda_0$$

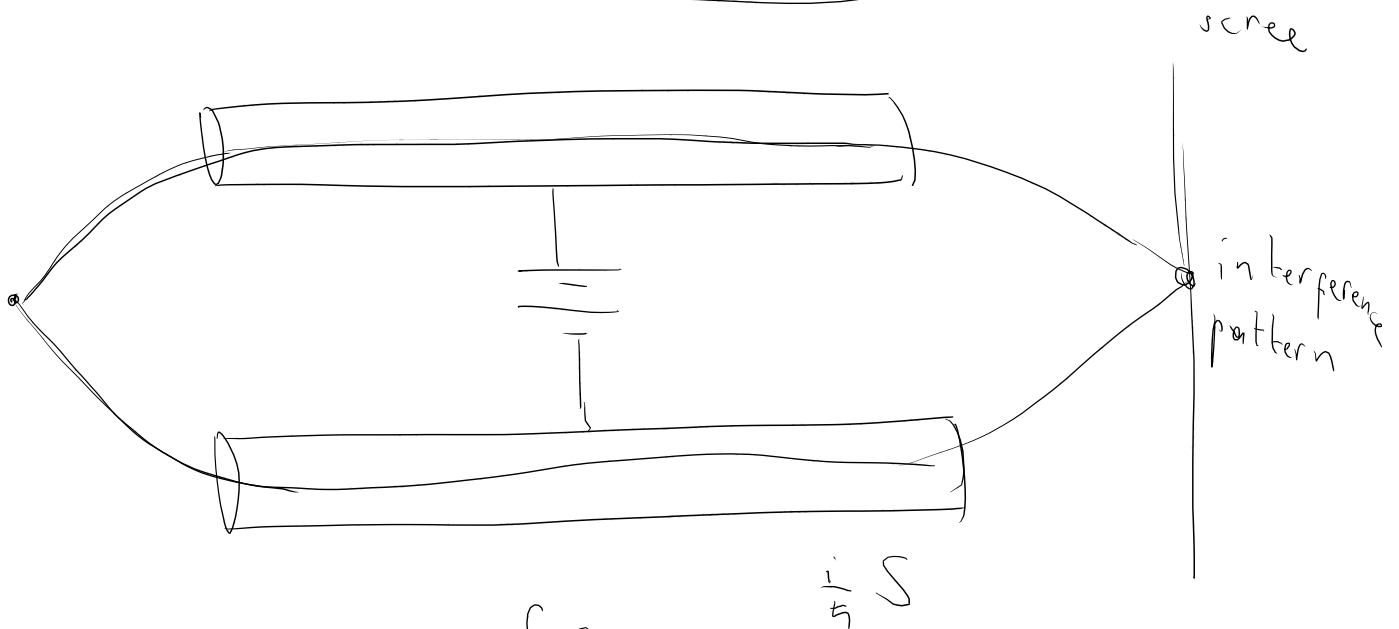
$$\langle \vec{r} | \tilde{\psi}(t) \rangle = \int \mathcal{D}[x(t)] e^{\frac{i}{\hbar} \int dt L - \frac{i}{\hbar} \int dt \Lambda_0}$$

$$\langle \vec{r} | \tilde{\psi}(t) \rangle = e^{-\frac{i}{\hbar} \int dt \Lambda_0} \int \mathcal{D}[x(t)] e^{\frac{i}{\hbar} \int dt L}$$

$$\langle \vec{r} | \tilde{\psi}(t) \rangle = e^{-\frac{i}{\hbar} \int dt \Lambda_0} \langle \vec{r} | \psi(t) \rangle$$

$$\begin{aligned} \tilde{\psi}(\vec{r}, t) &= \int d^3\vec{r}' \langle \vec{r}, t | \vec{r}', 0 \rangle \psi(\vec{r}', 0) \\ &= e^{-\frac{i}{\hbar} \int dt \Lambda_0} \int d^3\vec{r}' \langle \vec{r}, t | \vec{r}', 0 \rangle \psi(\vec{r}', 0) \end{aligned}$$

$$\tilde{\psi}(\vec{r}, t) = e^{-\frac{i}{\hbar} \int dt \Lambda_0} \psi(\vec{r}, 0)$$



$$\begin{aligned} \langle x_f, t_f | x_i, t_i \rangle &= \int \mathcal{D}[x] e^{\frac{i}{\hbar} S} \\ &= \int \mathcal{D}[x]_{\text{above}} e^{\frac{i}{\hbar} S_{\text{above}}} \\ &+ \int \mathcal{D}[x]_{\text{below}} e^{\frac{i}{\hbar} S_{\text{below}}} \end{aligned}$$

$$S_{\text{above}} = \int dt \left(\cancel{A} - \phi^{\text{above}} \right) = \cancel{S}^0 - \phi^{\text{above}}(t_f - t_i)$$

$$S_{\text{below}} = \cancel{S}^0 - \phi^{\text{below}}(t_f - t_i)$$

$$\langle x_f, t_f | x_i, t_i \rangle = \langle x_f, t_f | x_i, t_i \rangle_{\text{above}} e^{-\frac{i}{\hbar}(t_f - t_i)\phi^{\text{above}}} + \langle x_f, t_f | x_i, t_i \rangle_{\text{below}} e^{\frac{i}{\hbar}(t_f - t_i)\phi^{\text{below}}}$$

$$= \left[\cancel{A}_1 + \cancel{A}_2 e^{-\frac{i}{\hbar}(t_f - t_i)(\phi^{\text{below}} - \phi^{\text{above}})} \right]$$

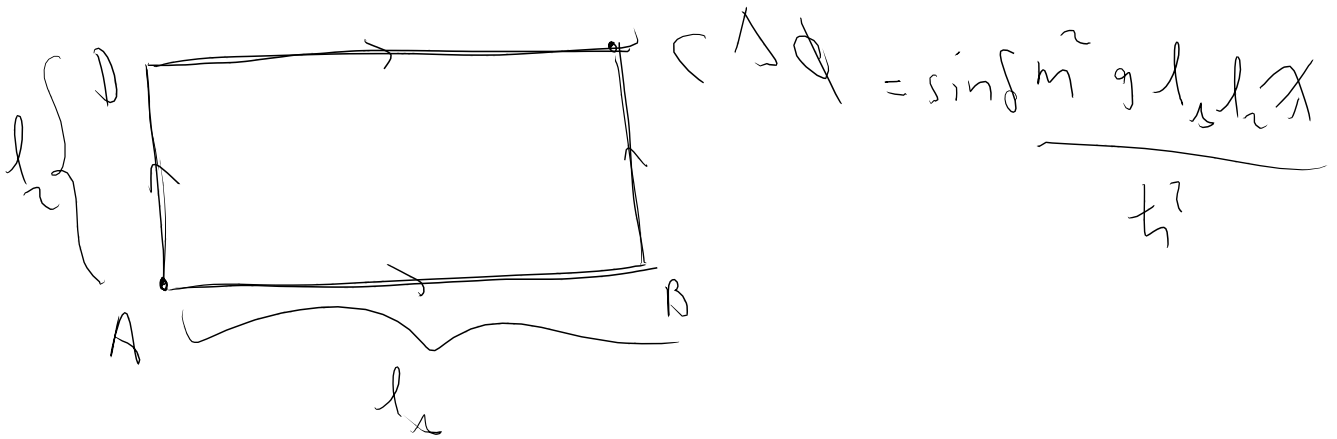
overall phase $\Rightarrow e^{-\frac{i}{\hbar}(t_f - t_i)\phi^{\text{above}}}$

$$L = \frac{1}{2} m v^2 - m g z$$

$$S = \int L dt$$

$$\delta S = 0 \Rightarrow \delta \int \left(\frac{1}{2} m v^2 - m g z \right) dt = 0$$

$$H = \frac{p^2}{2m} + m g z$$

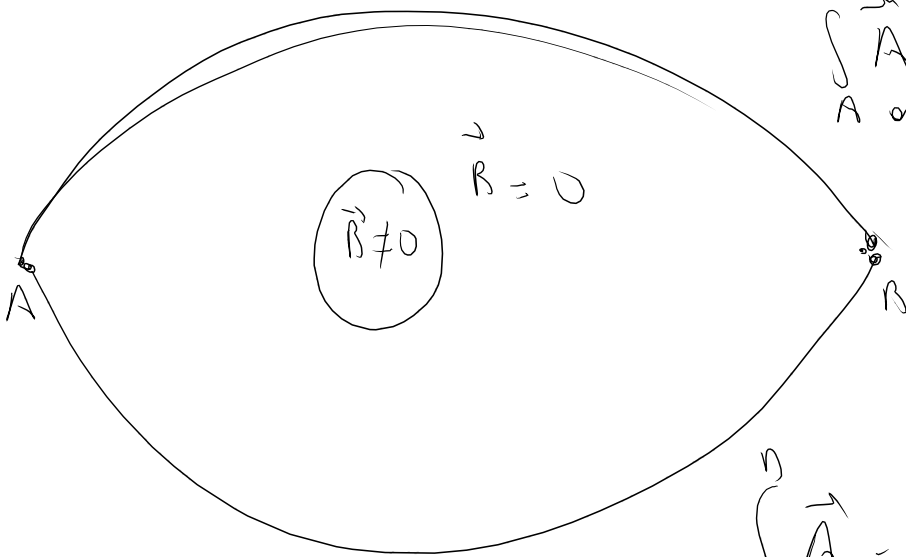


$$\cancel{\mathcal{L}} = (\mathcal{T} - U) - \frac{e}{c} \vec{v} \cdot \vec{A}$$

$$\int \vec{A} = \int_{\vec{A}=0} - \frac{e}{c} \int \vec{A} \cdot \vec{v} dt$$

$$= \int_{\vec{A}=0} - \frac{e}{c} \int \vec{A} \cdot d\vec{l}$$

$$\int_{A \text{ above}}^B \vec{A} \cdot d\vec{l}$$



$$\int_{A \text{ below}}^B \vec{A} \cdot d\vec{l}$$

$$\text{phase difference} = \int_{A \text{ above}}^B \vec{A} \cdot d\vec{l} - \int_{A \text{ below}}^B \vec{A} \cdot d\vec{l}$$

$$= \oint \vec{A} \cdot d\vec{l} = \int (\vec{\nabla} \times \vec{A}) \cdot d\vec{S}$$

$$\text{phase difference} = \int \vec{B} \cdot d\vec{S} = \Phi_B \text{ : magnetic flux}$$